Mathematical Foundations of Deep Neural Networks, M1407.001200 E. Ryu Spring 2024



Due 5pm, Monday, May 06, 2024

Problem 1: Transpose of downsampling. Consider the downsampling operator $\mathcal{T}: \mathbb{R}^{m \times n} \to \mathbb{R}^{(m/2) \times (n/2)}$, defined as the average pool with a 2×2 kernel and stride 2. For the sake of simplicity, assume m and n are even. Describe the action of \mathcal{T}^{\top} . More specifically, describe how to compute $\mathcal{T}^{\top}(Y)$ for any $Y \in \mathbb{R}^{(m/2) \times (n/2)}$.

Clarification. The downsampling operator \mathcal{T} is a linear operator (why?). Therefore, \mathcal{T} has a matrix representation $A \in \mathbb{R}^{(mn/4)\times (mn)}$ such that

$$\mathcal{T}(X) = (A(X.\operatorname{reshape}(mn))).\operatorname{reshape}(m/2, n/2)$$

for all $X \in \mathbb{R}^{m \times n}$. The adjoint \mathcal{T}^{\top} has two equivalent definitions. One definition is

$$\mathcal{T}^{\top}(Y) = (A^{\top}(Y.\operatorname{reshape}(mn/4))).\operatorname{reshape}(m,n)$$

for all $Y \in \mathbb{R}^{(m/2) \times (n/2)}$. Another is

$$\sum_{i=1}^{m/2} \sum_{j=1}^{n/2} Y_{ij}(\mathcal{T}(X))_{ij} = \sum_{i=1}^{m} \sum_{j=1}^{n} (\mathcal{T}^{\top}(Y))_{ij}(X)_{ij}$$

for all $X \in \mathbb{R}^{m \times n}$ and $Y \in \mathbb{R}^{(m/2) \times (n/2)}$.

 Hint . To spoil the suspence, \mathcal{T}^{\top} is a constant times the nearest neighbor upsampling. Explain why in your answer.

Solution. First, we will show that the downsampling operator \mathcal{T} is a linear operator. We will abuse the notation of matrix as vector, such as X, Y as

$$X = \begin{pmatrix} x_{11} & x_{12} & \cdots & x_{1n} \\ x_{21} & x_{22} & \cdots & x_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ x_{m1} & x_{m2} & \cdots & x_{mn} \end{pmatrix} = \begin{pmatrix} x_{11} \\ x_{21} \\ \vdots \\ x_{m1} \\ \vdots \\ x_{m2} \\ x_{13} \\ \vdots \\ \vdots \\ x_{mn} \end{pmatrix}$$

and

$$Y = \begin{pmatrix} y_{11} & y_{12} & \cdots & y_{1\frac{n}{2}} \\ y_{21} & y_{22} & \cdots & y_{2\frac{n}{2}} \\ \vdots & \vdots & \ddots & \vdots \\ y_{\frac{m}{2}1} & y_{\frac{m}{2}2} & \cdots & y_{\frac{m}{2}\frac{n}{2}} \end{pmatrix} = \begin{pmatrix} y_{11} \\ y_{21} \\ \vdots \\ y_{\frac{m}{2}1} \\ \vdots \\ y_{\frac{m}{2}2} \\ y_{13} \\ \vdots \\ \vdots \\ y_{\frac{m}{2}\frac{n}{2}} \end{pmatrix}.$$

This is equivalent to concatenating all column vectors in one column. Then, we have

$$\mathcal{T}(X) = \frac{1}{4} \begin{pmatrix} x_{11} + x_{12} + x_{21} + x_{22} \\ x_{31} + x_{32} + x_{41} + x_{42} \\ \vdots \\ x_{(m-1)1} + x_{(m-1)2} + x_{m1} + x_{m2} \\ \vdots \\ \vdots \\ x_{(m-1)(n-1)} + x_{(m-1)n} + x_{m(n-1)} + x_{mn} \end{pmatrix}.$$

Then for any $\alpha \in \mathbb{R}$,

$$\mathcal{T}(\alpha X) = \frac{1}{4} \begin{pmatrix} \alpha x_{11} + \alpha x_{12} + \alpha x_{21} + \alpha x_{22} \\ \alpha x_{11} + \alpha x_{12} + \alpha x_{21} + \alpha x_{22} \\ \vdots \\ \alpha x_{(m-1)1} + \alpha x_{(m-1)2} + \alpha x_{m1} + \alpha x_{m2} \\ \vdots \\ \alpha x_{(m-1)(n-1)} + \alpha x_{(m-1)n} + \alpha x_{m(n-1)} + \alpha x_{mn} \end{pmatrix} = \frac{\alpha}{4} \mathcal{T}(X)$$

so \mathcal{T} is a linear operator.

