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Comparative Analysis of Predictive Performance: Neural Networks vs. GRU in League of Legends Match Outcome Prediction

Bachelorarbeit
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Contents

1	Introduction	1
2	Background	3
2.1	League of Legends	3
2.2	Neural Networks	4
2.3	Recurrent Neural Networks	5
2.4	GRU	5
2.5	Related work	6
3	Experiments	9
3.1	Data Collection	9
3.2	Data Processing	10
3.3	Combination of static and temporal data	10
4	Results	11
5	Discussion	13
6	Conclusion	15
	Bibliography	17
	List of Figures	19
	List of Tables	21
	List of Abbreviations	23

1 Introduction

esports is highly relevant due to it being a huge and strongly growing market. many games are hard to understand, due to lots of information being displayed with very little explanation a win prediction graph can help viewers understand the action and the significance of certain plays better, thus increasing engagement and enjoyment. riot games has already implemented their own proprietary win prediction a win prediction model can also help players make more informed decisions about what the optimal path of actions is

2 Background

2.1 League of Legends

League of Legends is a Multiplayer Online Battle Arena (MOBA) game developed by Riot Games. MOBA games are a subgenre of real-time strategy games in which two teams, typically consisting of five players ('summoners') each, compete against each other with each player controlling a single character [1], called 'champion'. It is one of the most played video game genres CITATION NEEDED and attracts millions of players and fans watching the professional scene. Most MOBAs differ only slightly in terms of basic gameplay or map layout, but vary in details such as champions, abilities, graphics etc. As League of Legends is the most played game in the MOBA genre, we will focus on it. At the start of the game, each player picks a champion from a pool of currently 165 champions, each with distinct abilities and characteristics. The map consists of two bases which are connected by three lanes. Each base contains a large structure, the so called 'nexus', which is protected by two turrets. The goal of the game is to destroy the enemy nexus. The bases are connected by three lanes, separated by a jungle. Non-player characters (NPCs), so called 'minions', spawn in regular intervals and advance down the lanes. Killing minions grants gold and experience points (xp), which are used to improve different attributes by buying items or increasing ones level. It is conventional that the players split up at the start of the game, with one player going to the top lane, one to the mid lane and two players to the bottom lane. The last player gets his gold and xp from killing neutral monsters in the area between each lane, commonly referred to as 'the jungle'. It also contains two large neutral monsters, Baron Nashor and a dragon, which require multiple team member to be killed and grant improvements to the whole team. Larger fights are usually centered around either destroying a turret or killing a large neutral monster. Every year, the game enters a new 'season', where it undergoes major challenges. In between seasons, the developers release smaller patches every two weeks, which are usually aimed at changing the strength of different champions.

The players need to pick a champion that fits best into the team, taking into account the team strategy, the damage composition, the role the player has been assigned etc., while also selecting a champion the player has played before and can play well.

league of legends is a zero sum game

Esports and mobas in particular are hard to understand and follow. A live game prediction view can help fans understand the action and decisions made better and help immerse the audience by detecting upsets and swings in win probability.

patches can alter the game significantly, so it is important to train only(or mostly) on recent data

2 Background

the model should be able to answer the question, if team a is far enough ahead to win or if team b with their hyperscaling heroes can come back and win

a modified elo system is used to determine the skill of an individual player, which is the most important factor in which players get matched against each other

2.2 Neural Networks

Artificial Neural Networks (ANNs) have been originally designed to simulate the way the human brain processes information. The fundamental unit in an ANN is called a neuron, first proposed by McCulloch and Pitts [2]. A neuron is a function which takes a number of values $\mathbf{x} = (x_1, x_2, \dots, x_m)$, $m \in \mathbb{N}$ and outputs its activation a . The weighted input z is calculated as the dot product of the input vector \mathbf{x} and the weight vector $\mathbf{w} = (w_1, w_2, \dots, w_m)$ with the bias b added:

$$z = w_1x_1 + \dots + w_mx_m + b = \mathbf{w}^T \mathbf{x} + b. \quad (1)$$

z is then passed through an activation function ϕ , which provides non-linearity: $a = \phi(z) = \phi(\mathbf{w}^T \mathbf{x})$. Common activation functions include sigmoid functions, Rectified Linear Unit (ReLU) and more. The Multi-Layer Perceptron (MLP), first introduced by Rosenblatt [3] organizes neurons in layers. Input data is fed into the input layer, and computations propagate forward through the hidden layers to produce an output. In the simplest form of an ANN, every neuron in a layer is connected to every neuron in the subsequent layer, forming a fully connected architecture. There are no other connections, making it a feed-forward network, and it constitutes a directed acyclic graph. A fully connected feed-forward network can be described as a series of matrix-vector multiplications for each layer l :

$$\mathbf{a}^{(l)} = \phi(\mathbf{W}^{(l)} \mathbf{a}^{(l-1)} + \mathbf{b}^{(l)}) \quad (2)$$

In equation 2, $\mathbf{a}^{(l)}$ denotes the activation of layer l , $\mathbf{W}^{(l)}$ denotes the weight matrix of layer l and $\mathbf{b}^{(l)}$ is the corresponding bias vector with d being the number of neurons per layer. If l is the output layer L , the vector $\mathbf{a}^{(L)}$ represents the predicted output \hat{y} of the network.

