cepton_sdk Documentation

Cepton Technologies

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ONE

OVERVIEW

If a method is undocumented, consult the C/C++ SDK documentation, since many methods in this library are just wrapper functions.

1.1 Timestamps

Unless otherwise marked, all timestamps are seconds since the Unix epoch (UTC). Note that this differs from the C/C++ interface which uses microseconds.

TWO

ERRORS

4 Chapter 2. Errors

THREE

SETUP

3.1 Types

```
class cepton_sdk.ControlFlag
   An enumeration.

DISABLE_DISTANCE_CLIP = 8

DISABLE_IMAGE_CLIP = 4

DISABLE_NETWORK = 2

ENABLE_CROSSTALK_FILTER = 128

ENABLE_MULTIPLE_RETURNS = 16

ENABLE_STRAY_FILTER = 32

HOST_TIMESTAMPS = 64
```

3.2 Methods

6 Chapter 3. Setup

FOUR

GENERAL

```
API for code that is agnostic to live/replay mode.

cepton_sdk.get_time()
    Returns capture replay time or live time.

cepton_sdk.get_timestamp()
    Returns unix timestamp

cepton_sdk.is_end()
    Returns true if next call to wait will throw CEPTON_ERROR_EOF

cepton_sdk.is_live()
    Returns true if capture replay is not open.

cepton_sdk.is_realtime()
    Returns true if live or capture replay is running.

cepton_sdk.wait(duration=-1)
    Resumes capture replay or sleeps for duration.
```

If *duration* is 0, then waits forever.

8 Chapter 4. General

FIVE

SENSORS

5.1 Types

```
class cepton_sdk.SensorModel
    An enumeration.
    FUSION_790 = 8
    HR80M = 2
    HR80T = 1
    HR80T_R2 = 6
    HR80W = 3
    SORA_200 = 4
    SORA_P60 = 11
    VISTA_860 = 5
    VISTA_860_GEN2 = 7
    VISTA_M = 9
    VISTA_P60 = 12
    VISTA_X = 10
    VISTA_X15 = 13
class cepton_sdk.SensorInformation
    handle
    serial_number
    model_name
    model
           Type cepton_sdk.SensorModel
    firmware_version
    formal_firmware_version
    last_reported_temperature
    last_reported_humidity
```

```
last_reported_age
    last_reported_hv
    last_reported_optic_temperature
    gps_ts_year
    gps_ts_mont
    gps_ts_day
    gps_ts_hour
    gps_ts_min
    gps_ts_sec
    return_count
    is_mocked
    is_pps_connected
    is_nmea_connected
    is_calibrated
    is_over_heated
class cepton_sdk.Sensor(sensor_info)
    information
            Type cepton_sdk.SensorInformation
    classmethod create(serial_number)
    classmethod create_by_handle(sensor_handle)
    classmethod create_by_index(sensor_index)
    property handle
    property serial_number
    update()
        Update sensor information.
        Should be called often, to pull latest sensor information.
```

5.2 Methods

```
cepton_sdk.has_sensor(sensor_serial_number)
cepton_sdk.get_sensors(cls=<class 'cepton_sdk.api.Sensor'>)
    Returns attached sensors.

Returns Dictionary of sensors, indexed by serial number.
```

10 Chapter 5. Sensors

SIX

POINTS

6.1 Types

```
class cepton_sdk.Points(n=0)
     3D points array.
     timestamps_usec
     timestamps
     image_positions
     distances
     positions
     intensities
     return_strongest
     return_farthest
     valid
     saturated
cepton_sdk.combine_points(points_list)
     Combine list of points (ImagePoints, Points, etc).
     List must be nonempty. :returns: combined_points
All point array classes support numpy indexing and assignment as if they were 1-d arrays:
```

```
n_points = len(points_1)
points_2[10:20] = points_1[:10]
```

Multiple point arrays can also be combined:

```
points = cepton_sdk.combine_points([points_1, points_2])
```

6.2 Methods

See Listen.

The following methods return points directly from the C SDK callback.

```
cepton_sdk.listen_frames(callback)
     Register frames callback.
     Throws error if callback_id is currently registered.
          Returns callback_id
cepton_sdk.unlisten_frames(callback_id)
     Unregisters frames callback.
     Throws error if callback_id is not currently registered.
There are also listener classes that seamlessly handle accumulation and waiting.
class cepton_sdk.FramesListener
     Listener for getting all sensor frames.
class cepton_sdk.SensorFramesListener(serial_number)
6.3 Export
cepton_sdk.export.save_points_las (points, path)
     Save points to LAS file.
cepton_sdk.export.load_points_las(load_path, cls=<class'cepton_sdk.point.Points'>)
     Load points from LAS file.
          Returns Points, extra_data
cepton_sdk.export.save_points_ply (points, path)
     Save points to PLY file.
cepton_sdk.export.save_points_pcd(points, path)
     Save points to PCD file.
```

12 Chapter 6. Points

SEVEN

SERIAL

7.1 Methods

The following methods return serial lines directly from the C SDK callback.

cepton_sdk.listen_serial_lines(callback)

cepton_sdk.unlisten_serial_lines(callback_id)

There is also a listener class that seamlessly handle accumulation.

