

Comparing Graph Architectures for Deep Metric Learning

ADL4CV Final Presentation

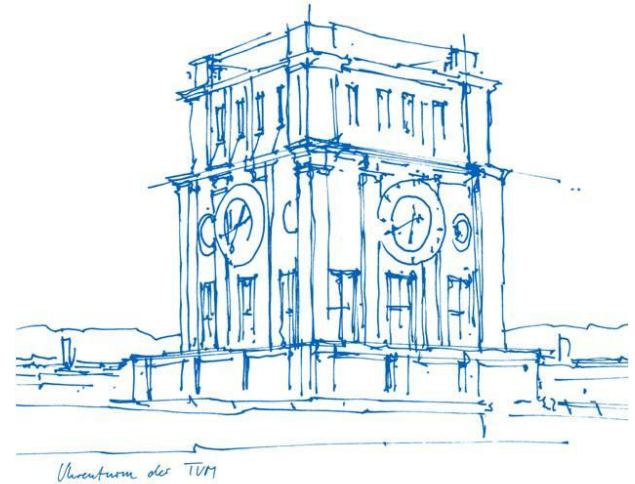
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1.1 Deep Metric Learning

A



B



Learn a **similarity** function:

$$d(A, B) > \tau$$

Goal:

- similar objects are close together
- dissimilar far apart

Why not classification?

- Doesn't scale for new classes

1.2 Research Objective

- Investigate attention mechanisms in metric learning
- Compare:
 - Jenny's architecture based on traditional attention
 - Graph Attention Network (**GAT**) v1 & v2
- Ablation Study
 - Does Attention benefit metric learning?
 - How important are the linear layers following attention?

1.3 Datasets



Stanford **CARS** Dataset

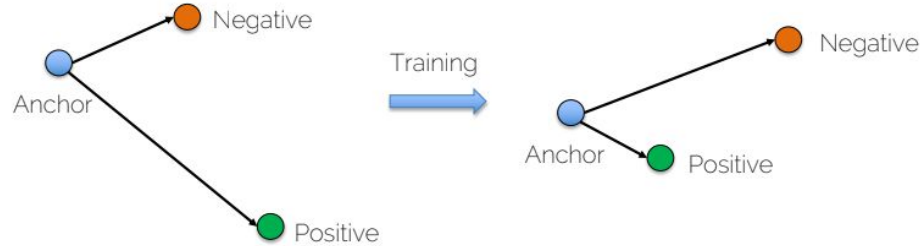
- 16.185 images
- 196 classes



Caltech **CUB** Dataset

- 11.788 images
- 200 classes

1.4 Traditional Deep Metric Learning



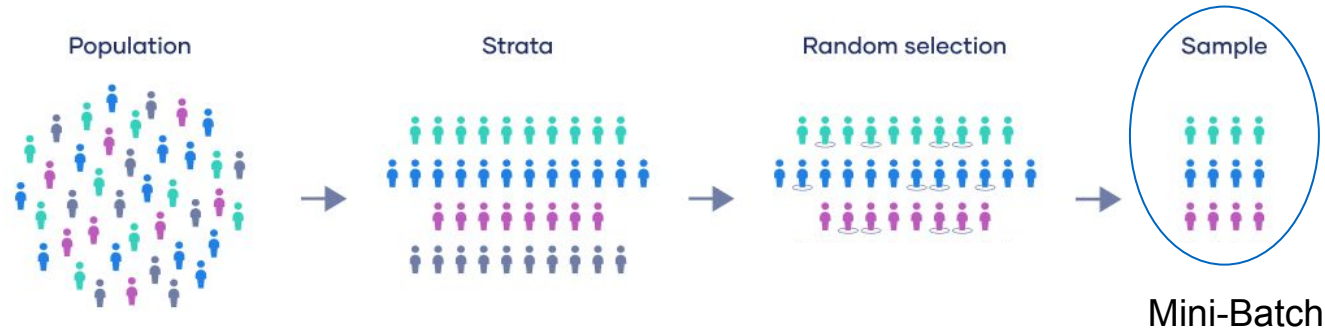
Triplet Loss

- shrink distance of similar samples
- increase distance of dissimilar samples

Problem: Which triplets to sample?

