High Performance Computing USN-HCMV, Paris 13 Joint Master 2022

Worksheet 3

Let A be the a) matrix defined in worksheet 1, b) The 1D Finite Difference Matrix for the Laplace operator c) The 2D Finite Difference Matrix for the Laplace operator d) Matrices defined in Matrix Market

In attached Directory Matrices , you will find some matrices harder to solve that come from Matrix Market

https://math.nist.gov/MatrixMarket/

mminfo.m, mmread.m are two functions that allow you to read these matrices as shown in the commented lines of tp1b.m

Exercise 1

With the codes that Prof. Halpern sent you, compare the incomplete choleski with an ILU(0) decomposition of the lap2D matrix.

(https://en.wikipedia.org/wiki/Incomplete_LU_factorization, you will find a good description of the ILU method)

Let A be a small size sparse symetric matrix (n=10). Comment the incomplete choleski and ILU(0), ILU(1)

Exercise 2

Left preconditioner : Solve MAx = Mb

Right preconditioner: Solve AMy = b, and then x = My

Using the above gmres.m, modify it to precgmres.m so as to be able to use a right preconditioner M that can be changed at each restart of gmres.

Validate your precembers.m defining M = diag(A)

Exercise 3

Look into the matlab function ilu that performs an ILU(0) approximation of A. [L0, U0] = ILU(A) Use this ILU(0) as a right preconditioner in precgmres.m to solve Ax = b as in TP1

Exercise 4

Look into the matlab function schur that performs a Schur decomposition of a matrix. (help schur)

Exercise 5

Following the algorithm below, modify precemres.m to obtain a function that performs a Deflation Preconditioned Gmres

```
Algorithm DEFLGMRES(m,l)
Choose x_0;
M=I_n;
U=;
1. r_0 = b - Ax_0, \beta = ||r_0||, v_1 := r_0/\beta;
2. Generate the Arnoldi basis applied to AM^{-1} and the associated Hessenberg
 matrix \tilde{H_m} starting with v_1;
3. Compute y_m which minimises \|\beta e_1 - \tilde{H}_m y\| and x_m = x_0 + M^{-1} V_m y_m;
4. If convergence Stop, else set;
       x_0 = x_m ;
       Compute l Schur vectors of H_m noted S_l;
       Compute the approximation of |\lambda_n|;
       Orthogonalize V_m S_l against U;
       Increase U with V_m S_l;
       T = U^T A U;
      M^{-1} = I_n + U(|\lambda_n|T^{-1} - I_r)U^T;
       Go To 1;
```