

### Forma 1: SITL [PC]



Instalado/Configurado:

- Java
- Python 2.7
- Dronekit
- Dronekit-SITL
- MAVProxy
- CPLEX
- QGroundControl
- Google Earth
- UAV-Toolkit
  - UAV-GCS
  - UAV-S2DK
  - UAV-IFA
  - UAV-MOSA

### Forma 2: HITL [PC + CC]



Instalado/Configurado:

- Java
- Python 2.7
- Dronekit-SITL
- QGroundControl
- Google Earth
- CPLEX
- UAV-Toolkit
  - UAV-GCS



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Instalado/Configurado:

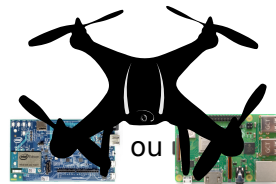
- Java
- Python 2.7
- Dronekit
- MAVProxy
- CPLEX
- UAV-Toolkit
  - UAV-S2DK
  - UAV-IFA
  - UAV-MOSA

### Forma 3: REAL\_FLIGHT [PC + CC + VANT]



Instalado/Configurado:

- Java
- Python 2.7
- QGroundControl
- Google Earth
- CPLEX
- UAV-Toolkit
  - UAV-GCS



Instalado/Configurado:

- Java
- Python 2.7
- Dronekit
- MAVProxy
- CPLEX
- UAV-Toolkit
  - UAV-S2DK
  - UAV-IFA
  - UAV-MOSA