### **Rocket Motor Calculations**

Optimisation of a solid fuel motor using RNX-57V propellant

Malcolm Snowdon

21 August 2009

## **Operating Parameters**

p chamber := 
$$4.5 \times 10^6$$
 \*Design pressure

## **Casing Geometry**

$$t_{casing} := 0.002_{*}$$
 Tube wall thickness  $N_{screws} := 8_{*}$ 

$$\phi\_i\_casing := 0.053_{\text{*}} \quad \text{Tube inner diameter} \qquad \qquad L\_segment := 0.11_{\text{*}} \quad \text{Segment length}$$

$$\phi_{segment} := \phi_{i\_casing} - 0.002$$
 \* Propellant OD  $t_{segment} := 0.020$  \* Segment wall thickness

$$\phi$$
 screw := 0.006\* Cap screw diameter N segments := 3\* # propellant segments

## **Material Properties**

$$\sigma$$
 yield casing :=  $250 \cdot 10^6$  \* Supplier (Atlas Steels) spec for mild steel tubing

$$\tau_{\text{screws\_yield}} := 500 \cdot 10^6 * Standard black finish cap screws$$

#### **Aerodynamic Parameters**

$$Cd := 0.75_*$$
 Drag coeff from CFD simulation  $m_dry := 6_*$  Allowing 1.2 kg more than 1st rocket for payload and

electronics, assuming

some mass will be lost

$$\phi$$
 airframe := .087

Area := 
$$\pi \cdot \frac{\phi_{airframe}^2}{4}$$
 \* Compatible with Cd  $\rho_{air} := 1.2_*$  Assume 25 deg. C, Patmos

#### Propellant Parameters

A 
$$RNX := 400.9_*$$
 From Nakka's charts, adjusted after static test

$$n RNX := 0.641_*$$
 From Nakka's charts

$$k := 1.055_*$$
 Determined from Nakka's charts

$$\rho$$
 RNX := 1664\* Measured by volumetric displacement, agrees with literature

### Burn Surface Area

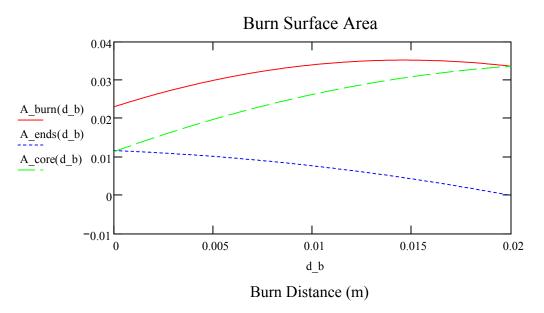
$$A\_ends(d\_burn) := \frac{N\_segments \cdot 2 \cdot \pi}{4} \cdot \left[ \phi\_segment^2 - \left( \phi\_segment - 2 \cdot t\_segment + 2 \cdot d\_burn \right)^2 \right] *$$

 $A\_core(d\_burn) := N\_segments \cdot \pi \cdot (\phi\_segment - 2 \cdot t\_segment + 2 \cdot d\_burn) \cdot (L\_segment - 2 \cdot d\_burn) *$ 

 $A_burn(d_burn) := A_core(d_burn) + A_ends(d_burn)_*$ 

N\_points := 100\*

 $\underline{d}_b := 0, \frac{\underline{t}_segment}{N \ points} ... \, \underline{t}_segment_* \qquad \text{Array of burn distance for plotting against burn surface area}$ 



#### Solve for the maximum burn area

$$Grad(d) := \frac{d}{dd} A_burn(d) \to 6 \cdot \pi \cdot (.11 - 2 \cdot d) - 6 \cdot \pi \cdot (.11e-1 + 2 \cdot d) + \frac{3}{2} \cdot \pi \cdot [(-.44e-1) - 8 \cdot d]_*$$