To allow the network to approximate any measurable function, at least one hidden layer is required [4]. During the training process, the weights and biases are iteratively adjusted using the backpropagation algorithm to minimize the loss function E . For regression tasks, a commonly used loss function is the Mean Squared Error (MSE) Loss

$$E_N = \frac{1}{N} \sum_{i=1}^N (y_i - \hat{y}_i)^2 \quad (3)$$

where N is the number of samples [5]. For binary classification, the Cross-Entropy Loss (CEL)

$$E_N = \frac{1}{N} \sum_{k=1}^N y_k \ln \hat{y}_k + (1 - y_k) \ln (1 - \hat{y}_k) \quad (4)$$

is widely used [6].

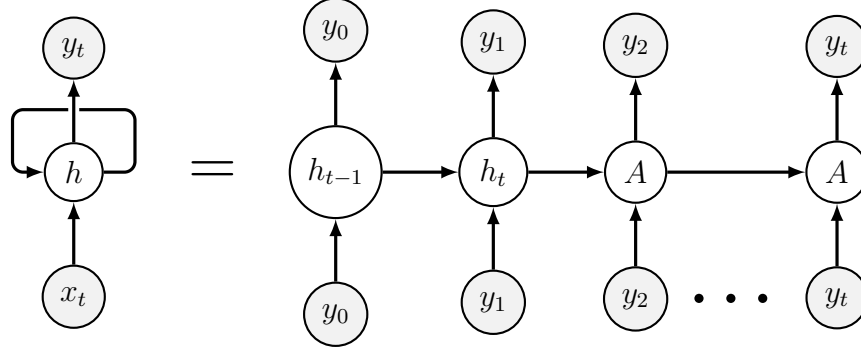


Figure 1: Unrolling of a RNN over time

2.3 Recurrent Neural Networks

Recurrent Neural Networks (RNNs) build upon the foundation of feed-forward neural networks. They are designed to handle sequential data by introducing the concept of recurrence. In an RNN, the output at each time step depends not only on the current input but also on the network's previous internal state or hidden state. This allows RNNs to capture dependencies over time, making them suitable for tasks involving sequential input such as speech and language [7]. The first fully connected RNN was proposed by Elman [8]. RNNs maintain a 'state vector' in their hidden units (see figure 2), implicitly containing information extracted from all the past elements of the sequence [7]. The output \hat{y} of a neural net can be calculated by

$$\hat{y}_t = \tanh(Vh_t + b_o) \quad (5)$$

where V and b_o are the weight matrix and the bias vector of the cell output. In addition to calculating the output, the forward propagation involves updating the hidden state h_t at every timestep t :

$$h_t = \begin{cases} 0, & \text{if } t = 0 \\ \sigma(Wx_t + Uh_{t-1} + b_h), & \text{otherwise} \end{cases} \quad (6)$$

where σ is the sigmoid function, U and b_h are the weight matrix and the bias of the hidden state and W is the weight matrix of the input. For an RNN with just one recurrent layer, one hidden weight matrix W_h is sufficient, as the weights are shared across timesteps.

Bengio et al. [9] showed, however, that RNNs have challenges with exploding or vanishing gradients, especially in long sequences, which can affect their ability to capture long-range dependencies [10].

2.4 GRU

In order to overcome the exploding/vanishing gradient problem of vanilla RNNs, gated networks like the Long Short-Term Memory (LSTM) [11] and Gated Recurrent Unit (GRU) [12] have been developed [13]. As they introduce an increased number of

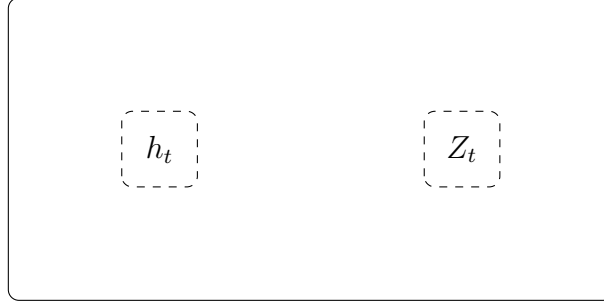


Figure 2: Elman Recurrent Unit

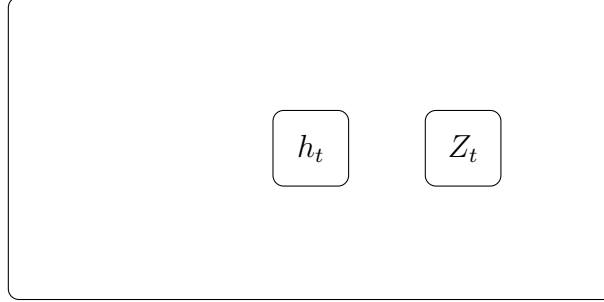


Figure 3: Gated Recurrent Unit

parameters compared to traditional RNNs, gated networks like the LSTM and GRU demand greater computational power [14]. Compared to the LSTM network, GRU reduces the number of gate networks to two, thus being simpler to implement and compute [12]. Chung et al. even found that GRU is at least comparable to LSTM most of the time [15]. The gates control the activation of each hidden unit. The reset gate is calculated by