Solution 1. We use the equation

$$\sum_{i=1}^{m/2} \sum_{j=1}^{n/2} Y_{ij}(\mathcal{T}(X))_{ij} = \sum_{i=1}^{m} \sum_{j=1}^{n} (\mathcal{T}^{\top}(Y))_{ij}(X)_{ij}$$

for any $X \in \mathbb{R}^{m \times n}$ and $Y \in \mathbb{R}^{(m/2) \times (n/2)}$ to describe \mathcal{T}^{T} . To avoid confusion, we refer to the index of Y by \bar{i} and \bar{j} . Due to the definition of our downsampling operator \mathcal{T} as an average pool,

$$(\mathcal{T}(X))_{i\bar{j}} = \frac{1}{4} \sum_{k=1}^{2} \sum_{l=1}^{2} x_{2\bar{i}-2+k, 2\bar{j}-2+k}.$$

Then we get

$$\sum_{\bar{i}=1}^{m/2} \sum_{\bar{j}=1}^{n/2} Y_{i\bar{j}}(\mathcal{T}(X))_{i\bar{j}} = \sum_{i=1}^{m} \sum_{j=1}^{n} (\mathcal{T}^{\top}(Y))_{ij}(X)_{ij}$$

$$= \sum_{\bar{i}=1}^{m/2} \sum_{\bar{j}=1}^{n/2} Y_{i\bar{j}} \cdot \frac{1}{4} \left(\sum_{k=1}^{2} \sum_{l=1}^{2} x_{2\bar{i}-2+k, 2\bar{j}-2+k} \right)$$

$$= \sum_{\bar{i}=1}^{m/2} \sum_{\bar{j}=1}^{n/2} \sum_{k=1}^{2} \sum_{l=1}^{2} \frac{1}{4} Y_{i\bar{j}} x_{2\bar{i}-2+k, 2\bar{j}-2+k}$$

From the index identification

$$\begin{cases} i = 2\bar{i} - 2 + k & (\bar{i} = 1, \dots, \frac{m}{2}, k = 1, 2) \\ j = 2\bar{j} - 2 + l & (\bar{j} = 1, \dots, \frac{n}{2}, l = 1, 2) \end{cases} \iff \begin{cases} \bar{i} = \lfloor \frac{i+1}{2} \rfloor & (i = 1, \dots, m) \\ \bar{j} = \lfloor \frac{j+1}{2} \rfloor & (j = 1, \dots, n) \end{cases}$$

where $t \mapsto \lfloor t \rfloor$ is a floor function, we can rephrase the above summation as

$$\sum_{\overline{i}=1}^{m/2} \sum_{\overline{j}=1}^{n/2} Y_{\overline{i}\overline{j}}(\mathcal{T}(X))_{\overline{i}\overline{j}} = \sum_{i=1}^{m} \sum_{j=1}^{n} (\mathcal{T}^{\top}(Y))_{ij}(X)_{ij}$$
$$= \sum_{i=1}^{m} \sum_{j=1}^{n} \frac{1}{4} y_{\lfloor \frac{i+1}{2} \rfloor, \lfloor \frac{j+1}{2} \rfloor} x_{ij}$$

Therefore, $(\mathcal{T}^{\uparrow}(Y))_{ij} = y_{\lfloor \frac{i+1}{2} \rfloor, \lfloor \frac{j+1}{2} \rfloor}$ and converting this to $m \times n$ matrix, we get

$$\mathcal{T}^{\top}(Y) = \frac{1}{4} \begin{pmatrix} y_{11} & y_{11} & \cdots & y_{1\frac{n}{2}} \\ y_{11} & y_{11} & \cdots & y_{1\frac{n}{2}} \\ \vdots & \vdots & \ddots & \vdots \\ y_{\frac{m}{2}1} & y_{\frac{m}{2}1} & \cdots & y_{\frac{m}{2}\frac{n}{2}} \end{pmatrix}$$

