视觉分类

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In [1]: import os
        import torch
        import torchvision
        from torch import nn
        from d2l import torch as d2l
In [2]: #@save
        d21.DATA_HUB['dog_tiny'] = (d21.DATA_URL + 'kaggle_dog_tiny.zip',
                                   '0cb91d09b814ecdc07b50f31f8dcad3e81d6a86d')
        # 如果使用KaggLe比赛的完整数据集,请将下面的变量更改为False
        demo = True
        if demo:
            data_dir = d21.download_extract('dog_tiny')
            data_dir = os.path.join('...', 'data', 'dog-breed-identification')
      Downloading ..\data\kaggle_dog_tiny.zip from http://d21-data.s3-accelerate.amazon
      aws.com/kaggle_dog_tiny.zip...
In [3]: def reorg_dog_data(data_dir, valid_ratio):
            labels = d21.read_csv_labels(os.path.join(data_dir, 'labels.csv'))
            d2l.reorg_train_valid(data_dir, labels, valid_ratio)
            d21.reorg_test(data_dir)
        batch size = 32 if demo else 128
        valid ratio = 0.1
        reorg_dog_data(data_dir, valid_ratio)
In [4]: transform train = torchvision.transforms.Compose([
            # 随机裁剪图像,所得图像为原始面积的0.08~1之间,高宽比在3/4和4/3之间。
           # 然后,缩放图像以创建224x224的新图像
           torchvision.transforms.RandomResizedCrop(224, scale=(0.08, 1.0),
                                                   ratio=(3.0/4.0, 4.0/3.0)),
           torchvision.transforms.RandomHorizontalFlip(),
           # 随机更改亮度,对比度和饱和度
           torchvision.transforms.ColorJitter(brightness=0.4,
                                             contrast=0.4,
                                             saturation=0.4),
           #添加随机噪声
           torchvision.transforms.ToTensor(),
            # 标准化图像的每个通道
            torchvision.transforms.Normalize([0.485, 0.456, 0.406],
                                           [0.229, 0.224, 0.225])])
In [5]: transform_test = torchvision.transforms.Compose([
           torchvision.transforms.Resize(256),
            # 从图像中心裁切224x224大小的图片
           torchvision.transforms.CenterCrop(224),
           torchvision.transforms.ToTensor(),
            torchvision.transforms.Normalize([0.485, 0.456, 0.406],
                                           [0.229, 0.224, 0.225])])
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In [6]: train_ds, train_valid_ds = [torchvision.datasets.ImageFolder(
             os.path.join(data_dir, 'train_valid_test', folder),
             transform=transform_train) for folder in ['train', 'train_valid']]
         valid_ds, test_ds = [torchvision.datasets.ImageFolder(
             os.path.join(data_dir, 'train_valid_test', folder),
             transform=transform_test) for folder in ['valid', 'test']]
In [7]: | train_iter, train_valid_iter = [torch.utils.data.DataLoader(
             dataset, batch_size, shuffle=True, drop_last=True)
             for dataset in (train_ds, train_valid_ds)]
         valid_iter = torch.utils.data.DataLoader(valid_ds, batch_size, shuffle=False,
                                                  drop_last=True)
         test_iter = torch.utils.data.DataLoader(test_ds, batch_size, shuffle=False,
                                                 drop last=False)
In [8]: def get_net(devices):
             finetune_net = nn.Sequential()
             finetune_net.features = torchvision.models.resnet34(pretrained=True)
             # 定义一个新的输出网络, 共有120个输出类别
             finetune_net.output_new = nn.Sequential(nn.Linear(1000, 256),
                                                    nn.ReLU(),
                                                     nn.Linear(256, 120))
             #将模型参数分配给用于计算的CPU或GPU
             finetune net = finetune net.to(devices[0])
             # 冻结参数
             for param in finetune_net.features.parameters():
                 param.requires_grad = False
             return finetune_net
In [9]: loss = nn.CrossEntropyLoss(reduction='none')
         def evaluate_loss(data_iter, net, devices):
             1_{sum}, n = 0.0, 0
             for features, labels in data_iter:
                 features, labels = features.to(devices[0]), labels.to(devices[0])
                 outputs = net(features)
                 1 = loss(outputs, labels)
