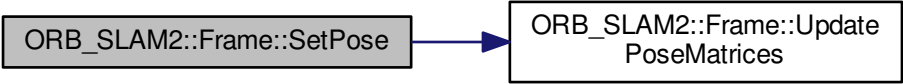


ORB_SLAM2::Frame::SetPose



```
graph LR; A[ORB_SLAM2::Frame::SetPose] --> B[ORB_SLAM2::Frame::UpdatePoseMatrices]
```

The diagram consists of two rectangular boxes connected by a horizontal arrow. The left box is shaded gray and contains the text 'ORB_SLAM2::Frame::SetPose'. The right box is white with a black border and contains the text 'ORB_SLAM2::Frame::UpdatePoseMatrices'. A blue arrow points from the right side of the left box to the left side of the right box.

ORB_SLAM2::Frame::Update
PoseMatrices