



A four-legged robotic arm is shown against a dark background. The arm is constructed from metal plates, black actuators, and various wires. It has four legs, each ending in a black wheel. The joints are labeled with white boxes containing black text. The 'Shoulder' label is positioned above the first joint of the right arm. The 'Elbow' label is positioned above the second joint of the right arm. The 'Wrist' label is positioned above the third joint of the right arm. The arm is positioned in the center of the frame, with its legs spread out.

Shoulder

Elbow

Wrist