

# Rouths Stability Criterion

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fast check of stability

The closed loop transfer function is

$$\frac{Y(s)}{R(s)} = \frac{D(s)G(s)}{1 + D(s)G(s)H(s)}$$

The characteristic equation of a system is:

$$1 + D(s)G(s)H(s) = 0$$

It can be written in polynomial form

$$a(s) = s^n + a_1s^{n-1} + a_2s^{n-2} + \dots + a_{n-1} + a_n$$

# Routh's Stability Criterion

The characteristic equation of a system is:

$$a(s) = s^n + a_1s^{n-1} + a_2s^{n-2} + \dots + a_{n-1} + a_n$$

necessary condition for stability:

- all roots have negative real parts

Routh: ( proof in the book)

A necessary and sufficient condition for stability is that all elements in the first column of the Routh array are positive.

It doesn't indicate the stability margins

# Routh's Array

$$a(s) = s^n + a_1s^{n-1} + a_2s^{n-2} + \dots + a_{n-1} + a_n$$

The coefficients of the characteristic polynomial are arranged in two rows followed by calculated elements

$$\begin{array}{ccccccc}
 s^n & 1 & a_2 & a_4 & \dots & & \\
 s^{n-1} & a_1 & a_3 & a_5 & \dots & & \\
 s^{n-2} & b_1 & b_2 & b_3 & \dots & & \\
 & & & & & & : \\
 s^2 & * & * & & & & \\
 s & * & & & & & \\
 s^0 & * & & & & & 
 \end{array}$$

# Routh Array elements

- $b_1 = \frac{-\det \begin{bmatrix} 1 & a_2 \\ a_1 & a_3 \end{bmatrix}}{a_1}$
- $b_2 = \frac{-\det \begin{bmatrix} 1 & a_4 \\ a_1 & a_5 \end{bmatrix}}{a_1}$
- $b_3 = \frac{-\det \begin{bmatrix} 1 & a_6 \\ a_1 & a_7 \end{bmatrix}}{a_1}$

- $c_1 = \frac{-\det \begin{bmatrix} a_1 & a_3 \\ b_1 & b_2 \end{bmatrix}}{b_1}$
- $c_2 = \frac{-\det \begin{bmatrix} a_1 & a_5 \\ b_1 & b_3 \end{bmatrix}}{b_1}$
- $c_3 = \frac{-\det \begin{bmatrix} a_1 & a_7 \\ b_1 & b_4 \end{bmatrix}}{b_1}$

# Example

- Given the characteristic polynomial
- $s^3 + 2s^2 + 4s + 6$
- The Routh array are:
- $s^3$ :    1      4      0
- $s^2$ :    2      6      0
- $s^1$ :     $\left( \frac{-(1*6-2*4)}{2} = 1 \right)$      $\left( \frac{-(1*0-2*0)}{2} = 0 \right)$
- $s^0$ :     $\left( \frac{-(2*0-1*6)}{1} = 6 \right)$      $\left( \frac{-(2*0-1*0)}{1} = 0 \right)$
- The system is stable since all the elements in the first row are positive.

# Example

Given the system  $D(s) = K$ ,  $G(s) = \frac{s+1}{s(s-1)(s+6)}$ ,  $H(s) = 1$

*notice: there is a positive pole*

The characteristic equation is

$$1 + K \frac{s+1}{s(s-1)(s+6)} = 0$$

or

$$s^3 + 5s^2 + (K-6)s + K = 0$$

Calculate the Routh array

Find values of K making the system stable

# Example

The closed loop characteristic equation is

$$s^3 + 5s^2 + (K - 6)s + K = 0$$

The Routh array is:

$s^3:$	1	$K - 6$
$s^2:$	5	$K$
$s^1:$	$\left(\frac{4K-30}{5}\right)$	0
$s^0:$	$(K)$	0



# Example

What is the limits for stabilization

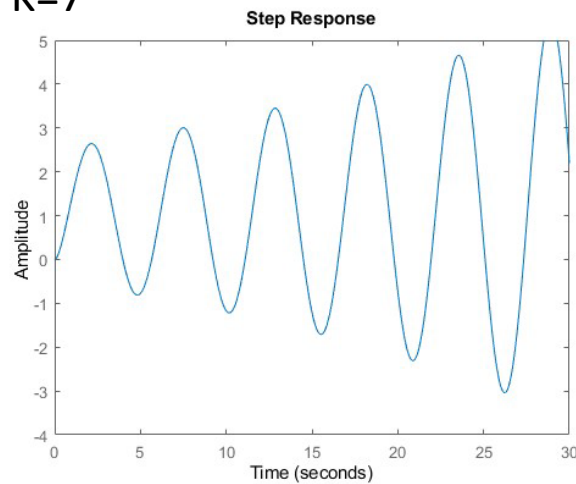
$$\frac{4K - 30}{5} > 0 \text{ and } K > 0$$

or

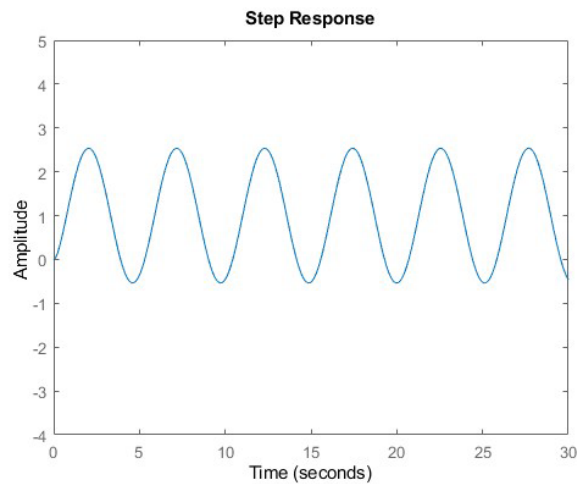
$$K > 7.5 \text{ and } K > 0$$

Closed loop step responses  $G(s) = \frac{s+1}{s(s-1)(s+6)}$ ,  $H(s) = 1$

K=7



K=7.5



K=8

