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# **cepton\_sdk Documentation**

**Cepton Technologies**

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## **OVERVIEW**

If a method is undocumented, consult the *C/C++ SDK* documentation, since many methods in this library are just wrapper functions.

### **1.1 Timestamps**

Unless otherwise marked, all timestamps are seconds since the Unix epoch (UTC). Note that this differs from the *C/C++* interface which uses microseconds.



## ERRORS

```
class cepton_sdk.C_ErrorCode
    An enumeration.

class cepton_sdk.C_Error (code=<C_ErrorCode.CEPTON_SUCCESS: 0>, msg=None,
                        data=None)
    Error thrown by most sdk functions.

    code
        ception_sdk.C_ErrorCode

class cepton_sdk.C_Warning
```





## 3.1 Types

```
class cepton_sdk.ControlFlag
    An enumeration.

    DISABLE_DISTANCE_CLIP = 8
    DISABLE_IMAGE_CLIP = 4
    DISABLE_NETWORK = 2
    ENABLE_MULTIPLE_RETURNS = 16
    ENABLE_STRAY_FILTER = 32
    HOST_TIMESTAMPS = 64
```

## 3.2 Methods

```
ception_sdk.initialize(capture_path=None, capture_seek=0, control_flags=0, error_callback=None,
                      port=None, **kwargs)
    Initializes SDK. Optionally starts capture replay.

    Parameters control_flags – ception_sdk.ControlFlag

ception_sdk.deinitialize()
```



**GENERAL**

API for code that is agnostic to live/replay mode.

`cepton_sdk.get_time()`

Returns capture replay time or live time.

`cepton_sdk.get_timestamp()`

Returns unix timestamp

`cepton_sdk.is_end()`

Returns true if next call to *wait* will throw *CEPTON\_ERROR\_EOF*

`cepton_sdk.is_live()`

Returns true if capture replay is not open.

`cepton_sdk.is_realtime()`

Returns true if live or capture replay is running.

`cepton_sdk.wait(duration=-1)`

Resumes capture replay or sleeps for duration.

If *duration* is 0, then waits forever.



## SENSORS

## 5.1 Types

```
class cepton_sdk.SensorModel
    An enumeration.

    FUSION_790 = 8
    HR80M = 2
    HR80T = 1
    HR80T_R2 = 6
    HR80W = 3
    SORA_200 = 4
    VISTA_860 = 5
    VISTA_860_GEN2 = 7

class cepton_sdk.SensorInformation

    handle
    serial_number
    model_name
    model
    Type ception_sdk.SensorModel
    firmware_version
    last_reported_temperature
    last_reported_humidity
    last_reported_age
    last_reported_hv
    last_reported_optic_temperature
    gps_ts_year
    gps_ts_month
    gps_ts_day
```

```

gps_ts_hour
gps_ts_min
gps_ts_sec
return_count
is_mocked
is_pps_connected
is_nmea_connected
is_calibrated
is_over_heated

```

```
class cepton_sdk.Sensor(sensor_info)
```

```

information
    Type ception_sdk.SensorInformation
classmethod create(serial_number)
classmethod create_by_handle(sensor_handle)
classmethod create_by_index(sensor_index)
handle
serial_number
update()
    Update sensor information.
    Should be called often, to pull latest sensor information.

```

## 5.2 Methods

```
ception_sdk.has_sensor(sensor_serial_number)
```

`ception_sdk.get_sensors` (*cls=<class 'ception\_sdk.api.Sensor'>*)  
 Returns attached sensors.

**Returns** Dictionary of sensors, indexed by serial number.

## 6.1 Types

**class** `cepton_sdk.Points` (*n=0*)  
3D points array.

**timestamps\_usec**

**timestamps**

**image\_positions**

**distances**

**positions**

**intensities**

**return\_strongest**

**return\_farthest**

**valid**

**saturated**

`cepton_sdk.combine_points` (*points\_list*)  
Combine list of points (*ImagePoints*, *Points*, etc).

List must be nonempty. :returns: combined\_points

All point array classes support numpy indexing and assignment as if they were 1-d arrays:

```
1 n_points = len(points_1)
2 points_2[10:20] = points_1[:10]
```

Multiple point arrays can also be combined:

```
1 points = cepton_sdk.combine_points([points_1, points_2])
```

## 6.2 Methods

See *Listen*.

The following methods return points directly from the C SDK callback.

`cepton_sdk.listen_frames (callback)`

Register frames callback.

Throws error if *callback\_id* is currently registered.

**Returns** *callback\_id*

`cepton_sdk.unlisten_frames (callback_id)`

Unregisters frames callback.

Throws error if *callback\_id* is not currently registered.

There are also listener classes that seamlessly handle accumulation and waiting.

**class** `cepton_sdk.FramesListener`

**class** `cepton_sdk.SensorFramesListener (serial_number)`

## 6.3 Export

`cepton_sdk.export.save_points_las (points, path)`

Save points to LAS file.

`cepton_sdk.export.load_points_las (load_path, cls=<class 'cepton_sdk.point.Points'>)`

Load points from LAS file.

**Returns** *Points*, *extra\_data*

`cepton_sdk.export.save_points_ply (points, path)`

Save points to PLY file.

`cepton_sdk.export.save_points_pcd (points, path)`

Save points to PCD file.



