Graphical models: Structure learning Hauptseminar Machine learning, WS 13/14

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Abstract

Super cool abstract

1. Introduction

The goal of this paper is to present the main ideas of [ref], which describes[?] a Bayesian approach for structure learning of Bayesian networks. Furthermore, we'll show the contribution of the author to the relevant field, as well as provide additional experimental results, which we conducted on our own.

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2. Related research

anderes paper gleicher author - neue papers researchen

3. Basics

In this chapter, we present the basics

3.1. Bayesian network

A Bayesian network (sometimes also called a Bayes or belief network) is a probabilistic graphical model which encodes the conditional dependencies between a set of random variables (RV) $X = \{X_1, ..., X_n\}$. Such a network is a Directed Acyclic Graph (DAG), which nodes represent the RV, and the edges describe the conditional dependencies between these RV. Therefore, each node in the Bayesian network can be seen as a conditional probability distribution of the random variable X_i under its parents Pa_i . This would result in $P(X_i|Pa_i)$. ?????

Figure[ref] shows a simple Bayesian network with three binary random variables, and the CPT for X_3 .

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3.2. Dirichlet probability distribution

The Dirichlet distribution is a multivariate continuous probability distribution, which depend on a vector α with positive entries. It is defined as

$$Dir(x_1, ..., x_m | \alpha_1, ..., \alpha_m) = \frac{1}{B(\alpha)} \prod_{i=1}^m x_i^{\alpha_i - 1}$$

where $\sum_{i} x_i = 1$, $x_i > 0$ and

$$B(\alpha) = \frac{\prod_{i=1}^{m} \Gamma(\alpha_i)}{\Gamma(\sum_{i=1}^{m} \alpha_i)}$$

with the Gamma function $\Gamma(x)$. Since $B(\alpha)$ is the multinomial extension of the Beta function, the Dirichlet distribution can be seen as the multivariate generalization of the Beta distribution. [[Note that equal a is uniform distribution and what ai stands for, and equivalent sample size + ref]]

The Dirichlet distribution is also the conjugated prior of the multinomial distribution. Therefore, it is often used in Bayesian probability theory to model the belief $P(\mu)$ about the parameter of a multinomial distribution $Multi(x|\mu)$ for a discrete random variable x. This yields the benefit of a simple calculation of the posterior $P(\mu|x)$. If x corresponds to a dataset D which contains Therefore, the posterior $P(\mu|D)$ is also Dirichlet distributed and is given by

$$P(\mu|D) \propto Dir(\mu|\alpha_1 + n_1, ..., \alpha_k + n_k)$$

where α_i is from the prior and n_i the number of occurences in D... For detailed information about the Dirichlet distribution, as well as the calculation of the posterior, we refer to [ref].

4. Structure learning

In order to learn the model of a Bayesian network from an observed dataset $D = \{d_1,...,d_N\}$ where d_i is a full observation of X, the authors of [ref] proposed a Bayesian approach and introduced the random variable m. It has the states $m_1,...m_M$ which correspond to the possible models of a Bayesian network for the set of random variables X.

4.1. Assumption

The authors of [ref] considered discrete random variables for X, which means every X_i has a finite number of states r_i . We use the notation x_i^k if the random variable X_i is in state k with $k=1...r_i$. Since every X_i has a finite number of parents Pa_i , there exists a finite amount of possible combinations for the parents states $q_i = \prod_{X_m \in Pa_i} r_m$. We denote a specific configuration j of Pa_i with pa_i^j and $j=1...q_i$.

In addition to discrete random variables, the authors also assumed that the state of X_i with a specific parent state combination pa_i^j is multinomial distributed with a parameter vector θ_{ij} .

This simplifies the construction and inference in the Bayesian network, because the probability distribution for each node can now be stored as a conditional probability table (CPT). In this CPT exists a parameter vector θ_{ij} for every random variable and every possible parent state combination. To denote the probability for a state k of X_i with parent state pa_i^j , we use the notation θ_{ijk} . Since the states of X_i are multinomial distributed it is clear that

$$\sum_{k=1}^{r_i} \theta_{ijk} = 1$$

In the following sections we refer to the full set of parameters as θ^m for a specific.

