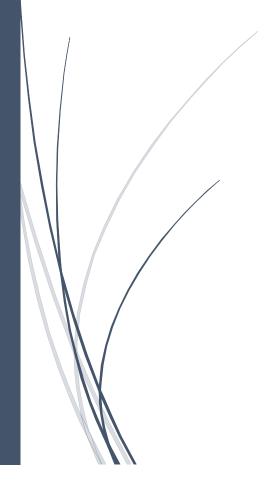
4/26/2023

# Lab2

Embedded C Lesson 3



Mostafa Mohamed Edrees LEARN-IN-DEPTH

# Lab2

# **Required:**

WRITE BAREMETAL SW ON ARM CORTEX-M3 32-BIT MICROCONTROLLER STM32F103C8T6 CHIP TO TOGGLE LED.

# **Physical Board:**

STM32F103C6

# **Processor:**

**Arm CORTEX-M3** 

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# Introduction

Hello everyone, we will write a bare metal SW on STM32F103C6 Board and ARM CORTEX-M3 Processor to toggle led.

We will write this lab from scratch so we will write app.c, app.h, startup, linker\_script.ld and Makefile and we will run this lab on Proteus and debug it on Proteus too.

#### ARM CORTEX-M3

We should know important information about this processor at first.

This processor when it is starts to work the PC (program counter) will point to the entry point and the entry point should contain the address of SP (stack pointer) so this processor initialize SP by itself without we write assembly code to do that so we can write startup code by C and put this code at the next address after the address that we put SP in it.

So we will do this lab with two versions:

1<sup>st</sup> Version: do this lab with **startup.s** 

2<sup>nd</sup> Version: do this lab with **startup.c** 

### Steps

Steps to do this lab:

- Write application file.
- Write startup.c or startup.s.
- Write linker script.
- Write makefile.
- Build the project by using makefile.
- Run the project on proteus.
- Debug the project on proteus.

#### Notes:

In the two versions we do the same thing so:

The application file will become common between the two versions.

So let's start to write application file.

### **Application File**

We want to write application to connect led to **GPIO\_PortA pin13** in **STM32F103C6** to toggle this led.

To Toggle Led we need to work with two peripherals:

- RCC (reset and clock control).
- GPIO (general purpose input/output).

We should open datasheet and get the base address of each peripheral:

- Base address of RCC is 0x40021000
- Base address of GPIO PortA is 0x40010800

#### RCC:

It has a bit2 (IOPAEN) in APB2ENR Register used to enable PortA.

Offset of APB2ENR Register is 0x18

Bit Number of IOPAEN is 2

#### GPIO\_PortA:

It has two regiseters:

CRH Register

We should write 2 "0010" on it from bit20 to bit24.

Offset of CRH Register is **0x04** 

ODR Register

It has pin13 that will connect led with it so we can turn on/off the led by sending 1/0 to this pin.

Offset of ODR Register is **0x0C** 

We will put a delay between turn on and turn off the led to notice the toggle.

We do the delay by using for loop.

#### Delay

#### Write app.h file

In this file we will put the definition of base addresses and registers.

#### app.h

```
1 -/**
     ************************
2
3
                    : app.h
     * @author
                   : Mostafa Edrees
4
                    : lab2 in lesson3 in Embedded C
     * @brief
5
     * @date
                    : 26/4/2023
6
     * @board
                    : STM32F103C8T6
7
     * @processor : ARM Cortex M3
8
     ****************************
10
11
12 #ifndef APP_H_
13 #define APP H
14
15
     //includes
16
    #include "Platform types.h"
17
18
     //Base Addresses
19
    #define RCC Base
                           0x40021000
20
    #define GPIO PA Base
                           0x40010800
21
22
     //APB2ENR Register and IOPAEN pin
23
     #define RCC APB2ENR *((vusint32 t *)(RCC Base + 0x18))
24
    #define RCC APB2ENR IOPAEN 2
25
26
    //CRH Register
     #define GPIO_PA_CRH
                      *((vusint32_t *)(GPIO_PA_Base + 0x04))
27
28
29 //ODR Register
30
    typedef union
31 🗖 {
        vusint32 t all fileds;
32
33
        struct
34
35
           vusint32 t reserved:13;
36
           vusint32 t pin 13:1;
37
        }Pins;
38
  -}R GPIO PA ODR t;
39
     //pointer to ODR Register
40
41
     volatile R GPIO PA ODR t *R ODR = (volatile R GPIO PA ODR t *) (GPIO PA Base + 0x0C);
42
43
44
     //Macro to SET & CLEAR bit
    #define SET_BIT(Register,BIT_NO) (Register |= (1 << BIT_NO))</pre>
45
    #define CLR BIT(Register, BIT NO) (Register &= (~(1 << BIT NO)))</pre>
46
47
48 L#endif
```

