Chapter 5 Network Layer: Control Plane

Network layer: "control plane" roadmap

- introduction
- routing protocols
 - link state
 - distance vector
- intra-ISP routing: OSPF
- routing among ISPs: BGP
- Internet Control Message Protocol



Network-layer functions

- forwarding: move packets from router's input to appropriate router output
 - routing: determine route taken by packets from source to destination

data plane

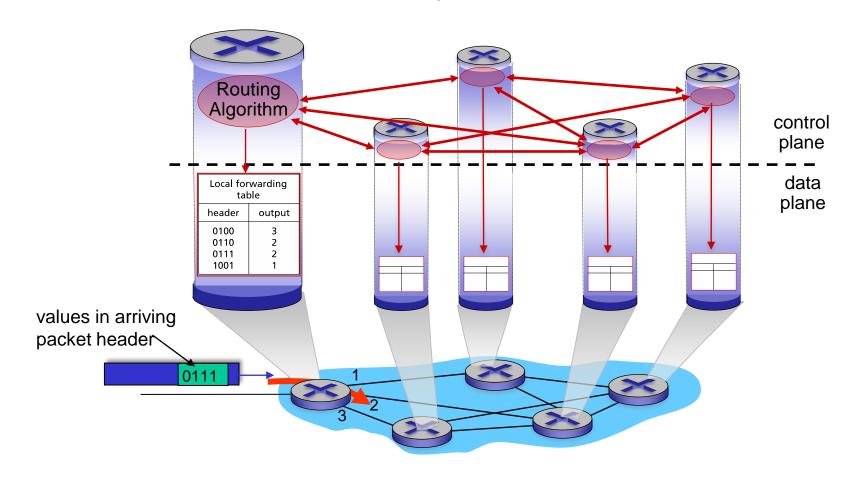
control plane

Two approaches to structuring network control plane:

- per-router control (traditional)
- logically centralized control (software defined networking)

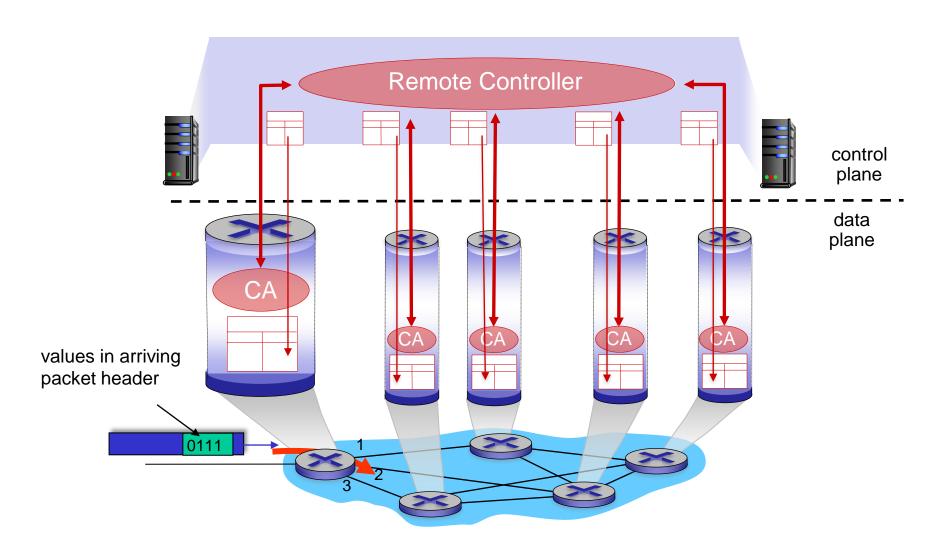
Per-router control plane

Individual routing algorithm components in each and every router interact in the control plane

