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# **cepton\_sdk Documentation**

**Cepton Technologies**

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# CONTENTS

<b>1</b>	<b>Overview</b>	<b>1</b>
<b>2</b>	<b>Errors</b>	<b>3</b>
<b>3</b>	<b>Setup</b>	<b>5</b>
<b>4</b>	<b>General</b>	<b>7</b>
<b>5</b>	<b>Sensors</b>	<b>9</b>
<b>6</b>	<b>Points</b>	<b>11</b>
<b>7</b>	<b>Serial</b>	<b>13</b>
<b>8</b>	<b>Capture Replay</b>	<b>15</b>
<b>9</b>	<b>Export</b>	<b>17</b>
<b>10</b>	<b>Samples</b>	<b>19</b>
	<b>Index</b>	<b>23</b>



## **OVERVIEW**

If a method is undocumented, consult the *C/C++ SDK* documentation, since many methods in this library are just wrapper functions.

### **1.1 Timestamps**

Unless otherwise marked, all timestamps are seconds since the Unix epoch (UTC). Note that this differs from the *C/C++* interface which uses microseconds.



## ERRORS

```
class cepton_sdk.C_ErrorCode
    An enumeration.

class cepton_sdk.C_Error (code=<C_ErrorCode.CEPTON_SUCCESS: 0>, msg=None,
                        data=None)
    Error thrown by most sdk functions.

    code
        cepton_sdk.C_ErrorCode

class cepton_sdk.C_Warning
```





## 3.1 Types

```
class cepton_sdk.ControlFlag
    An enumeration.

    DISABLE_DISTANCE_CLIP = 8
    DISABLE_IMAGE_CLIP = 4
    DISABLE_NETWORK = 2
    ENABLE_CROSSTALK_FILTER = 128
    ENABLE_MULTIPLE_RETURNS = 16
    ENABLE_STRAY_FILTER = 32
    HOST_TIMESTAMPS = 64
```

## 3.2 Methods

```
cepton_sdk.initialize(capture_path=None, capture_seek=0, control_flags=0, error_callback=None,
                     port=None, **kwargs)
    Initializes SDK. Optionally starts capture replay.

    Parameters control_flags – cepton_sdk.ControlFlag

cepton_sdk.deinitialize()
```



**GENERAL**

API for code that is agnostic to live/replay mode.

`cepton_sdk.get_time()`

Returns capture replay time or live time.

`cepton_sdk.get_timestamp()`

Returns unix timestamp

`cepton_sdk.is_end()`

Returns true if next call to *wait* will throw *CEPTON\_ERROR\_EOF*

`cepton_sdk.is_live()`

Returns true if capture replay is not open.

`cepton_sdk.is_realtime()`

Returns true if live or capture replay is running.

`cepton_sdk.wait(duration=-1)`

Resumes capture replay or sleeps for duration.

If *duration* is 0, then waits forever.



## SENSORS

## 5.1 Types

```
class cepton_sdk.SensorModel
    An enumeration.

    FUSION_790 = 8
    HR80M = 2
    HR80T = 1
    HR80T_R2 = 6
    HR80W = 3
    SORA_200 = 4
    SORA_P60 = 11
    VISTA_860 = 5
    VISTA_860_GEN2 = 7
    VISTA_M = 9
    VISTA_P60 = 12
    VISTA_X = 10
    VISTA_X15 = 13

class cepton_sdk.SensorInformation

    handle
    serial_number
    model_name
    model

    Type ception_sdk.SensorModel

    firmware_version
    formal_firmware_version
    last_reported_temperature
    last_reported_humidity
```

```
last_reported_age
last_reported_hv
last_reported_optic_temperature
gps_ts_year
gps_ts_mont
gps_ts_day
gps_ts_hour
gps_ts_min
gps_ts_sec
return_count
is_mocked
is_pps_connected
is_nmea_connected
is_calibrated
is_over_heated
```

```
class cepton_sdk.Sensor(sensor_info)
```

```
information
    Type cepton_sdk.SensorInformation
classmethod create(serial_number)
classmethod create_by_handle(sensor_handle)
classmethod create_by_index(sensor_index)
property handle
property serial_number
update()
    Update sensor information.
    Should be called often, to pull latest sensor information.
```

