

3/1/2026

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NOFDS & ML session 3 Mansoura AI 46

C Feature Scaling

0 → 1

"measures of spread"

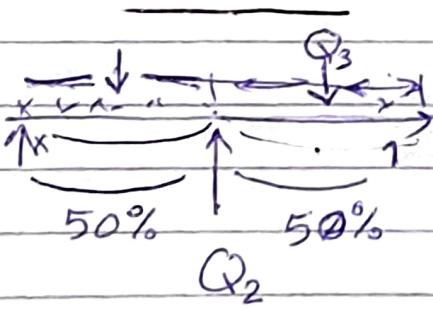
	x_1	x_2
1	100	
2	120	
3	150	

→ Range : $x_{\max} - x_{\min}$

→ Standard deviation $\sigma_x = \sqrt{S_x^2} = \sqrt{\frac{1}{n} \sum_{i=1}^n (x_i - \bar{x})^2}$

→ Interquartile range $IQR = Q_3 - Q_1$

Quartiles :



Q_0 : minimum value

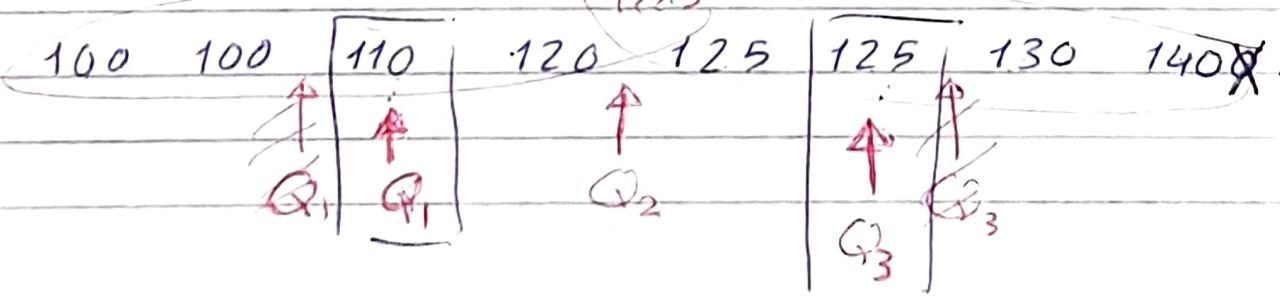
Q_1 : 25% : 75%

Q_2 : median

Q_3 : 75% : 25%

Q_4 : maximum value

$$Q_3 - Q_1 = IQR \rightarrow \underline{\text{Robust}}$$



feature scaling

$$\underline{x_i} \rightarrow \overline{x_i}$$

new scale (normalized)

$$\sim 0 \rightarrow 1$$

$$\sim -1 \rightarrow 1$$

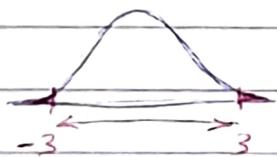
1) Range: min-max normalization

$$0 \leq \overline{x_i} = \frac{x_i - x_{\min}}{x_{\max} - x_{\min}} \leq 1$$

4, 2, 3, 3, 4, 5, ..., 5, 50

2) mean-normalization (standardization)

$$\overline{x_i} = \frac{x_i - \bar{x}}{\tilde{s}_x}$$

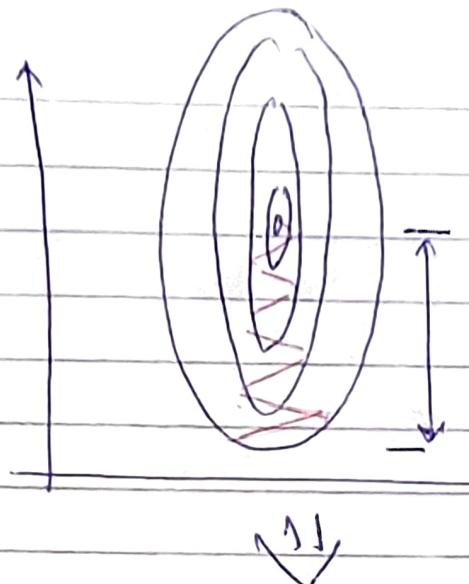


zero-mean, standard dev. = 1

3) Robust feature scaling (Robust scaling)

$$\overline{x_i} = \frac{x_i - \text{median}}{\text{IQR}} = \frac{x_i - Q_2}{Q_3 - Q_1}$$