 $guess := 0_*$  Initail guess for the solver to work with

d A max := root(Grad(guess), guess)\*

A burn  $max := A core(d A max) + A ends(d A max)_*$ 

### Propellant mass assuming square end faces

$$m\_propellant := N\_segments \cdot \rho\_RNX \cdot \frac{\pi}{4} \cdot \left[ \phi\_segment^2 - \left( \phi\_segment - 2 \cdot t\_segment \right)^2 \right] \cdot L\_segment * \left[ \phi\_segment - 2 \cdot t\_segment \right]^2 \cdot L\_segment * \left[ \phi\_segment - 2 \cdot t\_segment \right]^2 \cdot L\_segment * \left[ \phi\_segment - 2 \cdot t\_segment \right]^2 \cdot L\_segment * \left[ \phi\_segment - 2 \cdot t\_segment \right]^2 \cdot L\_segment * \left[ \phi\_segment - 2 \cdot t\_segment \right]^2 \cdot L\_segment * \left[ \phi\_segment - 2 \cdot t\_segment \right]^2 \cdot L\_segment * \left[ \phi\_segment - 2 \cdot t\_segment \right]^2 \cdot L\_segment * \left[ \phi\_segment - 2 \cdot t\_segment \right]^2 \cdot L\_segment * \left[ \phi\_segment - 2 \cdot t\_segment \right]^2 \cdot L\_segment * \left[ \phi\_segment - 2 \cdot t\_segment \right]^2 \cdot L\_segment * \left[ \phi\_segment - 2 \cdot t\_segment \right]^2 \cdot L\_segment * \left[ \phi\_segment - 2 \cdot t\_segment \right]^2 \cdot L\_segment * \left[ \phi\_segment - 2 \cdot t\_segment \right]^2 \cdot L\_segment * \left[ \phi\_segment - 2 \cdot t\_segment \right]^2 \cdot L\_segment * \left[ \phi\_segment - 2 \cdot t\_segment \right]^2 \cdot L\_segment * \left[ \phi\_segment - 2 \cdot t\_segment \right]^2 \cdot L\_segment * \left[ \phi\_segment - 2 \cdot t\_segment \right]^2 \cdot L\_segment * \left[ \phi\_segment - 2 \cdot t\_segment \right]^2 \cdot L\_segment * \left[ \phi\_segment - 2 \cdot t\_segment \right]^2 \cdot L\_segment * \left[ \phi\_segment - 2 \cdot t\_segment \right]^2 \cdot L\_segment * \left[ \phi\_segment - 2 \cdot t\_segment \right]^2 \cdot L\_segment * \left[ \phi\_segment - 2 \cdot t\_segment \right]^2 \cdot L\_segment * \left[ \phi\_segment - 2 \cdot t\_segment \right]^2 \cdot L\_segment * \left[ \phi\_segment - 2 \cdot t\_segment \right]^2 \cdot L\_segment * \left[ \phi\_segment - 2 \cdot t\_segment \right]^2 \cdot L\_segment * \left[ \phi\_segment - 2 \cdot t\_segment \right]^2 \cdot L\_segment * \left[ \phi\_segment - 2 \cdot t\_segment \right]^2 \cdot L\_segment * \left[ \phi\_segment - 2 \cdot t\_segment \right]^2 \cdot L\_segment * \left[ \phi\_segment - 2 \cdot t\_segment \right]^2 \cdot L\_segment * \left[ \phi\_segment - 2 \cdot t\_segment \right]^2 \cdot L\_segment * \left[ \phi\_segment - 2 \cdot t\_segment \right]^2 \cdot L\_segment * \left[ \phi\_segment - 2 \cdot t\_segment \right]^2 \cdot L\_segment * \left[ \phi\_segment - 2 \cdot t\_segment \right]^2 \cdot L\_segment * \left[ \phi\_segment - 2 \cdot t\_segment \right]^2 \cdot L\_segment * \left[ \phi\_segment - 2 \cdot t\_segment \right]^2 \cdot L\_segment * \left[ \phi\_segment - 2 \cdot t\_segment \right]^2 \cdot L\_segment * \left[ \phi\_segment - 2 \cdot t\_segment \right]^2 \cdot L\_segment * \left[ \phi\_segment - 2 \cdot t\_segment \right]^2 \cdot L\_segment * \left[ \phi\_segment - 2 \cdot t\_segment \right]^2 \cdot L\_segment * \left[ \phi\_segment - 2 \cdot t\_segment \right]^2 \cdot L\_segment * \left[ \phi\_seg$$

