Algorithms and Data Structures 2 5 - MERGE-SORT

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Outline

MERGE

- Properties
- MERGE-SORT
 - Properties
 - Improvements

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MERGE-SORT

Efficient divide-and-conquer sorting algorithm

- According to Knuth, it was invented in 1938 to merge two decks of punched cards in one pass
- First known implementation due to von Neumann in 1945

Intuitively it operates as follows

- Divide the n-element array to be sorted into two subarrays of n/2 elements each
- Conquer: Sort the two subarrays recursively using MERGE-SORT
- Combine: Merge the two sorted subarrays to produce the sorted answer
- The key operation of the MERGE-SORT algorithm is the merging of two sorted arrays in the Combine step

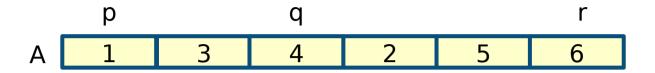
Via the MERGE procedure

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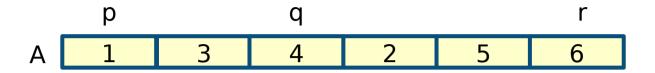
MERGE

- Input: Array A and three indexes p,
 q, r for A such that p ≤ q < r
 - Subarrays A[p..q] and A[q+1..r] are assumed sorted
- Output: sorted subarray A[p..r]
- We only copy L and R. Sorted array is stored in A
- We use sentinels (∞) to avoid checking at every step if L or R have been entirely scanned

```
MERGE(A,p,q,r)
  n_1 := q - p + 1
  n_2 := r - q
  copy A[p..q] to L[0..n_1]
  copy A[q+1..r] to R[0..n_2]
  L[n_1] := \infty
  R[n_2] := \infty
  i,j := 0
  for k = p to r
    if L[i] \leq R[j]
      A[k] := L[i]
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    else
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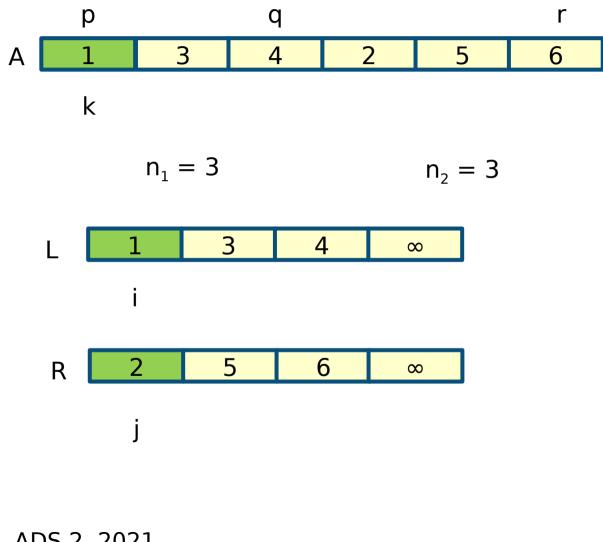