Solution 2. Since \mathcal{T} is a linear operator, we can consider $\mathcal{T}(X)$ as multiplying matrix T in the left side of X, where T is defined as

$$T = \frac{1}{4} \begin{pmatrix} T_{11} & T_{12} & \cdots & T_{1n} \\ T_{21} & T_{22} & \cdots & T_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ T_{\frac{n}{2}1} & T_{\frac{n}{2}2} & \cdots & T_{\frac{n}{2}n} \end{pmatrix}$$

that $T_{i,j}$ is $\frac{m}{2} \times m$ matrix, $T_{i,j} = 0$ except j = 2 * i - 1 or j = 2i, and

$$T_{i,2i} = T_{i,2i-1} = \begin{pmatrix} 1 & 1 & 0 & 0 & 0 & \cdots & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 1 & 0 & \cdots & 0 & 0 & 0 & 0 \\ \vdots & \vdots & \vdots & \vdots & \vdots & \ddots & \vdots & \vdots & \vdots & \vdots \\ 0 & 0 & 0 & 0 & 0 & \cdots & 1 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & \cdots & 0 & 0 & 1 & 1 \end{pmatrix}.$$

Therefore, \mathcal{T} can be represented as matrix, and it is linear operator. Now, we calculate \mathcal{T}^{\top} with T^{\intercal} . We have

$$T^{\mathsf{T}} = \frac{1}{4} \begin{pmatrix} T_{11}^{\mathsf{T}} & T_{21}^{\mathsf{T}} & \cdots & T_{\frac{n}{2}1}^{\mathsf{T}} \\ T_{12}^{\mathsf{T}} & T_{22}^{\mathsf{T}} & \cdots & T_{\frac{n}{2}2}^{\mathsf{T}} \\ \vdots & \vdots & \ddots & \vdots \\ T_{1n}^{\mathsf{T}} & T_{2n}^{\mathsf{T}} & \cdots & T_{\frac{n}{2}n}^{\mathsf{T}} \end{pmatrix},$$

which indicates

$$\mathcal{T}^{\top}(Y) = T^{\intercal} \begin{pmatrix} y_{11} \\ y_{21} \\ y_{21} \\ \vdots \\ y_{\frac{m}{2}1} \\ y_{11} \\ y_{21} \\ \vdots \\ y_{\frac{m}{2}1} \\ y_{12} \\ \vdots \\ y_{\frac{m}{2}2} \\ y_{13} \\ \vdots \\ \vdots \\ y_{\frac{m}{2}2} \\ y_{22} \\ y_{22} \\ y_{22} \\ \vdots \\ y_{\frac{m}{2}2} \\ y_{$$

Converting this to $m \times n$ matrix, we have

$$\mathcal{T}^{\top}(Y) = \frac{1}{4} \begin{pmatrix} y_{11} & y_{11} & \cdots & y_{1\frac{n}{2}} \\ y_{11} & y_{11} & \cdots & y_{1\frac{n}{2}} \\ \vdots & \vdots & \ddots & \vdots \\ y_{\frac{m}{2}1} & y_{\frac{m}{2}1} & \cdots & y_{\frac{m}{2}\frac{n}{2}} \end{pmatrix}$$

and this is also the nearest neighbor upsampling.

Problem 2: Nearest neighbor upsampling. How is the nearest neighbor upsampling operator an instance of transpose convolution? Specifically, describe how

```
layer = nn.Upsample(scale_factor=r, mode='nearest')
```

where r is a positive integer, can be equivalently represented by

```
layer = nn.ConvTranspose2d(...)
layer.weight.data = ...
```

with ... appropriately filled in.

Solution.

```
layer = nn.ConvTranspose2d(kernel_size=r, stride=r, bias=False)
layer.weight.data = torch.ones(r,r)
```

We can easily check that this perform nearest mode of Upsampling.

Problem 3: f-divergence. Let X and Y be two continuous random variables with densities p_X and p_Y . The f-divergence of X from Y is defined as

$$D_f(X||Y) = \int f\left(\frac{p_X(x)}{p_Y(x)}\right) p_Y(x) \ dx,$$

where f is a convex function such that f(1) = 0.

- (a) Show that $D_f(X||Y) \geq 0$.
- (b) Show that $f = -\log t$ and $f = t \log t$ correspond to the KL divergence.

Solution. (a) Use Jensen's Inequality since f is convex. We have

$$D_f(X||Y) = \int f\left(\frac{p_X(x)}{p_Y(x)}\right) p_Y(x) \ dx \ge f\left(\int \frac{p_X(x)}{p_Y(x)} p_Y(x)\right) \ dx = f(1) = 0.$$

(c) Put $f = -\log t$, then

$$D_f(X||Y) = \int -\log\left(\frac{p_X(x)}{p_Y(x)}\right) p_Y(x) dx = D_{KL}(Y||X),$$

which is exactly same as KL divergence's definition.