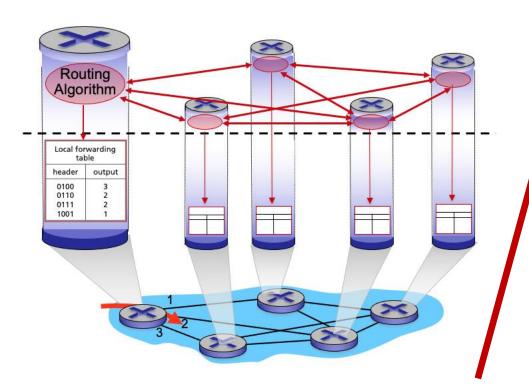


Software-Defined Networking (SDN) control plane

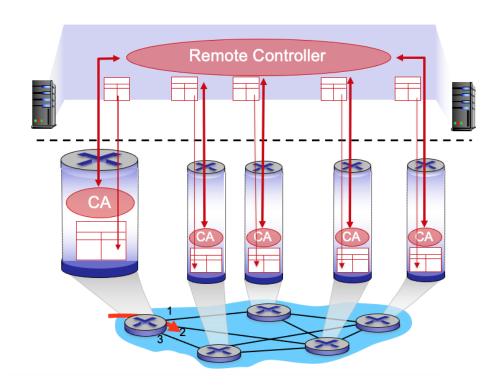
Remote controller computes, installs forwarding tables in routers



Per-router control plane



SDN control plane



Network layer: "control plane" roadmap

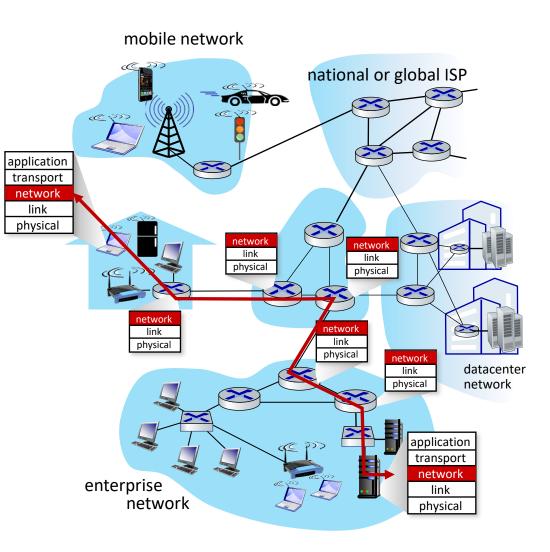
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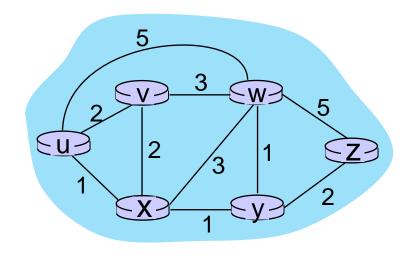
Routing protocols

Routing protocol goal: determine "good" paths (equivalently, routes), from sending hosts to receiving host, through network of routers

- path: sequence of routers packets traverse from given initial source host to final destination host
- "good": least "cost", "fastest", "least congested"
- routing: a "top-10" networking challenge!



Graph abstraction: link costs



graph: G = (N, E)

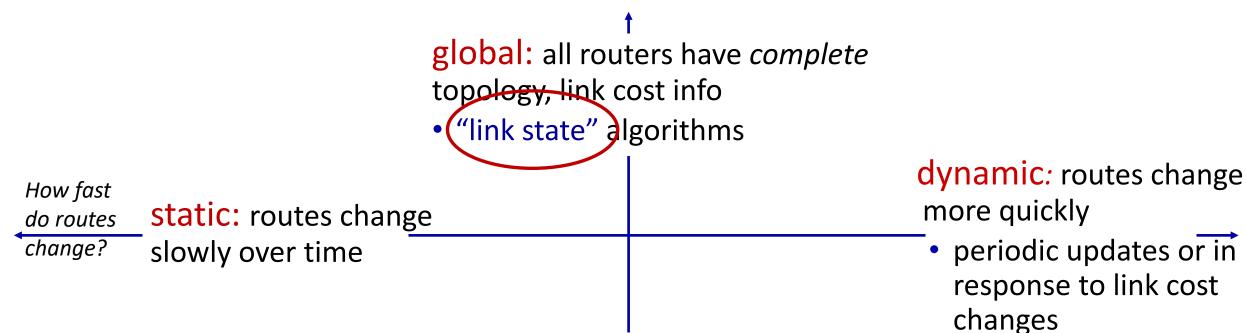
N: set of routers = $\{u, v, w, x, y, z\}$

E: set of links = $\{(u,v), (u,x), (v,x), (v,w), (x,w), (x,y), (w,y), (w,z), (y,z)\}$

 $c_{a,b}$: cost of *direct* link connecting a and be.g., $c_{w.z} = 5$, $c_{u.z} = \infty$

> cost defined by network operator: could always be 1, or inversely related to bandwidth, or inversely related to congestion

Routing algorithm classification



decentralized: iterative process of computation, exchange of info with neighbors

- routers initially only know link costs to attached neighbors
- ("distance vector") algorithms

global or decentralized information?