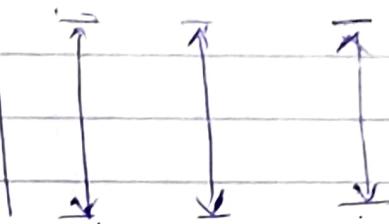
\longleftrightarrow



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$x_1 \quad x_2 \quad x_3$



max. f.
variance

$\sigma_{x_1}^2 \uparrow$

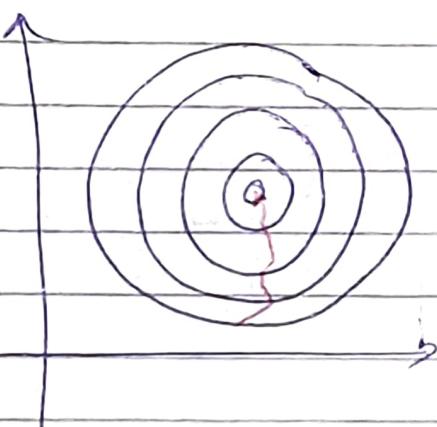
$$\kappa \approx \frac{\sigma_{x_3}^2}{\sigma_{x_1}^2}$$

Kappa

min. feature variance

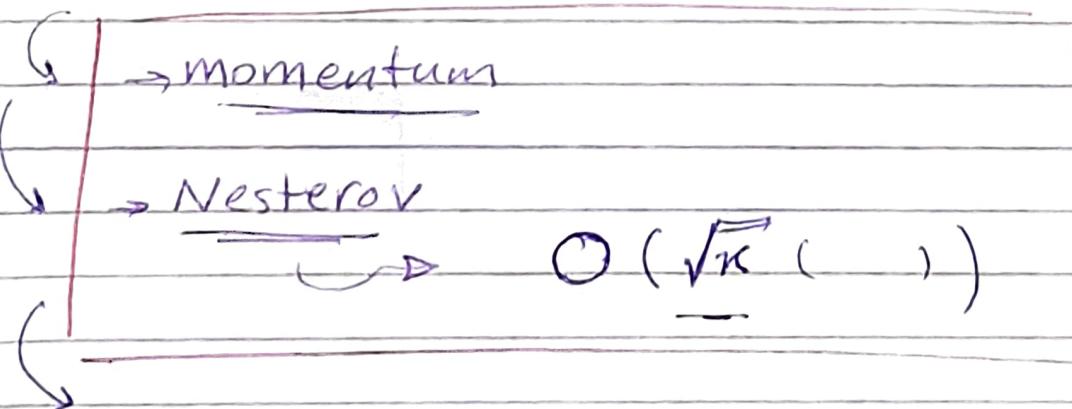
κ : condition number

of optimization



Computations of Convergence $\sim O(\kappa(1))$

Gradient descent Algorithms



Adaptive GD \rightarrow session 4

Review and further discussion

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(4)

$$\rightsquigarrow \boxed{\text{Gradient}}(\vec{J}) = \nabla J = \begin{bmatrix} \frac{\partial J}{\partial \theta_1} \\ \frac{\partial J}{\partial \theta_2} \\ \vdots \\ \frac{\partial J}{\partial \theta_n} \end{bmatrix}$$

scalar-valued
function

vector field

(4)
vector (after substituting for values of θ_i)

$$\rightsquigarrow \boxed{\text{Jacobian}} \text{ of a vector valued function}$$

$$f = \begin{bmatrix} f_1 \\ f_2 \\ \vdots \\ f_m \end{bmatrix} \quad \text{scalar valued functions}$$

$$J(\vec{f}) = \begin{bmatrix} \frac{\partial f_1}{\partial \theta_1} & \frac{\partial f_1}{\partial \theta_2} & \cdots & \frac{\partial f_1}{\partial \theta_n} \\ \vdots & & & \\ \frac{\partial f_m}{\partial \theta_1} & \frac{\partial f_m}{\partial \theta_2} & \cdots & \frac{\partial f_m}{\partial \theta_n} \end{bmatrix}$$

$$J(\vec{f}) = \begin{bmatrix} \nabla^T(f_1) \\ \nabla^T(f_2) \\ \vdots \\ \nabla^T(f_m) \end{bmatrix}$$