## 5.2 Methods

```
cepton_sdk.has_sensor(sensor_serial_number)
```

```
cepton_sdk.get_sensors(cls=<class 'cepton_sdk.api.Sensor'>)
    Returns attached sensors.
```

**Returns** Dictionary of sensors, indexed by serial number.

## 6.1 Types

**class** `cepton_sdk.Points` (*n=0*)  
3D points array.

**timestamps\_usec**

**timestamps**

**image\_positions**

**distances**

**positions**

**intensities**

**return\_strongest**

**return\_farthest**

**valid**

**saturated**

`cepton_sdk.combine_points` (*points\_list*)  
Combine list of points (*ImagePoints*, *Points*, etc).

List must be nonempty. :returns: combined\_points

All point array classes support numpy indexing and assignment as if they were 1-d arrays:

```
1 n_points = len(points_1)
2 points_2[10:20] = points_1[:10]
```

Multiple point arrays can also be combined:

```
1 points = cepton_sdk.combine_points([points_1, points_2])
```

## 6.2 Methods

See *Listen*.

The following methods return points directly from the C SDK callback.

`cepton_sdk.listen_frames (callback)`

Register frames callback.

Throws error if *callback\_id* is currently registered.

**Returns** *callback\_id*

`cepton_sdk.unlisten_frames (callback_id)`

Unregisters frames callback.

Throws error if *callback\_id* is not currently registered.

There are also listener classes that seamlessly handle accumulation and waiting.

**class** `cepton_sdk.FramesListener`

Listener for getting all sensor frames.

**class** `cepton_sdk.SensorFramesListener (serial_number)`

## 6.3 Export

`cepton_sdk.export.save_points_las (points, path)`

Save points to LAS file.

`cepton_sdk.export.load_points_las (load_path, cls=<class 'cepton_sdk.point.Points'>)`

Load points from LAS file.

**Returns** *Points*, *extra\_data*

`cepton_sdk.export.save_points_ply (points, path)`

Save points to PLY file.

`cepton_sdk.export.save_points_pcd (points, path)`

Save points to PCD file.



## 7.1 Methods

The following methods return serial lines directly from the C SDK callback.

`cepton_sdk.listen_serial_lines(callback)`

`cepton_sdk.unlisten_serial_lines(callback_id)`

There is also a listener class that seamlessly handle accumulation.

**class** `cepton_sdk.SerialLinesListener`



## CAPTURE REPLAY

To open/close capture files, use `cepton_sdk.initialize` and `cepton_sdk.deinitialize` methods respectively. The high level API methods will automatically resume the capture replay as necessary.

```
cepton_sdk.open_replay(capture_path, capture_seek=0, enable_loop=False)
```

```
cepton_sdk.close_replay()
```

```
cepton_sdk.capture_replay.get_filename()
```

```
cepton_sdk.capture_replay.get_length()
```

```
cepton_sdk.capture_replay.get_position()
```

```
cepton_sdk.capture_replay.get_start_time()
```

```
cepton_sdk.capture_replay.get_time()
```

```
cepton_sdk.capture_replay.is_end()
```

```
cepton_sdk.capture_replay.is_open()
```

```
cepton_sdk.capture_replay.seek(t)
```

```
cepton_sdk.capture_replay.seek_relative(t)
```



**EXPORT**

Methods to import/export points to common file formats.

**class** cepton\_sdk.export.**PointsFileType**

An enumeration.

**CSV** = 1

**LAS** = 2

**PCD** = 3

**PLY** = 4

cepton\_sdk.export.**save\_points** (*points, path, file\_type=<PointsFileType.LAS: 2>*)

Save points to file.

