# 1. Description

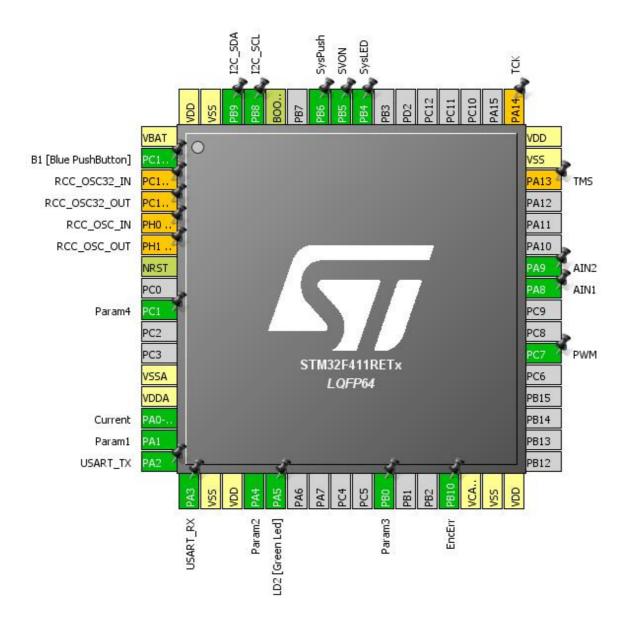
## 1.1. Project

Project Name	DCMotorControlShieldV1_0
Board Name	NUCLEO-F411RE
Generated with:	STM32CubeMX 4.22.0
Date	09/02/2017

## 1.2. MCU

MCU Series	STM32F4
MCU Line	STM32F411
MCU name	STM32F411RETx
MCU Package	LQFP64
MCU Pin number	64

## 2. Pinout Configuration



# 3. Pins Configuration

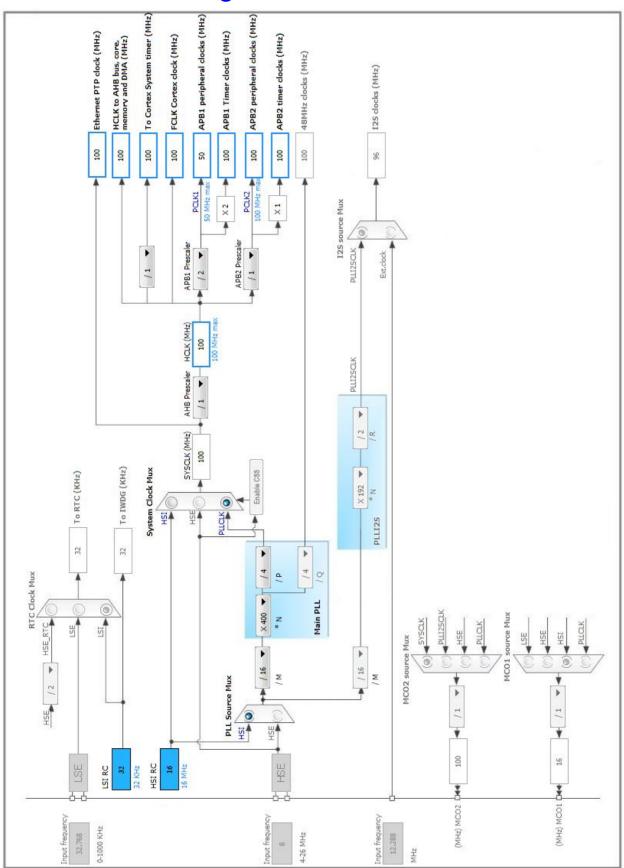
Pin Number	Pin Name	Pin Type	Alternate	Label
LQFP64	(function after		Function(s)	
EQI I O	reset)		r unotion(s)	
1	VBAT	Power		
2	PC13-ANTI_TAMP	1/0	GPIO_EXTI13	B1 [Blue PushButton]
3	PC14-OSC32_IN *	1/0	RCC_OSC32_IN	2 · [2:40 · 40:124:101.]
4	PC15-OSC32_OUT *	I/O	RCC_OSC32_OUT	
5	PH0 - OSC_IN *	I/O	RCC_OSC_IN	
6	PH1 - OSC_OUT *	I/O	RCC_OSC_OUT	
7	NRST	Reset		
9	PC1	I/O	ADC1_IN11	Param4
12	VSSA	Power	7.501	
13	VDDA	Power		
14	PA0-WKUP	I/O	ADC1_IN0	Current
15	PA1	I/O	ADC1_IN1	Param1
16	PA2	I/O	USART2_TX	USART_TX
17	PA3	I/O	USART2_RX	USART_RX
18	VSS	Power		
19	VDD	Power		
20	PA4	I/O	ADC1_IN4	Param2
21	PA5 **	I/O	GPIO_Output	LD2 [Green Led]
26	PB0	I/O	ADC1_IN8	Param3
29	PB10 **	I/O	GPIO_Output	EncErr
30	VCAP1	Power		
31	VSS	Power		
32	VDD	Power		
38	PC7	I/O	TIM3_CH2	PWM
41	PA8 **	I/O	GPIO_Output	AIN1
42	PA9 **	I/O	GPIO_Output	AIN2
46	PA13 *	I/O	SYS_JTMS-SWDIO	TMS
47	VSS	Power		
48	VDD	Power		
49	PA14 *	I/O	SYS_JTCK-SWCLK	TCK
56	PB4 **	I/O	GPIO_Output	SysLED
57	PB5 **	I/O	GPIO_Input	SVON
58	PB6 **	I/O	GPIO_Input	SysPush
60	воото	Boot		
61	PB8	I/O	I2C1_SCL	I2C_SCL
62	PB9	I/O	I2C1_SDA	I2C_SDA