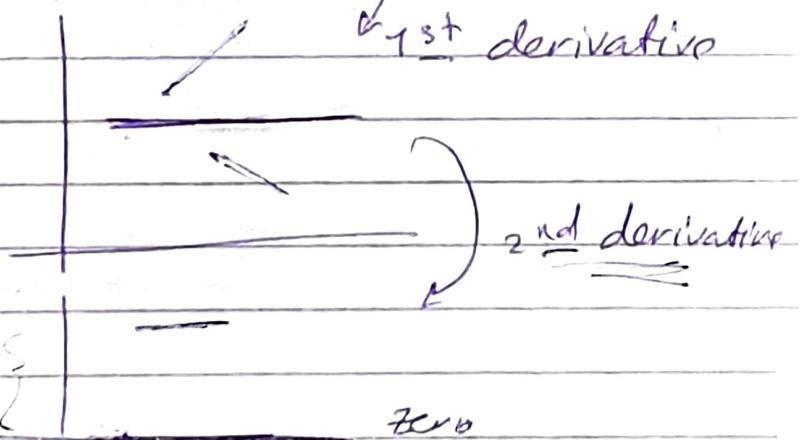
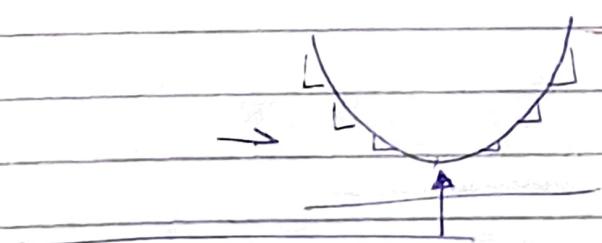
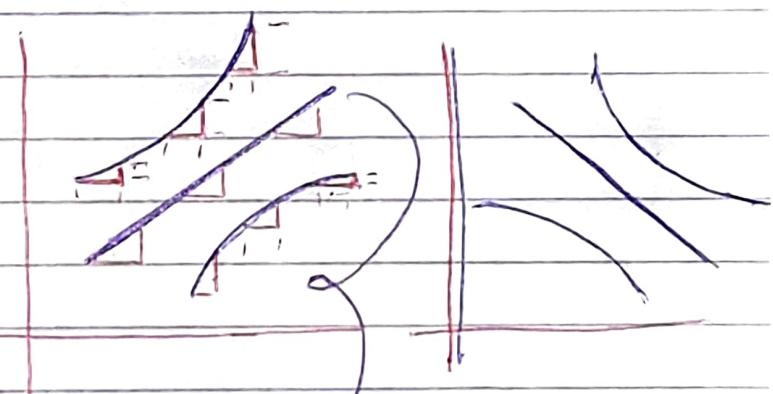
Hessian (J)

$\bar{\square}$ scalar-valued function

$$H(J) = \nabla^2(J) = \nabla \nabla(J)$$

$$H(J) = \begin{bmatrix} \frac{\partial^2 J}{\partial \theta_1^2} & \frac{\partial^2 J}{\partial \theta_1 \partial \theta_2} & \cdots & \frac{\partial^2 J}{\partial \theta_1 \partial \theta_n} \\ \vdots & \vdots & \ddots & \vdots \\ \frac{\partial^2 J}{\partial \theta_n \partial \theta_1} & \frac{\partial^2 J}{\partial \theta_n \partial \theta_2} & \cdots & \frac{\partial^2 J}{\partial \theta_n^2} \end{bmatrix}$$

→	Convex
→	Concave
	flat?
	inflection?



