```
function [phi] = getPhi(state,aind,centers,B,var,nactions)

    % 現在の状態に関する基底関数
    dist = sum((centers - repmat(state',B,1)).^2,2);

    phi = zeros(B*nactions,1);
    phi(B*(aind-1)+1:B*aind) = exp(-dist/2/var^2);
```