## CAPTURE REPLAY

To open/close capture files, use `cepton_sdk.initialize` and `cepton_sdk.deinitialize` methods respectively. The high level API methods will automatically resume the capture replay as necessary.

```
cepton_sdk.open_replay(capture_path, capture_seek=0)
cepton_sdk.close_replay()
cepton_sdk.capture_replay.get_filename()
cepton_sdk.capture_replay.get_length()
cepton_sdk.capture_replay.get_position()
cepton_sdk.capture_replay.get_start_time()
cepton_sdk.capture_replay.get_time()
cepton_sdk.capture_replay.is_end()
cepton_sdk.capture_replay.is_open()
cepton_sdk.capture_replay.seek(t)
cepton_sdk.capture_replay.seek_relative(t)
```



## EXPORT

Methods to import/export points to common file formats.

**class** cepton\_sdk.export.PointsFileType

An enumeration.

**CSV** = 1

**LAS** = 2

**PCD** = 3

**PLY** = 4

cepton\_sdk.export.**save\_points** (*points*, *path*, *file\_type*=<PointsFileType.LAS: 2>)

Save points to file.

Sets file extension based on type.

cepton\_sdk.export.**load\_points** (*path*, *file\_type*=None)

Load points from file.

File type is inferred from extension.

**Returns** Points, extra\_data



## SAMPLES

## 9.1 Listen

Listing 1: samples/listen.py

```
1  #!/usr/bin/env python3
2
3  import numpy
4
5  import cepton_sdk
6  from common import *
7
8
9  def on_frame(serial_number, points):
10     print("Received {} points from sensor {}".format(
11         len(points), serial_number))
12
13
14  if __name__ == "__main__":
15     # Initialize
16     cepton_sdk.initialize(capture_path=get_sample_capture_path())
17     sensors_dict = cepton_sdk.get_sensors()
18     sensor = next(iter(sensors_dict.values()))
19
20     callback_id = cepton_sdk.listen_frames(on_frame)
21     cepton_sdk.wait(0.1)
22     cepton_sdk.unlisten_frames(callback_id)
23
24     # Get next frames for all sensors. Wait until data is available.
25     listener = cepton_sdk.FramesListener()
26     points_dict = listener.get_points()
27     del listener
28
29     # Get next frames for single sensor. Wait until data is available.
30     listener = cepton_sdk.SensorFramesListener(sensor.serial_number)
31     points_list = listener.get_points()
32     del listener
33
34     # Get large chunk of data
35     listener = cepton_sdk.FramesListener()
36     cepton_sdk.wait(10)
37     points_dict = listener.get_points()
38     del listener
```

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```
39 points = cepton_sdk.combine_points(points_dict[sensor.serial_number])
40 print("Received {} seconds of data from sensor {}".format(
41     numpy.ptp(points.timestamps), sensor.serial_number))
```

## 9.2 Multiple Sensors

Listing 2: samples/multiple\_sensors.py

```
1  #!/usr/bin/env python3
2
3  import pprint
4
5  import cepton_sdk
6  import cepton_sdk.plot
7  from common import *
8
9  if __name__ == "__main__":
10     # Variables
11     capture_path = get_sample_capture_path()
12
13     # Initialize
14     cepton_sdk.initialize(capture_path=capture_path)
15
16     # Get sensors
17     sensors_dict = cepton_sdk.get_sensors()
18
19     # Get points
20     listener = cepton_sdk.FramesListener()
21     points_dict = listener.get_points()
22     del listener
23     points_list = next(iter(points_dict.values()))
24     points = points_list[0]
25
26     # Plot
27     cepton_sdk.plot.plot_points(points)
```

## 9.3 Single Live Sensor

Listing 3: samples/single\_live\_sensor.py

```
1  #!/usr/bin/env python3
2
3  import pprint
4
5  import cepton_sdk
6  import cepton_sdk.plot
7  from common import *
8
9  if __name__ == "__main__":
10     # Variables
11     frame_length = 0.1
```

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```
12
13     # Initialize
14     cepton_sdk.initialize()
15
16     # Get sensor
17     sensor = cepton_sdk.Sensor.create_by_index(0)
18     pprint.pprint(sensor.information.to_dict())
19
20     # Get points
21     listener = cepton_sdk.SensorFramesListener(sensor.serial_number)
22     points_list = listener.get_points()
23     del listener
24     points = points_list[0]
25
26     # Plot
27     cepton_sdk.plot.plot_points(points)
```

## 9.4 Single Sensor

Listing 4: samples/single\_sensor.py

```
1  #!/usr/bin/env python3
2
3  import pprint
4
5  import numpy
6
7  import cepton_sdk
8  import cepton_sdk.plot
9  from common import *
10
11  if __name__ == "__main__":
12      # Variables
13      capture_path = get_sample_capture_path()
14
15      # Initialize
16      cepton_sdk.initialize(capture_path=capture_path)
17
18      # Get sensor
19      sensor = cepton_sdk.Sensor.create_by_index(0)
20      pprint.pprint(sensor.information.to_dict())
21
22      # Get points
23      listener = cepton_sdk.SensorFramesListener(sensor.serial_number)
24      points_list = listener.get_points()
25      del listener
26      points = points_list[0]
27
28      # Plot
29      cepton_sdk.plot.plot_points(points)
```





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