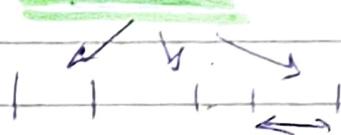
$$\kappa = \frac{\lambda_{\max}(H)}{\lambda_{\min}(H)}$$

$$O(\underline{\kappa}(\underline{\underline{\lambda}}))$$

GD Variants

Review

Vanilla GD / Batch GD



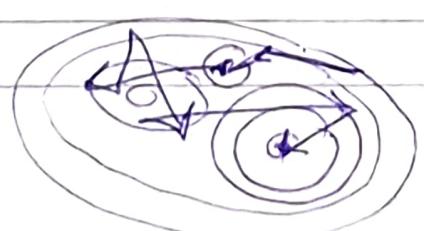
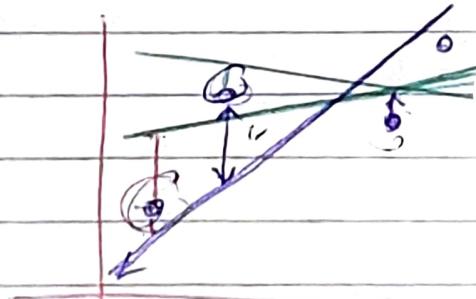
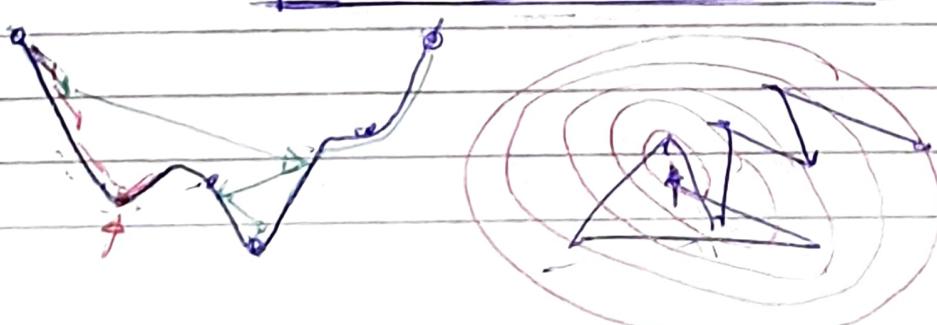
repeat }
until }
conver- }
gence } $\theta^{\text{new}} = \theta^{\text{old}}$
 $\theta^{(k+1)} = \theta^{(k)} - \alpha \nabla J(\theta)$

for MSE : $\nabla \left(\frac{1}{2m} \sum_{i=1}^m (y_i - \hat{y}_i)^2 \right)$

e.g., in Linear Regression $\nabla \left(\frac{1}{2m} \sum_{i=1}^m (y_i - (\theta_0 + \theta_1 x_i))^2 \right)$

Stochastic GD "SGD"

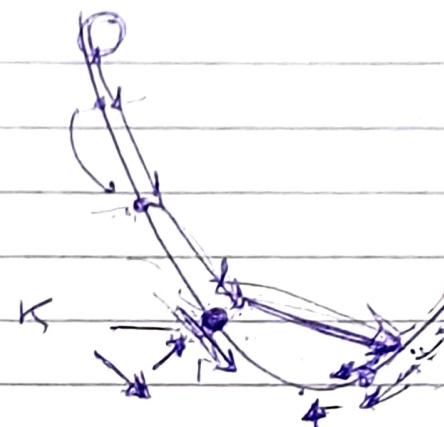
mini-batch GD



BGD
 ~~$\frac{\partial}{\partial}$~~

Momentum

→ "heavy-ball"



$$\underline{\theta}^{(K+1)} = \underline{\theta}^{(\text{new})} = \underline{\theta}^{(K)} - \alpha \nabla J(\underline{\theta}^{(K)})$$

$$\underline{\theta}^{(K+1)} = \underline{\theta}^{(K)} + \boxed{\begin{array}{l} \text{Current} \\ \text{Velocity} - \text{gradient} \end{array}}$$

$$\underline{v}^{(K+1)} = \underline{\mu v}^{(K)} - \alpha \nabla J(\underline{\theta}^{(K)})$$

