High Performance Computing USN-HCMV, Paris 13 Joint Master 2022

Worksheet 2

Let A be the a) matrix defined in worksheet 1, b) The 1D Finite Difference Matrix c) Matrices defined in Matrix Market

Exercise 1

In the restarting gmres.m you received , add the missing lines that transform the Hessenberg matrix into an upper matrix by applying Givens rotation and which also provides the error at iteration $j\!+\!1$

Check that your restarting gmres.m is correct using manufactured solutions

- First, use a restart parameter that is greater than the matrix dimension. What does this imply?
- Analyse in terms of computing and memory storage, the effect of the restarting parameter

Comment the efficiency of gmres compared to the previous iterative methods worksheet 1)

Exercise 2

Left preconditioner : Solve MAx = Mb

Right preconditioner: Solve AMy = b, and then x = My

Using the above gmres.m, modify it to precgmres.m so as to be able to use a right preconditioner M that can be changed at each restart of gmres.

Validate your precgmres.m defining M = diag(A)

Exercise 3

Look into the matlab function ilu that performs an ILU(0) approximation of A. [L0, U0] = ILU(A) Use this ILU(0) as a right preconditioner in precgmres.m to solve Ax = b as in TP1

Exercise 4

Look into the matlab function schur that performs a Schur decomposition of a matrix. (help schur)

Exercise 5

Following the algorithm below, modify precemres.m to obtain a function that performs a Deflation Preconditioned Gmres

```
Algorithm DEFLGMRES(m,l)
Choose x_0;
M=I_n;
U=;
1. r_0 = b - Ax_0, \beta = ||r_0||, v_1 := r_0/\beta;
2. Generate the Arnoldi basis applied to AM^{-1} and the associated Hessenberg
 matrix \tilde{H_m} starting with v_1;
3. Compute y_m which minimises \|\beta e_1 - \tilde{H}_m y\| and x_m = x_0 + M^{-1} V_m y_m;
4. If convergence Stop, else set;
       x_0 = x_m ;
       Compute l Schur vectors of H_m noted S_l;
       Compute the approximation of |\lambda_n|;
       Orthogonalize V_m S_l against U;
       Increase U with V_m S_l;
       T = U^T A U;
      M^{-1} = I_n + U(|\lambda_n|T^{-1} - I_r)U^T;
       Go To 1;
```