#### Write app.c file

In this file we will implement the application to toggle the led.

#### app.c

```
1 -/**
2
3
     * @file
                   : app.c
                   : Mostafa Edrees
4
    * @author
    * @brief
5
                   : lab2 in lesson3 in Embedded C
    * @date
                   : 26/4/2023
6
                    : STM32F103C8T6
7
    * @board
    * @processor : ARM Cortex M3
8
10 L**/
11
12 //includes
13 #include "Platform Types.h"
14 #include "app.h"
15
16 //to create .data & .rodata & .bss sections on memmory
                                               // 8Bytes
17  usint8 t g variables[] = "Mostafa";
usint8 t const const variables[] = " Edrees"; // 8Bytes
19 usint32 t uninitalized variables;
                                               // 4Bytes
20
21
   //main function
22 int main(void)
23 -{
24
        //set IOPAEN in APB2ENR Register
25
        SET BIT (RCC APB2ENR, RCC APB2ENR IOPAEN);
26
27
        //SET "Mode pin13 = 2" from bit20 to bit24 on CRH Register on GPIO PortA
28
        GPIO_PA_CRH &= 0xff0fffff; //zero bits from bit20 to bit24
29
        GPIO PA CRH |= 0x002000000; //put the value of bits from bit20 to bit24 = 2
30
31
        //toggle led
32
        while (1)
33 -
           34
35
36
           R ODR->Pins.pin 13 = 0;
                                        //turn off the led
           for(int i = 0; i < 5000; i++); //delay
37
38
        }
39
40
        return 0;
41 | -}
```

# Lab2 Version1

We will write Makefile & startup.s & linker\_script.ld files for this version then build the project by using make file then run it on proteus.

#### Makefile

In this file we write makefile to auto build the lab.

#### Makefile

```
#* @file
                : Makefile
                 : Mostafa Edrees
: lab2 in lesson3 in Embedded C
   #* @author
4 #* @brief
5 #* @date
                  : 26/4/2023
   #* @board : STM32F103C8T6
#* @processor : ARM Cortex M3
#* @level_debug : -gdwarf-2 to debug on proteus
   10
11 CC = arm-none-eabi-
12 CFLAGS = -gdwarf-2 -mcpu=cortex-m3 -mthumb
13
    INCS = -I .
14
15
    SRC = $(wildcard *.c)
16
   OBJ = $(SRC:.c=.0)
17 As = $ (wildcard *.s)
18 AsOBj = $(As:.s=.o)
19
20 Project_Name = learn-in-depth-Cortex-M3
    Copyrights = Mostafa Edrees
22 Board = STM32F103C8T6
23 Arm Processor = cortex-m3
24 date = 26/4/2023
25
26 all: $(Project_Name).bin
     @echo -e "\n*******************
27
       @echo -e "\tBuild is Done"
28
      @echo -e "Project Name:" $(Project_Name)
29
      @echo -e "Copyrights:" $ (Copyrights)
30
      @echo -e "date:" $(date)
31
32
      @echo -e "Board:" $(Board)
       @echo -e "Arm Processor:" $(Arm_Processor)
33
      34
35
36 startup.o: startup.s
37
      $(CC)as.exe $(CFLAGS) $< -o $@
38
39
    %.o: %.c
40
      $(CC)gcc.exe -c $(INCS) $(CFLAGS) $< -o $@
41
42
   $(Project Name).elf: $(OBJ) $(AsOBj)
43
      $(CC)ld.exe -T linker_script.ld $(LIBS) $(OBJ) $(AsOBj) -Map=Map_file.map -o $@
44
45
   $(Project_Name).bin: $(Project_Name).elf
46
      $(CC)objcopy.exe -0 binary $< $@
47
48
49 clean all:
50
     rm *.o *.elf *.bin
51
52 clean:
53 rm *.elf *.bin
```

### Startup.s

In this file we write startup code with assembly language.