Sets file extension based on type.

cepton\_sdk.export.**load\_points** (*path, file\_type=None*)

Load points from file.

File type is inferred from extension.

**Returns** Points, extra\_data



## 10.1 Multiple Sensors

Listing 1: samples/multiple\_sensors.py

```
1  #!/usr/bin/env python3
2  """
3  Sample script for getting points from multiple sensors simultaneously.
4  """
5
6  import pprint
7
8  import cepton_sdk
9  import cepton_sdk.plot
10 from common import *
11
12 if __name__ == "__main__":
13     # Variables
14     capture_path = get_sample_capture_path()
15
16     # Initialize
17     cepton_sdk.initialize(capture_path=capture_path)
18
19     # Get sensors
20     sensors_dict = cepton_sdk.get_sensors()
21
22     # Get points
23     listener = cepton_sdk.FramesListener()
24     points_dict = listener.get_points()
25     del listener
26     points_list = next(iter(points_dict.values()))
27     points = points_list[0]
28
29     # Plot
30     cepton_sdk.plot.plot_points(points)
```

## 10.2 Single Sensor

Listing 2: samples/single\_sensor.py

```
1  #!/usr/bin/env python3
2  """
3  Sample script for getting points from a single sensor.
4  """
5
6  import pprint
7
8  import numpy
9
10 import cepton_sdk
11 import cepton_sdk.plot
12 from common import *
13
14 if __name__ == "__main__":
15     # Variables
16     capture_path = get_sample_capture_path()
17
18     # Initialize
19     cepton_sdk.initialize(capture_path=capture_path)
20
21     # Get sensor
22     sensor = cepton_sdk.Sensor.create_by_index(0)
23     pprint.pprint(sensor.information.to_dict())
24
25     # Get points
26     listener = cepton_sdk.SensorFramesListener(sensor.serial_number)
27     points_list = listener.get_points()
28     del listener
29     points = points_list[0]
30
31     # Plot
32     cepton_sdk.plot.plot_points(points)
```

## 10.3 Advanced

### 10.3.1 Listen

Listing 3: samples/advanced/listen.py

```
1  #!/usr/bin/env python3
2  """
3  Sample script for the different methods of getting points.
4  """
5
6  import numpy
7
8  import cepton_sdk
9  from common import *
10
11
12 def on_frame(serial_number, points):
13     print("Received {} points from sensor {}".format(
```