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Dijkstra's link-state routing algorithm

- centralized: network topology, link costs known to all nodes
 - accomplished via "link state broadcast"
 - all nodes have same info
- computes least cost paths from one node ("source") to all other nodes
 - gives *forwarding table* for that node
- iterative: after k iterations, know least cost path to k destinations

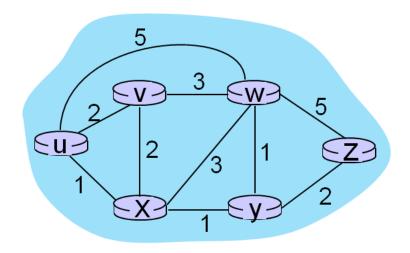
notation

- $c_{x,y}$: direct link cost from node x to y; = ∞ if not direct neighbors
- D(v): current estimate of cost of least-cost-path from source to destination v
- p(v): predecessor node along path from source to v
- N': set of nodes whose leastcost-path definitively known

Dijkstra's link-state routing algorithm

```
1 Initialization:
   N' = \{u\}
                                 /* compute least cost path from u to all other nodes */
   for all nodes v
     if v adjacent to u
                                /* u initially knows direct-path-cost only to direct neighbors
      then D(v) = c_{u,v}
                                                                                        */
                                /* but may not be minimum cost!
    else D(v) = \infty
   Loop
     find w not in N' such that D(w) is a minimum
     add w to N'
     update D(v) for all v adjacent to w and not in N':
        D(v) = \min (D(v), D(w) + c_{w,v})
     /* new least-path-cost to v is either old least-cost-path to v or known
     least-cost-path to w plus direct-cost from w to v */
15 until all nodes in N'
```

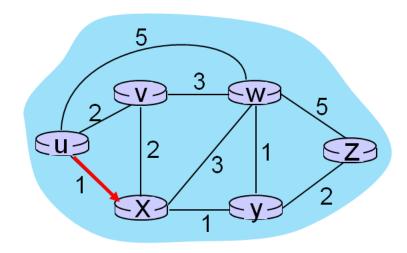
		V	W	X	У	Z
Step	N'	D(v),p(v)	D(w),p(w)	D(x),p(x)	D(y),p(y)	D(z),p(z)
0	u	2,u	5,u	1,u	∞	∞
1						
2						
3						
4						
5						



Initialization (step 0):

For all a: if a adjacent to u then $D(a) = c_{u,a}$

		V	W	(X)	У	Z
Step	N'	D(v),p(v)	D(w),p(w)	D(x),p(x)	D(y),p(y)	D(z),p(z)
0	u	2,u	5,u	(1,u)	∞	∞
1	(IX)					
2						
3						
4						
5						



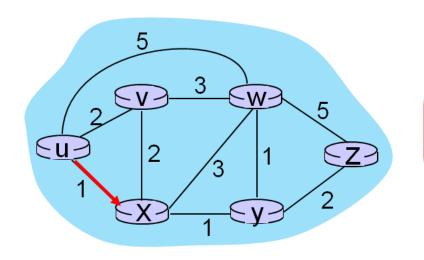
- 8 Loop
- find a not in N' such that D(a) is a minimum
- 10 add *a* to *N'*

if the value of D(a) change you change the p(a) node, if the value of D(a) doesnt change you don't change the p(a) node

ux

node V	W	X	У	Z
D(v),p(v)	D(w),p(w)	D(x),p(x)	D(y),p(y)	D(z),p(z)
2,u	5,u	(1,u)	∞	∞
2,u	4 ,x		2,x	∞

Step



- find a not in N' such that D(a) is a minimum
- add a to N' 10
- update D(b) for all b adjacent to a and not in N': 11

