

Algorithms and Data Structures 2

8 - HEAPSORT

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Outline

- **Recap**

- MERGE-SORT
- QUICKSORT

- **HEAPSORT**

- **Lower bounds for comparison sorts**
 - Decision tree model

Recap

- **MERGE-SORT** and **QUICKSORT** are two efficient **divide-and-conquer** sorting algorithm

	MERGE-SORT	QUICKSORT
Best case running time	$O(n \log n)$	$O(n \log n)$
Average case running time	$O(n \log n)$	$O(n \log n)$
Worst case running time	$O(n \log n)$	$O(n^2)$
Space complexity	$O(n)$	$O(\log n)$
Stable	Yes	No

HEAPSORT

- **Efficient $O(n \log n)$ sorting algorithm**
 - Originally invented by Williams in 1964
- **Inspired by SELECTION-SORT (see Lab sheet 1)**
 - Divide the input array into a sorted and an unsorted region
 - Iteratively extract the **maximum** from the unsorted region and move it to the sorted region
 - We use a **heap** data structure rather than a linear-time search to find the maximum
- **The heap data structure is useful for HEAPSORT, but it also makes an efficient **priority queue****

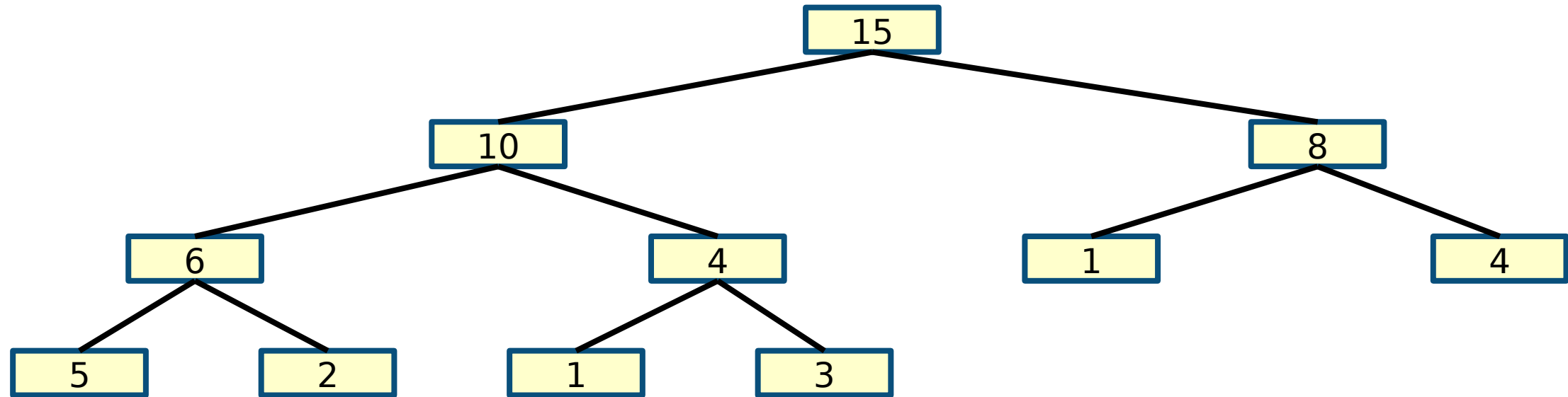
The heap data structure

- A heap is a **nearly complete** binary tree that satisfies the **heap property**

if **p** is a parent node of **c**, then the the value of **p** is either greater than or equal to the value of **c**

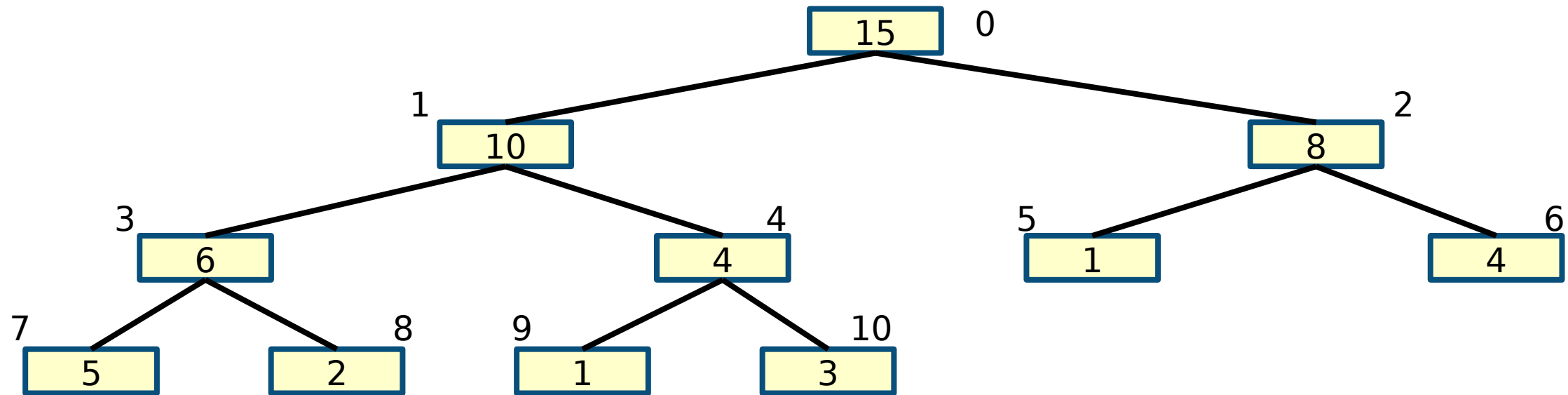
- This is also called **max-heap** because the the **maximum** element is stored at the **root** of the heap
 - A **min-heap** stores the **minimum** element at the root and has dual heap property
- **Heaps can be implemented as arrays**

Max-heap example

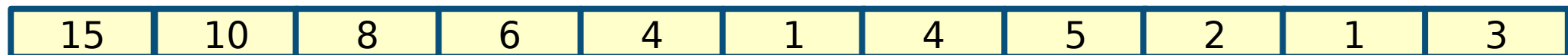


- The max-heap property holds for each subtree
- **Nearly complete**: all levels are complete but the last one

Max-heap example



- A max-heap is represented as an **array** by assigning index **0** starting from the root and then increasing the index while going downwards from left to right on each tree level