#### startup.s

```
1
      *************************************
3
     * @file
                    : startup.s
4
     * @author
                  : Mostafa Edrees
5
     * @brief
                   : lab2 in lesson3 in Embedded C
6
    * @date
                   : 26/4/2023
    * @board
                    : STM32F103C8T6
8
     * @processor
                    : ARM Cortex M3
9
10
    **/
11
12 /* Entry point of SRAM is 0x20000000 */
13
14 .section .vectors
                                            /* .vectors section
                                                                         */
15
16 .word
              0x20001000
                                            /* address of sp (stack pointer)
17 .word
              Reset
                                            /* reset section
   .word
18
              Vector handler
                                           /* 2 NMI (non maskable interrupt) */
19 .word
                                           /* 3 Hard Fault
             Vector handler
             Vector handler
20 .word
                                           /* 4 MM Fault (Memory Management) */
21 .word Vector_handler
22 .word Vector_handler
                                          /* 5 Bus Fault
                                          /* 6 Usage Fault
                                           /* 7 RESERVED
                                                                         */
23 .word
             Vector handler
24 .word
             Vector handler
                                           /* 8 RESERVED
                                                                         */
   .word
            Vector_handler
                                           /★ 9 RESERVED
25
                                                                         */
                                           /* 10 RESERVED
                                                                         */
26 .word
             Vector handler
27 .word
             Vector handler
                                           /* 11 SV call
                                                                         */
28 .word Vector_handler
29 .word Vector_handler
                                          /* 12 Debug reserved
                                                                         */
                                          /* 13 RESERVED
                                           /* 14 PendSV
                                                                         */
30 .word
             Vector handler
31 .word
             Vector handler
                                           /* 15 SysTick
                                                                         */
             Vector handler
    .word
32
                                           /* 16 IRQ0
33 .word Vector_handler
                                           /* 17 IRQ1
                                                                         */
            Vector_handler
Vector_handler
                                           /* 18 IRO2
34 .word
35 .word
                                           /* 19 ...
                     /* On to IRQ67 */
36
37
38
39 .section .text
                                            /* .text section
40
     Reset:
41
                                            /* reset section
42
        bl main
43
        b.
44
45 .thumb func
                                            /* enable 16 bit instructions
                                                                          */
46
47
   Vector Handler:
                                            /* vector handler section
                                                                        */
48
       b Reset
```

# Linker\_script.ld

In this file we write linker\_script but in this file we will but .data section in FLASH and don't copy it to RAM and we don't initialize .bss section in RAM with zero we will do this in Lab2\_Version2.

#### linker\_script.ld

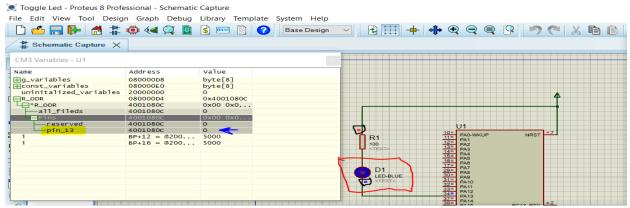
```
1 /**
2
   ********************
                 : linker script.ld
                 : Mostafa Edrees
  * @author
                 : lab2 in lesson3 in Embedded C
5
  * @brief
6 * @date
                 : 26/4/2023
7 * @board
                 : STM32F103C8T6
                 : ARM Cortex M3
8
  * @processor
9
  *******************
10 **/
11
12 MEMORY
13 {
14
      FLASH (rx): ORIGIN = 0x08000000, LENGTH = 128k
15
      SRAM (rwx) : ORIGIN = 0x20000000, LENGTH = 20k
16
17
18
19 SECTIONS
20 {
21
      .text :
22
23
         *(.vectors*)
24
        *(.text*)
25
      }> FLASH
26
27
      .data :
28
29
         *(.data)
      }> FLASH
31
      .rodata :
32
33
34
         *(.rodata)
35
      }> FLASH
36
37
      .bss :
38
39
         *(.bss)
40
      }> SRAM
41 }
```

