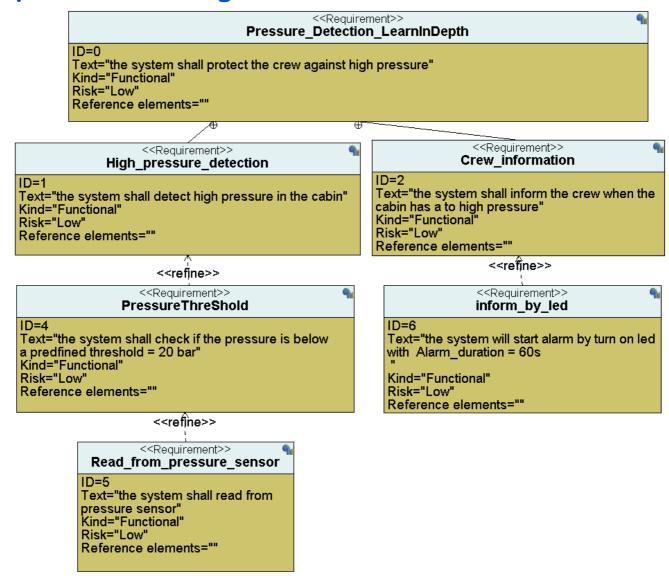
Pressure Controller

spacification (from the client)

A pressure controller informs the crew of a cabin with an alarm when the pressure exceeds 20 bars in the cabin.

. The alarm duration equals 60 seconds

1-Requirements Diagram



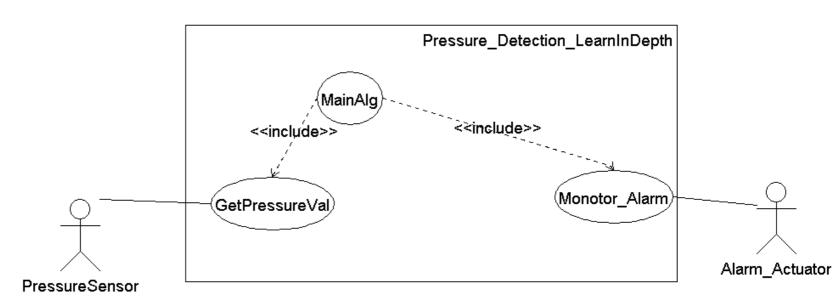
2-System Analysis

1. Use Case Diagram

this diagram describes main functionality in system, and how the system interacts with outside system which boundary of system..

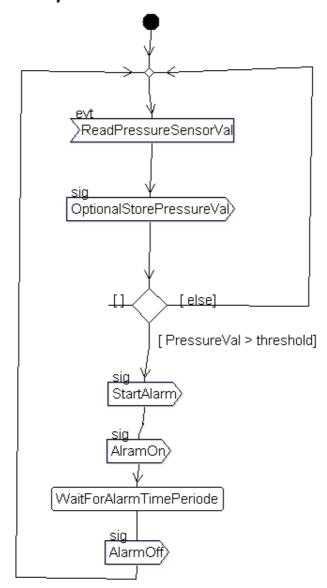
> Pressure Sensor to get pressure value,

> Alarm monitor to occur the action of high pressure on it.



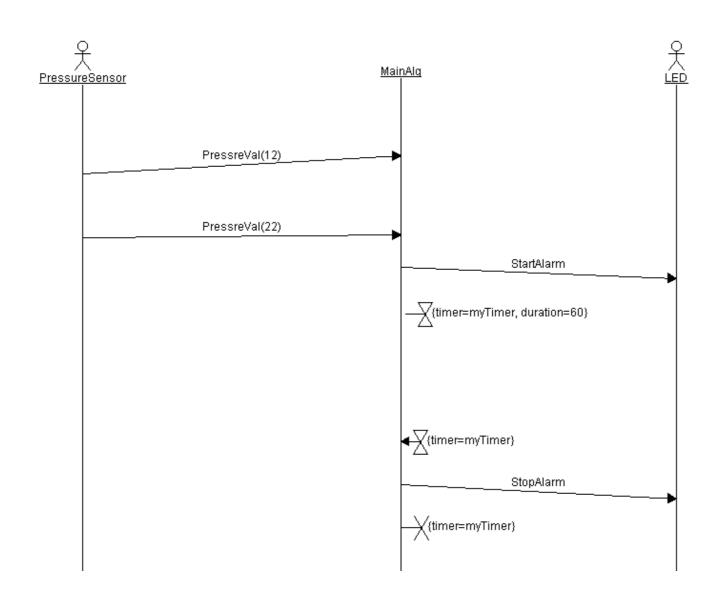
2. Activity Diagram

Activity diagrams describe the workflow behavior of a system



2. Sequence Diagram

- > case 1:Pressure sensor get '12bar'
 it be sent to main Algorithm this value is less than '20 bar'
 not action
- > case 2: Pressure sensor get '22bar' it be sent to main Algorithm this value is bigger than '20 bar', then led on ,waiting 2s and led of and so on while the value stile bigger than '20bar'.