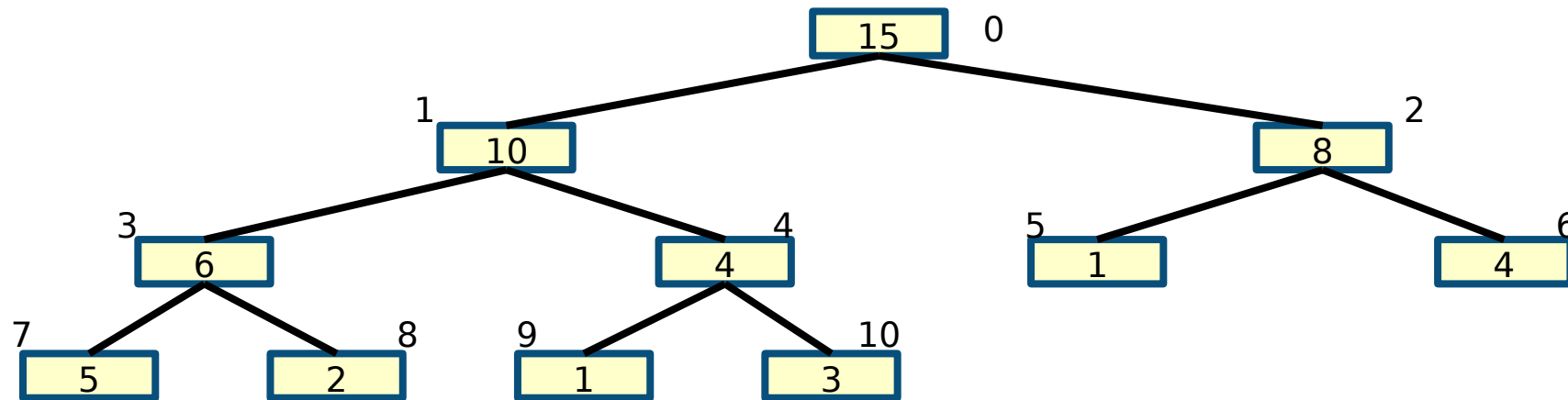
HEAPSORT

- **Input:** Array **A** of size **n**
- **Output:** sorted array **A**
- **BUILD-MAX-HEAP(A)**
 - build a max-heap from an unordered input array in **linear time**
- **MAX-HEAPIFY(A,0,s)**
 - Maintain the max-heap property on **A[0..s-1]**
 - Assume **A[0..s-1]** is a max-heap **but** root **A[0]** might be smaller than its children, thus violating the max-heap property
 - **$O(\log n)$**

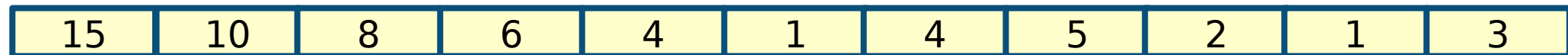
```
HEAPSORT(A)
  BUILD-MAX-HEAP(A)
  s := n    // the size of the heap
  for i = n-1 downto 1
    SWAP(A[0], A[i])
    s := s - 1
  MAX-HEAPIFY(A, 0, s)
```


Example execution of HEAPSORT(A)

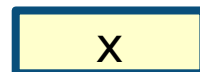
- Assume **BUILD-MAX-HEAP(A)** produces the heap below



```
HEAPSORT(A)
BUILD-MAX-HEAP(A)
s := n
for i = n-1 downto 1
    SWAP(A[0], A[i])
    s := s - 1
    MAX-HEAPIFY(A, 0, s)
```



– Elements in the heap

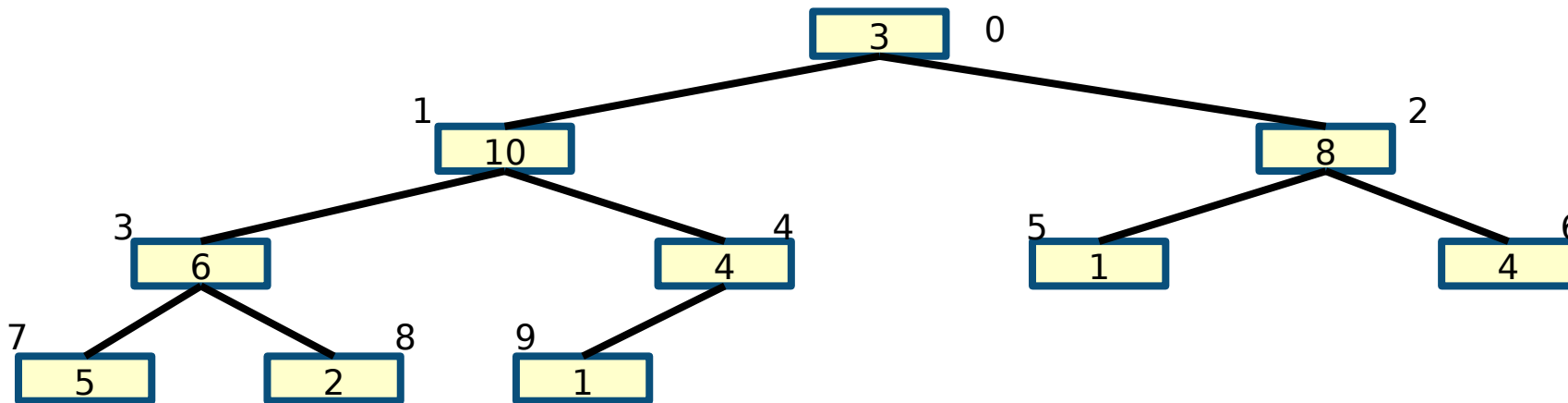


– Sorted elements

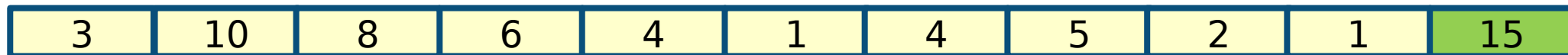


$s = n = 11$

Example execution of HEAPSORT(A)

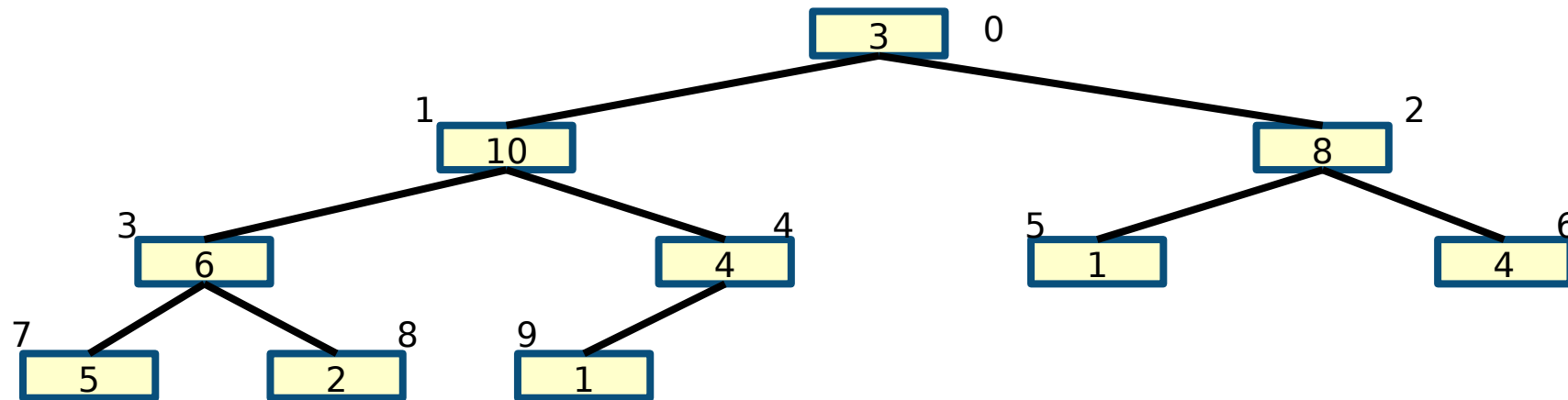


```
HEAPSORT(A)
  BUILD-MAX-HEAP(A)
  s := n
  for i = n-1 downto 1
    SWAP(A[0], A[i])
    s := s - 1
    MAX-HEAPIFY(A, 0, s)
```



