First part is an Inference Project Against supplied Digit Image Recognition Datasets.

Trained model for the supplied data set

Augmenting our data by inverting the original images. Turn the white pixels to black and vice-versa. Then we will train our network using the original and inverted images and I saw that classification is improved.

I trained a model using the LeNet network for 15 epochs. The reason for chosen this network that datasets contain grayscale images and this the only choice and performed well which give me on validation data 99.01% accuracy.

When classifying 8 new images of digit-written that weren't in the training set this model showed 90.19% accuracy on test set.

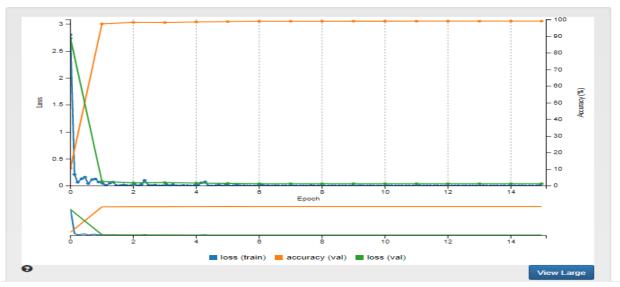


Fig 1.0

| , , | , oldomodiono | | |
|-----|-------------------------------------------|-----------------------------------------------|-------|
| | Path | Top predictions | |
| 1 | /data/notebooks/test_images/image-1-1.jpg | 1 (89,71%) 7 (10.08%) 9 (0.09%) 4 (0.07%) 2 (| 0.02% |
| 2 | /data/notebooks/test_images/image-2-1.jpg | 2 (99.67%) 7 (0.29%) 0 (0.02%) 1 (0.02%) 3 | 0.0% |
| 3 | /data/notebooks/test_images/image-3-1.jpg | 3 (99.97%) 2 (0.02%) 1 (0.01%) 5 (0.0%) 7 | 0.0% |
| 4 | /data/notebooks/test_images/image-4-1.jpg | 4 (99.97%) 7 (0.02%) 1 (0.01%) 9 (0.0%) 5 | 0.0% |
| 5 | /data/notebooks/test_images/image-7-1.jpg | 7 (93.95%) 1 (5.67%) 2 (0.36%) 0 (0.01%) 8 (| 0.0% |
| 6 | /data/notebooks/test_images/image-8-1.jpg | 8 (100.0%) 3 (0.0%) 2 (0.0%) 5 (0.0%) 0 (| 0.0% |
| 7 | /data/notebooks/test_images/image-8-2.jpg | 2 (99.66%) 8 (0.12%) 7 (0.12%) 1 (0.05%) 3 (| 0.04% |

All classifications

Inference Robotics

Abstract:

In this project I am going to talk about sorting cups, my problem that I used to drink and left them cups where I was sitting and my mother was always complaining about that bad habit so I decide to make robot to help her to bring cups to kitchen.

Introduction:

my problem that I used to drink and left them cups where I was sitting and my mother was always complaining about that bad habit so I decide to make robot to help her to bring cups to kitchen.

I used to leave the cups under chairs everywhere in the sitting room which is not easy to see them.

So, I decided to make robot that can perceive the environment and classify the cups in the home to bring them back to kitchen.

Background / Formulation:

To classify images of cups two types of standard neural network models, AlexNet and GoogleNet. The reason for chosen these network that datasets contain colored images of cups, and these networks are commonly used in image classification problems and has shown great results in accuracy and time. In both models base learning rate is set to 0.01, solver type is SGD (Stochastic Gradient Decent), and models are trained 30 with epochs.

Numerous other learning rates and solving types were tested, but these showed the best result. I tried to used AlexNet but it given me a 93.5% accuracy (val), then I tried GoogleNet performed best with 30 epochs, achieving 99.43 % accuracy (val).

Data Acquisition:

Dataset is consisted of three classes cup of coffee, cup of ice cream and mug. Two of classes have 2 different type the last one with one type.

200 images for each type with 400 for each class with total 1200 images.25% of images is used for validation, and the data was a color image with size 256 x 256 pixel.

I used my phone to collect the data then I used online site to resize and format them in *.PNG.

Results:

When training with AlexNet network model, on 30th epoch validation accuracy was 93.83% accuracy. When classifying new images of cups that weren't in the training set this model showed 99.17% accuracy for mug and cup of coffee with 98.18% for one type and other misclassified as you can see in the figures below. As well it takes 4 inference time.