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```
14         len(points), serial_number))
15
16
17 if __name__ == "__main__":
18     # Initialize
19     cepton_sdk.initialize(capture_path=get_sample_capture_path())
20     sensors_dict = cepton_sdk.get_sensors()
21     sensor = next(iter(sensors_dict.values()))
22
23     callback_id = cepton_sdk.listen_frames(on_frame)
24     cepton_sdk.wait(0.1)
25     cepton_sdk.unlisten_frames(callback_id)
26
27     # Get next frames for all sensors. Wait until data is available.
28     listener = cepton_sdk.FramesListener()
29     points_dict = listener.get_points()
30     del listener
31
32     # Get next frames for single sensor. Wait until data is available.
33     listener = cepton_sdk.SensorFramesListener(sensor.serial_number)
34     points_list = listener.get_points()
35     del listener
36
37     # Get large chunk of data
38     listener = cepton_sdk.FramesListener()
39     cepton_sdk.wait(10)
40     points_dict = listener.get_points()
41     del listener
42     points = cepton_sdk.combine_points(points_dict[sensor.serial_number])
43     print("Received {} seconds of data from sensor {}".format(
44         numpy.ptp(points.timestamps), sensor.serial_number))
```



## C

`C_Error` (class in `cepton_sdk`), 3  
`C_ErrorCode` (class in `cepton_sdk`), 3  
`C_Warning` (class in `cepton_sdk`), 3  
`close_replay()` (in module `cepton_sdk`), 15  
`code` (`cepton_sdk.C_Error` attribute), 3  
`combine_points()` (in module `cepton_sdk`), 11  
`ControlFlag` (class in `cepton_sdk`), 5  
`create()` (`cepton_sdk.Sensor` class method), 10  
`create_by_handle()` (`cepton_sdk.Sensor` class method), 10  
`create_by_index()` (`cepton_sdk.Sensor` class method), 10  
`CSV` (`cepton_sdk.export.PointsFileType` attribute), 17

## D

`deinitialize()` (in module `cepton_sdk`), 5  
`DISABLE_DISTANCE_CLIP` (`cepton_sdk.ControlFlag` attribute), 5  
`DISABLE_IMAGE_CLIP` (`cepton_sdk.ControlFlag` attribute), 5  
`DISABLE_NETWORK` (`cepton_sdk.ControlFlag` attribute), 5  
`distances` (`cepton_sdk.Points` attribute), 11

## E

`ENABLE_CROSSTALK_FILTER` (`cepton_sdk.ControlFlag` attribute), 5  
`ENABLE_MULTIPLE_RETURNS` (`cepton_sdk.ControlFlag` attribute), 5  
`ENABLE_STRAY_FILTER` (`cepton_sdk.ControlFlag` attribute), 5

## F

`firmware_version` (`cepton_sdk.SensorInformation` attribute), 9  
`formal_firmware_version` (`cepton_sdk.SensorInformation` attribute), 9  
`FramesListener` (class in `cepton_sdk`), 12  
`FUSION_790` (`cepton_sdk.SensorModel` attribute), 9

## G

`get_filename()` (in module `cepton_sdk.capture_replay`), 15  
`get_length()` (in module `cepton_sdk.capture_replay`), 15  
`get_position()` (in module `cepton_sdk.capture_replay`), 15  
`get_sensors()` (in module `cepton_sdk`), 10  
`get_start_time()` (in module `cepton_sdk.capture_replay`), 15  
`get_time()` (in module `cepton_sdk`), 7  
`get_time()` (in module `cepton_sdk.capture_replay`), 15  
`get_timestamp()` (in module `cepton_sdk`), 7  
`gps_ts_day` (`cepton_sdk.SensorInformation` attribute), 10  
`gps_ts_hour` (`cepton_sdk.SensorInformation` attribute), 10  
`gps_ts_min` (`cepton_sdk.SensorInformation` attribute), 10  
`gps_ts_mont` (`cepton_sdk.SensorInformation` attribute), 10  
`gps_ts_sec` (`cepton_sdk.SensorInformation` attribute), 10  
`gps_ts_year` (`cepton_sdk.SensorInformation` attribute), 10

## H

`handle` (`cepton_sdk.SensorInformation` attribute), 9  
`handle()` (`cepton_sdk.Sensor` property), 10  
`has_sensor()` (in module `cepton_sdk`), 10  
`HOST_TIMESTAMPS` (`cepton_sdk.ControlFlag` attribute), 5  
`HR80M` (`cepton_sdk.SensorModel` attribute), 9  
`HR80T` (`cepton_sdk.SensorModel` attribute), 9  