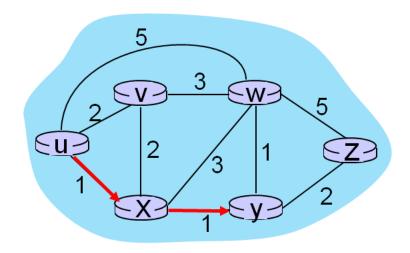
$$D(b) = \min(D(b), D(a) + c_{a,b})$$

$$D(v) = min(D(v), D(x) + c_{x,v}) = min(2, 1+2) = 2$$

$$D(w) = min(D(w), D(x) + c_{x,w}) = min(5, 1+3) = 4$$

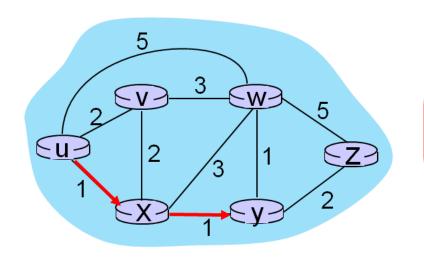
$$D(y) = min(D(y), D(x) + c_{x,y}) = min(inf, 1+1) = 2$$

			V	W	X	(Y)	Z
St	ер	N'	D(v),p(v)	D(w),p(w)	D(x),p(x)	D(y),p(y)	D(z),p(z)
	0	u	2,u	5,u	(1,u)	∞	∞
	1	ux	2,tr	4,x		(2,x)	∞
	2	uxy					
	3						
	4						
	5						



- find a not in N' such that D(a) is a minimum
- 10 add *a* to *N'*

			V	W	X	У	Z
S	tep	N'	D(v),p(v)	D(w),p(w)	D(x),p(x)	D(y),p(y)	D(z),p(z)
	0	u	2,u	5,u	(1,u)	∞	∞
	1	ux	2,u	4,x		(2,x)	∞
	2	uxy	2,u	3,y			4 ,y
	3			· •			
	4						
	5						



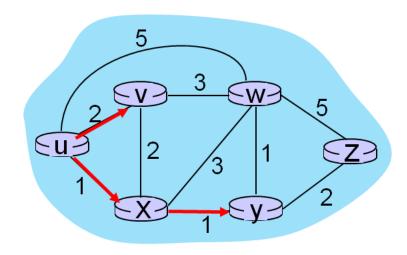
- find a not in N' such that D(a) is a minimum
- 10 add *a* to *N'*
- 11 update D(b) for all b adjacent to a and not in N':

$$D(b) = \min(D(b), D(a) + c_{a,b})$$

$$D(w) = min(D(w), D(y) + c_{y,w}) = min(4, 2+1) = 3$$

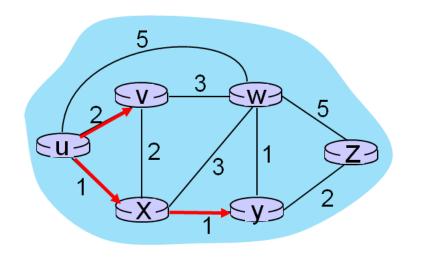
 $D(z) = min(D(z), D(y) + c_{y,z}) = min(inf, 2+2) = 4$

		V	W	X	У	Z
Step	N'	$\cancel{p}(v),p(v)$	D(w),p(w)	D(x),p(x)	D(y),p(y)	D(z),p(z)
0	u	/ 2,u	5,u	(1,u)	∞	∞
1	ux /	2,u	4,x		(2,x)	∞
2	uxy /	(2,u)	3,y			4 ,y
3	uxyv		. •			
4						
5						



- find a not in N' such that D(a) is a minimum
- 10 add *a* to *N'*

		V	W	X	У	Z
Step	N'	D(v),p(v)	D(w),p(w)	D(x),p(x)	D(y),p(y)	D(z),p(z)
0	u	2,u	5,u	(1,u)	∞	∞
1	ux	2,u	4 ,x		(2,x)	∞
2	uxy	(2,u)	3,y			4 ,y
3	uxyv		3,y			4,y
4						
5						

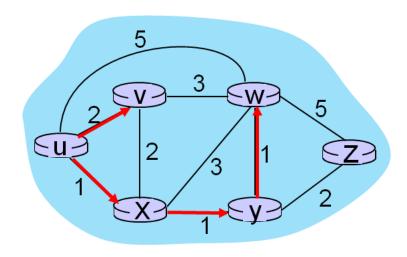


- find a not in N' such that D(a) is a minimum
- 10 add *a* to *N'*
- 11 update D(b) for all b adjacent to a and not in N':

$$D(b) = \min (D(b), D(a) + c_{a,b})$$

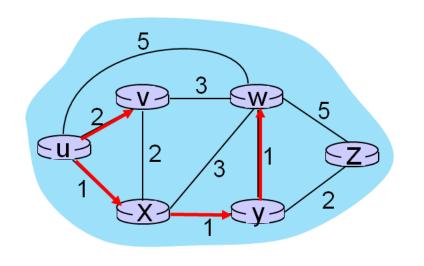
$$D(w) = min(D(w), D(v) + c_{v,w}) = min(3, 2+3) = 3$$