- Swap $A[0]$ with $A[i]$
- $A[0]$ is the maximum so it is in its **final** position after the swap

Example execution of HEAPSORT(A)



HEAPSORT(A)

BUILD-MAX-HEAP(A)

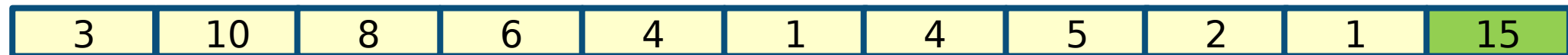
$s := n$

for $i = n-1$ downto 1

SWAP(A[0], A[i])

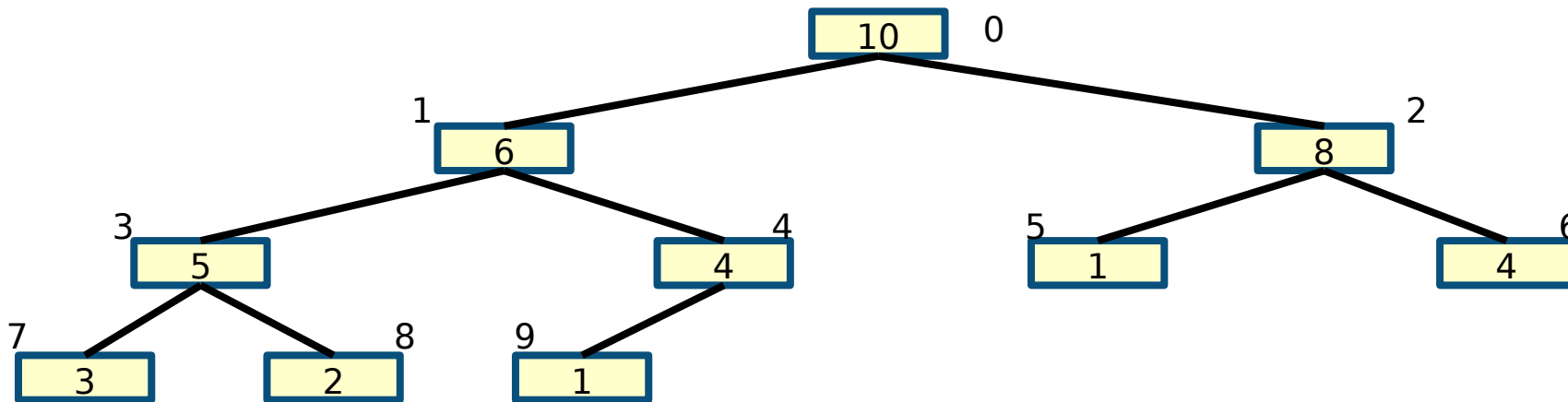
$s := s - 1$

MAX-HEAPIFY(A, 0, s)



- Heap has now $s=10$ elements
- The heap property is not satisfied: invoke **MAX-HEAPIFY(A,0,10)**

Example execution of HEAPSORT(A)



HEAPSORT(A)

BUILD-MAX-HEAP(A)

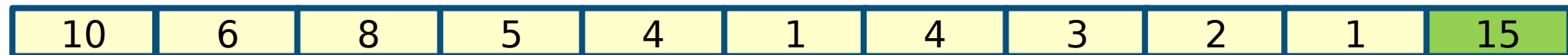
$s := n$

for $i = n-1$ **downto** 1

 SWAP(A[0],A[i])

$s := s - 1$

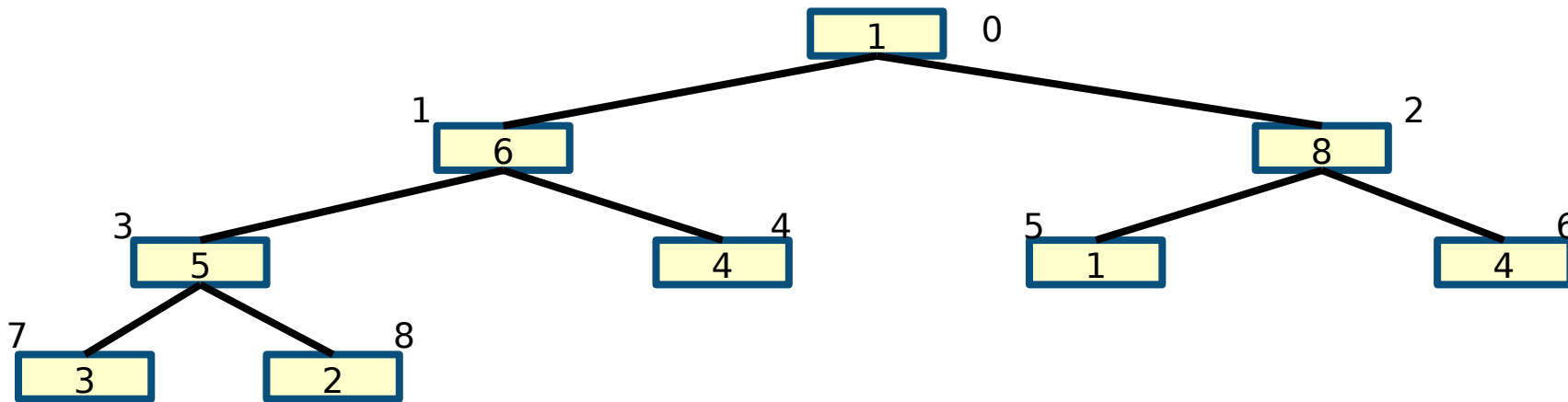
 MAX-HEAPIFY(A,0,s)



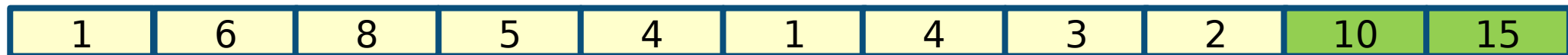
i

- MAX-HEAPIFY recursively swaps the root with its largest child stopping when the heap property is satisfied