#### **Motor Operating Conditions**

Potter and Wiggert Equation 9.3.12:

$$Mach\_exit := \left[ \left( \frac{2}{k-1} \right) \cdot \left( \frac{p\_chamber}{p\_exit} \right)^{\frac{k-1}{k}} - \frac{2}{k-1} \right]^{\frac{1}{2}}$$

$$Mach\_exit := 2.82$$

Combining Potter and Wiggert Equations 9.3.12 and 9.3.13:

$$T\_chamber := T\_exit \cdot \left[ 1 + \left( \frac{k-1}{2} \right) \cdot Mach\_exit^2 \right] * T\_chamber = 1.571 \times 10^3$$

## Casing Stresses

$$\sigma_{-}hoop := p\_chamber \cdot \frac{\phi\_i\_casing}{2 \cdot t\_casing} * \qquad \sigma_{-}hoop = 5.963 \times 10^7$$

$$\sigma_{-}axial := p\_chamber \cdot \frac{\phi\_i\_casing^2}{\left(\phi\_i\_casing + 2 \cdot t\_casing\right)^2 - \phi\_i\_casing^2} * \qquad \sigma_{-}axial = 2.873 \times 10^7$$

$$\sigma_{-}von\_Mises := \left[\frac{1}{2} \cdot \left[ \left(\sigma\_hoop - \sigma\_axial\right)^2 + \left(\sigma\_axial - p\_chamber\right)^2 + \left(p\_chamber - \sigma\_hoop\right)^2 \right]^{\frac{1}{2}} *$$

$$Safety\_factor\_casing := \frac{\sigma\_yield\_casing}{\sigma\_von\_Mises} * \qquad \sigma\_von\_Mises = 4.786 \times 10^7$$

$$Safety\_factor\_casing := \frac{\sigma\_yield\_casing}{\sigma\_von\_Mises} * \qquad Safety\_factor\_casing = 5.224$$

$$\tau\_screws := p\_chamber \cdot \frac{\phi\_i\_casing^2}{\phi\_screw^2 \cdot N\_screws} * \qquad (Assumes pure shear)$$

$$Safety\_factor\_screws := \frac{\tau\_screws\_yield}{\tau\_screws} * \qquad Safety\_factor\_screws = 11.392$$

$$\sigma\_holes := p\_chamber \cdot \frac{\pi}{4} \phi\_i\_casing \cdot N\_screws * \qquad (Assumes pressure acts uniformly over a rectangle of dimensions  $\phi\_hole \times t\_wall)$$$

$$Safety\_factor\_holes := \frac{\sigma\_yield\_casing}{\sigma\_holes} * \sigma holes = 1.034 \times 10^8 \\ Safety\_factor\_holes = 2.417$$

(Assumes pressure acts uniformly over a 

## Nozzle Geometry at Design Condition

$$K_n := A_RNX \cdot \left(\frac{p\_chamber}{10^6}\right)^{n\_RNX} *$$

(Ratio of burn surface area to throat area, p conv. to MPa) Note: For p\_chamber = 1 MPa, n\_RNX has no effect on K n. A RNX only was adjusted to correct chamber pressure from previous iteration

Nakka Equation 14 - Nozzle Theory

Expansion\_ratio := 
$$\left(\frac{k+1}{2}\right)^{\frac{1}{k-1}} \cdot \left(\frac{p\_exit}{p\_chamber}\right)^{\frac{1}{k}} \cdot \left[\frac{k+1}{k-1} \cdot \left[1 - \left(\frac{p\_exit}{p\_chamber}\right)^{\frac{k-1}{k}}\right]^{\frac{1}{2}} \right]^{\frac{1}{2}}$$
Expansion\_ratio = 0.116

Expansion ratio = 0.116

$$A\_star := \frac{A\_burn\_max}{K\_n} * A\_star = 3.353 \times 10^{-5}$$

$$A_{\text{exit}} := \frac{A_{\text{star}}}{\text{Expansion ratio}} * A_{\text{exit}} = 2.882 \times 10^{-4}$$

$$\phi\_throat := \sqrt{4 \cdot \frac{A\_star}{\pi}} * \qquad \qquad \phi\_throat = 6.534 \times 10^{-3}$$

$$\phi_{\text{exit}} := \sqrt{\frac{4 \cdot A_{\text{exit}}}{\pi}} * \qquad \qquad \phi_{\text{exit}} = 0.019$$

#### Perfromance Metrics

Nakka Equation 3 - Solid Rocket Motor Thrust Calculations:

Thrust := A\_star·p\_chamber· 
$$\frac{2 \cdot k^2}{k-1} \cdot \left[ \left( \frac{2}{k+1} \right)^{\frac{k+1}{k-1}} \cdot \left[ 1 - \left( \frac{p_exit}{p_chamber} \right)^{\frac{k-1}{k}} \right] \right]^{\frac{1}{2}} *$$
 Thrust = 244.976 \*

Potter and Wigert Equation ???:

## Trajectory Approximation by Numerical Method

$$\begin{array}{ll} t\_inc := 0.1_* & t\_sim := 70_* & N\_sim := floor \\ \hline \begin{pmatrix} \underline{t\_sim} \\ \underline{t\_inc} \end{pmatrix} tim := 0, t\_inc...t\_sim \\ \\ thrust(tim) := \begin{bmatrix} Thrust & if tim < Burn\_time \\ 0 & otherwise \\ \end{bmatrix}$$

$$mass(tim) := \begin{bmatrix} m\_propellant + m\_dry - \frac{m\_propellant}{Burn\_time} \cdot tim & if \ tim < Burn\_time \\ m\_dry & otherwise \end{bmatrix}$$

$$\begin{split} \mathbf{U} \coloneqq & \begin{vmatrix} \mathbf{U}_0 \leftarrow \mathbf{1} \cdot \mathbf{10}^{-12} \\ \text{for } \mathbf{i} \in \mathbf{1} ... \, \mathbf{N}_{\text{sim}} - \mathbf{1} \end{vmatrix} \\ & \begin{vmatrix} \mathbf{F} \mathbf{d}_i \leftarrow \frac{1}{2} \cdot \mathbf{C} \mathbf{d} \cdot \boldsymbol{\rho}_{\text{air}} \cdot \mathbf{Area} \cdot \left(\mathbf{U}_{i-1}\right)^2 \cdot \frac{\mathbf{U}_{i-1}}{\left|\mathbf{U}_{i-1}\right|} \\ & \mathbf{F}_{\text{total}}_i \leftarrow \text{thrust}(\mathbf{i} \cdot \mathbf{t}_{\text{inc}}) - \mathbf{F} \mathbf{d}_i - 9.81 \cdot \text{mass}(\mathbf{i} \cdot \mathbf{t}_{\text{inc}}) \\ & \mathbf{U}_i \leftarrow \mathbf{U}_{i-1} + \frac{\mathbf{F}_{\text{total}}_i}{\text{mass}(\mathbf{i} \cdot \mathbf{t}_{\text{inc}})} \cdot \mathbf{t}_{\text{inc}} \\ & \text{return } \mathbf{U} \end{aligned}$$

$$\begin{aligned} \mathbf{h} &\coloneqq & \begin{vmatrix} \mathbf{h}_0 \leftarrow \mathbf{0} \\ &\text{for } i \in 0.. \, \mathbf{N}\_\mathbf{sim} - 1 \\ &\mathbf{h}_{i+1} \leftarrow \mathbf{h}_i + \mathbf{U}_i \cdot \mathbf{t}\_\mathbf{inc} \\ &\text{return } \mathbf{h} \end{aligned}$$

$$h_{max} := max(h)$$
 $h_{max} = 1.679 \times 10^{3}$ 
 $U_{max} := max(U)$ 
 $U_{max} = 175.248$ 

# Results Summary

m\_propellant = 
$$1.07$$
 \*

Mach\_exit =  $2.82$  \*

T\_chamber =  $1.571 \times 10^3$  \*

Safety\_factor\_casing =  $5.224$  \*

Safety\_factor\_screws =  $11.392$  \*

Safety\_factor\_holes =  $2.417$  \*

 $\phi$ \_throat =  $6.534 \times 10^{-3}$  \*

 $\phi$ \_exit =  $0.019$  \*

Thrust =  $244.976$  \*

Burn\_time =  $7.692$  \*

 $\phi$ \_max =  $1.679 \times 10^3$ 

U\_max =  $175.248$ 

# Output to Excel Spreadsheet 'Motor Parameters'

Solid Rocket Motor Parameters		
For use with SolidWorks and MathCad		
Malcolm Snowdon		
24/08/2009		
Parameter	Value	Details
Throat Diameter	0.006534201	0.0032671
Exit Diameter	0.019155699	0.00957785
Segment Length	0.11	
Segment Wall	0.02	
Segment Diameter	0.051	