                 1_sum += 1.sum()
                 n += labels.numel()
             return (1 sum / n).to('cpu')
In [10]: def train(net, train_iter, valid_iter, num_epochs, lr, wd, devices, lr_period,
                   lr decay):
             # 只训练小型自定义输出网络
             net = nn.DataParallel(net, device ids=devices).to(devices[0])
             trainer = torch.optim.SGD((param for param in net.parameters()
                                        if param.requires_grad), lr=lr,
                                       momentum=0.9, weight_decay=wd)
             scheduler = torch.optim.lr_scheduler.StepLR(trainer, lr_period, lr_decay)
             num batches, timer = len(train iter), d21.Timer()
             legend = ['train loss']
             if valid iter is not None:
                 legend.append('valid loss')
             animator = d2l.Animator(xlabel='epoch', xlim=[1, num_epochs],
                                     legend=legend)
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for epoch in range(num_epochs):
                metric = d21.Accumulator(2)
                for i, (features, labels) in enumerate(train_iter):
                    features, labels = features.to(devices[0]), labels.to(devices[0])
                    trainer.zero grad()
                    output = net(features)
                    1 = loss(output, labels).sum()
                    1.backward()
                    trainer.step()
                    metric.add(1, labels.shape[0])
                    timer.stop()
                    if (i + 1) % (num_batches // 5) == 0 or i == num_batches - 1:
                         animator.add(epoch + (i + 1) / num_batches,
                                      (metric[0] / metric[1], None))
                measures = f'train loss {metric[0] / metric[1]:.3f}'
                if valid_iter is not None:
                    valid_loss = evaluate_loss(valid_iter, net, devices)
                    animator.add(epoch + 1, (None, valid_loss.detach().cpu()))
                scheduler.step()
            if valid_iter is not None:
                measures += f', valid loss {valid_loss:.3f}'
            print(measures + f'\n{metric[1] * num_epochs / timer.sum():.1f}'
                  f' examples/sec on {str(devices)}')
In [ ]: devices, num_epochs, lr, wd = d21.try_all_gpus(), 10, 1e-4, 1e-4
        lr_period, lr_decay, net = 2, 0.9, get_net(devices)
        train(net, train_iter, valid_iter, num_epochs, lr, wd, devices, lr_period,
              lr_decay)
       c:\Users\DELL\anaconda3\envs\pytorch\lib\site-packages\torchvision\models\_utils.
       py:208: UserWarning: The parameter 'pretrained' is deprecated since 0.13 and may
       be removed in the future, please use 'weights' instead.
         warnings.warn(
       c:\Users\DELL\anaconda3\envs\pytorch\lib\site-packages\torchvision\models\ utils.
       py:223: UserWarning: Arguments other than a weight enum or `None` for 'weights' a
       re deprecated since 0.13 and may be removed in the future. The current behavior i
       s equivalent to passing `weights=ResNet34_Weights.IMAGENET1K_V1`. You can also us
       e `weights=ResNet34_Weights.DEFAULT` to get the most up-to-date weights.
         warnings.warn(msg)
       Downloading: "https://download.pytorch.org/models/resnet34-b627a593.pth" to C:\Us
       ers\DELL/.cache\torch\hub\checkpoints\resnet34-b627a593.pth
In [ ]: net = get_net(devices)
        train(net, train_valid_iter, None, num_epochs, lr, wd, devices, lr_period,
              lr decay)
        preds = []
        for data, label in test_iter:
            output = torch.nn.functional.softmax(net(data.to(devices[0])), dim=1)
            preds.extend(output.cpu().detach().numpy())
        ids = sorted(os.listdir(
            os.path.join(data_dir, 'train_valid_test', 'test', 'unknown')))
        with open('submission.csv', 'w') as f:
            f.write('id,' + ','.join(train_valid_ds.classes) + '\n')
            for i, output in zip(ids, preds):
                f.write(i.split('.')[0] + ',' + ','.join(
                     [str(num) for num in output]) + '\n')
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