Example execution of HEAPSORT(A)

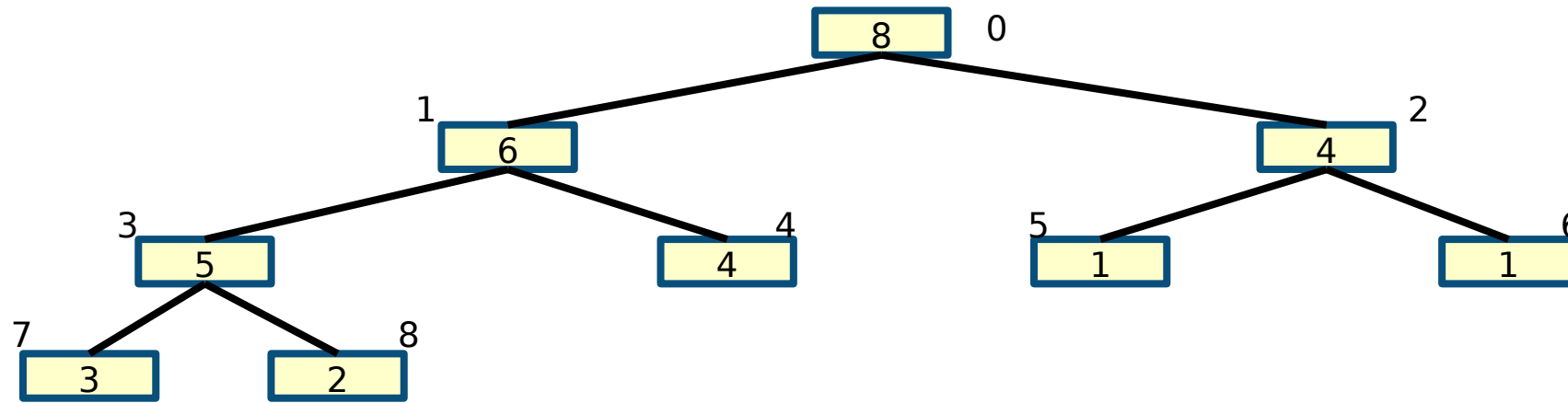


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  BUILD-MAX-HEAP(A)
  s := n
  for i = n-1 downto 1
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```



- Swap $A[0]$ with $A[i]$
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Example execution of HEAPSORT(A)



HEAPSORT(A)

BUILD-MAX-HEAP(A)

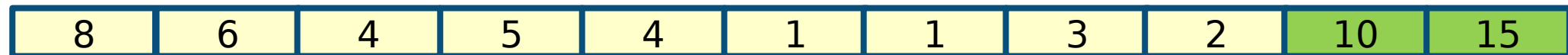
$s := n$

for $i = n-1$ **downto** 1

 SWAP(A[0],A[i])

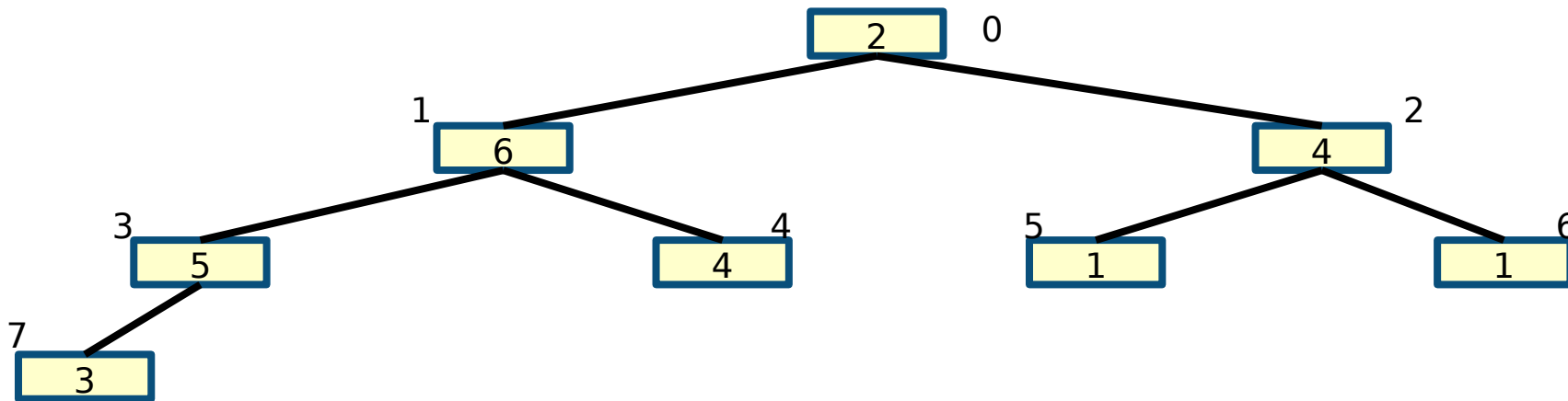
$s := s - 1$

 MAX-HEAPIFY(A,0,s)



– Heap restored

Example execution of HEAPSORT(A)



HEAPSORT(A)

BUILD-MAX-HEAP(A)

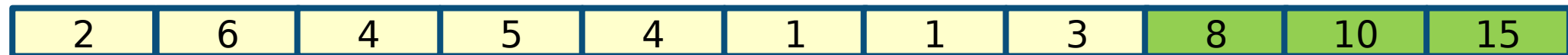
$s := n$

for $i = n-1$ **downto** 1

 SWAP(A[0], A[i])

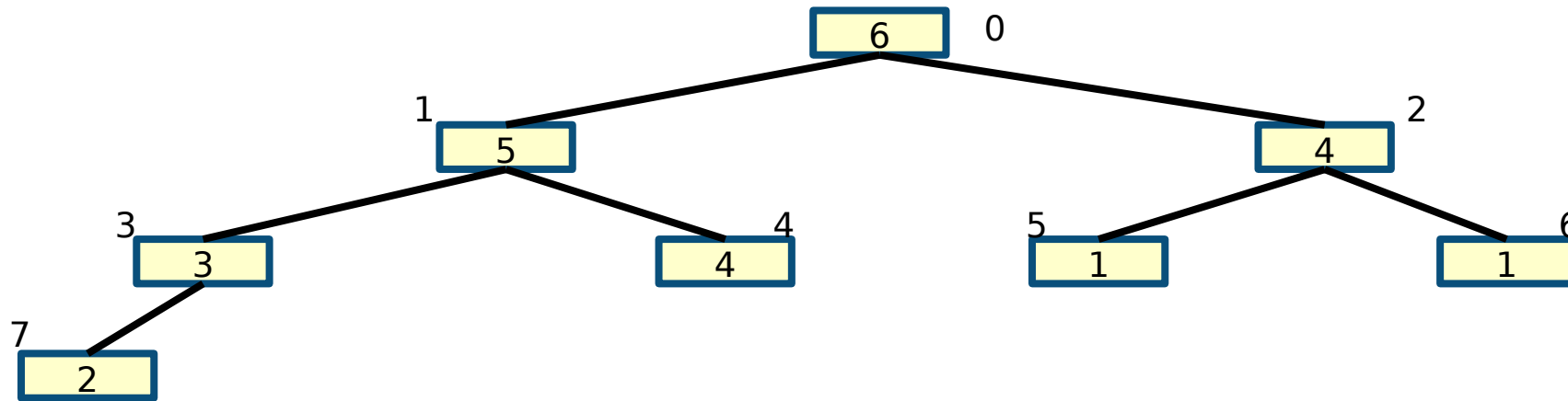
$s := s - 1$

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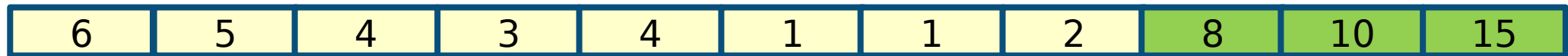