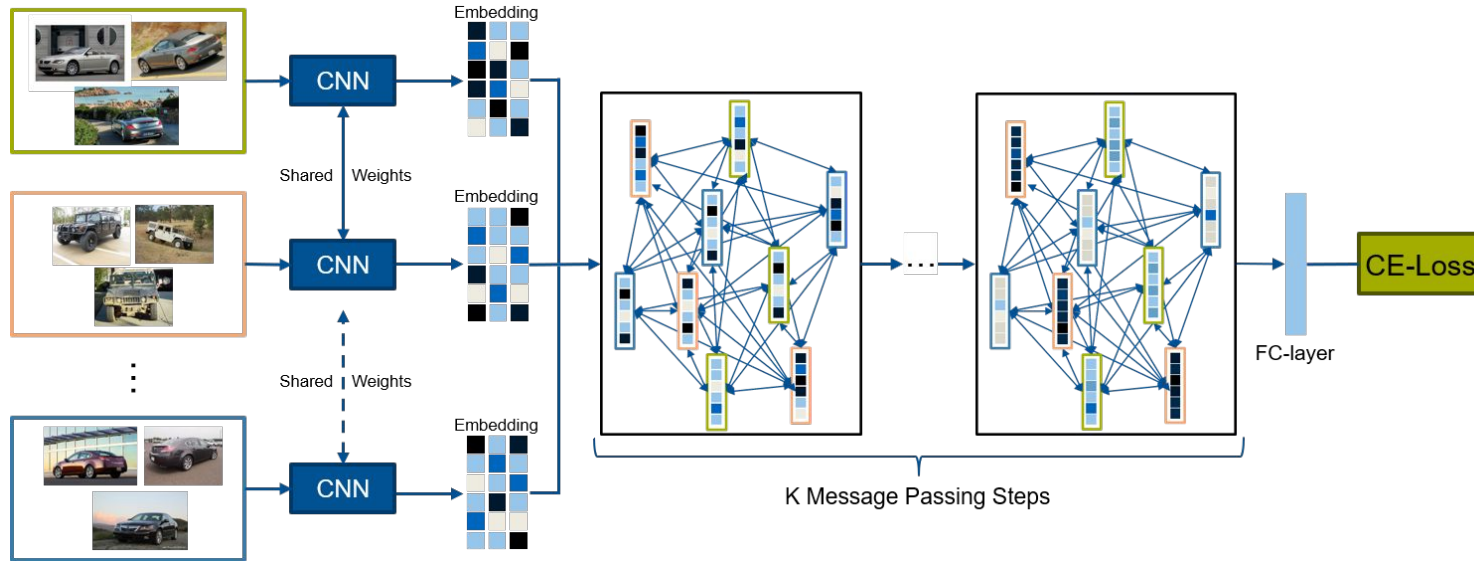
2.1 Sampling

Stratified sampling



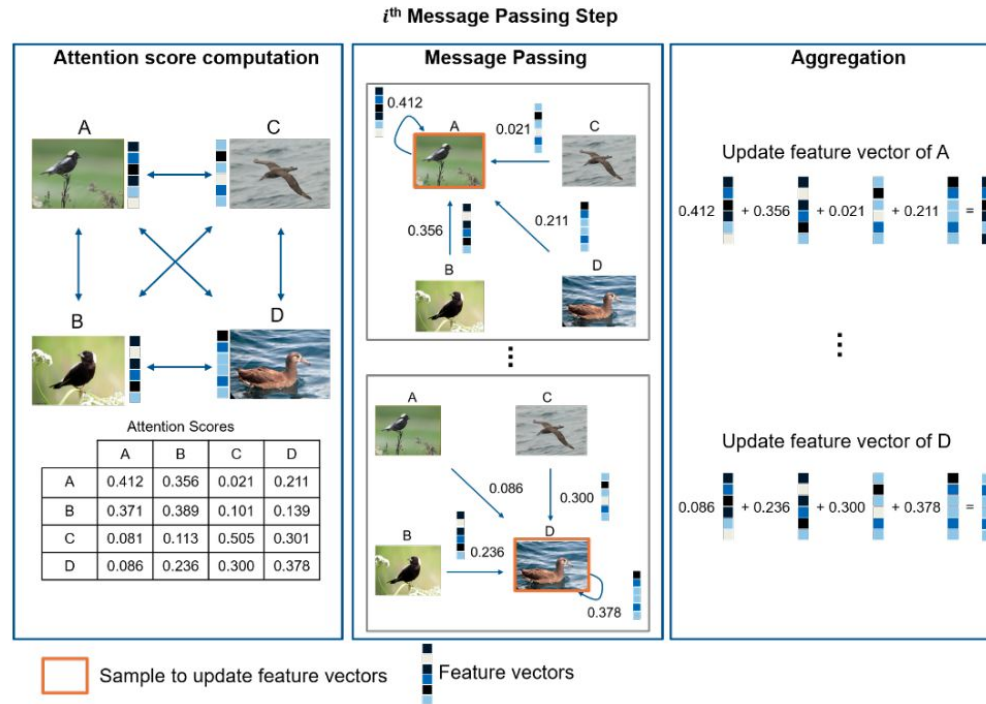
- Each class is a **Strata**
- Randomly choose X classes
- Randomly sample same amount from those classes