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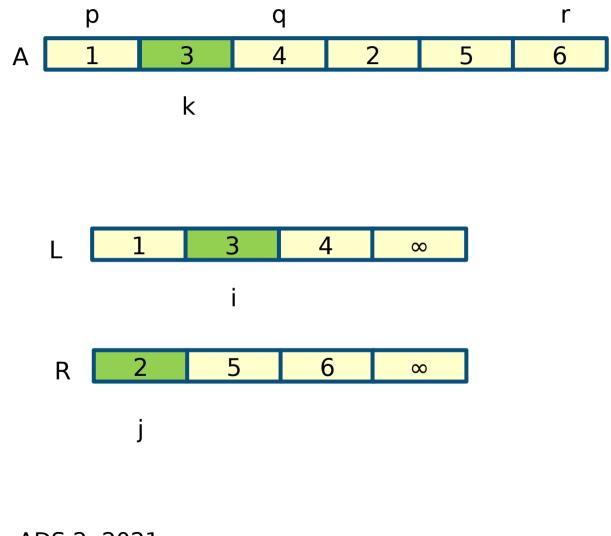
$$n_1 = 3$$

$$n_2 = 3$$

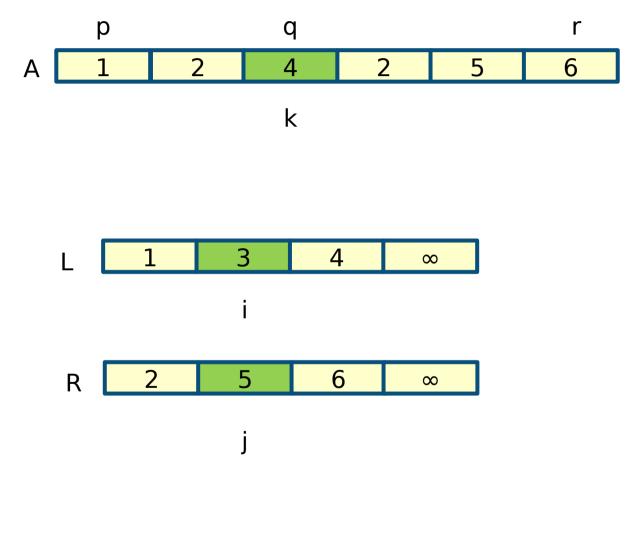
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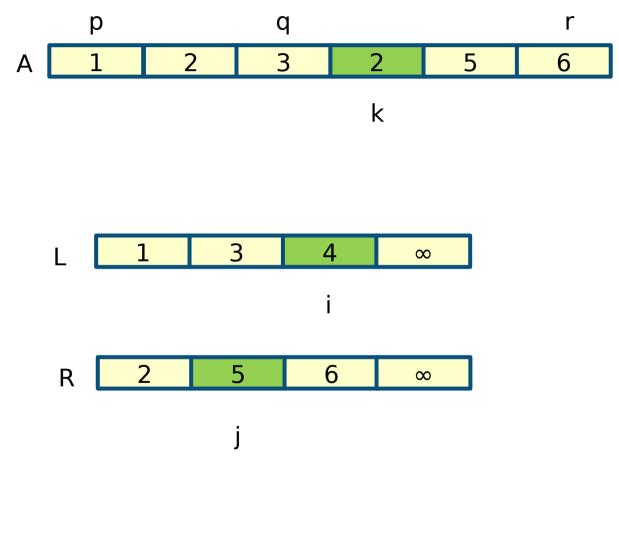
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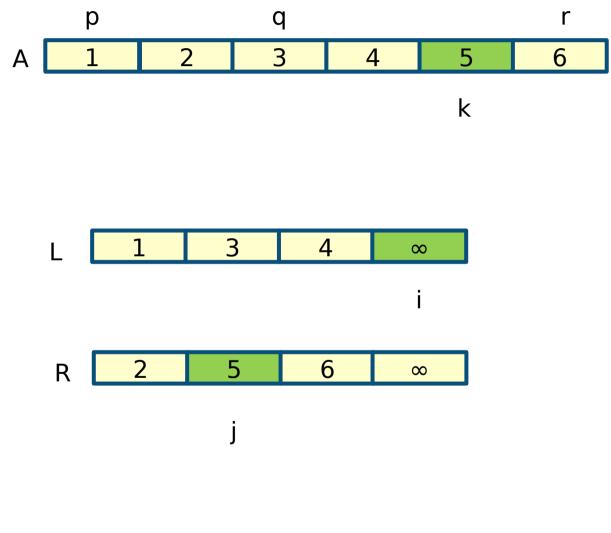
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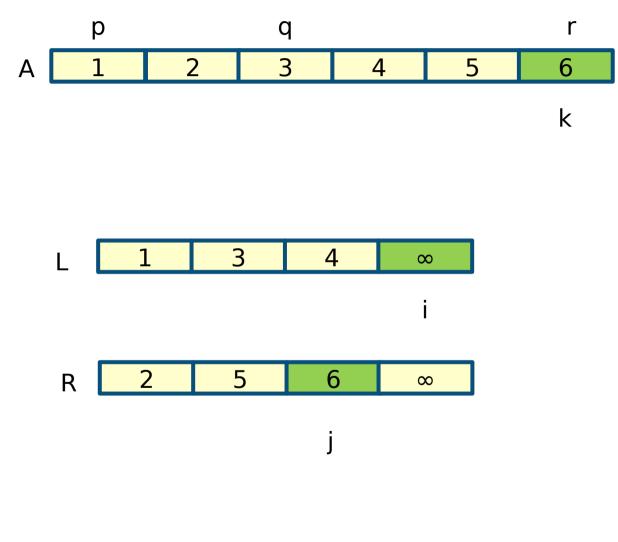
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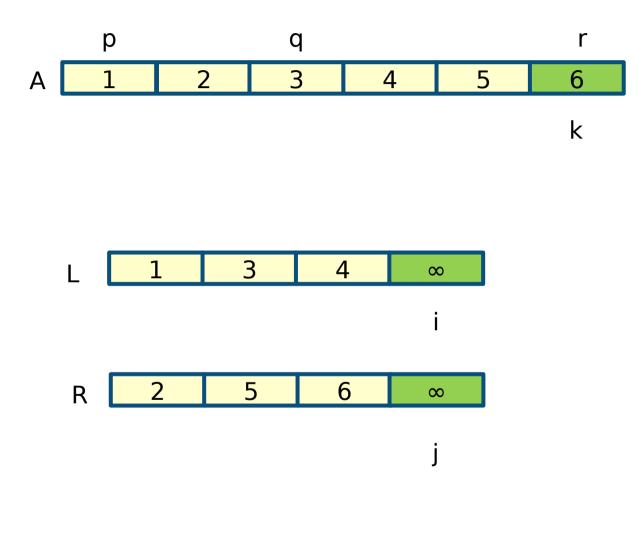
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Properties of MERGE

Running time: O(n)

- Initialisation of L and R is O(n)
- For loop is executed n times and contains only constant operations

Stable

 It preserves the order of elements with the same sorting key