- Swap $A[0]$ with $A[i]$
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Example execution of HEAPSORT(A)

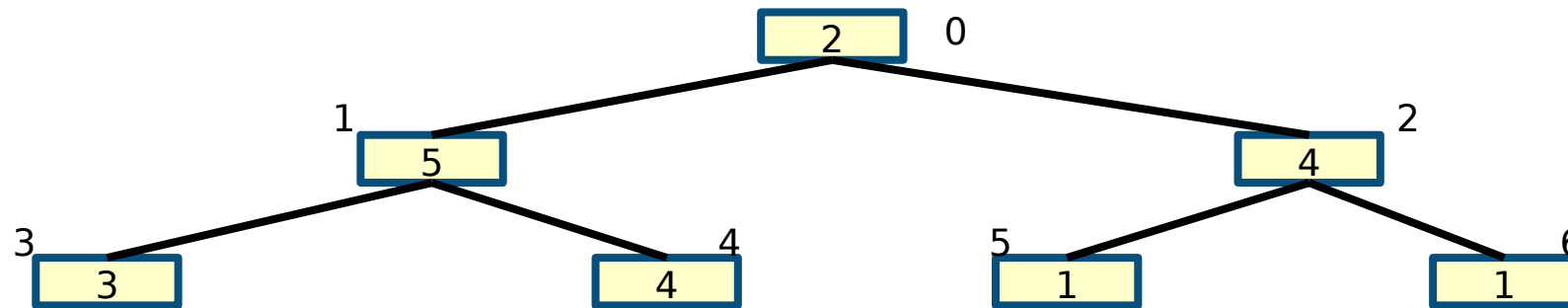


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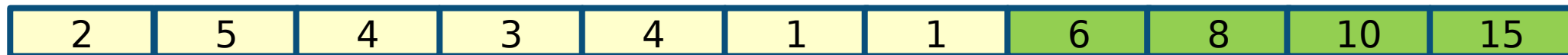


– Heap restored

Example execution of HEAPSORT(A)

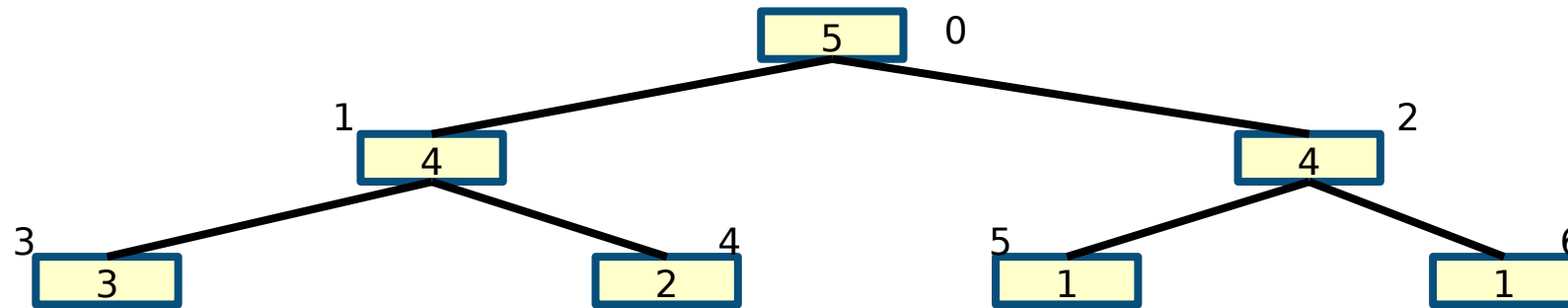


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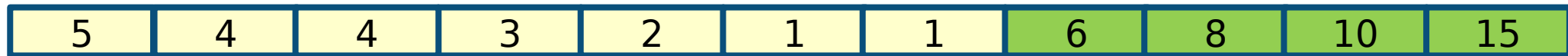


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Example execution of HEAPSORT(A)

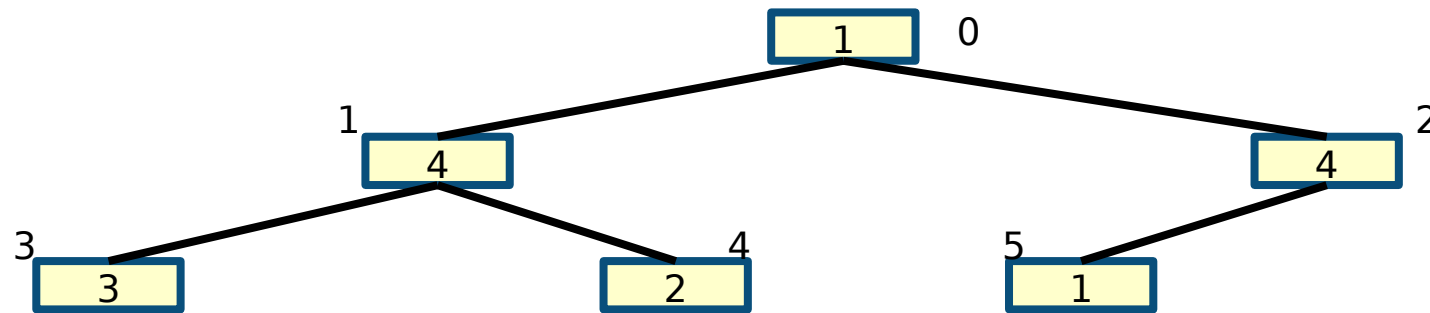


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```



– Heap restored

Example execution of HEAPSORT(A)



HEAPSORT(A)

BUILD-MAX-HEAP(A)

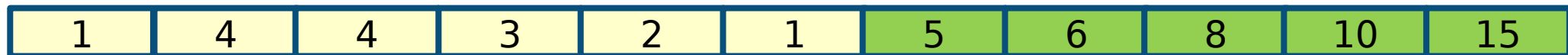
$s := n$

for $i = n-1$ **downto** 1

 SWAP($A[0]$, $A[i]$)

