# ATMega328P-Based Banking System Project Report

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## **Project Overview**

The project implements a basic banking system using an ATMega328P microcontroller. The system provides core banking functionalities through a user interface consisting of an LCD display, a 4x3 numeric keypad, and four control buttons.

## System Assumptions

### Hardware Components

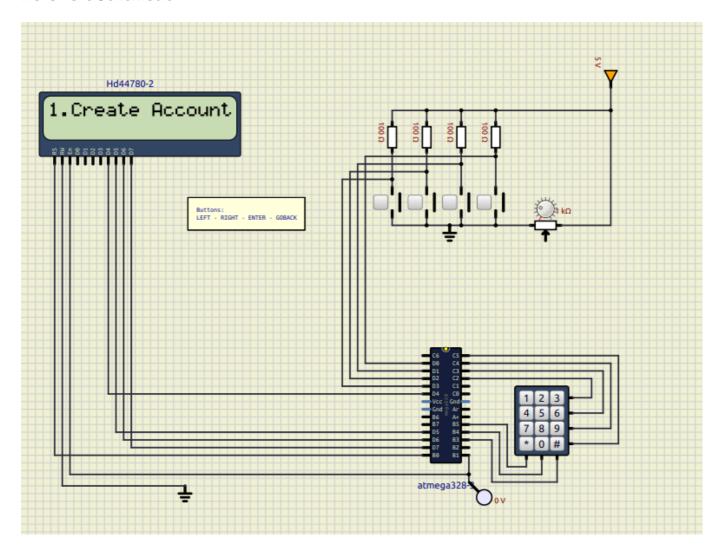
- ATMega328P microcontroller
- LCD display (16x2 characters)
- 4x3 numeric keypad
- Four control buttons (LEFT, RIGHT, ENTER, BACK)
- Pull-up resistors for buttons (100k $\Omega$ )

#### Software Constraints

- Maximum of 10 user accounts
- Account ID: 4 digits
- PIN: 4 digits
- Balance stored as unsigned 32-bit integer (maximum as 9 digits)
- Menu-driven interface with 4 main options

## System Architecture

### Hardware Schematic



The provided schematic shows the following connections:

- HD44780 LCD connected to digital pins
- 4x3 matrix keypad interface
- Four buttons with pull-up resistors
- Power supply connection (5V)

#### Software Architecture

The system is organized into several key components:

- 1. Core Components:
  - Main control loop (main.c)
  - LCD interface (HD44780.hpp)
  - Keypad (keypad.hpp)
  - Button (buttons.hpp)
- 2. Data Structures:

```
struct Account {
   char id[ID_LENGTH + 1];
   char pin[PIN_LENGTH + 1];
   uint32_t balance;
};
```

#### 3. Main Features:

- Account creation
- Balance checking
- Money deposit
- Money withdrawal

#### Custom Libraries

#### **Buttons**

The buttons library provides a simple way for handling four push buttons connected to Port D (pins 0-3).

- 1. Hardware Configuration:
  - Four independent push buttons
  - Connected to PORTD (PD0-PD3)
  - Functions:
    - BUTTON\_BACK (PD0): Delete/return
    - BUTTON\_ENTER (PD1): Confirm selections
    - BUTTON\_RIGHT (PD2): Menu navigation
    - BUTTON LEFT (PD3): Menu navigation

#### 2. Key Functions:

```
void buttons_init() {
    // Configure pins 0-3 on Port D for button inputs

    // Set pins as inputs by clearing bits 0-3 in DDRD (Data
Direction Register)
    DDRD &= ~((1 << PD0) | (1 << PD1) | (1 << PD2) | (1 << PD3));

    // Enable internal pull-up resistors on these pins by setting
bits in PORTD
    // This ensures pins read high when buttons are not pressed
    PORTD |= (1 << PD0) | (1 << PD1) | (1 << PD2) | (1 << PD3);
}</pre>
```

- Configures pins 0-3 on Port D as inputs
- Enables internal pull-up resistors
- Called once during system initialization

```
uint8_t read_buttons() {
     // Check status of 4 buttons connected to Port D pins 0-3
     // Returns the index (0-3) of the first pressed button, or 255 if
no button is pressed
     for(uint8_t i = 0; i < 4; i++) {
         // Check if button i is pressed by checking if its bit in
PIND is 0
         // PIND & (1 << i) creates a mask to isolate the button's pin
         // Buttons are active low, meaning a pressed button reads as
0
         if(!(PIND & (1 << i))) {
             _{delay_ms(50)};
             return i;
         }
     }
     return 255;
}
```

- Polls all four buttons
- Returns index (0-3) of pressed button
- Returns 255 if no button is pressed
- Includes 50ms debounce delay

#### **Keypad Interface**

The keypad library manages a 4x3 matrix keypad for numeric input.

