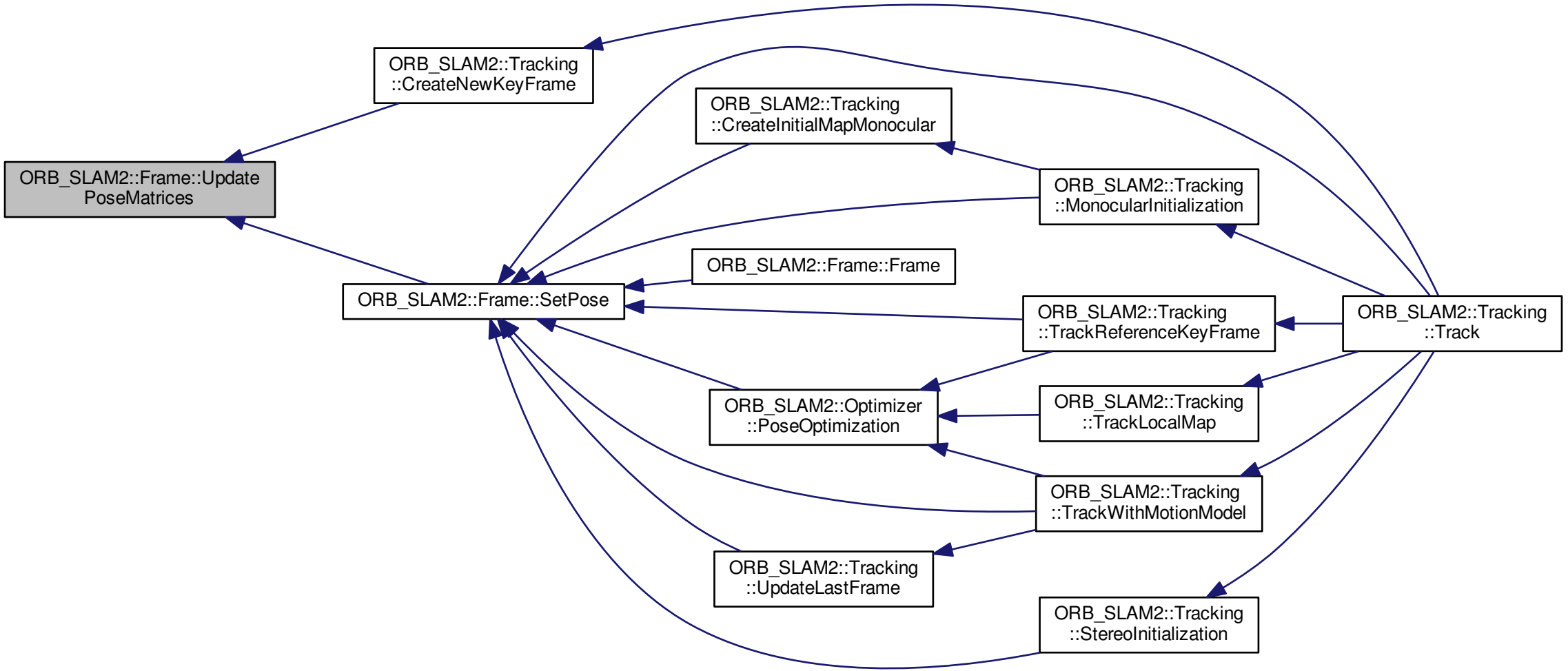
ORB_SLAM2::Frame::Update PoseMatrices
ORB_SLAM2::Tracking ::CreateNewKeyFrame
ORB_SLAM2::Tracking ::CreateInitialMapMonocular
ORB_SLAM2::Tracking ::MonocularInitialization
ORB_SLAM2::Frame::Frame
ORB_SLAM2::Frame::SetPose
ORB_SLAM2::Tracking ::TrackReferenceKeyFrame
ORB_SLAM2::Tracking ::Track
ORB_SLAM2::Optimizer ::PoseOptimization
ORB_SLAM2::Tracking ::TrackLocalMap
ORB_SLAM2::Tracking ::TrackWithMotionModel
ORB_SLAM2::Tracking ::UpdateLastFrame
ORB_SLAM2::Tracking ::StereoInitialization