$$r_t = \sigma(W_r x_t + U_r h_{t-1} + b_r) \quad (7)$$

and the update gate z_t by

$$z_t = \sigma(W_z x_t + U_z h_{t-1} + b_z) \quad (8)$$

[14]. The hidden state update is a linear interpolation between the previous activation h_{t-1} and the candidate activation \tilde{h}_t , where the update gate z_t influences how much the hidden state is changed [15]:

$$h_t = (1 - z_t) \odot h_{t-1} + z_t \odot \tilde{h}_t \quad (9)$$

with

$$\tilde{h}_t = g(W_h x_t + U_h(r_t \odot h_{t-1} + b_h)) \quad (10)$$

. In equations 9 and 10 \odot denotes the elementwise (Hadamard) multiplication and the function g in equation 10 is the activation function.

2.5 Related work

Utilizing machine learning methods to extract information from data generated by e-sport games is an area of ongoing research. Most scientific research focuses on the

similar MOBA DotA 2, which has easier and more fine-grained data collection methods (see section 3.1). Due to the high similarity between these two games, it is to be expected that any findings for one game can be replicated and used for the other game with minimal adaptations.

Silva et al. have used RNNs to predicting the winner using data of different time intervals. They achieved an accuracy of 75% when using data from between the 10 and 15 minute mark. An evaluation of LSTM resulted in lower accuracy, most likely due to the large amount of data required [16].

3 Experiments

As two very different experiments are compared against each other, two different datasets need to be constructed: one dataset containing all relevant information prior to the start of the game and one dataset containing only the temporal information from the beginning of the game.

3.1 Data Collection

High-Rank Matches The focus of data acquisition was directed towards high-rank matches, in which a mix of excellent amateur and professional players play. Lower rank matches are not considered due to their higher unpredictability as less skilled players make huge, game-changing mistakes way more often. Pro matches, defined as professional players playing with their respective teams in an esports tournament or league, were not included as there are way less matches and they are not available through the official Riot Games API. High rank matches in this context are defined as having at least one player holding the rank of Master, Grandmaster or Challenger. Riot Games themselves considers any rank above Diamond 3 as 'Elite' [17], but we raise this bar just slightly to only include any rank above Diamond 1. Due to the fact that for a match to be included in the dataset, only one out of ten players needs to hold one of the aforementioned highest ranks, some slightly lower ranked players are also present in the dataset. These ranks combined account for the top 0.2% of all players [18].

Riot Games API The primary source of data stemmed from the Riot Games API, a comprehensive repository of information pertaining to League of Legends gameplay. The Riot Games API provided access to a plethora of essential data points, including champion statistics, general match information, timeline details, and player-specific information. These variables collectively form a comprehensive and multifaceted dataset crucial for the development of an effective predictive model.

Other Data Sources However, not all pertinent data were available directly from the Riot Games API. These include the winning chance of each champion and statistics on how each player performs on each relevant champion. To address this limitation, a web-scraping approach was employed to gather additional relevant information. The amalgamation of Riot Games API data and web-scraped data was meticulously organized and stored in a Database. This central repository served as the foundational storehouse from which distinct datasets were constructed, ensuring an organized and structured approach to data management.

3 Experiments

Regions Multiple regions were included in the data collection process, including Europe West (EUW), Europe Nordic & East (EUN), Korea (KR), and North America (NA). This regional diversity contributes to the model’s generalizability across different player bases and playing styles.

In summary, the data collection process for this study involved a dual-pronged approach, leveraging the extensive resources provided by the Riot Games API alongside a targeted web-scraping strategy. The resulting dataset, stored in a PostgreSQL Database, reflects a comprehensive and meticulously curated compilation of high-rank amateur League of Legends matches.

3.2 Data Processing

3.3 Combination of static and temporal data

4 Results

5 Discussion

6 Conclusion

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List of Figures

1	Unrolling of a RNN over time	5
2	Elman Recurrent Unit	6
3	Gated Recurrent Unit	6

List of Tables

List of Abbreviations

ANN Artificial Neural Network

CEL Cross-Entropy Loss

FNN Feedforward Neural Network

GRU Gated Recurrent Unit

LSTM Long Short-Term Memory

MLP Multi-Layer Perceptron

MOBA Multiplayer Online Battle Arena

MSE Mean Squared Error

NN Neural Network

NPC non-player character

ReLU Rectified Linear Unit

RNN Recurrent Neural Network

xp experience points