2.2 Jenny's Architecture



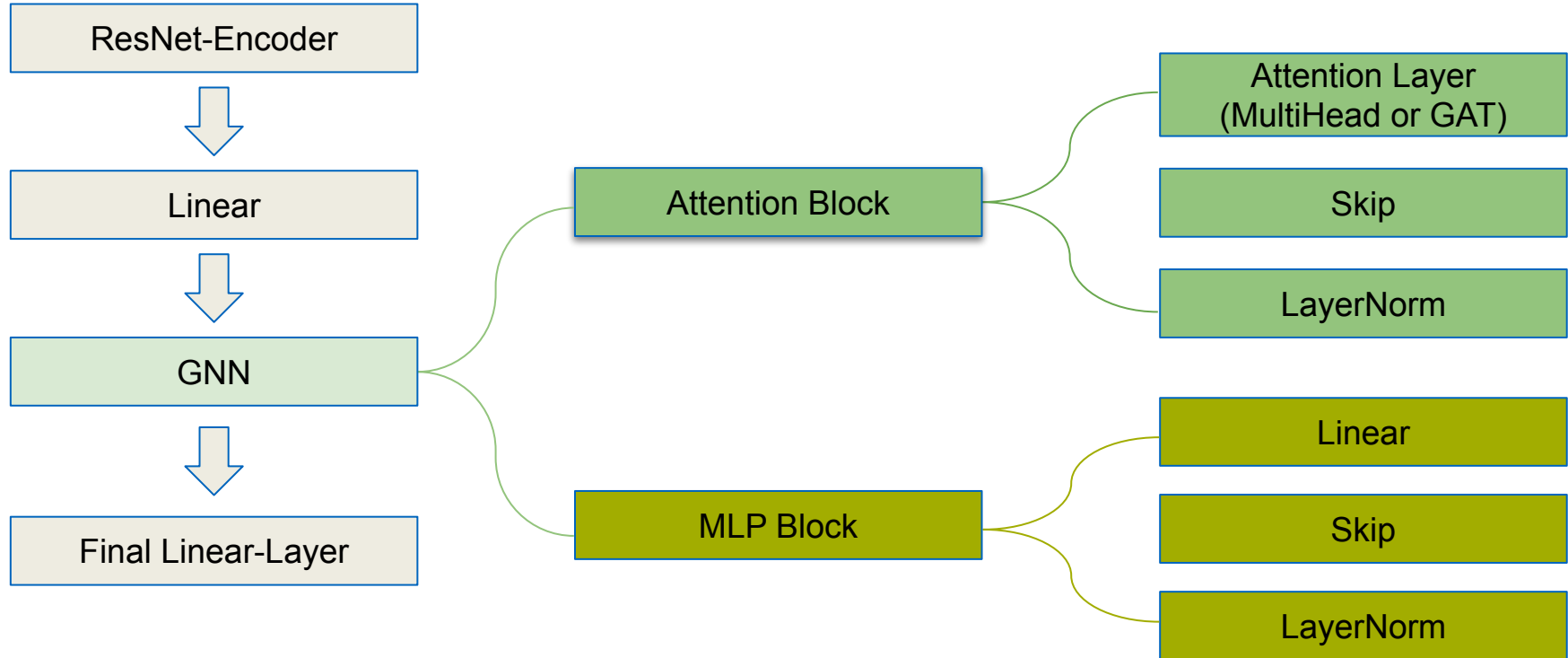
- takes whole (mini-) batch into account
- learns connection between samples