# Build the project

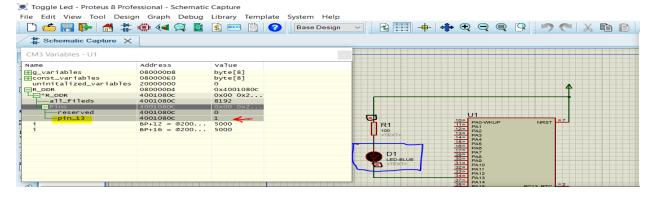
We will build the project by using Makefile.

### Run the project on Proteus

#### led is turn on:



#### Led is turn off:



You can see the video of running project from this link:

# **Video**

## Lab2 Version2

We will modify something in Makefile and write startup.c & linker\_script.ld files for this version then build the project by using make file then run it on proteus and debug it on proteus.

#### Makefile

We will delete this two lines from Makefile because we will write startup code with C.

```
startup.o: startup.s
$(CC)as.exe $(CFLAGS) $< -o $@</pre>
```

#### <u>Makefile</u>

```
2 #* Ofile : Makefile
   #* @author : Mostafa Edrees
#* @brief : lab2 in lessor
#* @date : 26/4/2023
#* @board : STM32F103C8T6
#* @processor : ARM Cortex M3
                     : Mostafa Edrees
: lab2 in lesson3 in Embedded C
5 #* @date
 6 #* @board
   #* @processor : ARM Cortex M3
#* @level debug : -gdwarf-2 to debug on proteus
8
9 #**********************
    CC = arm-none-eabi-
12 CFLAGS = -gdwarf-2 -mcpu=cortex-m3 -mthumb
13 INCS = -I .
14
    LIBS =
    SRC = $(wildcard *.c)
15
16 OBJ = $(SRC:.c=.o)
17 As = $(wildcard *.s)
    AsOBj = $(As:.s=.o)
19
20 Project_Name = learn-in-depth-Cortex-M3
    Copyrights = Mostafa Edrees
21
22 Board = STM32F103C8T6
23 Arm Processor = cortex-m3
24 date = 26/4/2023
26 all: $(Project_Name).bin
     @echo -e "\n***********************
27
       @echo -e "\tBuild is Done"
@echo -e "Project Name:" $(Project_Name)
28
29
       @echo -e "Copyrights:" $(Copyrights)
30
31
       @echo -e "date:" $(date)
32
33
       @echo -e "Board:" $(Board)
@echo -e "Arm Processor:" $(Arm_Processor)
       @echo -e "***************************
34
35
36
37 %.o: %.c
38
       $(CC)gcc.exe -c $(INCS) $(CFLAGS) $< -o $@
39
40 $(Project_Name).elf: $(OBJ) $(AsOBj)
       $(CC)ld.exe -T linker script.ld $(LIBS) $(OBJ) $(AsOBj) -Map=Map file.map -o $@
41
42
    $(Project_Name).bin: $(Project_Name).elf
43
       $(CC)objcopy.exe -0 binary $< $@
44
45
46
47 clean_all:
       rm *.o *.elf *.bin
48
49
      rm *.elf *.bin
51
```