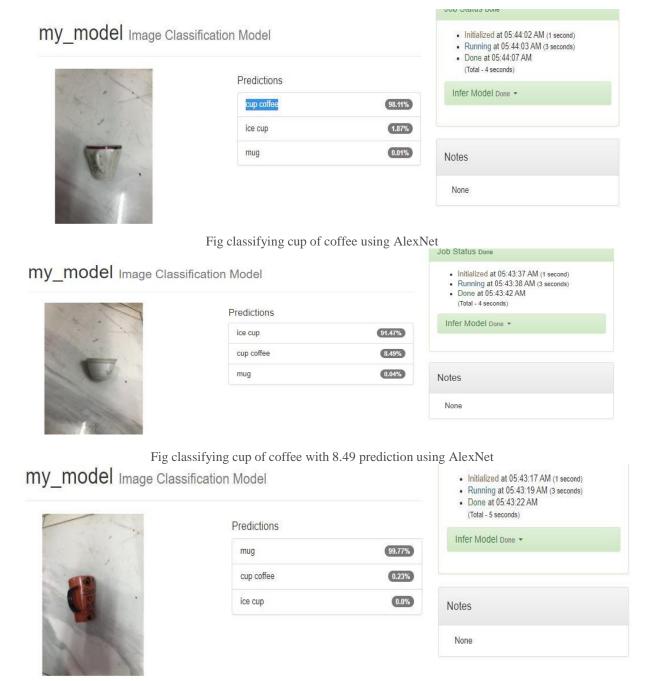
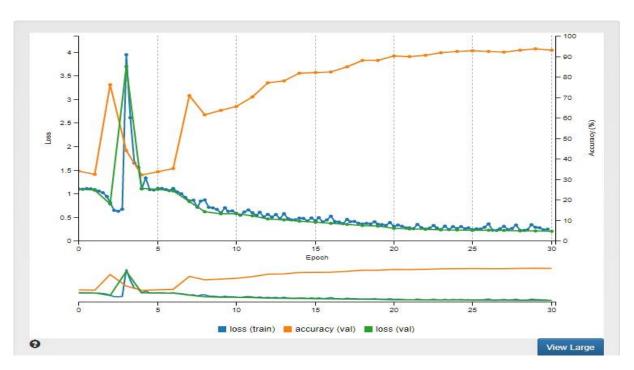


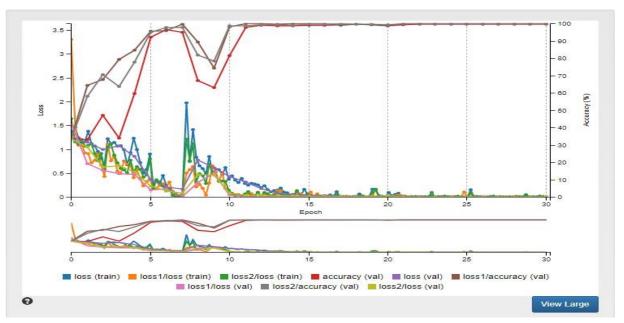
Fig classifying mug using AlexNet



Fig classifying ice of cup using AlexNet



AlexNet on Vaildation and Training Set



GoogleNet on Vaildation and Training Set



Fig classifying cup of coffee using GoogleNet

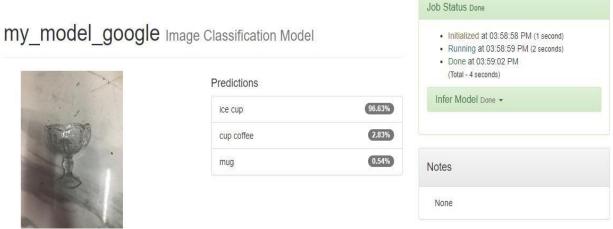


Fig classifying ice cup using GoogleNet

my_model_google Image Classification Model Predictions mug ice cup cup coffee Initialized at 03:59:58 PM (1 second) Running at 03:59:59 PM (3 seconds) Done at 04:00:02 PM (Total - 4 seconds) Infer Model Done ▼ Notes None

Job Status Done

Fig classifying mug using GoogleNet

Discussion:

As can be seen from the results even though GoogLeNet model showed better result when classifying data set and validation set, AlexNet model resulted higher accuracy on test images. And AlexNet model showed more than 90% accuracy in 2 classes, as well GoogLeNet but with high accuracy on training and validation set. Additionally looking at inference time, two model performed similarly when classifying one image, GoogLeNet and AlexNet model only took 4 seconds.

Classifying images of cups for making robot help older people at their home. Given the results, for this particular problem the AlexNet model might be more suitable.

One may believe the accuracy on the dataset is low because some images are too small to show the necessary detail. That's why cup of coffee is misclassified.

In regards to my project, Accuracy and inference time are in a hyperbolic relationship which with high accuracy given me 4 fps on

Conclusion / Future Work:

Both network models showed similar results classifying validation and testing sets, but the model using AlexNet network resulted higher accuracy when classifying images of cups that were not in the training set. Both models showed more than 90% accuracy classifying images of cup of coffee.

It might be due to the fact that training set for cup of coffee class had images with mostly look like ice cup in color tone.

Collecting images of cups with different colors should improve the accuracy. To be commercially viable product both number of cups types and the variety of cups in one class with different color schemes and patterns need to be increased.

when collecting data, along with angle and ratio, the way that cups lays on the floor should be considered too. These types of classification can also be applied in areas like e-commerce.

Also I notice that after more training it increases accuracy(val) of the model I think this network going to memorize the dataset.