		V	W	X	У	Z
Step	N'	D(v),p(v)	D(w),p(w)	D(x),p(x)	D(y),p(y)	D(z),p(z)
0	u	2,u	5,u	(1,u)	∞	∞
1	ux	2 ,u	4,x		(2,x)	∞
2	uxy	(2,u)	3,y			4 ,y
3	uxyv		(3,y)			4,y
4	uxyvw					<u> </u>
5						



- find a not in N' such that D(a) is a minimum
- 10 add *a* to *N'*

			V	W	X	У	Z
S	tep	N'	D(v),p(v)	D(w),p(w)	D(x),p(x)	D(y),p(y)	D(z),p(z)
	0	u	2,u	5,u	(1,u)	∞	∞
	1	ux	2,u	4,x		(2,x)	∞
	2	uxy	2,u	3,y			4 ,y
	3	uxyv		(3,y)			4,y
	4	uxyvw					4 ,y
	5						

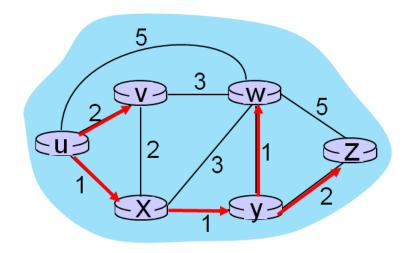


- find a not in N' such that D(a) is a minimum
- 10 add *a* to *N'*
- 11 update D(b) for all b adjacent to a and not in N':

$$D(b) = \min \left(D(b), D(a) + c_{a,b} \right)$$

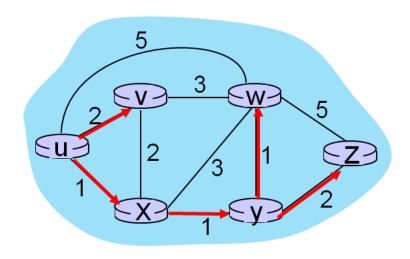
$$D(z) = min(D(z), D(w) + c_{w,z}) = min(4, 3+5) = 4$$

			V	W	X	У	Z
Ste	ер	N'	D(v),p(v)	D(w),p(w)	D(x),p(x)	D(y),p(y)	D(z),p(z)
	0	u	2,u	5,u	(1,u)	8	∞
	1	ux	2,u	4,x		(2,x)	∞
	2	uxy	(2,u)	3,4			4 ,y
	3	uxyv		(3,y)			4,y
	4	uxyvw					<u>4,y</u>
	5	uxvvwz					

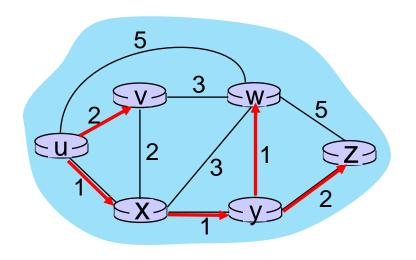


- find a not in N' such that D(a) is a minimum
- 10 add *a* to *N'*

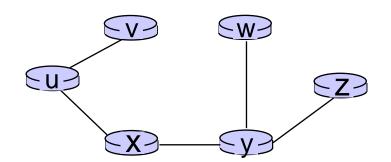
			V	W	X	У	Z
Ste	ер	N'	D(v),p(v)	D(w),p(w)	D(x),p(x)	D(y),p(y)	D(z),p(z)
	0	u	2,u	5,u	(1,u)	∞	∞
	1	ux	2,u	4 ,x		(2,x)	∞
	2	uxy	2,u	3,y			4 ,y
	3	uxyv		(3,y)			4 ,y
	4	uxyvw					<u>4,y</u>
	5	uxvvwz					



- 8 Loop
- 9 find a not in N' such that D(a) is a minimum
- 10 add *a* to *N'*
- update D(b) for all b adjacent to a and not in N': $D(b) = \min (D(b), D(a) + c_{a,b})$