2.3 Message Passing



- Initial embeddings from Backbone
- Calculate temporal embeddings with NN (K times)
- Update node embeddings

2.4 Full Architecture in Detail



3.1 Conducted Experiments



- Train only Encoder
- Remove whole GNN
- Remove Attention
- Remove MLP
- Change Attention Mechanism

ResNet-Encoder

GNN

Attention Block

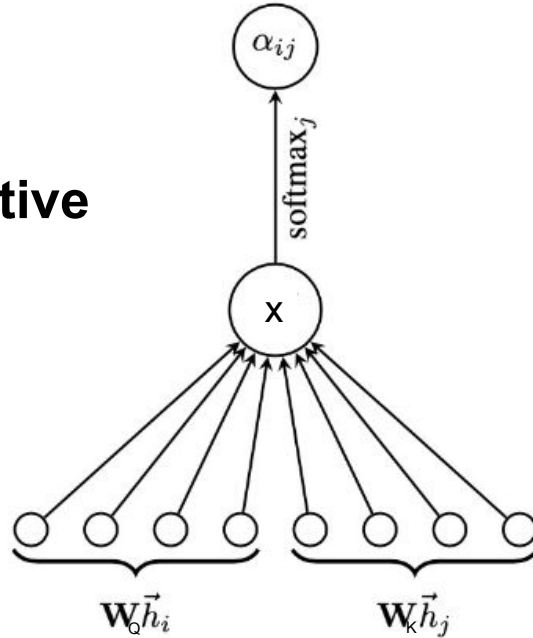
MLP Block

Attention Layer
(MultiHead or GAT)

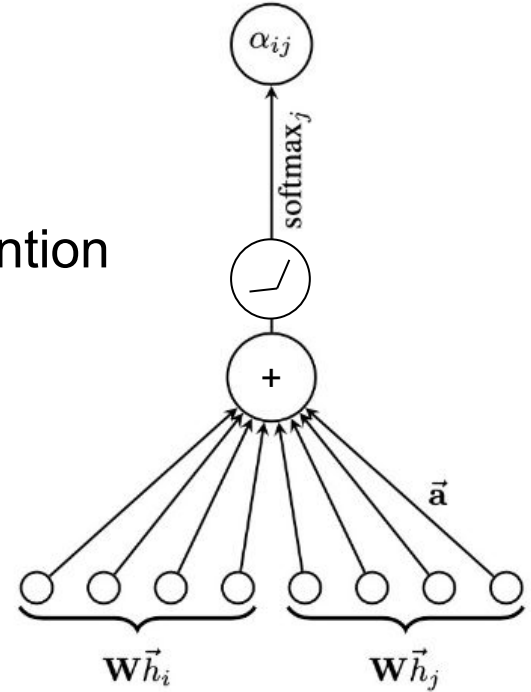
3.2 Attention Mechanisms

Attention between two nodes h_i and h_j :

Traditional
Multiplicative
Attention:



Additive Attention
used in GAT:



3.3 GAT vs GATv2

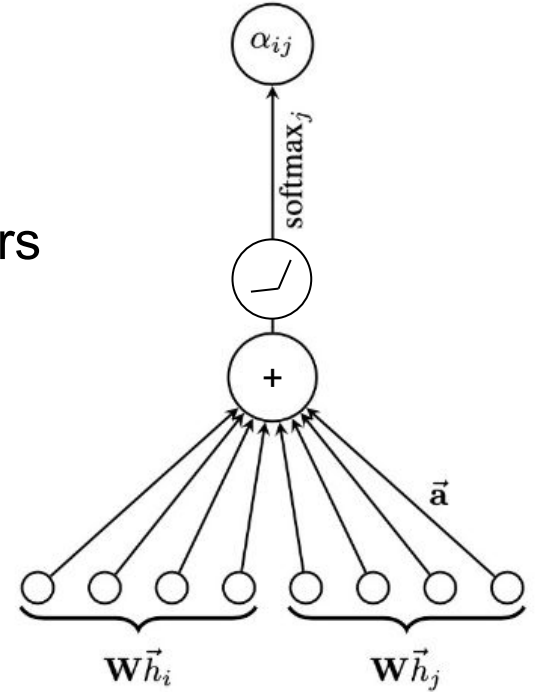
Motivation:

- GAT tends to compute a **global ranking** of “influential” nodes
- GATv2 computes **different rankings** of neighbors

$$\text{LeakyReLU}(\mathbf{a}^T \cdot [\mathbf{W}\mathbf{h}_i || \mathbf{W}\mathbf{h}_j])$$



$$\mathbf{a}^T \cdot \text{LeakyReLU}(\mathbf{W}[\mathbf{h}_i || \mathbf{h}_j])$$



3.3 Reproducibility

Results **varied** a lot across runs

=> Goal: Make everything deterministic

- Rewrote **Attention** Mechanism
- Rewrote **GAT & GATv2** Implementation

=> Now: *Deterministic* Training



4.1 Experiment Results on CARS



Method	<i>Paper</i>
<i>Baseline</i>	87.1
<i>Method</i>	88.1
<i>Difference</i>	+1.0

s

4.2 Experiment Results on CUB

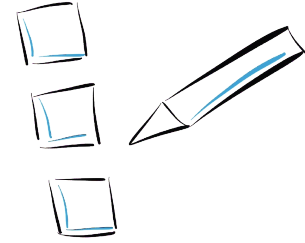


Method	<i>Paper</i>	ResNet50 only	No MLP + No Att	No Attention	No MLP	GAT	GATv2
<i>Baseline</i>	69.4	69.4	69.4	69.4	69.4	69.4	69.4
<i>Method</i>	70.3	67.7	69.1	69.3	67.9	68.9	69.8
Difference	+0.9	-1.7	-0.3	-0.1	-1.5	-0.5	+0.4

4.3 Experiments over 5 Seeds

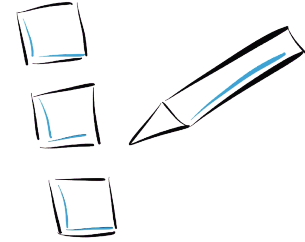
Method	CARS	CUB	CARS mAP	CUB mAP	CARS NMI	CUB NMI
<i>Original</i>	87.48 +- 0.37	69.05 +- 1.04	25.87 +- 0.98	27.15 +- 0.74	71.56 +- 0.83	72.51 +- 0.92
<i>GATv2</i>	87.23 +- 0.38	69.24 +- 0.30	26.86 +- 0.50	27.22 +- 0.39	72.39 +- 0.40	72.52 +- 0.74

5. Conclusion



- Attention *beneficial* to Metric Learning in general
- Linear Layers not necessarily needed for Attention
- GATv2 *outperforms* GAT
- GATv2 outperform traditional attention by a small margin

4. Future Work



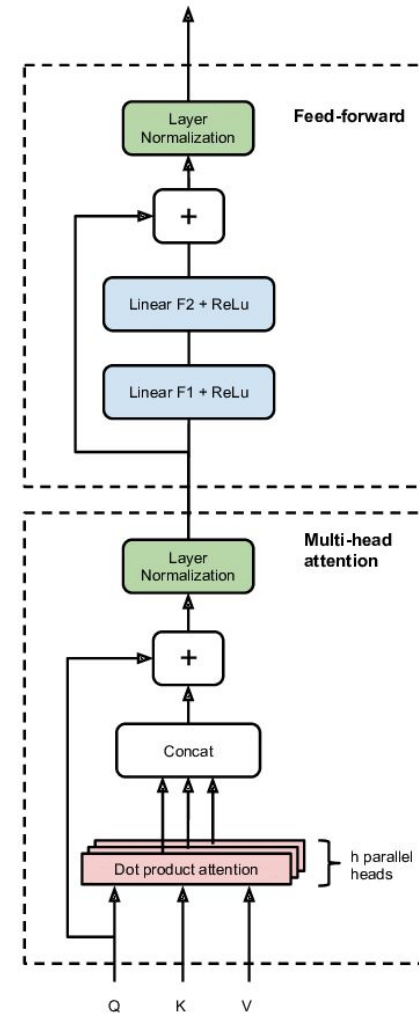
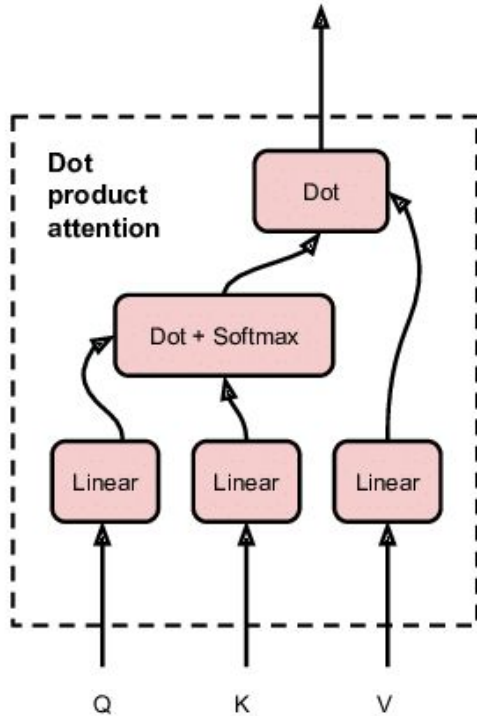
- mAP@R für Gatv2
- tSNE of the embeddings