O(n) working memory requirement

- To store L and R
- In-place version is possible, but stability is lost!

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```

MERGE-SORT

- Input: Array A and two indexes p, r for A such that $p \le r$
- Output: sorted array A[p..r]

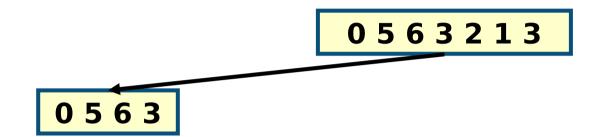
```
MERGE-SORT(A,p,r)
if p < r
  q := (p+r)/2
  MERGE-SORT(A,p,q)
  MERGE-SORT(A,q+1,r)
  MERGE(A,p,q,r)</pre>
```

To sort an array A with n elements the initial call is MERGE-SORT(A,0,n-1)

MERGE-SORT(A,0,6) with A=[0,5,6,3,2,1,3]

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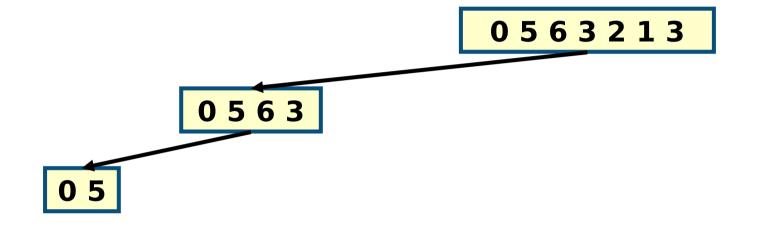
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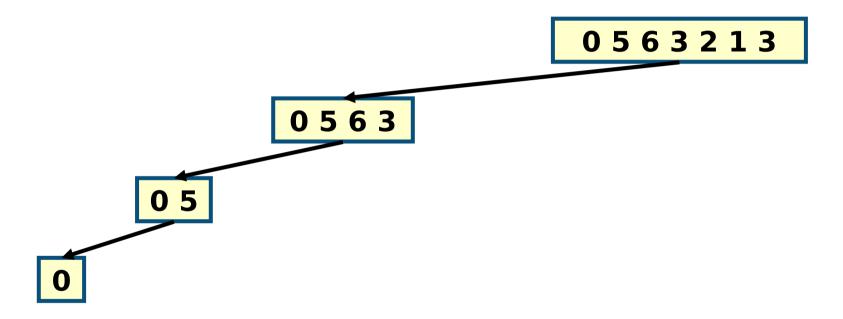
$$- q = p+r/2 = 0+6/2 = 3$$