#### startup.c

```
* @file
                           : startup.c
         * @author
                                 : Mostafa Edrees
 5
         * @brief
                               : lab2 in lesson3 in Embedded C
        * @date
                                 : 26/4/2023
        * @board
                               : STM32F103C8T6
        * @processor
                                 : ARM Cortex M3
                                                      10
      //includes
11
       #include "Platform_Types.h"
       extern int main(void);
14
15
       extern usint32_t _stack_top;
16
17
       //Vector Handler
18
       void Reset Handler(void);
19
       void NMI_Handler(void) __attribute__((weak,alias("Default_Handler")));
       void Hard Fault_Handler(void) _attribute_ ((weak,alias("Default_Handler")));
void MM_Fault_Handler(void) _attribute_ ((weak,alias("Default_Handler")));
void Bus_Fault_Handler(void) _attribute_ ((weak,alias("Default_Handler")));
void Usage_Fault_Handler(void) _attribute_ ((weak,alias("Default_Handler")));
20
21
24
25
26
        vusint32 t vectors[] attribute ((section(".vectors"))) =
27
28
     ₩ {
              (vusint32_t) &_stack_top,
              (vusint32_t) &Reset_Handler,
(vusint32_t) &NMI_Handler,
29
              (usint32_t) &Hard_Fault_Handler,
(usint32_t) &MM_Fault_Handler,
31
32
             (usint32_t) &Bus_Fault_Handler,
(usint32_t) &Usage_Fault_Handler
34
36
       extern usint32_t _E_text;
      extern usint32 t E text;
extern usint32 t S data;
extern usint32 t E data;
extern usint32 t S rodata;
extern usint32 t E rodata;
extern usint32 t S bss;
extern usint32 t E bss;
38
39
40
41
42
43
44
4.5
       void Reset Handler (void)
46
    ₩ (
47
48
             int i;
49
50
             //copy .data section from flash to ram
51
             usint32 t DATA size = (usint8 t *) & E data - (usint8 t *) & S data ;
             usint8 t *P src = (usint8 t *) & E text;
usint8 t *P dst = (usint8 t *) & S data;
52
             for (i = 0; \bar{i} < DATA size; \bar{i}++)
54
             {
                   *((usint8_t *)P_dst++) = *((usint8_t *)P_src++);
56
57
59
             //locate .bss section in ram and initalize it with zero
60
             usint32_t BSS_size = (usint8_t *)&_E_bss - (usint8_t *)&_S_bss ;
61
             P dst = (usint8 t *) & S bss ;
62
             for(i = 0; i < BSS_size; i++)</pre>
63
64
                   *((usint8 t *)P dst++) = (usint8 t)0;
65
66
67
             //iump to main()
68
             main();
69
70
71
       void Default_Handler (void)
     □{
72
73
             Reset Handler();
74
75
```

#### In startup.c:

- We put the address of SP (stack pointer) at the entry point of flash memory.
- We copy .data section from FLASH to RAM.
- We locate .bss section in RAM and initialize it with zero.

### Linker script.ld

In this file we put symbols to define start and end of each section to use it to copy .data section from FLASH to RAM and locate .bss section in RAM.

```
MEMORY
13
    {
        FLASH (rx) : ORIGIN = 0 \times 080000000, LENGTH = 128k
15
        SRAM (rwx) : ORIGIN = 0x20000000, LENGTH = 20k
16
17
18
    SECTIONS
19
20
         .text :
21
22
            *(.vectors*)
23
            *(.text)
24
            . = ALIGN(4);
             E text = .;
25
        }> FLASH
26
27
28
         .data :
29
30
            . = ALIGN(4);
31
             S_data = . ;
            *(.data*)
32
33
            . = ALIGN(4);
             E data = . ;
34
        }> SRAM AT> FLASH
35
36
37
        .rodata :
38
39
            . = ALIGN(4);
             S_rodata = .;
40
41
            *(.rodata*)
42
            . = ALIGN(4);
43
             E rodata = . ;
44
        }> FLASH
45
46
         .bss :
47
48
            . = ALIGN(4);
49
             s_bss = .;
50
            *(.bss*)
51
            . = ALIGN(4);
            * (COMMON*)
52
53
            . = ALIGN(4);
             E_bss = .;
54
55
        }> SRAM
56
57
        . = ALIGN(4);
58
        . = . + 0 \times 1000 ;
59
        _stack_top = .;
60
```

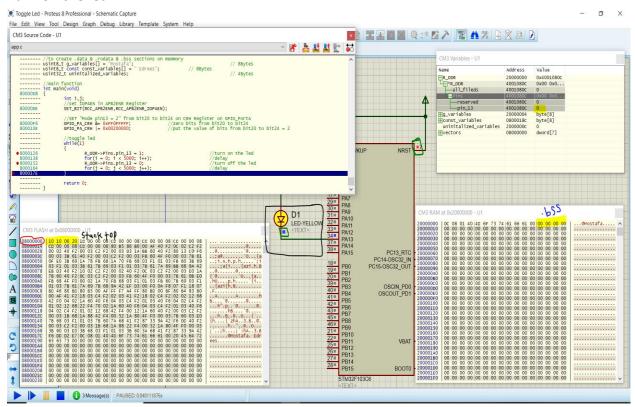
# Build the project

We will build the project by using Makefile.