Pin Number LQFP64	Pin Name (function after reset)	Pin Type	Alternate Function(s)	Label
63	VSS	Power		
64	VDD	Power		

<sup>\*\*</sup> The pin is affected with an I/O function

<sup>\*</sup> The pin is affected with a peripheral function but no peripheral mode is activated

## 4. Clock Tree Configuration



## 5. IPs and Middleware Configuration

### 5.1. ADC1

mode: IN0 mode: IN1 mode: IN4 mode: IN8 mode: IN11

## 5.1.1. Parameter Settings:

#### ADC\_Settings:

Clock Prescaler PCLK2 divided by 4

Resolution 12 bits (15 ADC Clock cycles)

Data Alignment

Scan Conversion Mode

Enabled \*

Continuous Conversion Mode

Disabled

Discontinuous Conversion Mode

Disabled

DMA Continuous Requests

Enabled \*

End Of Conversion Selection EOC flag at the end of all conversions \*

### ADC\_Regular\_ConversionMode:

Number Of Conversion 5 \*

External Trigger Conversion Source

Timer 3 Trigger Out event \*

External Trigger Conversion Edge

Trigger detection on the rising edge

Rank

Channel Channel 0
Sampling Time 144 Cycles \*

Rank 2 \*

Channel 1 \*
Sampling Time 28 Cycles \*

<u>Rank</u> 3 \*

Channel Channel 4 \*
Sampling Time 28 Cycles \*

<u>Rank</u> 4 \*

Channel 8 \*
Sampling Time 28 Cycles \*

<u>Rank</u> 5 \*

Channel 11 \*
Sampling Time 28 Cycles \*

ADC\_Injected\_ConversionMode:

Number Of Conversions 0

WatchDog:

Enable Analog WatchDog Mode false

## 5.2. I2C1

12C: 12C

## 5.2.1. Parameter Settings:

#### **Master Features:**

I2C Speed Mode Fast Mode \*

I2C Clock Speed (Hz) 400000

Fast Mode Duty Cycle Duty cycle Tlow/Thigh = 2

**Slave Features:** 

Clock No Stretch Mode Disabled
Primary Address Length selection 7-bit
Dual Address Acknowledged Disabled
Primary slave address 0x00
General Call address detection Disabled

## 5.3. SYS

**Timebase Source: SysTick** 

## 5.4. TIM3

**Channel2: PWM Generation CH2** 

## 5.4.1. Parameter Settings:

#### **Counter Settings:**

Prescaler (PSC - 16 bits value) 0
Counter Mode Up

Counter Period (AutoReload Register - 16 bits value ) 4999 \*
Internal Clock Division (CKD) No Division

**Trigger Output (TRGO) Parameters:** 

Master/Slave Mode Disable (no sync between this TIM (Master) and its Slaves

Trigger Event Selection Update Event \*

**PWM Generation Channel 2:** 

Mode PWM mode 1

Pulse (16 bits value) 0
Fast Mode Disable
CH Polarity High

### 5.5. USART2

**Mode: Asynchronous** 

### 5.5.1. Parameter Settings:

#### **Basic Parameters:**

Baud Rate 115200

Word Length 8 Bits (including Parity)

