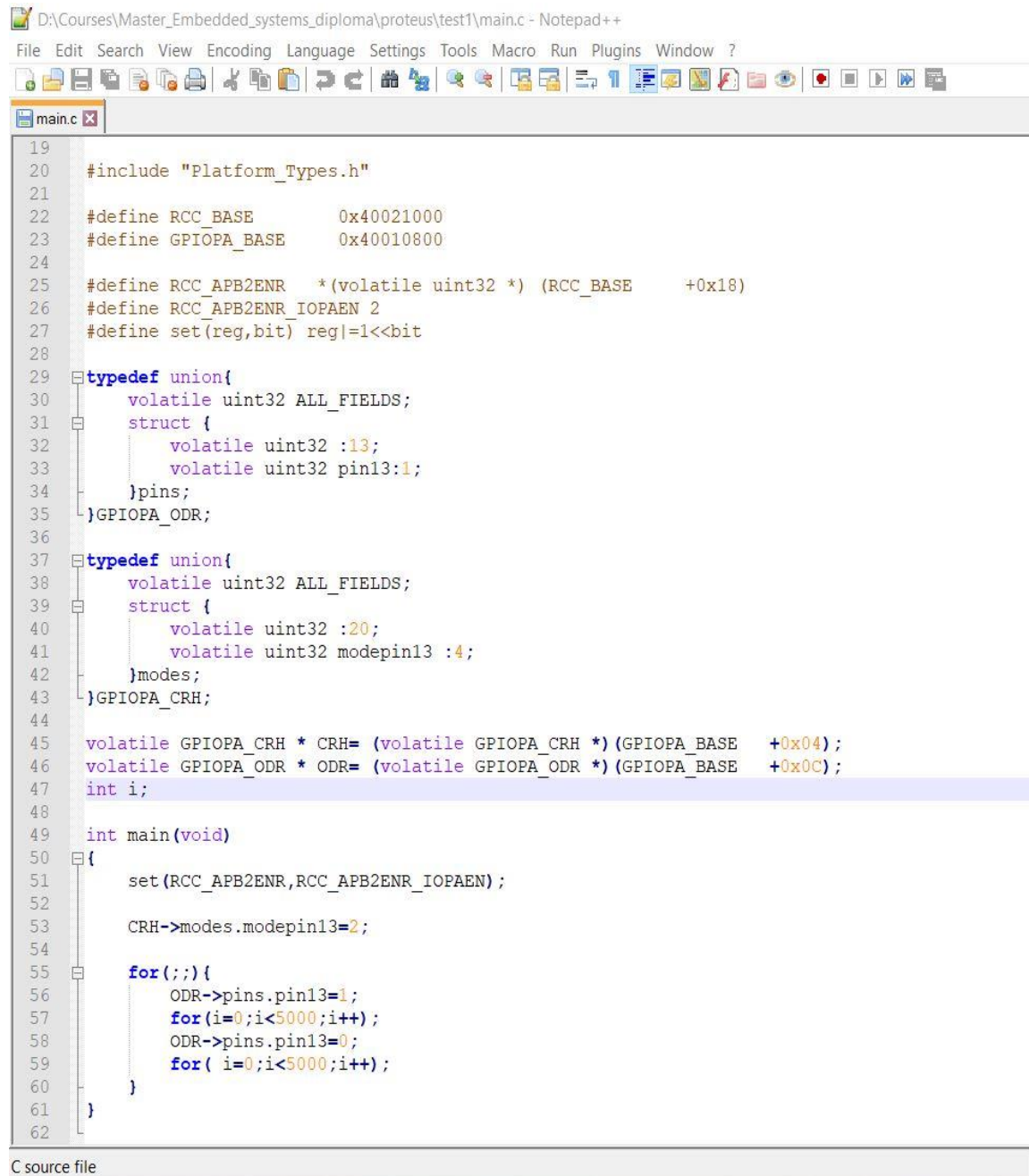


LAB3:

- First writing the (main.c and startup.c) code files:-

-main.c



```
D:\Courses\Master_Embedded_systems_diploma\proteus\test1\main.c - Notepad++
File Edit Search View Encoding Language Settings Tools Macro Run Plugins Window ?
main.c
19
20 #include "Platform_Types.h"
21
22 #define RCC_BASE      0x40021000
23 #define GPIOA_BASE    0x40010800
24
25 #define RCC_APB2ENR    *(volatile uint32 *) (RCC_BASE +0x18)
26 #define RCC_APB2ENR_IOPAEN 2
27 #define set(reg,bit) reg|=1<<bit
28
29 typedef union{
30     volatile uint32 ALL_FIELDS;
31     struct {
32         volatile uint32 :13;
33         volatile uint32 pin13:1;
34     }pins;
35 }GPIOA_ODR;
36
37 typedef union{
38     volatile uint32 ALL_FIELDS;
39     struct {
40         volatile uint32 :20;
41         volatile uint32 modepin13 :4;
42     }modes;
43 }GPIOA_CRH;
44
45 volatile GPIOA_CRH * CRH= (volatile GPIOA_CRH *) (GPIOA_BASE +0x04);
46 volatile GPIOA_ODR * ODR= (volatile GPIOA_ODR *) (GPIOA_BASE +0x0C);
47 int i;
48
49 int main(void)
50 {
51     set(RCC_APB2ENR,RCC_APB2ENR_IOPAEN);
52
53     CRH->modes.modepin13=2;
54
55     for(;;){
56         ODR->pins.pin13=1;
57         for(i=0;i<5000;i++);
58         ODR->pins.pin13=0;
59         for( i=0;i<5000;i++);
60     }
61 }
62
C source file
```

-startup.c:

*D:\Courses\Master_Embedded_systems_diploma\proteus\test1\startup.c - Notepad++

File Edit Search View Encoding Language Settings Tools Macro Run Plugins Window ?

startup.c

```
2  #include "Platform_Types.h"
3  extern int main(void);
4  void Reset_Handler();
5  void Default_Handler(){
6      Reset_Handler();
7  }
8  void NMI_Handler() __attribute__((weak,alias("Default_Handler")));
9  void H_fault_Handler() __attribute__((weak,alias("Default_Handler")));
10 void MM_fault_Handler() __attribute__((weak,alias("Default_Handler")));
11 void Bus_fault_Handler() __attribute__((weak,alias("Default_Handler")));
12 void Usage_fault_Handler() __attribute__((weak,alias("Default_Handler")));
13 extern uint32 _stack_top;
14 extern uint32 _E_text;
15 extern uint32 _S_data;
16 extern uint32 _E_data;
17 extern uint32 _S_bss;
18 extern uint32 _E_bss;
19 uint32 vectors[] __attribute__((section(".vectors"))) ={
20     (uint32)&_stack_top,
21     (uint32)&Reset_Handler,
22     (uint32)&NMI_Handler,
23     (uint32)&H_fault_Handler,
24     (uint32)&MM_fault_Handler,
25     (uint32)&Bus_fault_Handler,
26     (uint32)&Usage_fault_Handler
27 };
28 void Reset_Handler(){
29     /*copy data section*/
30     uint32 i;
31     uint32 DATA_size= (uint8*)&_E_data-(uint8*)&_S_data;
32     uint8 *P_src =(uint8*)&_E_text;
33     uint8 *P_dst =(uint8*)&_S_data;
34     for(i=0;i<DATA_size;i++){
35         *((uint8*)P_dst++)=*((uint8*)P_src++);
36     }
37     /*init bss section*/
38     uint32 BSS_size=(uint8*)&_E_bss-(uint8*)&_S_bss;
39     P_dst=(uint8*)&_S_bss;
40     for(i=0;i<BSS_size;i++){
41         *((uint8*)P_dst++)=(uint8)0;
42     }
43     /*call main()*/
44     main();
45 }
```

