
cepton_sdk Documentation

Cepton Technologies

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OVERVIEW

If a method is undocumented, consult the *C/C++ SDK* documentation, since many methods in this library are just wrapper functions.

1.1 Timestamps

Unless otherwise marked, all timestamps are seconds since the Unix epoch (UTC). Note that this differs from the *C/C++* interface which uses microseconds.

ERRORS

```
class cepton_sdk.C_ErrorCode
    An enumeration.

class cepton_sdk.C_Error (code=<C_ErrorCode.CEPTON_SUCCESS: 0>, msg=None,
                        data=None)
    Error thrown by most sdk functions.

    code
        cepton_sdk.C_ErrorCode

class cepton_sdk.C_Warning
```


3.1 Types

```
class cepton_sdk.ControlFlag
    An enumeration.

    DISABLE_DISTANCE_CLIP = 8
    DISABLE_IMAGE_CLIP = 4
    DISABLE_NETWORK = 2
    ENABLE_MULTIPLE_RETURNS = 16
    ENABLE_STRAY_FILTER = 32
    HOST_TIMESTAMPS = 64
```

3.2 Methods

```
ception_sdk.initialize(capture_path=None, capture_seek=0, control_flags=0, error_callback=None,
                      port=None, **kwargs)
    Initializes SDK. Optionally starts capture replay.

    Parameters control_flags – ception_sdk.ControlFlag

ception_sdk.deinitialize()
```


GENERAL

API for code that is agnostic to live/replay mode.

`cepton_sdk.get_time()`

Returns capture replay time or live time.

`cepton_sdk.get_timestamp()`

Returns unix timestamp

`cepton_sdk.is_end()`

Returns true if next call to *wait* will throw *CEPTON_ERROR_EOF*

`cepton_sdk.is_live()`

Returns true if capture replay is not open.

`cepton_sdk.is_realtime()`

Returns true if live or capture replay is running.

`cepton_sdk.wait(duration=-1)`

Resumes capture replay or sleeps for duration.

If *duration* is 0, then waits forever.

SENSORS

5.1 Types

```
class cepton_sdk.SensorModel
    An enumeration.

    FUSION_790 = 8
    HR80M = 2
    HR80T = 1
    HR80T_R2 = 6
    HR80W = 3
    SORA_200 = 4
    VISTA_860 = 5
    VISTA_860_GEN2 = 7

class cepton_sdk.SensorInformation

    handle
    serial_number
    model_name
    model
        Type ception_sdk.SensorModel
    firmware_version
    formal_firmware_version
    last_reported_temperature
    last_reported_humidity
    last_reported_age
    last_reported_hv
    last_reported_optic_temperature
    gps_ts_year
    gps_ts_mont
```

```

    gps_ts_day
    gps_ts_hour
    gps_ts_min
    gps_ts_sec
    return_count
    is_mocked
    is_pps_connected
    is_nmea_connected
    is_calibrated
    is_over_heated
class cepton_sdk.Sensor(sensor_info)

    information
        Type ception_sdk.SensorInformation
    classmethod create(serial_number)
    classmethod create_by_handle(sensor_handle)
    classmethod create_by_index(sensor_index)
    handle
    serial_number
    update()
        Update sensor information.
        Should be called often, to pull latest sensor information.

```

5.2 Methods

```

ception_sdk.has_sensor(sensor_serial_number)
ception_sdk.get_sensors(cls=<class 'ception_sdk.api.Sensor'>)
    Returns attached sensors.
    Returns Dictionary of sensors, indexed by serial number.

```

6.1 Types

class `cepton_sdk.Points` (*n=0*)
3D points array.

timestamps_usec

timestamps

image_positions

distances

positions

intensities

return_strongest

return_farthest

valid

saturated

`cepton_sdk.combine_points` (*points_list*)
Combine list of points (*ImagePoints*, *Points*, etc).

List must be nonempty. :returns: combined_points

All point array classes support numpy indexing and assignment as if they were 1-d arrays:

```
1 n_points = len(points_1)
2 points_2[10:20] = points_1[:10]
```

Multiple point arrays can also be combined:

```
1 points = cepton_sdk.combine_points([points_1, points_2])
```

6.2 Methods

See *Listen*.

The following methods return points directly from the C SDK callback.

`cepton_sdk.listen_frames (callback)`

Register frames callback.

Throws error if *callback_id* is currently registered.

Returns *callback_id*

`cepton_sdk.unlisten_frames (callback_id)`

Unregisters frames callback.

Throws error if *callback_id* is not currently registered.

There are also listener classes that seamlessly handle accumulation and waiting.

class `cepton_sdk.FramesListener`

class `cepton_sdk.SensorFramesListener (serial_number)`

6.3 Export

`cepton_sdk.export.save_points_las (points, path)`

Save points to LAS file.

`cepton_sdk.export.load_points_las (load_path, cls=<class 'cepton_sdk.point.Points'>)`

Load points from LAS file.