Parity None Stop Bits 1

**Advanced Parameters:** 

Data Direction Receive and Transmit

Over Sampling 16 Samples

## 5.6. FREERTOS

mode: Enabled

## 5.6.1. Config parameters:

**Versions:** 

FreeRTOS version 9.0.0
CMSIS-RTOS version 1.02

Kernel settings:

USE\_PREEMPTION Enabled

CPU\_CLOCK\_HZ SystemCoreClock

1000 TICK\_RATE\_HZ 7 MAX\_PRIORITIES MINIMAL\_STACK\_SIZE 128 MAX\_TASK\_NAME\_LEN 30 \* Disabled USE\_16\_BIT\_TICKS Enabled IDLE\_SHOULD\_YIELD Enabled USE\_MUTEXES USE\_RECURSIVE\_MUTEXES Disabled Disabled USE\_COUNTING\_SEMAPHORES QUEUE\_REGISTRY\_SIZE Disabled USE\_APPLICATION\_TASK\_TAG Enabled ENABLE\_BACKWARD\_COMPATIBILITY USE\_PORT\_OPTIMISED\_TASK\_SELECTION Enabled Disabled USE\_TICKLESS\_IDLE USE\_TASK\_NOTIFICATIONS Enabled

#### Memory management settings:

Memory Allocation Dynamic

TOTAL\_HEAP\_SIZE 15360

Memory Management scheme heap\_1 \*

#### **Hook function related definitions:**

USE\_IDLE\_HOOK Disabled

USE\_TICK\_HOOK Disabled

USE\_MALLOC\_FAILED\_HOOK Enabled \*

USE\_DAEMON\_TASK\_STARTUP\_HOOK Disabled

CHECK\_FOR\_STACK\_OVERFLOW Option2 \*

#### Run time and task stats gathering related definitions:

GENERATE\_RUN\_TIME\_STATS Disabled
USE\_TRACE\_FACILITY Disabled
USE\_STATS\_FORMATTING\_FUNCTIONS Disabled

#### Co-routine related definitions:

USE\_CO\_ROUTINES Disabled MAX\_CO\_ROUTINE\_PRIORITIES 2

#### Software timer definitions:

USE\_TIMERS Disabled

#### Interrupt nesting behaviour configuration:

LIBRARY\_LOWEST\_INTERRUPT\_PRIORITY 15
LIBRARY\_MAX\_SYSCALL\_INTERRUPT\_PRIORITY 5

#### 5.6.2. Include parameters:

#### Include definitions:

vTaskPrioritySet Enabled uxTaskPriorityGet Enabled Enabled vTaskDelete Disabled vTaskCleanUpResources vTaskSuspend Enabled vTaskDelayUntil Enabled \* vTaskDelay Enabled xTaskGetSchedulerState Enabled xTaskResumeFromISR Enabled xQueueGetMutexHolder Disabled xSemaphoreGetMutexHolder Disabled pcTaskGetTaskName Disabled uxTaskGetStackHighWaterMark Disabled xTaskGetCurrentTaskHandle Disabled eTaskGetState Disabled xEventGroupSetBitFromISR Disabled  $x \\ Timer \\ Pend \\ Function \\ Call$ Disabled xTaskAbortDelay Disabled xTaskGetHandle Disabled

#### \* User modified value

# 6. System Configuration

## 6.1. GPIO configuration

IP	Pin	Signal	GPIO mode	GPIO pull/up pull down	Max Speed	User Label
ADC1	PC1	ADC1_IN11	Analog mode	No pull-up and no pull-down	n/a	Param4
	PA0-WKUP	ADC1_IN0	Analog mode	No pull-up and no pull-down	n/a	Current
	PA1	ADC1_IN1	Analog mode	No pull-up and no pull-down	n/a	Param1
	PA4	ADC1_IN4	Analog mode	No pull-up and no pull-down	n/a	Param2
	PB0	ADC1_IN8	Analog mode	No pull-up and no pull-down	n/a	Param3
I2C1	PB8	I2C1_SCL	Alternate Function Open Drain	No pull-up and no pull- down *	Very High	I2C_SCL
	PB9	I2C1_SDA	Alternate Function Open Drain	No pull-up and no pull- down *	Very High *	I2C_SDA
TIM3	PC7	TIM3_CH2	Alternate Function Push Pull	No pull-up and no pull-down	Very High *	PWM
USART2	PA2	USART2_TX	Alternate Function Push Pull	Pull-up	Very High	USART_TX
	PA3	USART2_RX	Alternate Function Push Pull	Pull-up	Very High	USART_RX
Single Mapped	PC14- OSC32_IN	RCC_OSC32_IN	n/a	n/a	n/a	
Signals	PC15- OSC32_OU T	RCC_OSC32_O UT	n/a	n/a	n/a	
	PH0 - OSC_IN	RCC_OSC_IN	n/a	n/a	n/a	
	PH1 - OSC_OUT	RCC_OSC_OUT	n/a	n/a	n/a	
	PA13	SYS_JTMS- SWDIO	n/a	n/a	n/a	TMS
	PA14	SYS_JTCK- SWCLK	n/a	n/a	n/a	TCK
GPIO	PC13- ANTI_TAMP	GPIO_EXTI13	External Interrupt Mode with Falling edge trigger detection	No pull-up and no pull-down	n/a	B1 [Blue PushButton]
	PA5	GPIO_Output	Output Push Pull	No pull-up and no pull-down	Low	LD2 [Green Led]
	PB10	GPIO_Output	Output Push Pull	No pull-up and no pull-down	Very High *	EncErr