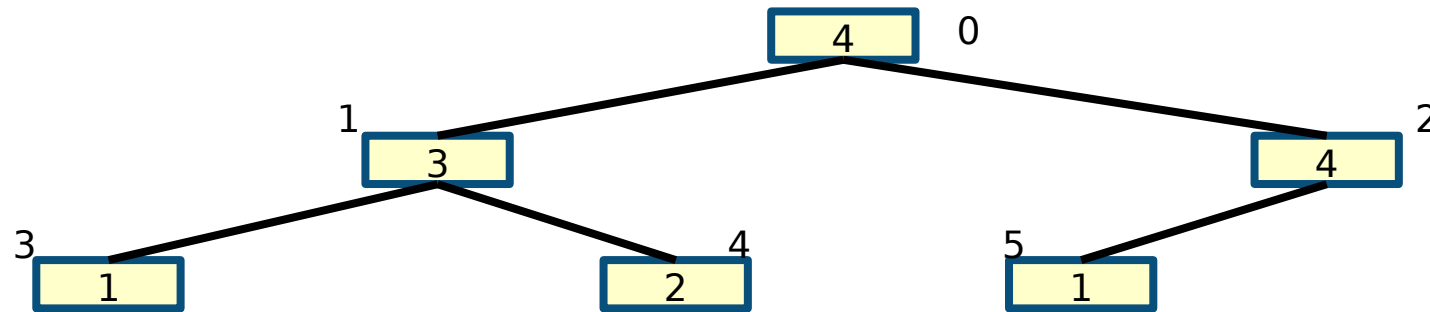
$s := s - 1$

 MAX-HEAPIFY($A, 0, s$)

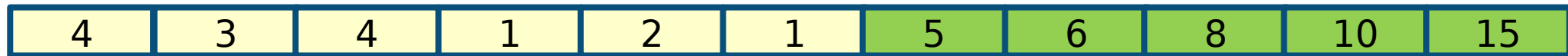


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Example execution of HEAPSORT(A)

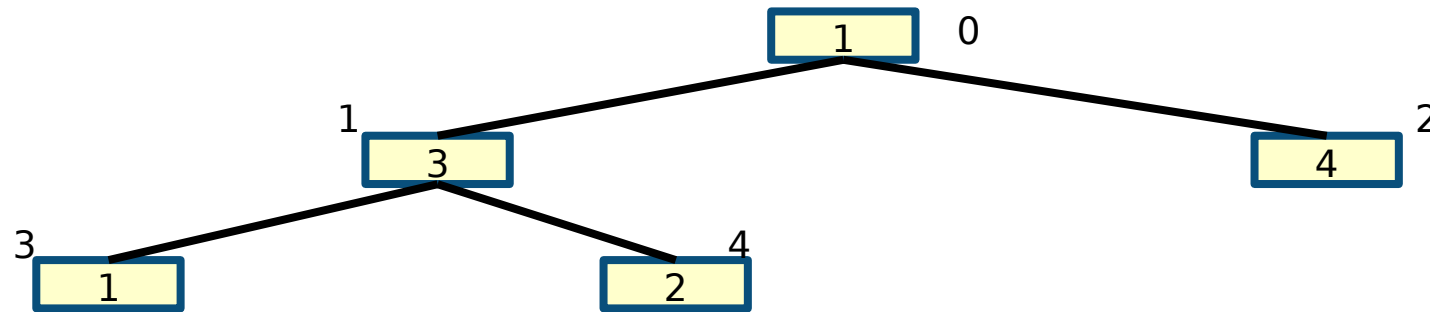


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– Heap restored

Example execution of HEAPSORT(A)

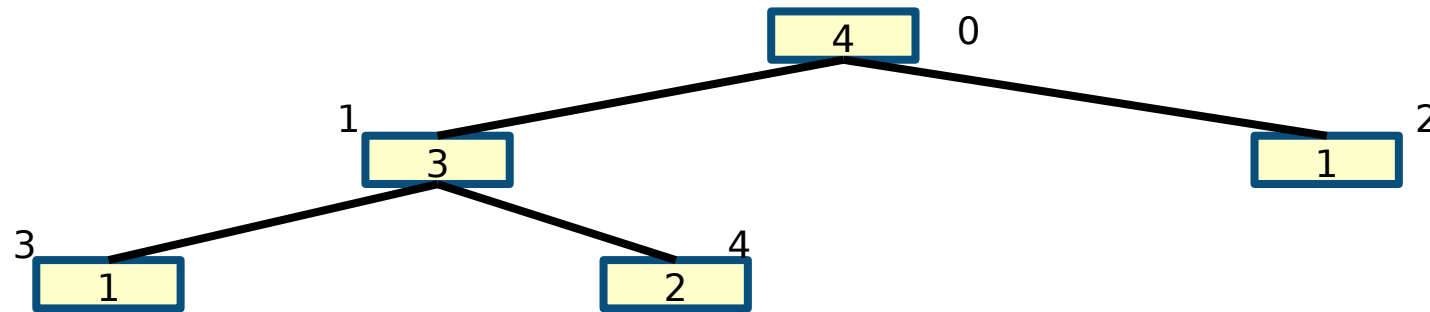


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Example execution of HEAPSORT(A)

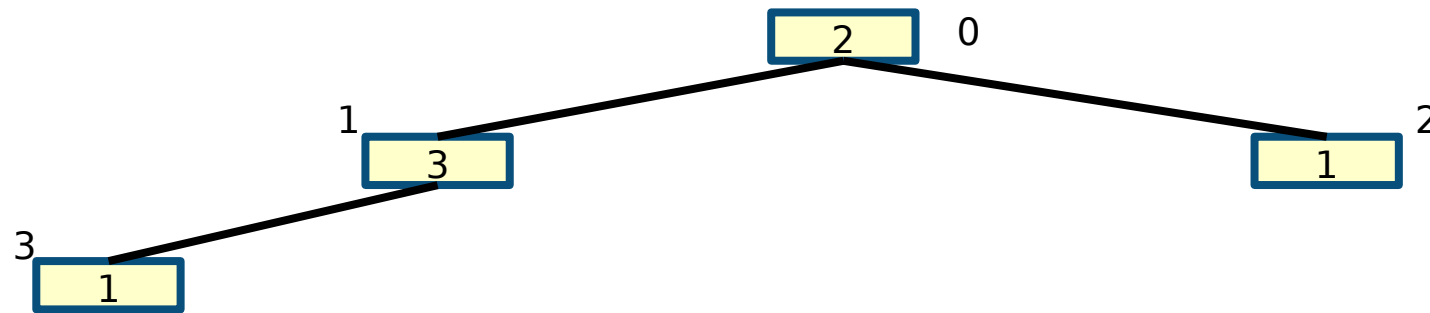


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```



– Heap restored

Example execution of HEAPSORT(A)