OR β

$(\mu=1)$
 $(T=\mu)$
 $(1-\beta)$

$$K=0 \quad \underline{v}^{(0)} = 0$$

$$K=1 \quad \underline{v}^{(1)} = \underline{\mu} \times 0 - \alpha \text{ gradient } (\underline{\theta}^{(0)})$$

$$K=2 \quad \underline{v}^{(2)} = \underline{\mu} (\underline{v}^{(1)}) - \alpha \text{ gradient } (\underline{\theta}^{(1)})$$

$$= \underline{\mu} (-\alpha \text{ grad } (\underline{\theta}^{(0)})) - \alpha \text{ grad } (\underline{\theta}^{(1)})$$

$$K=3 \quad \underline{v}^{(3)} = \underline{\mu} (\underline{v}^{(2)}) - \alpha \text{ grad } (\underline{\theta}^{(2)})$$

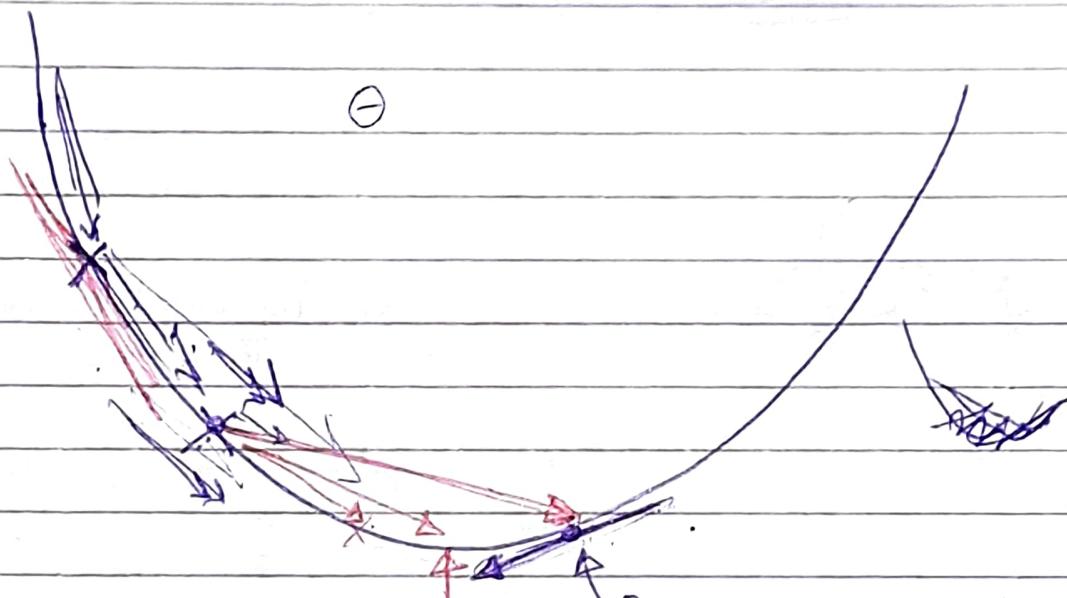
$$= \underline{\mu} (\underline{\mu} (-\alpha \text{ grad } (\underline{\theta}^{(0)})) - \alpha \text{ grad } (\underline{\theta}^{(1)}))$$

$$- \alpha \text{ grad } \underline{\theta}^{(2)}$$

↑
EWA
EWMA

Nesterov method

\Rightarrow look ahead !



? look ahead
gradient at θ |
look ahead.

β optimally $\underline{\approx} 0.9$

$$\underline{0.8} < \beta < 0.999$$

Nesterov

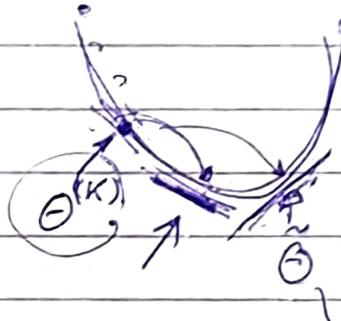
→ look-ahead parameter

→ temp. value of θ ; $\tilde{\theta}^{(k)}$

$$\tilde{\theta}^{(k)} = \theta^{(k)} + \mu v^{(k)}$$

extrapolated Value of θ

~~gradient~~



$$v^{(k+1)} = v^{(k)} \propto \nabla J(\tilde{\theta}^{(k)})$$

θ_{top}

$$\theta^{(k+1)} = \theta^{(k)} + v^{(k+1)}$$