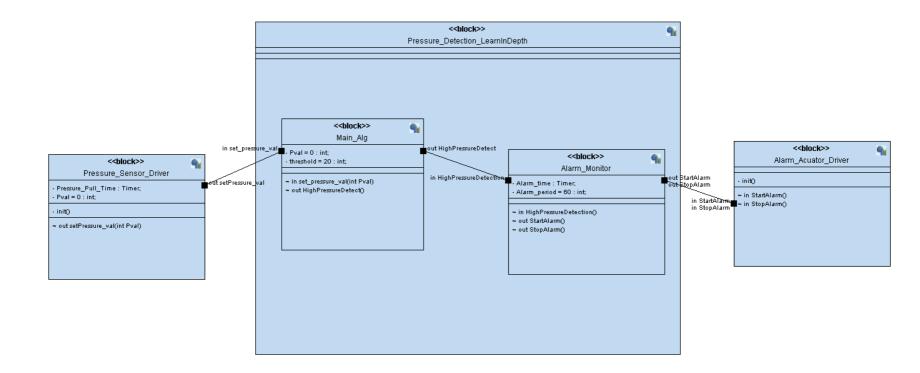


4- Block Diagram

this diagram describes the module in system which

- > Pressure Sensor Driver
- ➤ Main Algorithm

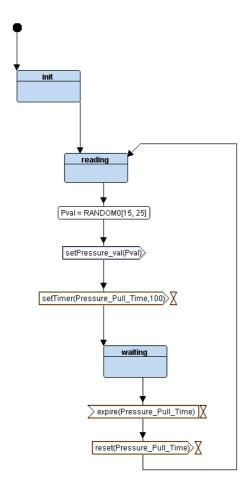
- > Alarm Monitor
- > Alarm Actuator Driver



5-State Machine

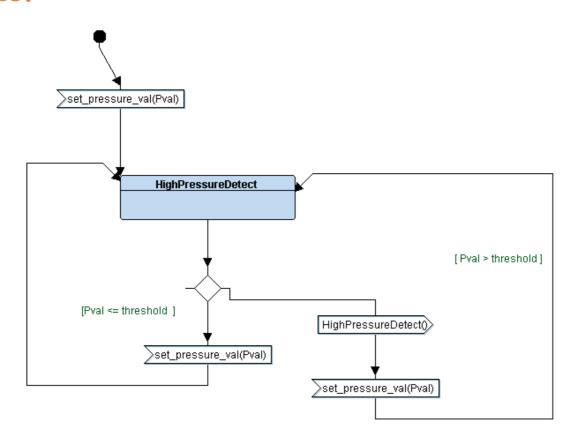
1. Pressure Sensor Driver

start initialization and get values of Pressure with period 100s and sent it to main Algorithm to process it

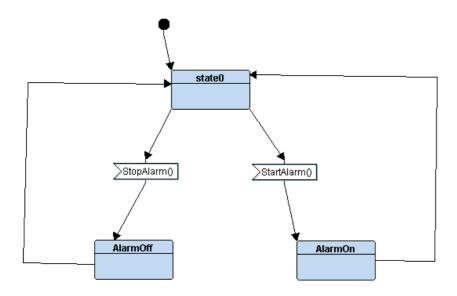


2. Main Algorithm

it receives the pressure value from pressure sensor and test it if it less than 20bar it sent to high pressure Detected function and if the value bigger than 20 bar it repeats revise values.

