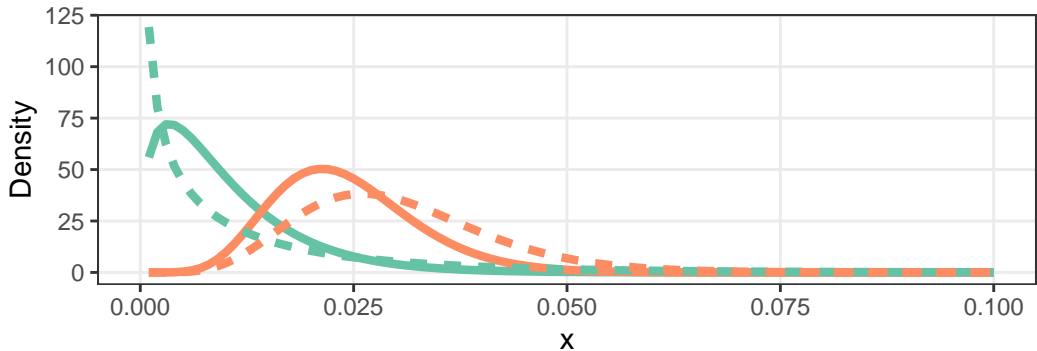


# Enthusiastic prior



Assumed event probabilities: Control arm ( $p_0=0.01$ ), Active arm ( $p_1=0.01$ )  
Posterior standard deviation: Control arm=0.008, Active arm=0.008