 ${\tt class} \ {\tt cepton_sdk}. {\tt SerialLinesListener}$

14 Chapter 7. Serial

EIGHT

CAPTURE REPLAY

To open/close capture files, use <code>cepton_sdk.initialize</code> and <code>cepton_sdk.deinitialize</code> methods respectively. The high level API methods will automatically resume the capture replay as necessary.

```
cepton_sdk.open_replay(capture_path, capture_seek=0, enable_loop=False)
cepton_sdk.close_replay()
cepton_sdk.capture_replay.get_filename()
cepton_sdk.capture_replay.get_length()
cepton_sdk.capture_replay.get_position()
cepton_sdk.capture_replay.get_start_time()
cepton_sdk.capture_replay.get_time()
cepton_sdk.capture_replay.is_end()
cepton_sdk.capture_replay.is_open()
cepton_sdk.capture_replay.seek(t)
cepton_sdk.capture_replay.seek_relative(t)
```

NINE

EXPORT

Methods to import/export points to common file formats.

```
class cepton_sdk.export.PointsFileType
    An enumeration.

CSV = 1

LAS = 2

PCD = 3

PLY = 4

cepton_sdk.export.save_points(points, path, file_type=<PointsFileType.LAS: 2>)
    Save points to file.

Sets file extension based on type.

cepton_sdk.export.load_points(path, file_type=None)
    Load points from file.

File type is inferred from extension.
```

Returns Points, extra_data

18 Chapter 9. Export

TEN

SAMPLES

10.1 Multiple Sensors

Listing 1: samples/multiple_sensors.py

```
#!/usr/bin/env python3
   Sample script for getting points from multiple sensors simultaneously.
   import pprint
   import cepton_sdk
   import cepton_sdk.plot
   from common import *
11
   if __name__ == "__main__":
12
       # Variables
13
       capture_path = get_sample_capture_path()
14
15
       # Initialize
       cepton_sdk.initialize(capture_path=capture_path)
17
       # Get sensors
19
       sensors_dict = cepton_sdk.get_sensors()
20
21
       # Get points
22
       listener = cepton_sdk.FramesListener()
23
24
       points_dict = listener.get_points()
25
       del listener
       points_list = next(iter(points_dict.values()))
26
       points = points_list[0]
27
28
       # Plot
29
       cepton_sdk.plot.plot_points(points)
```

10.2 Single Sensor

Listing 2: samples/single_sensor.py

```
#!/usr/bin/env python3
2
   Sample script for getting points from a single sensor.
3
   import pprint
   import numpy
   import cepton_sdk
10
   import cepton_sdk.plot
11
   from common import *
12
13
   if __name__ == "__main__":
14
        # Variables
15
       capture_path = get_sample_capture_path()
16
17
        # Initialize
18
       cepton_sdk.initialize(capture_path=capture_path)
20
       # Get sensor
21
       sensor = cepton_sdk.Sensor.create_by_index(0)
22
       pprint.pprint(sensor.information.to_dict())
23
24
        # Get points
25
       listener = cepton_sdk.SensorFramesListener(sensor.serial_number)
26
       points_list = listener.get_points()
27
       del listener
28
       points = points_list[0]
29
30
        # Plot
31
       cepton_sdk.plot.plot_points(points)
```

10.3 Advanced

10.3.1 Listen

Listing 3: samples/advanced/listen.py

```
#!/usr/bin/env python3
    """

Sample script for the different methods of getting points.

"""

import numpy

import cepton_sdk

from common import *

def on_frame(serial_number, points):
    print("Received {} points from sensor {}".format(
```

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```
len(points), serial_number))
14
15
16
   if __name__ == "__main__":
17
       # Initialize
18
       cepton_sdk.initialize(capture_path=get_sample_capture_path())
19
       sensors_dict = cepton_sdk.get_sensors()
20
       sensor = next(iter(sensors_dict.values()))
21
22
       callback_id = cepton_sdk.listen_frames(on_frame)
23
       cepton_sdk.wait(0.1)
24
       cepton_sdk.unlisten_frames(callback_id)
25
26
27
       # Get next frames for all sensors. Wait until data is available.
       listener = cepton_sdk.FramesListener()
28
       points_dict = listener.get_points()
29
       del listener
30
31
       # Get next frames for single sensor. Wait until data is available.
32
       listener = cepton_sdk.SensorFramesListener(sensor.serial_number)
33
       points_list = listener.get_points()
34
       del listener
35
36
       # Get large chunk of data
37
       listener = cepton_sdk.FramesListener()
       cepton_sdk.wait(10)
       points_dict = listener.get_points()
40
       del listener
41
       points = cepton_sdk.combine_points(points_dict[sensor.serial_number])
42
       print("Received {} seconds of data from sensor {}".format(
43
           numpy.ptp(points.timestamps), sensor.serial_number))
44
```

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