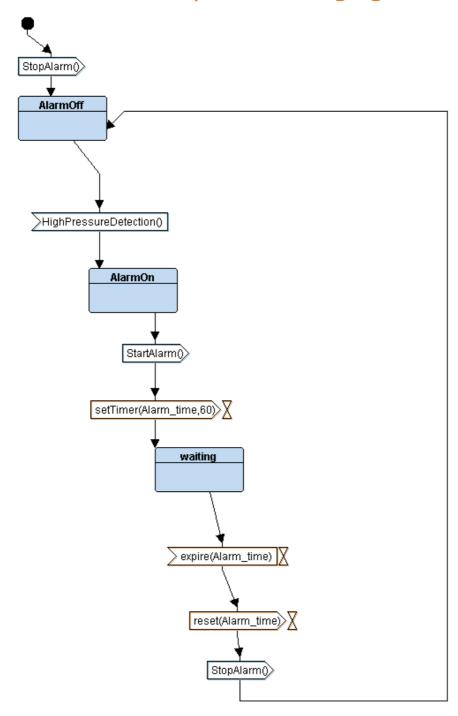


3. State Machine Alarm Actuator Driver



4. State Machine of Alarm Monitor

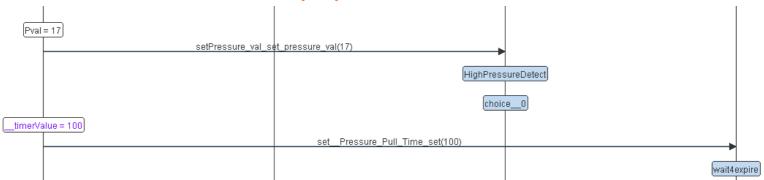
it starts the LED is off if it detects high pressure value from main Algorithm it makes LED is on and waiting 60s and make LED off and repat checking again.



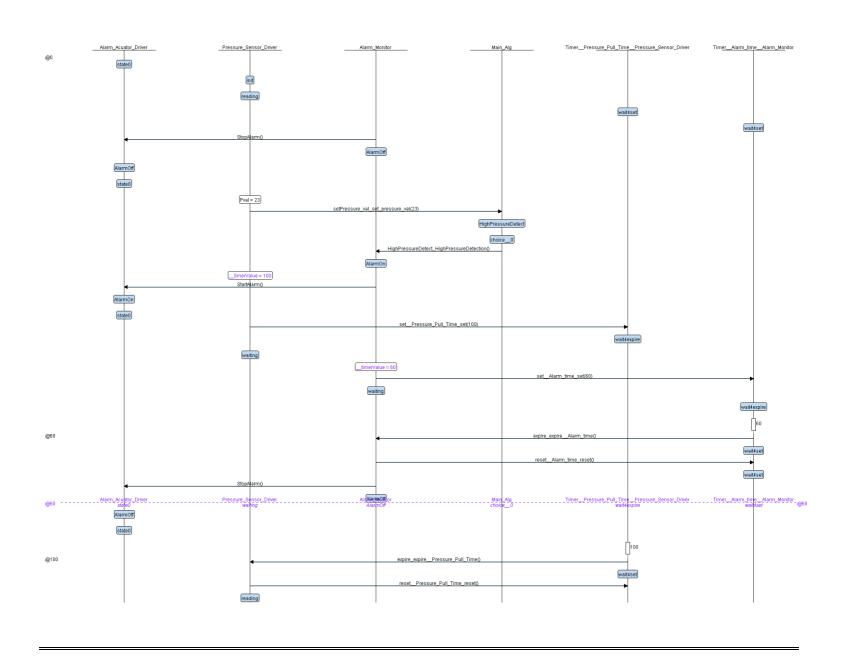
Simulation to show sequence of system



case 1: the value is less (17) than 20 bar



case 2: the pressure value bigger(23) than 20 bar



Then I'm developed the project and this is result

1-Code sections

1. Startup Sections.o

```
PS D:\study\GNU-Tools-ARM-Embedded\7 2017-q4-major\bin> .\arm-none-eabi-objdump.exe -h startup.o
                    file format elf32-littlearm
startup.o:
Sections:
                                                               File off
00000034
Idx Name
0 .text
                        Size
00000008
                                     VMA LMA 00000000 00000000
                                                                             Algn
2**1
                                     ALLOC, LOAD, RELOC, 00000000 00000000
                                                                READONLY,
                                                                             CODE 2**0
                        CONTENTS, 00000000
                                                                000003c
  1 .data
                                     ALLOC, LOAD, DATA
00000000 00000000
                        CONTENTS, 00000000
                                                               0000003c
                                                                             2**0
  2 .bss
                        ALLOC
00000050 00000000 00000000 0000003c
  3 .vectors
  CONTENTS, RELOC, READONLY

4 .ARM.attributes 00000021 00000000 00000000 0000008c 2**0

CONTENTS, READONLY
```

2. Sections Of Driver.o

```
PS D:\study\GNU-Tools-ARM-Embedded\7 2017-q4-major\bin> .\arm-none-eabi-objdump.exe -h driver.o
driver.o:
                 file format elf32-littlearm
Sections:
                                   VMA LMA File off 00000000 000000034
                       Size
000000c4
  0 .text
                                   ALLOC, LOAD, READONLY, CODE
00000000 00000000 000000f8
ALLOC, LOAD, DATA
00000000 00000000 000000f8
                       CONTENTS,
                       00000000
  1 .data
                       CONTENTS, 00000000
                                                             000000f8 2**0
  2 .bss
                       ALLOC
                       0000007f
  3 .comment
                                   00000000 00000000 000000f8 2**0
  CONTENTS, READONLY
4 .ARM.attributes 00000033 00000000 00000000 00000177 2**0
```