## DCMotorControlShieldV1\_0 Project Configuration Report

IP	Pin	Signal	GPIO mode	GPIO pull/up pull	Max	User Label
				down	Speed	
	PA8	GPIO_Output	Output Push Pull	Pull-down *	Very High	AIN1
	PA9	GPIO_Output	Output Push Pull	Pull-down *	Very High	AIN2
	PB4	GPIO_Output	Output Push Pull	No pull-up and no pull-down	Very High	SysLED
	PB5	GPIO_Input	Input mode	No pull-up and no pull-down	n/a	SVON
	PB6	GPIO_Input	Input mode	Pull-up *	n/a	SysPush

## 6.2. DMA configuration

DMA request	Stream	Direction	Priority
ADC1	DMA2_Stream0	Peripheral To Memory	Very High *
I2C1_RX	DMA1_Stream0	Peripheral To Memory	Very High *

## ADC1: DMA2\_Stream0 DMA request Settings:

Mode: Circular \*
Use fifo: Disable
Peripheral Increment: Disable
Memory Increment: Enable \*
Peripheral Data Width: Half Word
Memory Data Width: Half Word

## I2C1\_RX: DMA1\_Stream0 DMA request Settings:

Mode: Normal
Use fifo: Disable
Peripheral Increment: Disable
Memory Increment: Enable \*\*

Peripheral Data Width: Byte Memory Data Width: Byte

## 6.3. NVIC configuration

Interrupt Table	Enable	Preenmption Priority	SubPriority
Non maskable interrupt	true	0	0
Hard fault interrupt	true	0	0
Memory management fault	true	0	0
Pre-fetch fault, memory access fault	true	0	0
Undefined instruction or illegal state	true	0	0
System service call via SWI instruction	true	0	0
Debug monitor	true	0	0
Pendable request for system service	true	15	0
System tick timer	true	15	0
DMA1 stream0 global interrupt	true	5	0
ADC1 global interrupt	true	5	0
I2C1 event interrupt	true	5	0
I2C1 error interrupt	true	5	0
DMA2 stream0 global interrupt	true	5	0
PVD interrupt through EXTI line 16		unused	
Flash global interrupt		unused	
RCC global interrupt	unused		
TIM3 global interrupt	unused		
USART2 global interrupt	unused		
EXTI line[15:10] interrupts	unused		
FPU global interrupt	unused		

<sup>\*</sup> User modified value

# 7. Power Consumption Calculator report

### 7.1. Microcontroller Selection

Series	STM32F4
Line	STM32F411
MCU	STM32F411RETx
Datasheet	026289 Rev4

#### 7.2. Parameter Selection

Temperature	25
Vdd	null

# 8. Software Project

## 8.1. Project Settings

Name	Value
Project Name	DCMotorControlShieldV1_0
Project Folder	C:\SW4STM32\DCMotorControlShield\V1_0\Rev_1_0\Nucleo-
Toolchain / IDE	SW4STM32
Firmware Package Name and Version	STM32Cube FW_F4 V1.16.0

## 8.2. Code Generation Settings

Name	Value
STM32Cube Firmware Library Package	Copy only the necessary library files
Generate peripheral initialization as a pair of '.c/.h' files	Yes
Backup previously generated files when re-generating	No
Delete previously generated files when not re-generated	Yes
Set all free pins as analog (to optimize the power	No
consumption)	