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MERGE-SORT(A,0,6) with A=[0,5,6,3,2,1,3]



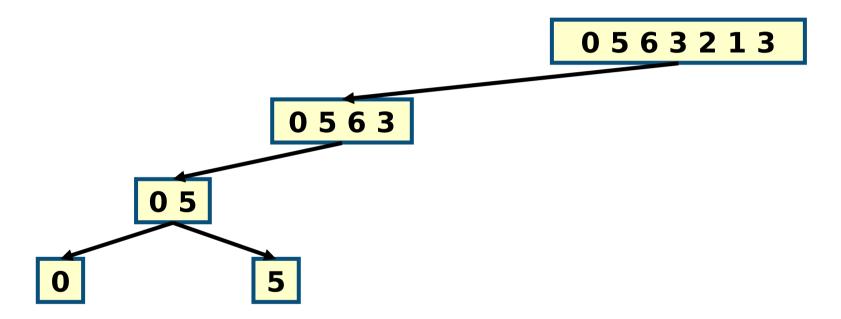
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- Recursion stopping condition
- Now we execute the second recursive call

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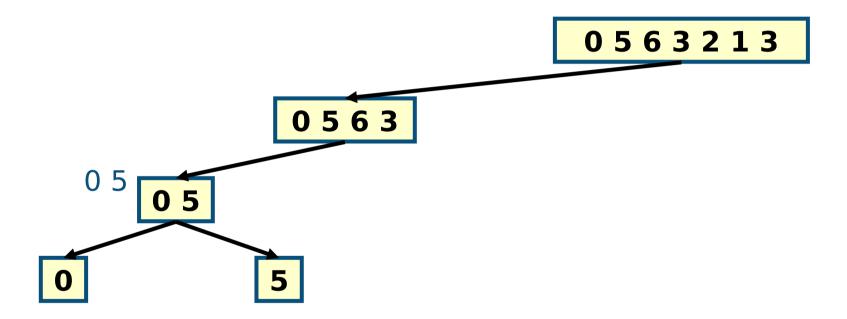
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Now we perform the combine step by calling MERGE on the two subarrays

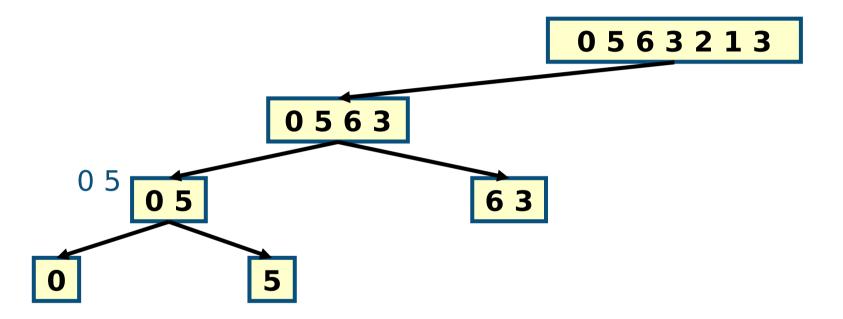
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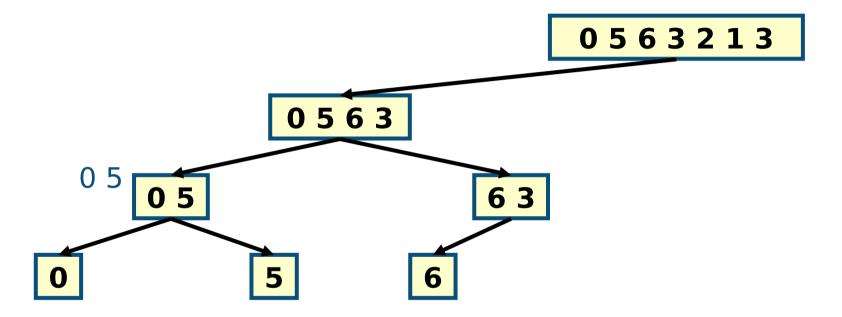


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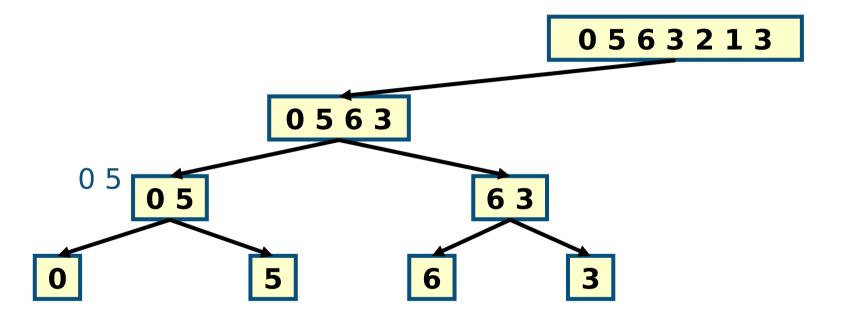


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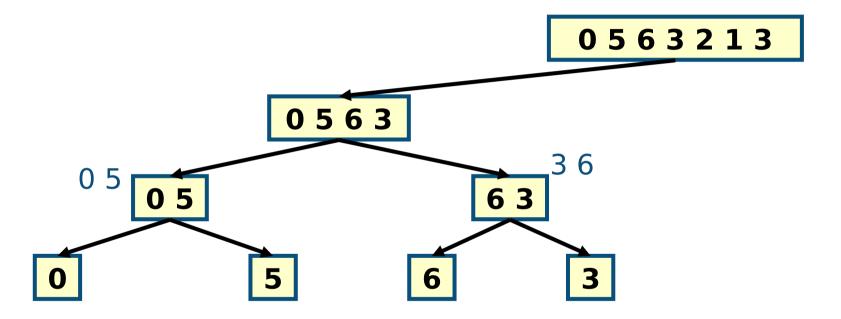