3. Sections Of Main.o

```
PS D:\study\GNU-Tools-ARM-Embedded\7 2017-q4-major\bin> .\arm-none-eabi-objdump.exe -h main.o
main.o:
               file format elf32-littlearm
Sections:
                                                              File off 00000034
Idx Name
0 .text
                       Size
00000030
                                    00000000 00000000
                                    ALLOC, LOAD, RELOC, 00000000 00000000
                                                              READONLY,
00000064
                                                                           CODE 2**0
                       CONTENTS, 00000000
  1 .data
                       CONTENTS,
00000000
                                    ALLOC, LOAD, DATA
00000000 00000000
                                                              00000064
  2 .bss
                       ALLOC
0000007f
  3 .comment
                                    00000000 00000000 00000064
  CONTENTS, READONLY
4 .ARM.attributes 00000033 00000000 00000000 000000e3 2**0
CONTENTS, READONLY
PS D:\study\GNU-Tools-ARM-Embedded\7 2017-q4-major\bin>
```

4. Sections Of Alarm_control.o

2-Symbols of code

1-Symbols of startup.o

```
PS D:\study\GNU-Tools-ARM-Embedded\7 2017-q4-major\bin> .\arm-none-eabi-nm.exe .\startup.o
00000000 t _reset
U main
00000006 t Vector_handler
```

2-Symbols of driver.o

```
PS D:\study\GNU-Tools-ARM-Embedded\7 2017-q4-major\bin> .\arm-none-eabi-nm.exe .\driver.o
00000000 T Delay
00000020 T getPressureVal
00000074 T GPIO_INITIALIZATION
00000038 T Set_Alarm_actuator
```

3-Symbols of Alarm control

```
PS D:\study\GNU-Tools-ARM-Embedded\7 2017-q4-major\bin> .\arm-none-eabi-nm.exe .\Alarm_control.o
U Delay
00000000 T High_Pressure_Detected
```

4-Symblos of main.o

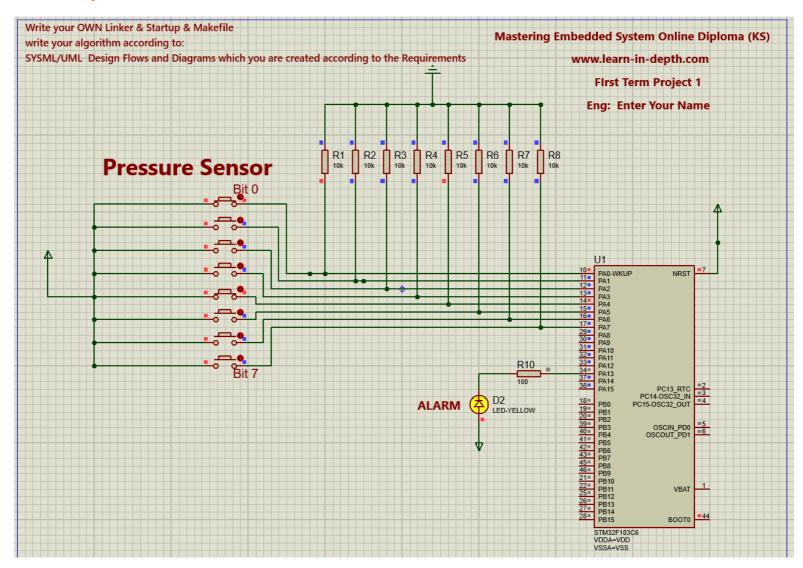
```
PS D:\study\GNU-Tools-ARM-Embedded\7 2017-q4-major\bin> .\arm-none-eabi-nm.exe main.o
U Delay
U getPressureVal
U GPIO_INITIALIZATION
U High_Pressure_Detected
00000000 T main
```

5-Symbols of Pressure Controller.elf

```
PS D:\study\GNU-Tools-ARM-Embedded\7 2017-q4-major\bin> .\arm-none-eabi-nm.exe .\Pressure-Controller-cortex-m3.elf
08000168 t _reset
08000074 T Delay
08000094 T getPressureVal
08000088 T GPIO_INITIALIZATION
08000050 T High_Pressure_Detected
08000138 T main
080000ac T Set_Alarm_actuator
0800016e t Vector_handler
```

Simulation on proteus

Case1: when pressure value is 17 bar (less than 20bar)



Case2: when pressure value is 23 bar (bigger than 20bar)