C source file

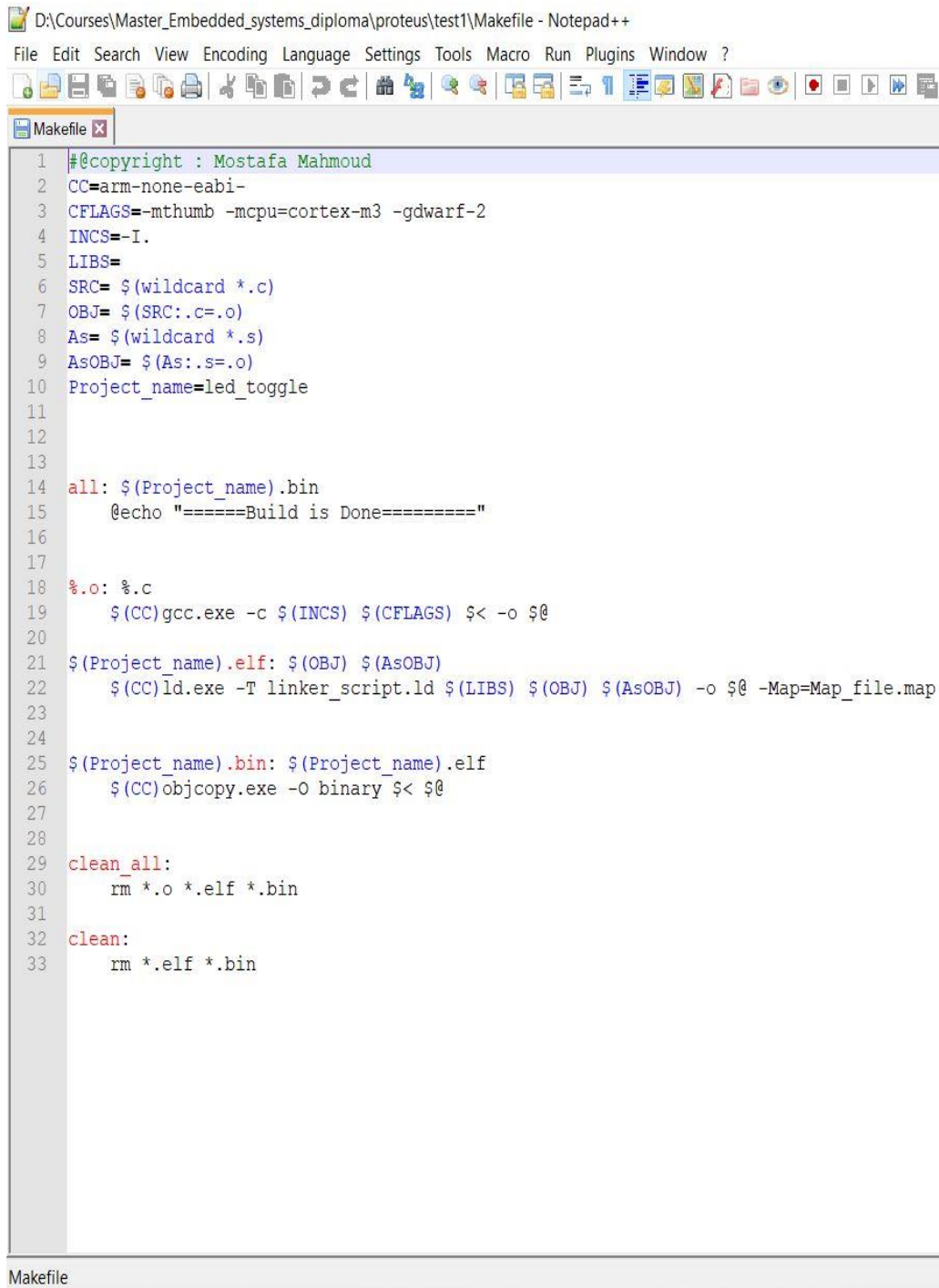
- Then writing linker script:

linker_script.ld:

```
D:\Courses\Master_Embedded_systems_diploma\proteus\test1\linker_script.ld - Notepad++
File Edit Search View Encoding Language Settings Tools Macro Run Plugins Window ?
linker_script.ld
1  /*linker script CortexM3
2  Mostafa Mahmoud */
3
4  MEMORY
5  {
6  flash (rx) : ORIGIN = 0x08000000, LENGTH = 128k
7  sram (rwx) : ORIGIN = 0x20000000, LENGTH = 20k
8  }
9
10 SECTIONS{
11
12     .text :
13     {
14         *(.vectors*)
15         *(.text*)
16         *(.rodata*)
17         _E_text = . ;
18     }>flash
19
20     .data :
21     {
22         _S_data = . ;
23         *(.data)
24         . = ALIGN(4) ;
25         _E_data = . ;
26     }> sram AT> flash
27
28     .bss :
29     {
30         _S_bss = . ;
31         *(.bss)
32         . = ALIGN(4);
33         _E_bss = . ;
34         . = ALIGN(4) ;
35         . = . +0x1000 ;
36         _stack_top = . ;
37     }>sram
38
39 }
```