HEAPSORT(A)

BUILD-MAX-HEAP(A)

$s := n$

for $i = n-1$ **downto** 1

 SWAP($A[0]$, $A[i]$)

$s := s - 1$

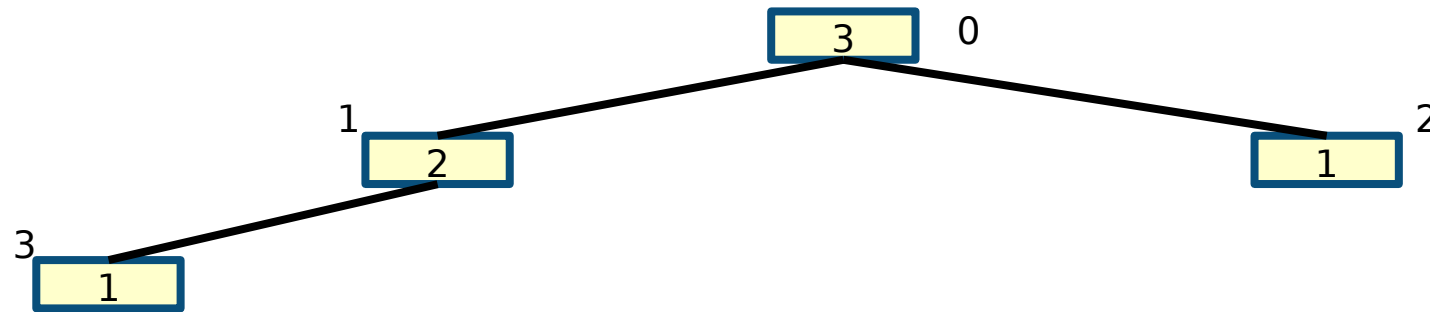
 MAX-HEAPIFY($A, 0, s$)



i

- Swap $A[0]$ with $A[i]$
- $A[0]$ is the maximum so it is in its **final** position after the swap

Example execution of HEAPSORT(A)



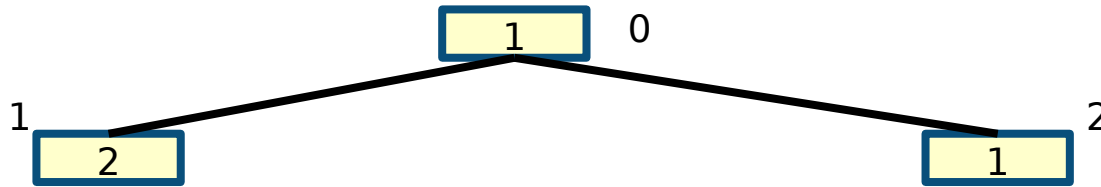
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BUILD-MAX-HEAP(A)  
s := n  
for i = n-1 downto 1  
    SWAP(A[0],A[i])  
    s := s - 1  
    MAX-HEAPIFY(A,0,s)
```



i

– Heap restored

Example execution of HEAPSORT(A)

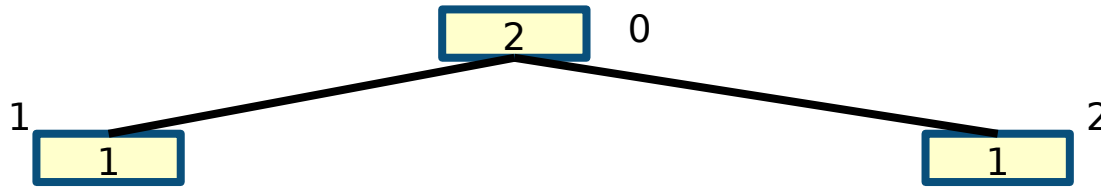


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```



- Swap $A[0]$ with $A[i]$
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Example execution of HEAPSORT(A)

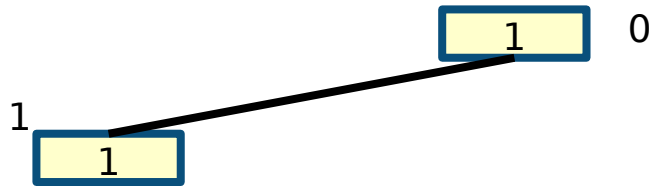


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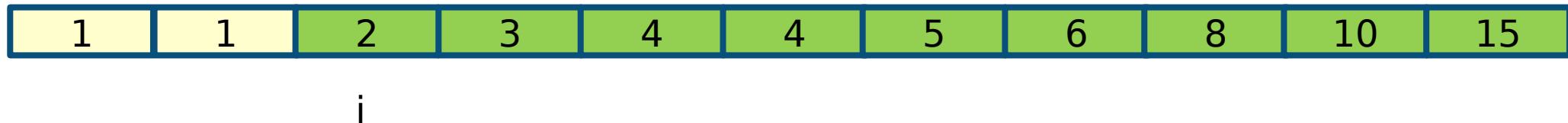


– Heap restored

Example execution of HEAPSORT(A)



```
HEAPSORT(A)
  BUILD-MAX-HEAP(A)
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- Swap $A[0]$ with $A[i]$
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Example execution of HEAPSORT(A)

1 0

```
HEAPSORT(A)  
  BUILD-MAX-HEAP(A)  
  s := n  
  for i = n-1 downto 1  
    SWAP(A[0], A[i])  
    s := s - 1  
    MAX-HEAPIFY(A, 0, s)
```

1	1	2	3	4	4	5	6	8	10	15
---	---	---	---	---	---	---	---	---	----	----

i

– Termination

MAX-HEAPIFY and BUILD-MAX-HEAP

```
LEFT(i)  
return (2 * i) + 1
```

```
RIGHT(i)  
return (2 * i) + 2
```

```
MAX-HEAPIFY(A, i, n)  
  l := LEFT(i)  
  r := RIGHT(i)  
  if l < n and A[l] > A[i]  
    largest := l  
  else largest := i  
  if r < n and A[r] > A[largest]  
    largest := r  
  if largest != i  
    SWAP(A[i], A[largest])  
    MAX-HEAPIFY(A, largest, n)
```

```
BUILD-MAX-HEAP(A)  
  for i = (n / 2) - 1 downto 0  
    MAX-HEAPIFY(A, i, n)
```