Put $f = t \log t$, then

$$D_f(X||Y) = \int \log\left(\frac{p_X(x)}{p_Y(x)}\right) p_X(x) dx = D_{KL}(X||Y),$$

which is exactly same as KL divergence's definition.

Problem 4: Generalized inverse transform sampling. Let $F: \mathbb{R} \to [0,1]$ be the CDF of a random variable and let $U \sim \text{Uniform}([0,1])$. If F is continuous and strictly increasing and therefore invertible, then $F^{-1}(U)$ is a random variable with CDF F, because

$$\mathbb{P}(F^{-1}(U) \le t) = \mathbb{P}(U \le F(t)) = F(t).$$

When F is not necessarily invertible, the generalized inverse of F is $G:(0,1)\to\mathbb{R}$ with

$$G(u) = \inf\{x \in \mathbb{R} \mid u \le F(x)\}.$$

Show that G(U) is a random variable with CDF F.

Hint. Use the fact that F is right-continuous, i.e., $\lim_{h\to 0^+} F(x+h) = F(x)$ for all $x\in\mathbb{R}$, and that $\lim_{x\to -\infty} F(x) = 0$.

Solution. We first show $G(u) \leq x \iff u \leq F(x)$ for any $u \in (0,1)$ and $x \in \mathbb{R}$.

- (\Leftarrow) If $u \leq F(x)$, then $G(u) = \inf\{w \mid u \leq F(w)\} \leq x$.
- (\Rightarrow) The infimum of $G(u)=\inf\{x\in\mathbb{R}\,|\,u\leq F(x)\}$ is attained since F right-continuous and nondecreasing and since $\lim_{x\to-\infty}F(x)=0$. Therefore, $u\leq F(G(u))\leq F(x)$, since F is nondecreasing.

We now complete the proof:

$$\mathbb{P}\left(G(U) \leq x\right) = \mathbb{P}\left(U \leq F(x)\right) = F(x).$$

Problem 5: Change of variables formula for Gaussians. If $\varphi \colon \mathbb{R}^n \to \mathbb{R}^n$ is a one-to-one differentiable function, $Y = \varphi(X)$, and Y is a continuous random variable with density function p_Y , then X is a continuous random variable with density function

$$p_X(x) = p_Y(\varphi(x)) \left| \det \frac{\partial \varphi}{\partial x}(x) \right|.$$

Let $Y \in \mathbb{R}^n$ be a continuous random vector with density

$$p_Y(y) = \frac{1}{(2\pi)^{n/2}} e^{-\frac{1}{2}||y||^2},$$

i.e., $Y \sim \mathcal{N}(0, I)$. Let X = AY + b with an invertible matrix $A \in \mathbb{R}^{n \times n}$ and a vector $b \in \mathbb{R}^n$. Define $\Sigma = AA^{\mathsf{T}}$. Show that X is a continuous random vector with density

$$p_X(x) = \frac{1}{\sqrt{(2\pi)^n \det \Sigma}} e^{-\frac{1}{2}(x-b)^{\mathsf{T}}\Sigma^{-1}(x-b)}.$$

Solution. $\left| \det A^{-1} \right| = \left| \det A \right|^{-1} = \left| \det A \det A^{\mathsf{T}} \right|^{-\frac{1}{2}} = \left| \det \Sigma \right|^{-\frac{1}{2}}$, so

$$p_X(x)$$

$$= p_Y(A^{-1}(x-b)) \left| \det \frac{\partial A^{-1}(x-b)}{\partial x} \right|$$

$$= p_Y(A^{-1}(x-b)) \left| \det A^{-1} \right|$$

$$= \frac{1}{(2\pi)^{n/2}} e^{-\frac{1}{2} ||A^{-1}(x-b)||^2} \left| \det \Sigma \right|^{-\frac{1}{2}}$$

$$= \frac{1}{\sqrt{(2\pi)^n \det \Sigma}} e^{-\frac{1}{2}(x-b)^\intercal A^{-\intercal} A^{-1}(x-b)}$$

$$= \frac{1}{\sqrt{(2\pi)^n \det \Sigma}} e^{-\frac{1}{2}(x-b)^\intercal \Sigma^{-1}(x-b)}.$$

Problem 6: Inverse permutation. Let S_n denote the group of length-n permutations. Note that the map $i \mapsto \sigma(i)$ is a bijection. Define $\sigma^{-1} \in S_n$ as the permutation representing the inverse of this map, i.e, $\sigma^{-1}(\sigma(i)) = i$ for $i = 1, \ldots, n$. Describe an algorithm for computing σ^{-1} given σ .