Normal text file

- Now Adjusting Make file to build the project:
Makefile:



```
1 #@copyright : Mostafa Mahmoud
2 CC=arm-none-eabi-
3 CFLAGS=-mthumb -mcpu=cortex-m3 -gdwarf-2
4 INCS=-I.
5 LIBS=
6 SRC= $(wildcard *.c)
7 OBJ= $(SRC:.c=.o)
8 As= $(wildcard *.s)
9 AsOBJ= $(As:.s=.o)
10 Project_name=led_toggle
11
12
13
14 all: $(Project_name).bin
15     @echo "====Build is Done===="
16
17
18 %.o: %.c
19     $(CC)gcc.exe -c $(INCS) $(CFLAGS) $< -o $@
20
21 $(Project_name).elf: $(OBJ) $(AsOBJ)
22     $(CC)ld.exe -T linker_script.ld $(LIBS) $(OBJ) $(AsOBJ) -o $@ -Map=Map_file.map
23
24
25 $(Project_name).bin: $(Project_name).elf
26     $(CC)objcopy.exe -O binary $< $@
27
28
29 clean_all:
30     rm *.o *.elf *.bin
31
32 clean:
33     rm *.elf *.bin
```

- Building the project:

```

MINGW32:/d/Courses/Master_Embedded_systems_diploma/proteus/test1
mosta@Mostafa-PC MINGW32 /d/Courses/Master_Embedded_systems_diploma/proteus/test1
$ make
arm-none-eabi-gcc.exe -c -I. -mthumb -mcpu=cortex-m3 -gdwarf-2 main.c -o main.o
arm-none-eabi-gcc.exe -c -I. -mthumb -mcpu=cortex-m3 -gdwarf-2 startup.c -o startup.o
arm-none-eabi-ld.exe -T linker_script.ld main.o startup.o -o led_toggle.elf -Map=Map_file.map
arm-none-eabi-objcopy.exe -O binary led_toggle.elf led_toggle.bin
=====Build is Done=====
mosta@Mostafa-PC MINGW32 /d/Courses/Master_Embedded_systems_diploma/proteus/test1
$ |

```

- Viewing symbols in main.o, startup.o and led_toggle.elf:

```

MINGW32:/d/Courses/Master_Embedded_systems_diploma/proteus/test1
mosta@Mostafa-PC MINGW32 /d/Courses/Master_Embedded_systems_diploma/proteus/test1
$ arm-none-eabi-nm.exe main.o
00000000 D CRH
00000004 C i
00000000 T main
00000004 D ODR

mosta@Mostafa-PC MINGW32 /d/Courses/Master_Embedded_systems_diploma/proteus/test1
$ arm-none-eabi-nm.exe startup.o
U _E_bss
U _E_data
U _E_text
U _S_bss
U _S_data
U _stack_top
00000000 W Bus_fault_Handler
00000000 T Default_Handler
00000000 W H_fault_Handler
U main
00000000 W MM_fault_Handler
00000000 W NMI_Handler
0000000c T Reset_Handler
00000000 W Usage_fault_Handler
00000000 D vectors

mosta@Mostafa-PC MINGW32 /d/Courses/Master_Embedded_systems_diploma/proteus/test1
$ arm-none-eabi-nm.exe led_toggle.elf
20000008 B _E_bss
20000008 D _E_data
080001a8 T _E_text
20000008 B _S_bss
20000000 D _S_data
20001008 B _stack_top
080000e8 W Bus_fault_Handler
20000000 D CRH
080000e8 T Default_Handler
080000e8 W H_fault_Handler
20001008 B i
0800001c T main
080000e8 W MM_fault_Handler
080000e8 W NMI_Handler
20000004 D ODR
080000f4 T Reset_Handler
080000e8 W Usage_fault_Handler
08000000 T vectors

```


- Running simulation and debugging on proteus:

The image displays two screenshots of the Proteus simulation environment, showing the initial state and a change in the GPIO pin output.

