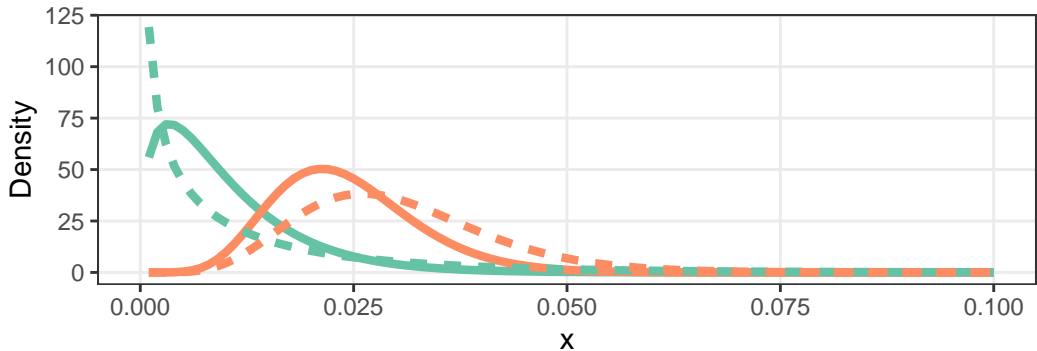


Enthusiastic prior



Assumed event probabilities: Control arm ($p_0=0.01$), Active arm ($p_1=0.01$)
Posterior standard deviation: Control arm=0.008, Active arm=0.008