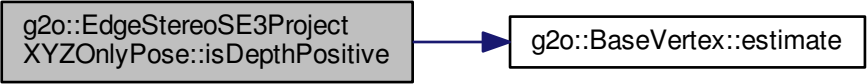


g2o::EdgeStereoSE3Project
XYZOnlyPose::isDepthPositive



```
graph LR; A["g2o::EdgeStereoSE3Project<br/>XYZOnlyPose::isDepthPositive"] --> B["g2o::BaseVertex::estimate"]
```

g2o::BaseVertex::estimate