- 4x3 matrix keypad configuration
- Hardware Configuration:
  - Rows connected to PORTC (PC2-PC5)
  - Columns connected to PORTB (PB3-PB5)
  - Matrix layout:

#### 2. Key Functions:

```
void keypad_init() {
    // Set row pins as outputs

DDRC |= (1 << PC5) | (1 << PC4) | (1 << PC3) | (1 << PC2);</pre>
```

```
// Set column pins as inputs
DDRB &= ~((1 << PB5) | (1 << PB4) | (1 << PB3));

// Enable internal pull-up resistors for column pins
PORTB |= (1 << PB5) | (1 << PB4) | (1 << PB3);
}</pre>
```

- Configures row pins as outputs (PORTC)
- Configures column pins as inputs (PORTB)
- Enables pull-up resistors on column pins

```
char scan_keypad() {
     uint8_t row;
     for(row = 0; row < 4; row++) {
         // Set all rows high
         PORTC |= (1 << PC5) | (1 << PC4) | (1 << PC3) | (1 << PC2);
         // Set current row low (active)
         // PC2 is top row (row 0), PC5 is bottom row (row 3)
         PORTC \&= \sim (1 << (PC2 + row));
         _delay_us(10);
         // Check each column for the current row
         if(!(PINB & (1 << PB5))) return keypad[row][0]; // Left
column
         if(!(PINB & (1 << PB4))) return keypad[row][1]; // Middle</pre>
column
         if(!(PINB & (1 << PB3))) return keypad[row][2]; // Right</pre>
column
     }
     return 0;
 }
```

#### 3. Implementation Details:

- Uses row-scanning technique:
  - For each row:
  - All rows are first set HIGH (inactive)
  - The current row is set LOW (active)
  - Each column is checked for a LOW state
  - If a LOW is detected, the corresponding key is returned
- Direct port manipulation for performance

## Implementation Details

#### User Interface

The system implements a menu-driven interface with the following navigation:

- LEFT/RIGHT buttons: Navigate through menu options
- ENTER: Select current option
- BACK: Delete input during data entry

#### Menu Structure

- 1. Create Account
  - Enter 4-digit ID
  - Enter 4-digit PIN
  - Account created with 0 balance
- 2. Check Balance
  - Enter ID and PIN
  - Display current balance
- 3. Deposit Money
  - Enter ID and PIN
  - Enter amount
  - Update balance
- 4. Withdraw Money
  - Enter ID and PIN
  - Enter amount
  - Check sufficient funds
  - Update balance if possible

## System Operation

#### **Account Creation**

- 1. System checks for available account slots
- 2. User enters 4-digit ID
- 3. System verifies ID uniqueness
- 4. User enters 4-digit PIN
- 5. Account created with 0 balance



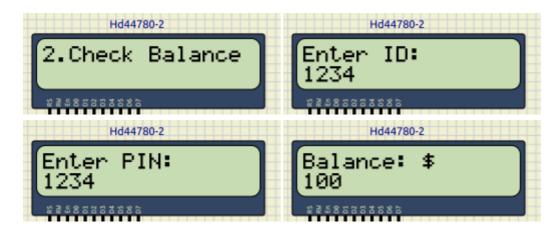
### Transaction Flow (Deposit/Withdrawal)

- 1. User selects operation from menu
- 2. Enters account credentials
- 3. System validates credentials
- 4. User enters transaction amount (for deposit/withdrawal)
- 5. System performs operation and displays result

#### Deposit



#### **Check Balance**

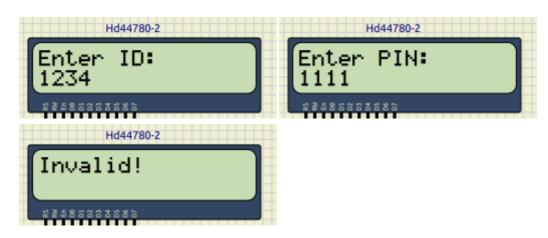


#### Withdrawal



### Error Handling

#### Invalid login



#### Insufficient funds





# Github Repo

The code for this project is available at:

• https://github.com/Moreira-26/Arduino