# Okonkwo Moses Chukwuka

NO.38, ZHEDA ROAD ZHEJIANG UNIVERSITY YUOUAN CAMPUS.

XIHU, HANGZHOU, ZHEJIANG, P.R. CHINA. Tel: 0086-151-972-70-103; 0086-177-435-075-22. Email: chukwukaokonkwo8@gmail.com: Facebook: Chukwuka Okonkwo

Research gate: Moses C. Okonkwo

## **PERSONAL DATA**

Date/Place of Birth: 8<sup>th</sup> July, 1997, Enugu City, Enugu State.

Marital Status: Single. Nationality: Nigerian.

Permanent Address: 15 Obgaru Street, Independence Layout, Enugu State, Nigeria.

Shenyang University of Technology, No. 111, Shenliao West Road, Current Address:

Economic And Technological Development Zone, Shenyang, China.

#### **EDUCATION AND ACADEMIC QUALIFICATIONS**

2016 - 2017: International Exchange College, Xiangtan University, Hunan, China.

Chinese Language Proficiency. HSK4

College of Automation and Electronic Information Engineering, 2017 - 2021:

Xiangtan University, Hunan, China.

Bachelor of Engineering Degree in Electronic Information

Engineering.

2021-2024 College of Electrical Engineering,

Shenyang University of Technology, Liaoning, China.

Masters in Electrical Engineering: Computer Vision for Robotics

2024-Present School of Electrical Engineering,

Zhejiang University, Zhejiang Hangzhou, China.

PhD in Electrical Engineering- Computer Vision for Autonomous

Systems.

2025-Present AutoLab, School of Engineering,

WestLake University, Zhejiang Hangzhou, China.

Visiting student under Prof. Kaicheng Yu

#### **Professional References.**

Prof. Yang Jiaqiang

Relationship PhD. Supervisor. Zhejaing University

Email y.j.qiang@zju.edu.cn

Prof. Junyou Yang

Relationship MSc. Thesis Advisor. Shenyang Uni. of Tech.

junyouyang@sut.edu.cn Email

#### **PAPERS AND PUBLICATIONS.**

2024: **Moses Chukwuka Okonkwo**, Junyou Yang, Yizhen Sun, Guang Yang, Fausto Pedro García Márquez. RDSP-SLAM: Robust Object-Aware SLAM based on Deep Shape Priors. IEEE ACCESS, 12th, January, 2024. http://dx.doi.org/10.1109/ACCESS.2024.3368859

#### **HONOURS, CERTIFICATES AND AWARDS**

2017:	Certificate of Proficiency, HSK level IV, Confucius Institute Headquarters, Hanban.
2017:	Chinese Speech Contest for Foreigners in Xiangtan - Second Position.
2018:	Hunan Government Scholarship for International Students, Hunan, China.
2019:	Hunan Government Scholarship for International Students, Hunan, China.
2019:	Xiangtan University Scholarship for International Students, Xiangtan, Hunan, China.
2021:	Chinese Government Scholarship CSC, Shenyang University of Technology.
2024:	Chinese Government Scholarship CSC, Zhejiang University of Technology.

#### WORK EXPERIENCE AND TRAINING

- 2019: Xiangtan University Summer Engineering Boot Camp, Embedded Systems and Programming in C.
- 2023 Internship Perception Research Lab at Northeast University(东北大学):
  - a) Training of **crop row detetion deep learning** models
  - b) Training of deep learing models for farm scene panoptic segmentation
  - c) Deployment of deep learning models using Pytorch and ROS for rubost visual navigation of Agricultural Robots
  - d) Visual Navigation: ORB-SLAM(2/3).

#### **MEMBERSHIP OF COMMITTEES**

i. Member, Xiangtan University, Embedded System Development Lab - C programming. (2018 to 2021)

## **Engineering projects**

(Please click the title to watch demo video)

2023: Robust Keyframe segmentation of visual Object-SLAM Based on Deepshape

priors (ORBSLAM2, DeepSDF, YOLOv8/RTM-Det) [Ms Project]

2021: <u>STM32 based mobile car with PID controlled motors</u>[BSc Project].

2021: <u>Servo motor PID speed control.</u>

2020: Display of IMU and GPS sensor data using STM32 embedded system. [link 1]

[link 2]

2020: Sound Detection Reading Glass for Deaf People, Blinks and vibrates when e.g.

the phone rings. [Team ]

2020: Time based stepper motor control for dressing robot.

2019: 51 McU Line tracking mobile car based on photo-resistors

2019: Oscillator based Clock and Alarm using 8051 McU.

## ENGINEERING FIELD (SKILLS).

i. C/C++ programming Language

ii. ROS

iii. Gazebo

iv. Python( OpenCV, OpenMMLab, Pytorch)

v. Linux(Ubuntu)[high]

vi. Scientific Writing.

vii. Simultaneous Localization and Mapping SLAM

### **ENGINEERING AND RESEARCH INTERESTS.**

- i. Computer vision, Machine Learning & Deep Learning
- ii. Self Driving Vehicle, Mobile Robots, 3D Vision and Spatial Intelligence
- iii. Sensor Fusion
- iv. Semantic SLAM

## **GENERAL INTERESTS.**

- i. Psychology
- ii. Philosophy
- iii. Management
- iv. Entrepreneurship

#### Languages Spoken:

- **a.** English Language Very good and fluent.
- **b.** Igbo Fluent.
- **c.** Mandarin Fluent.

#### **Hobbies:**

- a. Photography and Video Making.
- b. Playing Basketball.
- c. Reading.