Clarification. In this class, we defined σ as a list of length n containing the elements of $\{1, \ldots, n\}$ exactly once. The output of the algorithm, σ^{-1} , should also be provided as a list.

Clarification. For this problem, it is sufficient to describe the algorithm in equations or pseudocode. There is no need to submit a Python script for this problem.

Solution. When the input permutation $\sigma \in S_n$ is in form of list as $\sigma[i] = \sigma(i)$, we can calculate the inverse of given permutation σ in the following steps.

- 1. Define a list π with a length n.
- 2. For i = 1, ..., n, repeat $\pi[\sigma[i]] \leftarrow i$
- 3. return π

 π is σ^{-1} , an inverse of σ since $\pi(\sigma(i)) = \pi[\sigma[i]] = i$ for i = 1, ..., n.

Problem 7: Permutation matrix. Given a permutation $\sigma \in S_n$, the permutation matrix of σ is defined as

$$P_{\sigma} = \begin{bmatrix} e_{\sigma(1)}^{\mathsf{T}} \\ e_{\sigma(2)}^{\mathsf{T}} \\ \vdots \\ e_{\sigma(n)}^{\mathsf{T}} \end{bmatrix} \in \mathbb{R}^{n \times n},$$

where $e_1, \ldots, e_n \in \mathbb{R}^n$ are the standard unit vectors. Show

- (a) $(P_{\sigma}x)_i = x_{\sigma(i)}$ for all $x \in \mathbb{R}^n$ and $i = 1, \dots, n$,
- (b) $P_{\sigma}^{\mathsf{T}} = P_{\sigma}^{-1} = P_{\sigma^{-1}}$ and
- (c) $|\det P_{\sigma}| = 1$.

Hint. If the rows of $U \in \mathbb{R}^{n \times n}$ are orthonormal, we say U is an orthogonal matrix. Orthogonal matrices satisfy $UU^{\intercal} = U^{\intercal}U = I$.

Solution.

- (a) This result comes from $(P_{\sigma}x)_i = e_{\sigma(i)}^{\mathsf{T}}x = \langle e_{\sigma(i)}, \sum_{i=1}^n x_i e_i \rangle = x_{\sigma(i)}$.
- (b) First, P_{σ} is an orthogonal matrix since $\langle e_{\sigma(i)}, e_{\sigma(j)} \rangle = \delta_{\sigma(i)\sigma(j)} = \delta_{ij}$ due to the bijectivity of σ . Hence, $P_{\sigma}^{\mathsf{T}} = P_{\sigma}^{-1}$.

Second equality comes from $P_{\pi}P_{\sigma}=P_{\sigma\circ\pi}$. Since $P_{\sigma}P_{\sigma^{-1}}=P_{\sigma^{-1}\circ\sigma}=P_{id}=I$ where $id\in S_n$ is an identity permutation, it follows that $P_{\sigma^{-1}}=P_{\sigma}^{-1}$.

$$P_{\pi}P_{\sigma} = \begin{bmatrix} e_{\pi(1)}^{\mathsf{T}} \\ e_{\pi(2)}^{\mathsf{T}} \\ \vdots \\ e_{\pi(n)}^{\mathsf{T}} \end{bmatrix} \begin{bmatrix} e_{\sigma(1)}^{\mathsf{T}} \\ e_{\sigma(2)}^{\mathsf{T}} \\ \vdots \\ e_{\sigma(n)}^{\mathsf{T}} \end{bmatrix} = \begin{bmatrix} e_{\sigma(\pi(1))}^{\mathsf{T}} \\ e_{\sigma((\pi 2))}^{\mathsf{T}} \\ \vdots \\ e_{\sigma(\pi(n))}^{\mathsf{T}} \end{bmatrix} = P_{\sigma \circ \pi}$$

(c) Since P_{σ} is an orthogonal matrix, $1 = \det(P_{\sigma}^{\mathsf{T}}P_{\sigma}) = \det(P_{\sigma})^2$. Thus, $|\det(P_{\sigma})| = 1$.