References

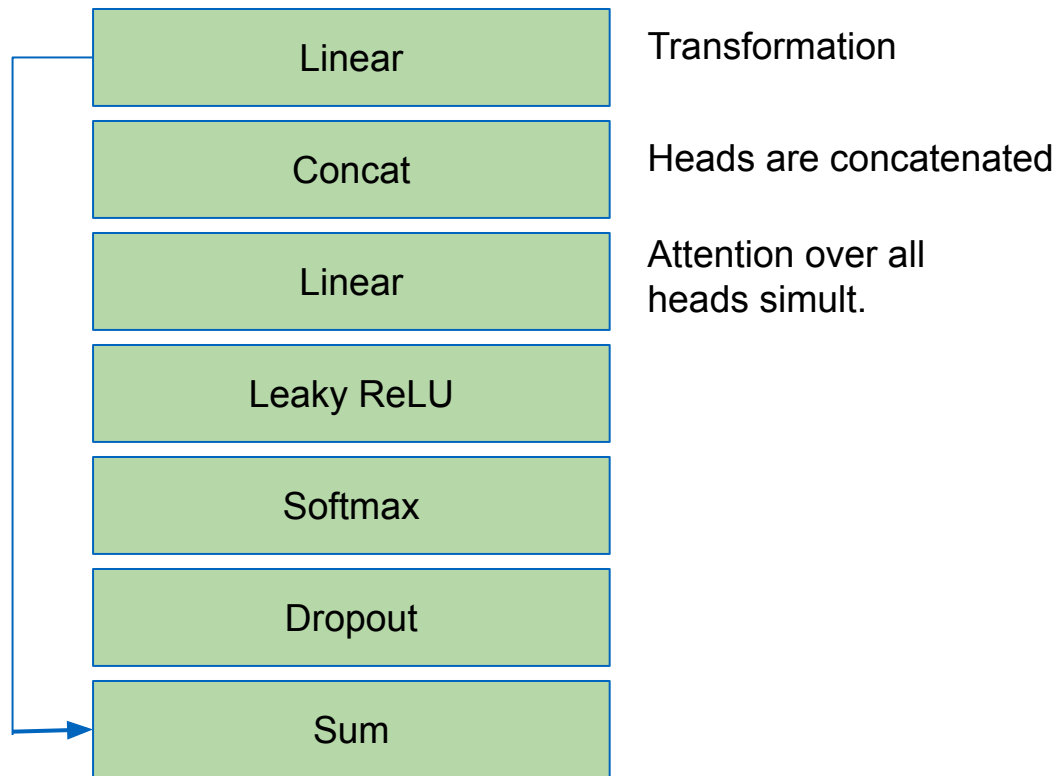
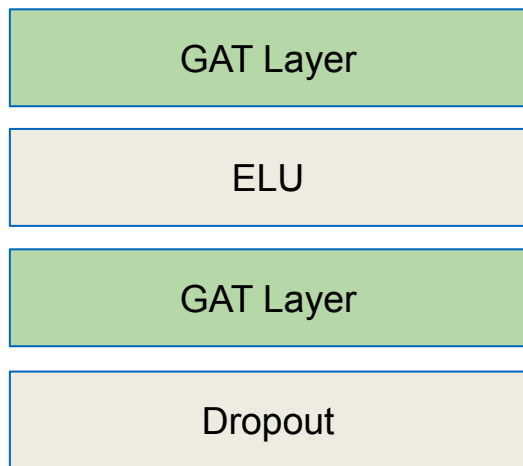
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<https://arxiv.org/pdf/2102.07753.pdf>
- [2] Velikovi et al. “Graph attention networks”. 2018.
<https://arxiv.org/pdf/1710.10903.pdf>
- [3] Brody et al. “How attentive are graph attention networks?”. 2021.
<https://arxiv.org/pdf/2105.14491.pdf>
- [4] Dong et al. “Attention is not all you need: Pure attention loses rank doubly exponentially with depth”. 2021.
<https://arxiv.org/pdf/2103.03404.pdf>