Top Screenshot:

- CM3 Variables - U1:**

Name	Address	Value
ODR	20000004	0x4001080C
*ODR	4001080C	0x00 0x00 0x00 0x00
ALL_FIELDS	4001080C	0
pins	4001080C	0x00 0x00 0x00 0x00
pin13	4001080C	0
vectors	08000000	5000
vectors[0]	08000000	536875020
vectors[1]	08000004	134217973
vectors[2]	08000008	134217961
vectors[3]	0800000C	134217961
vectors[4]	08000010	134217961
vectors[5]	08000014	134217961
vectors[6]	08000018	134217961
CRH	20000000	0x40010804
*CRH	40010804	0x44 0x44 0x24 0x44
ALL_FIELDS	40010804	1143227460
modes	40010804	0x44 0x44 0x24 0x44
modepin13	40010804	2
- CM3 Source Code - U1:**

```

main.c
-----
* This software component is licensed by ST under BSD 3-
* the "License"; You may not use this file except in com
* License. You may obtain a copy of the license at:
* opensource.org/licenses/bsd-3-c
-----
#include "platform_types.h"
#define RCC_BASE 0x40021000
#define GPIOA_BASE 0x40010800
#define RCC_APB2ENR (*(volatile uint32 *) (RCC_BASE
#define RCC_APB2ENR_IOPAEN 2
#define set(reg,bit) reg|=1<<bit
-----
typedef union{
    volatile uint32 ALL_FIELDS;
    struct {
        volatile uint32 :13;
        volatile uint32 pin13:1;
    };
}GPIOA_ODR;
-----
typedef union{
    volatile uint32 ALL_FIELDS;
    struct {
        volatile uint32 :20;
        volatile uint32 modepin13 :4;
    };
}modes;
-----
volatile GPIOA_CRH * CRH= (volatile GPIOA_CRH *) (GPIOA
volatile GPIOA_ODR * ODR= (volatile GPIOA_ODR *) (GPIOA
int i;
-----
int main(void)
{
    set(RCC_APB2ENR,RCC_APB2ENR_IOPAEN);
    CRH->modes.modepin13=2;
    for(;;){
        ODR->pins.pin13=1;
        for(i=0;i<3000;i++);
        ODR->pins.pin13=0;
        for(i=0;i<3000;i++);
    }
}

```

Bottom Screenshot:

- CM3 Variables - U1:**

Name	Address	Value
ODR	20000004	0x4001080C
*ODR	4001080C	0x00 0x20 0x00 0x00
ALL_FIELDS	4001080C	8192
pins	4001080C	0x00 0x20 0x00 0x00
pin13	4001080C	1
vectors	08000000	5000
vectors[0]	08000000	536875020
vectors[1]	08000004	134217973
vectors[2]	08000008	134217961
vectors[3]	0800000C	134217961
vectors[4]	08000010	134217961
vectors[5]	08000014	134217961
vectors[6]	08000018	134217961
CRH	20000000	0x40010804
*CRH	40010804	0x44 0x44 0x24 0x44
ALL_FIELDS	40010804	1143227460
modes	40010804	0x44 0x44 0x24 0x44
modepin13	40010804	2
- CM3 Source Code - U1:**

```

main.c
-----
* This software component is licensed by ST under BSD 3-
* the "License"; You may not use this file except in com
* License. You may obtain a copy of the License at:
* opensource.org/licenses/bsd-3-c
-----
#include "platform_types.h"
#define RCC_BASE 0x40021000
#define GPIOA_BASE 0x40010800
#define RCC_APB2ENR (*(volatile uint32 *) (RCC_BASE
#define RCC_APB2ENR_IOPAEN 2
#define set(reg,bit) reg|=1<<bit
-----
typedef union{
    volatile uint32 ALL_FIELDS;
    struct {
        volatile uint32 :13;
        volatile uint32 pin13:1;
    };
}GPIOA_ODR;
-----
typedef union{
    volatile uint32 ALL_FIELDS;
    struct {
        volatile uint32 :20;
        volatile uint32 modepin13 :4;
    };
}modes;
-----
volatile GPIOA_CRH * CRH= (volatile GPIOA_CRH *) (GPIOA
volatile GPIOA_ODR * ODR= (volatile GPIOA_ODR *) (GPIOA
int i;
-----
int main(void)
{
    set(RCC_APB2ENR,RCC_APB2ENR_IOPAEN);
    CRH->modes.modepin13=2;
    for(;;){
        ODR->pins.pin13=1;
        for(i=0;i<3000;i++);
        ODR->pins.pin13=0;
        for(i=0;i<3000;i++);
    }
}

```