Returns *Points*, *extra_data*

`cepton_sdk.export.save_points_ply (points, path)`

Save points to PLY file.

`cepton_sdk.export.save_points_pcd (points, path)`

Save points to PCD file.

CAPTURE REPLAY

To open/close capture files, use `cepton_sdk.initialize` and `cepton_sdk.deinitialize` methods respectively. The high level API methods will automatically resume the capture replay as necessary.

```
cepton_sdk.open_replay(capture_path, capture_seek=0)
cepton_sdk.close_replay()
cepton_sdk.capture_replay.get_filename()
cepton_sdk.capture_replay.get_length()
cepton_sdk.capture_replay.get_position()
cepton_sdk.capture_replay.get_start_time()
cepton_sdk.capture_replay.get_time()
cepton_sdk.capture_replay.is_end()
cepton_sdk.capture_replay.is_open()
cepton_sdk.capture_replay.seek(t)
cepton_sdk.capture_replay.seek_relative(t)
```


EXPORT

Methods to import/export points to common file formats.

class cepton_sdk.export.PointsFileType

An enumeration.

CSV = 1

LAS = 2

PCD = 3

PLY = 4

cepton_sdk.export.**save_points** (*points, path, file_type=<PointsFileType.LAS: 2>*)

Save points to file.

Sets file extension based on type.

cepton_sdk.export.**load_points** (*path, file_type=None*)

Load points from file.

File type is inferred from extension.

Returns Points, extra_data

SAMPLES

9.1 Multiple Sensors

Listing 1: samples/multiple_sensors.py

```
1  #!/usr/bin/env python3
2  """
3  Sample script for getting points from multiple sensors simultaneously.
4  """
5
6  import pprint
7
8  import cepton_sdk
9  import cepton_sdk.plot
10 from common import *
11
12 if __name__ == "__main__":
13     # Variables
14     capture_path = get_sample_capture_path()
15
16     # Initialize
17     cepton_sdk.initialize(capture_path=capture_path)
18
19     # Get sensors
20     sensors_dict = cepton_sdk.get_sensors()
21
22     # Get points
23     listener = cepton_sdk.FramesListener()
24     points_dict = listener.get_points()
25     del listener
26     points_list = next(iter(points_dict.values()))
27     points = points_list[0]
28
29     # Plot
30     cepton_sdk.plot.plot_points(points)
```

9.2 Single Sensor

Listing 2: samples/single_sensor.py

```
1  #!/usr/bin/env python3
2  """
3  Sample script for getting points from a single sensor.
4  """
5
6  import pprint
7
8  import numpy
9
10 import cepton_sdk
11 import cepton_sdk.plot
12 from common import *
13
14 if __name__ == "__main__":
15     # Variables
16     capture_path = get_sample_capture_path()
17
18     # Initialize
19     cepton_sdk.initialize(capture_path=capture_path)
20
21     # Get sensor
22     sensor = cepton_sdk.Sensor.create_by_index(0)
23     pprint.pprint(sensor.information.to_dict())
24
25     # Get points
26     listener = cepton_sdk.SensorFramesListener(sensor.serial_number)
27     points_list = listener.get_points()
28     del listener
29     points = points_list[0]
30
31     # Plot
32     cepton_sdk.plot.plot_points(points)
```

9.3 Advanced

9.3.1 Listen

Listing 3: samples/advanced/listen.py

```
1  #!/usr/bin/env python3
2  """
3  Sample script for the different methods of getting points.
4  """
5
6  import numpy
7
8  import cepton_sdk
9  from common import *
10
11
12 def on_frame(serial_number, points):
13     print("Received {} points from sensor {}".format(
```

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```
14         len(points), serial_number))
15
16
17 if __name__ == "__main__":
18     # Initialize
19     cepton_sdk.initialize(capture_path=get_sample_capture_path())
20     sensors_dict = cepton_sdk.get_sensors()
21     sensor = next(iter(sensors_dict.values()))
22
23     callback_id = cepton_sdk.listen_frames(on_frame)
24     cepton_sdk.wait(0.1)
25     cepton_sdk.unlisten_frames(callback_id)
26
27     # Get next frames for all sensors. Wait until data is available.
28     listener = cepton_sdk.FramesListener()
29     points_dict = listener.get_points()
30     del listener
31
32     # Get next frames for single sensor. Wait until data is available.
33     listener = cepton_sdk.SensorFramesListener(sensor.serial_number)
34     points_list = listener.get_points()
35     del listener
36
37     # Get large chunk of data
38     listener = cepton_sdk.FramesListener()
39     cepton_sdk.wait(10)
40     points_dict = listener.get_points()
41     del listener
42     points = cepton_sdk.combine_points(points_dict[sensor.serial_number])
43     print("Received {} seconds of data from sensor {}".format(
44         numpy.ptp(points.timestamps), sensor.serial_number))
```


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