`HR80T_R2` (`cepton_sdk.SensorModel` attribute), 9  
`HR80W` (`cepton_sdk.SensorModel` attribute), 9

## I

`image_positions` (`cepton_sdk.Points` attribute), 11  
`information` (`cepton_sdk.Sensor` attribute), 10  
`initialize()` (in module `cepton_sdk`), 5

intensities (*cepton\_sdk.Points* attribute), 11  
is\_calibrated (*cepton\_sdk.SensorInformation* attribute), 10  
is\_end() (in module *cepton\_sdk*), 7  
is\_end() (in module *cepton\_sdk.capture\_replay*), 15  
is\_live() (in module *cepton\_sdk*), 7  
is\_mocked (*cepton\_sdk.SensorInformation* attribute), 10  
is\_nmea\_connected (*cepton\_sdk.SensorInformation* attribute), 10  
is\_open() (in module *cepton\_sdk.capture\_replay*), 15  
is\_over\_heated (*cepton\_sdk.SensorInformation* attribute), 10  
is\_pps\_connected (*cepton\_sdk.SensorInformation* attribute), 10  
is\_realtime() (in module *cepton\_sdk*), 7

## L

LAS (*cepton\_sdk.export.PointsFileType* attribute), 17  
last\_reported\_age (*cepton\_sdk.SensorInformation* attribute), 9  
last\_reported\_humidity (*cepton\_sdk.SensorInformation* attribute), 9  
last\_reported\_hv (*cepton\_sdk.SensorInformation* attribute), 10  
last\_reported\_optic\_temperature (*cepton\_sdk.SensorInformation* attribute), 10  
last\_reported\_temperature (*cepton\_sdk.SensorInformation* attribute), 9  
listen\_frames() (in module *cepton\_sdk*), 11  
listen\_serial\_lines() (in module *cepton\_sdk*), 13  
load\_points() (in module *cepton\_sdk.export*), 17  
load\_points\_las() (in module *cepton\_sdk.export*), 12

## M

model (*cepton\_sdk.SensorInformation* attribute), 9  
model\_name (*cepton\_sdk.SensorInformation* attribute), 9

## O

open\_replay() (in module *cepton\_sdk*), 15

## P

PCD (*cepton\_sdk.export.PointsFileType* attribute), 17  
PLY (*cepton\_sdk.export.PointsFileType* attribute), 17  
Points (class in *cepton\_sdk*), 11  
PointsFileType (class in *cepton\_sdk.export*), 17  
positions (*cepton\_sdk.Points* attribute), 11

## R

return\_count (*cepton\_sdk.SensorInformation* attribute), 10

return\_farthest (*cepton\_sdk.Points* attribute), 11  
return\_strongest (*cepton\_sdk.Points* attribute), 11

## S

saturated (*cepton\_sdk.Points* attribute), 11  
save\_points() (in module *cepton\_sdk.export*), 17  
save\_points\_las() (in module *cepton\_sdk.export*), 12  
save\_points\_pcd() (in module *cepton\_sdk.export*), 12  
save\_points\_ply() (in module *cepton\_sdk.export*), 12  
seek() (in module *cepton\_sdk.capture\_replay*), 15  
seek\_relative() (in module *cepton\_sdk.capture\_replay*), 15  
Sensor (class in *cepton\_sdk*), 10  
SensorFramesListener (class in *cepton\_sdk*), 12  
SensorInformation (class in *cepton\_sdk*), 9  
SensorModel (class in *cepton\_sdk*), 9  
serial\_number (*cepton\_sdk.SensorInformation* attribute), 9  
serial\_number() (*cepton\_sdk.Sensor* property), 10  
SerialLinesListener (class in *cepton\_sdk*), 13  
SORA\_200 (*cepton\_sdk.SensorModel* attribute), 9  
SORA\_P60 (*cepton\_sdk.SensorModel* attribute), 9

## T

timestamps (*cepton\_sdk.Points* attribute), 11  
timestamps\_usec (*cepton\_sdk.Points* attribute), 11

## U

unlisten\_frames() (in module *cepton\_sdk*), 12  
unlisten\_serial\_lines() (in module *cepton\_sdk*), 13  
update() (*cepton\_sdk.Sensor* method), 10

## V

valid (*cepton\_sdk.Points* attribute), 11  
VISTA\_860 (*cepton\_sdk.SensorModel* attribute), 9  
VISTA\_860\_GEN2 (*cepton\_sdk.SensorModel* attribute), 9  
VISTA\_M (*cepton\_sdk.SensorModel* attribute), 9  
VISTA\_P60 (*cepton\_sdk.SensorModel* attribute), 9  
VISTA\_X (*cepton\_sdk.SensorModel* attribute), 9  
VISTA\_X15 (*cepton\_sdk.SensorModel* attribute), 9

## W

wait() (in module *cepton\_sdk*), 7