4.2. Bayesian approach

In order to find the optimal model m for an observation D, one has to maximize the posterior of m under D. Using the Bayes' rules this yields

$$P(m|D) = \frac{P(D|m)P(m)}{P(D)} = \frac{P(D|m)P(m)}{\sum_{m} P(D|m)P(m)}$$

for the posterior of m. Similar, one can compute the posterior for the parameter set θ^m dependent on the observed data

$$P(\theta^m|D,m) = \frac{P(D|\theta^m,m)P(\theta^m|m)}{p(D|m)}$$

In both equations it is necessary to compute the likelihood of the dataset D under a specific model m. The authors refer to it as the *marginal likelihood*, which is given as an integral over all possible values for θ^m

$$P(D|m) = \int P(D|\theta^m, m)P(\theta^m|m)d\theta^m$$

Before going into detail how to calculate the marginal likelihood, or how to choose the model and parameter priors, we want to focus on the benefits of the Bayesian approach as pointed out by the authors. In contrast to other methods [[find references]], which learn only the most probable model, the Bayesian approach yields a probability distribution over all possible models. This allows a comparison of the probability between different models or the selection of models which have a similar probability than the best.

Another important benefit is the ability to determine the probability of a hypothesis, i.e. the likelihood of a new data sample d_{N+1} , over all possible models instead on only the most likely one. The probability of the new data sample is then

$$P(d_{N+1}|D) = \sum_{m} P(m|D) \int P(d_{N+1}|\theta^{m}, m) P(\theta^{m}|m) d\theta^{m}$$

The author call these a full Bayesian approach, since the probability is determined as an average over all possible models. Unfortunately, the number of possible models in a DAG with n nodes grows super exponentially with n. Therefore, the averaging over all possible models is impractical and one often chooses a fixed number of the most likely models and pretend that these are exhaustive.

4.3. Model prior

The most simple choice for the model prior P(m) is a uniform distribution. This represents the belief that no information about the model structure is available and thus every model is same likely. If some information about the problem domain are available, the search space of models can be reduced by excluding specific models or model families (e.g. if some random variables cant have parents or children). This is achieved by setting the prior P(m) for these model to zero and assume an uniform distribution over the remaining models.

An other possibility for the choice of the model prior, as mentioned by the authors, is given by Buntine [ref]. In this case the prior distribution can be computed under the assumption that the random variables can be ordered (e.g. through time precedence). For detailed information we refer to the original paper [ref].

4.4. Parameter prior

Another important choice is the prior distribution for the parameters $P(\theta^m|m)$. To simplify the computation the authors assumed parameter independence, which means that the joint probability distribution can be computed with

$$P(\theta^m|m) = \prod_{i=1}^n \prod_{j=1}^{q_i} P(\theta_{ij}|m)$$

The parameter independence also holds for the posterior $P(\theta_{ij}|D,m)$, which means that each θ_{ij} can be updated individually.

As mentioned before, a common choice in Bayesian probability theory for unknown parameter distributions is to use the conjugated prior distribution of the likelihood. Since the authors assumed a multinomial distribution for X_i , the likelihood $P(D|\theta_{ij},m)$ is also multinomial distributed, and hence the conjugated prior would be the Dirichlet distribution

$$P(\theta_{ij}|m) = Dir(\theta_{ij}|\alpha)$$

with $\alpha_i > 0$.

An important contribution of the authors is the proof that certain assumptions on the network structure actually imply a Dirichlet distribution of the parameter prior $P(\theta^m|m)$. For the complete proof, as well as detailed information for these assumptions, we refer to [ref] which is also by the authors of the original paper [ref].