Backup

2 Multi Head Attention



2 GAT

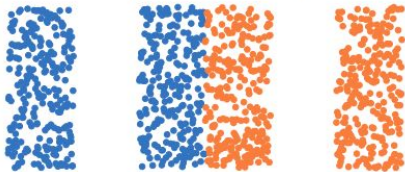


3.2 Metrics

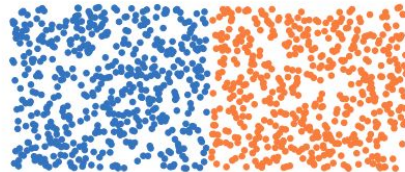
Recall@K: 1. k-means clustering
2. Get k nearest neighbors
3. If match: score=1, if not score=0

NMI: 1. Split into clusters (1) and class labels (2)
2. How do (1) and (2) agree?
High:1 , Low: 0

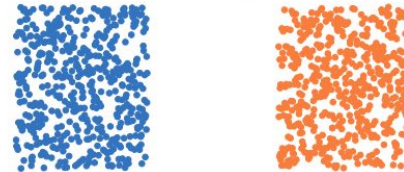
NMI: 95.6% F1: 100% R@1: 99%,
R-Precision: 77.4% MAP@R: 71.4%



NMI: 100% F1: 100% R@1: 99.8%
R-Precision: 83.3% MAP@R: 77.9%



NMI: 100% F1: 100% R@1: 100%,
R-Precision: 99.8% MAP@R: 99.8%



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4.1 Message Passing formally

MP & **Attention** Weights:

$$\mathbf{h}_i^{l+1} = \sum_{j \in N_i} \alpha_{ij}^l \mathbf{W}^l \mathbf{h}_j^l$$

Attention computation:

$$e_{ij}^l = \frac{\mathbf{W}_q^l \mathbf{h}_i^l (\mathbf{W}_k^l \mathbf{h}_j^l)^T}{\sqrt{d}} \quad \alpha_{ij}^l = \text{softmax}_j(e_{ij}^l)$$

Residual Block:

$$f(\mathbf{h}_i^{l+1}) = \text{LayerNorm}(\mathbf{h}_i^{l+1} + \mathbf{h}_i^l)$$


Added **Linear** Block:

$$g(\mathbf{h}_i^{l+1}) = \text{LayerNorm}(FF(f(\mathbf{h}_i^{l+1})) + f(\mathbf{h}_i^{l+1}))$$

4.2 Graph Attention Network

Most popular framework for attentional *GNNs*!

Difference lies in the **attention** computation:

$$e_{ij}^l = \frac{W_q^l h_i^l (W_k^l h_j^l)^T}{\sqrt{d}}$$


$$e(\mathbf{h}_i, \mathbf{h}_j) = \text{LeakyReLU}(\mathbf{a}^\top \cdot [\mathbf{W}\mathbf{h}_i \parallel \mathbf{W}\mathbf{h}_j])$$

5.1 First Experiments

- Reproducing Paper
- GAT
- GATv2

Measure the impact of *attention* & *linear* block:

- Remove *linear* Block:
$$g(h_i^{l+1}) = f(h_i^{l+1})$$

- Remove *attention*:
$$f(h_i^{l+1}) = f(h_i^l)$$

6. Challenges and Next Steps

- Challenges
 - Setting up Google Colab
 - Getting Google Cloud credits
 - Running experiments (takes a lot of time)
 - Reproducibility (Training still non-deterministic)
- Next Steps
 - Run hyperparameter tuning to improve results
 - Graph construction