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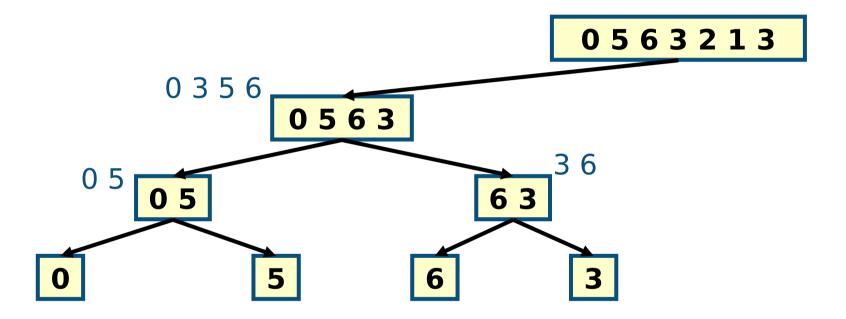
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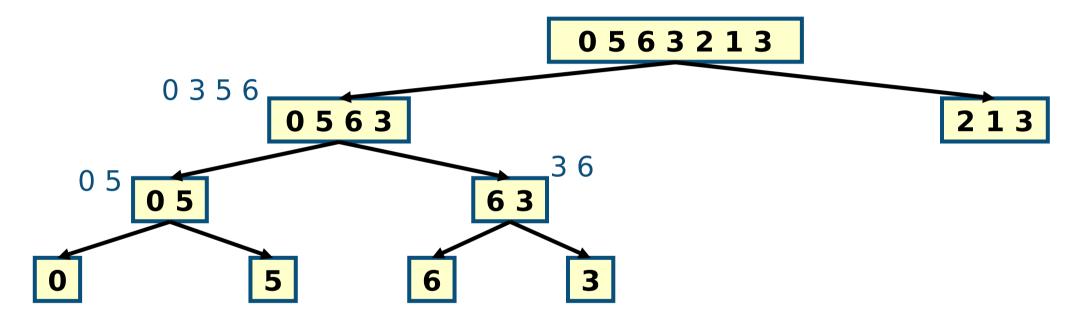
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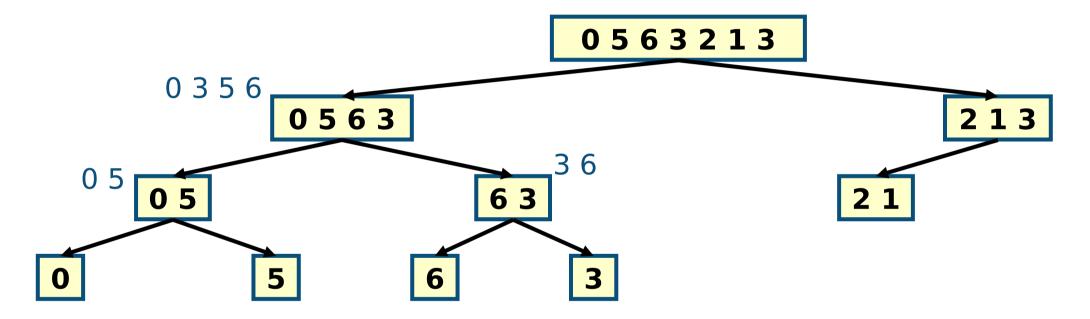
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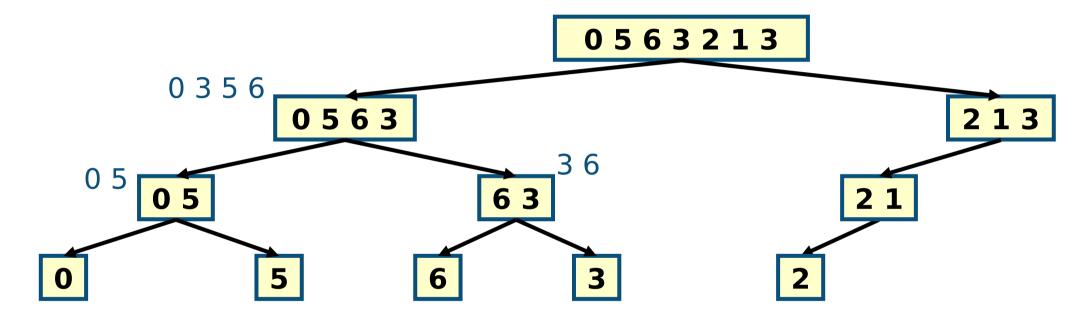
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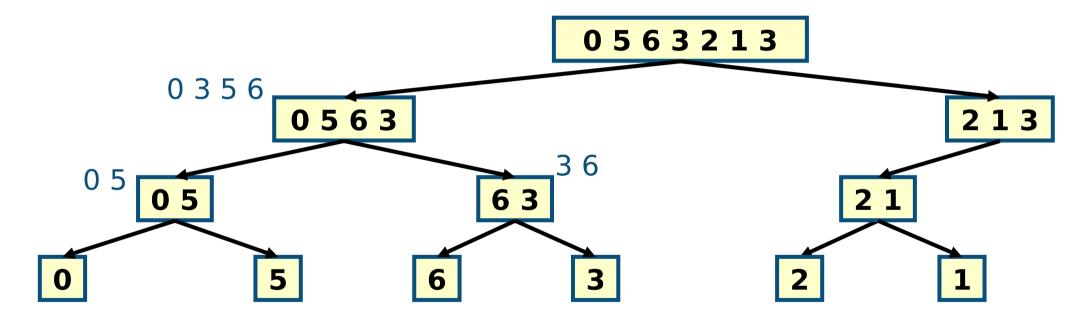


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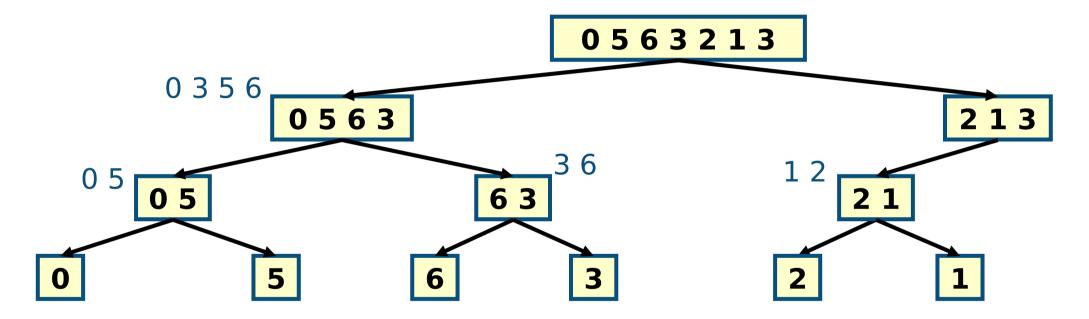


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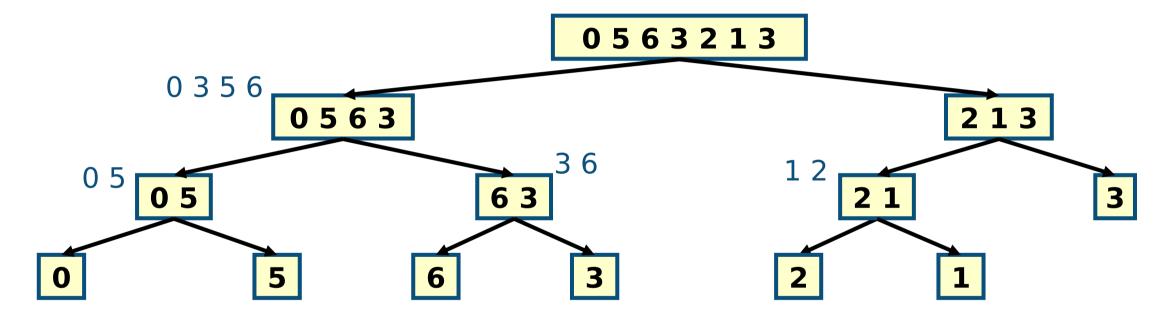
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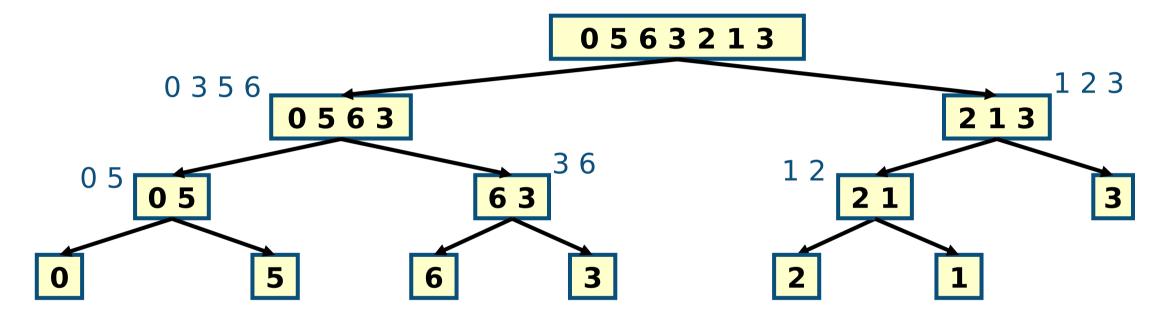
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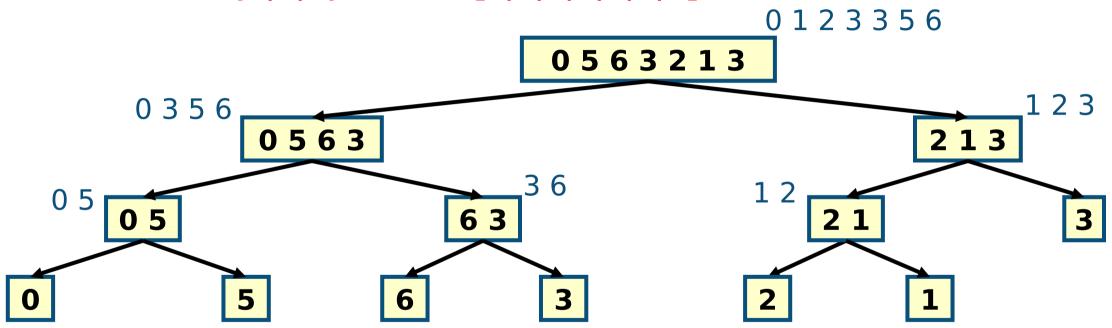
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- Termination

Properties of MERGE-SORT

- Stable as MERGE is stable
- Not in-place as MERGE requires O(n) memory
- Running time is O(n log n) both in the best and worst cases
 - We will see how to compute that in the next lecture

Improvements on standard MERGE-SORT

- In-place (through in-place MERGE)
- Bottom-up (iterative)
- Organise the merges so that all the merges of arrays of length 2 are done in one pass
- Then do a second pass to merge those arrays in pairs, and so forth
- Continue until we do a merge that encompasses the whole array
- Use INSERTION-SORT on small instances
 - Cut-off typically $5 \le n \le 20$

You will implement some of those in Lab 2

Summary

•MERGE

- Properties
- MERGE-SORT
 - Properties
 - Improvements