4.5. Computation of the marginal likelihood

As seen in the previous section, the model prior is closed loop evaluation

5. Heuristics

6. evaluation results

7. relevance

8. conclusion

9. Electronic Submission

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- References must include page numbers whenever possible and be as complete as possible. Place multiple citations in chronological order.

Please see below for details on each of these items.

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Those who use LATEX to format their accepted papers need to pay close attention to the typefaces used. Specifically, when producing the PDF by first converting the dvi output of LATEX to Postscript the default behavior is to use non-scalable Type-3 PostScript bitmap fonts to represent the standard LATEX fonts. The resulting document is difficult to read in electronic form; the type appears fuzzy. To avoid this problem, dvips must be instructed to use an alternative font map. This can be achieved with something like the following commands:

dvips -Ppdf -tletter -G0 -o paper.ps paper.dvi ps2pdf paper.ps

Note that it is a zero following the "-G". This tells dvips to use the config.pdf file (and this file refers to a better font mapping).

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Note that the 2014 style files use the hyperref package to make clickable links in documents. If this causes problems for you, add nohyperref as one of the options to the icml2014 usepackage statement.

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We will continue the ICML tradition in which the authors are given the option of providing a short reaction to the initial reviews. These reactions will be taken into account in the discussion among the reviewers and area chairs.

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The footnote, "Preliminary work. Under review by the International Conference on Machine Learning (ICML). Do not distribute." must be modified to "Proceedings of the 31st International Conference on Machine Learning, Beijing, China, 2014. JMLR: W&CP volume 32. Copyright 2014 by the author(s)."

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Section headings should be numbered, flush left, and set in 11 pt bold type with the content words capitalized. Leave 0.25 inches of space before the heading and 0.15 inches after the heading.

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Within each section or subsection, you should further partition the paper into paragraphs. Do not indent the first line of a given paragraph, but insert a blank line between succeeding ones.

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Label all distinct components of each figure. If the figure takes the form of a graph, then give a name for each axis and include a legend that briefly describes each curve. Do not include a title inside the figure; instead, the caption

 $^{^{1}}$ For the sake of readability, footnotes should be complete sentences.

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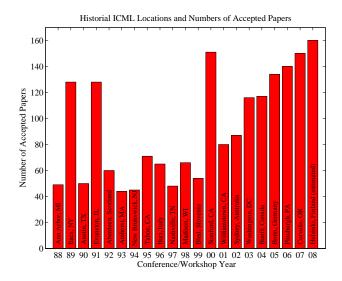


Figure 1. Historical locations and number of accepted papers for International Machine Learning Conferences (ICML 1993 – ICML 2008) and International Workshops on Machine Learning (ML 1988 – ML 1992). At the time this figure was produced, the number of accepted papers for ICML 2008 was unknown and instead estimated.

should serve this function.

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You may also want to include tables that summarize material. Like figures, these should be centered, legible, and numbered consecutively. However, place the title *above* the table with at least 0.1 inches of space before the title and the same after it, as in Table 1. The table title should be set in 9 point type and centered unless it runs two or more

```
Algorithm 1 Bubble Sort

Input: data x_i, size m
repeat

Initialize noChange = true.

for i = 1 to m - 1 do

if x_i > x_{i+1} then

Swap x_i and x_{i+1}

noChange = false
end if
end for
until noChange is true
```

Table 1. Classification accuracies for naive Bayes and flexible Bayes on various data sets.

DATA SET	NAIVE	FLEXIBLE	BETTER?
BREAST CLEVELAND GLASS2 CREDIT HORSE META PIMA	95.9 ± 0.2 83.3 ± 0.6 61.9 ± 1.4 74.8 ± 0.5 73.3 ± 0.9 67.1 ± 0.6 75.1 ± 0.6	96.7 ± 0.2 80.0 ± 0.6 83.8 ± 0.7 78.3 ± 0.6 69.7 ± 1.0 76.5 ± 0.5 73.9 ± 0.5	√ × √ × √
VEHICLE	44.9 ± 0.6	61.5 ± 0.4	$\sqrt{}$

lines, in which case it should be flush left.

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