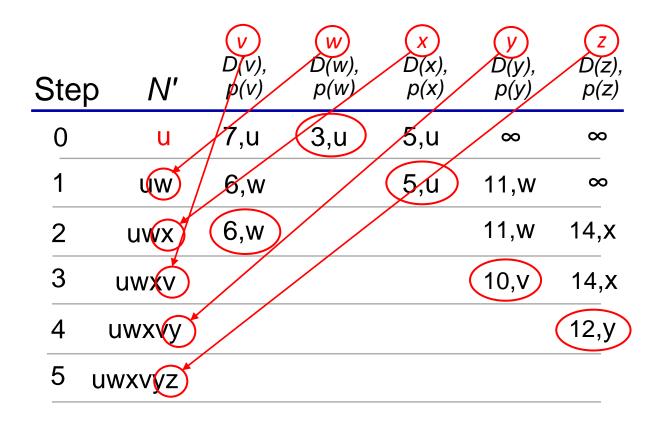


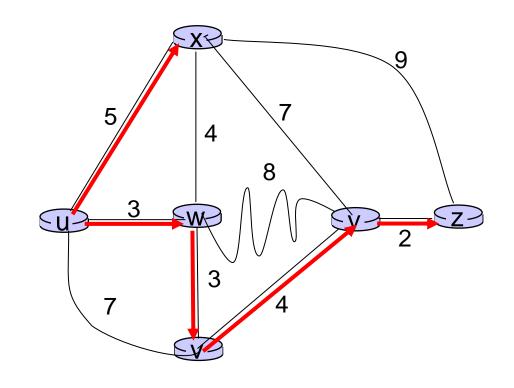
resulting least-cost-path tree from u:



resulting forwarding table in u:

destination	outgoing link	
V	(u,v) —	route from u to v directly
X	(u,x)	
У	(u,x)	route from u to all
W	(u,x)	other destinations
Z	(u,x)	via <i>x</i>





notes:

- construct least-cost-path tree by tracing predecessor nodes
- ties can exist (can be broken arbitrarily)

Dijkstra's algorithm: discussion

algorithm complexity: *n* nodes

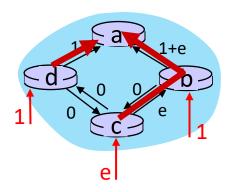
- each of n iteration: need to check all nodes, w, not in N
- n(n+1)/2 comparisons: $O(n^2)$ complexity
- more efficient implementations possible: O(nlogn)

message complexity:

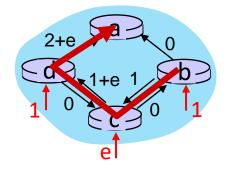
- each router must broadcast its link state information to other n routers
- efficient (and interesting!) broadcast algorithms: O(n) link crossings to disseminate a broadcast message from one source
- each router's message crosses O(n) links: overall message complexity: $O(n^2)$

Dijkstra's algorithm: oscillations possible

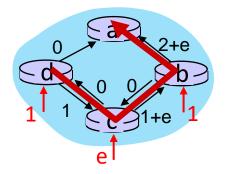
- when link costs depend on traffic volume, route oscillations possible
- sample scenario:
 - routing to destination a, traffic entering at d, c, e with rates 1, e (<1), 1
 - link costs are directional, and volume-dependent



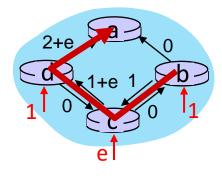
initially



given these costs, find new routing.... resulting in new costs



given these costs, find new routing.... resulting in new costs



given these costs, find new routing.... resulting in new costs

Network layer: "control plane" roadmap

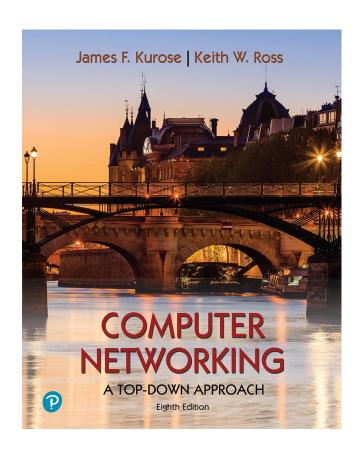
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Important Dates

- 07-19-2024(Friday), Midnight(11:59PM)–
 Homework4 due date
- 07-22-2024 (Monday)- Quiz 2
 From LectureD_11_Chapter_3
 To LectureD 17 Chapter 5
- 07-26-2024 (Friday)- Exam 2
 From LectureD_11_Chapter_3
 To LectureD 19 Chapter 5

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Computer Networking: A Top-Down Approach

8th edition Jim Kurose, Keith Ross Pearson, 2020

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