Running time

- **BUILD-MAX-HEAP** is $O(n)$
- In **HEAPSORT** extracting the maximum takes $O(1)$ (pick element **$A[0]$**) but we have to restore the heap at each step with **MAX-HEAPIFY** which takes $O(\log n)$
 - In **SELECTION-SORT** extracting the maximum element takes $O(n)$
- There are $n - 1$ iterations of for loop
- $T(n) = O(n) + O(n \log n) = O(n \log n)$
- This applies both to the **best** and **worst** case

```
HEAPSORT(A)
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```

Properties

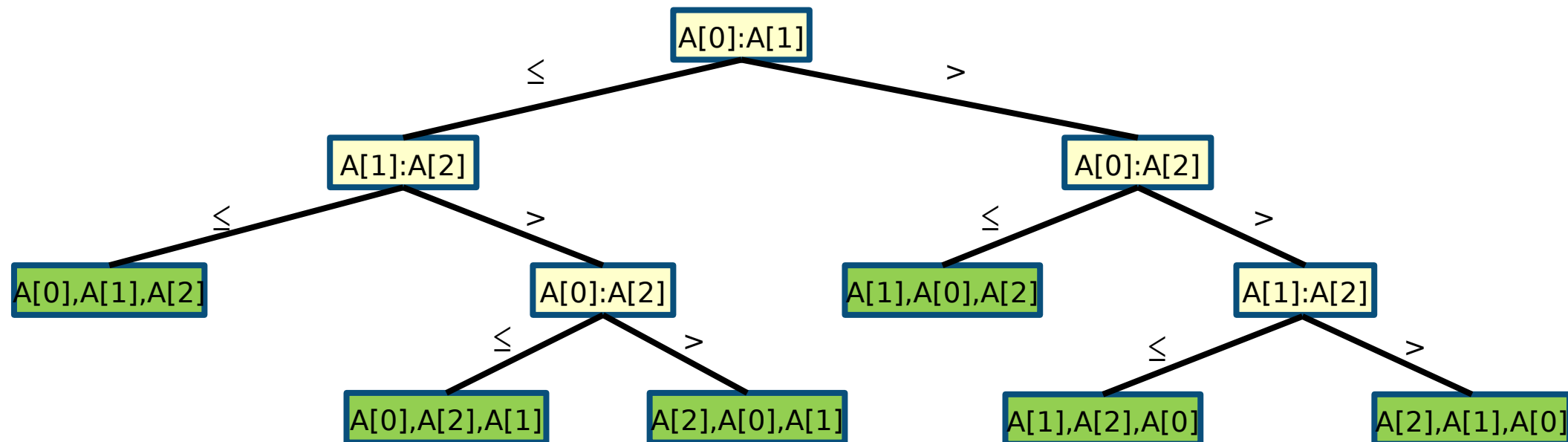
- In place: **$O(1)$** space complexity
- Not stable

Comparison sorts

- **All the sorting algorithms we have studied so far are comparison sorts**
 - The sorted order is determined **only** by comparing the input elements
 - **They can be studied abstractly using the decision tree model**
 - Consider **only** comparisons and ignore all other aspects of the algorithm
 - Introduced by Ford and Johnson in “A tournament problem”. The American Mathematical Monthly, 66(5):387–389, 1959.
 - **A decision tree is a full binary tree that represents the comparisons between elements that are performed by a sorting algorithm operating on an input of a given size**
 - Assume all the input elements are **distinct**
- ADS 2, 2021
- Assume all comparisons have the form **A[i] A[j]**

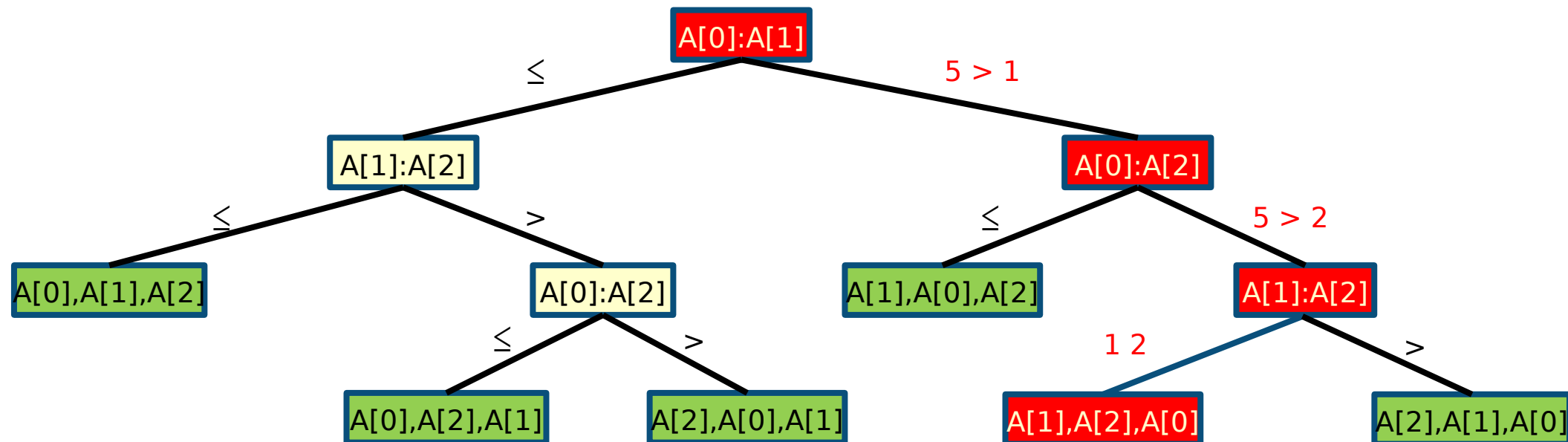
Decision tree example

- **Sort three elements $A[0..2]$**
 - Node $A[i]:A[j]$ indicates a comparison between $A[i]$ and $A[j]$
 - Green **leaves** are all the sorted **permutations** of the input



Decision tree example

- The execution of an algorithm corresponds to tracing a **path** from the root to a leaf
 - Example: the sorted permutation for $A = [5, 1, 2]$ is $(A[1], A[2], A[0]) = [1, 2, 5]$



Decision tree

- **Any correct sorting algorithm must be able to produce each permutation of its input**
 - $n!$ permutations on n elements
 - Therefore, there are $n!$ leaves in the decision tree
- **Each of leaf must be **reachable** from the root by a downward path corresponding to an actual execution of the comparison sort**
- **The length of the longest path from the root of a decision tree to any of its reachable leaves represents the **worst-case** number of comparisons that the sorting algorithm performs**
 - This is also the **height** of the decision tree

A lower bound for comparison sort

- We need to compute a lower bound on the **height** of the decision tree
- Recall the following facts
 - A binary tree of height **h** has at most **2^h** leaves
 - **$n^{n/2}$** **$n!$** **n^n**
- Then we have
 - $n! \leq 2^h$
 - $\log 2^h = h \log 2$
 - $h \log 2 = \log n! = \log n^n = n \log n$
- Any comparison sort algorithm requires **$\Omega(n \log n)$** comparisons in the worst case
 - MERGE-SORT and HEAPSORT are **asymptotically optimal**
 - No comparison sort exists that is faster by more than a constant factor

Summary

- **HEAPSORT**
 - Heap data structure
 - Running time
 - Properties
- **Lower bounds for comparison sorts**
 - Decision tree model