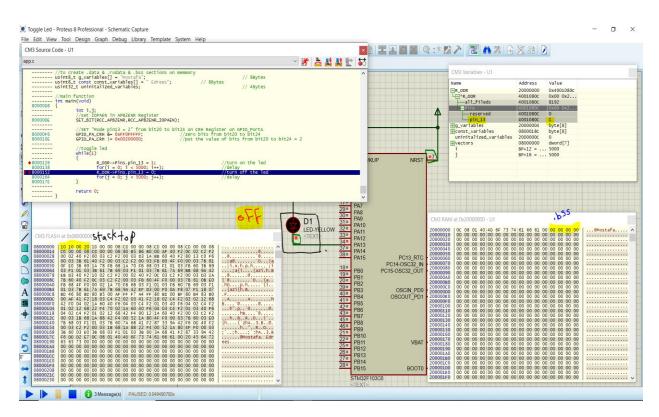
After that we will run & debug lab on Proteus.

## Run the project

#### Turn on the led



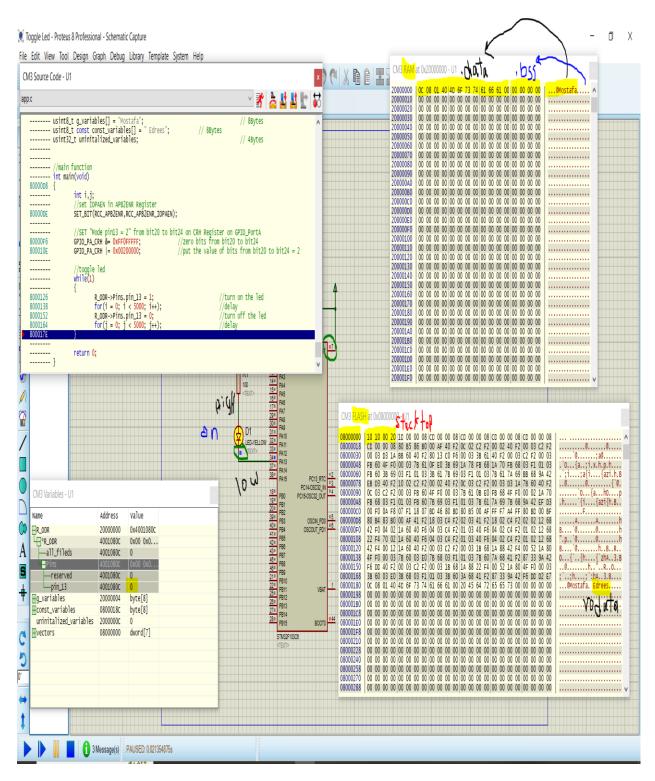
#### Turn off the led



### Debug the project

You can see the debug of the lab on proteus in this video:

# **Video**

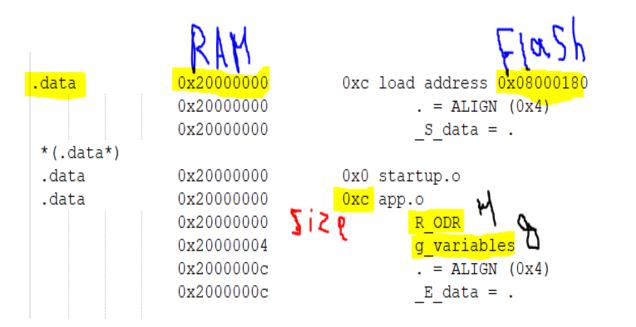


# **Analyze Mapfile**

Allaryze Maprile		
<u>Memory</u>		
Memory Configuration		
Name FLASH SRAM *default* .text section	Origin 0x08000000 0x20000000 0x00000000	Length Attributes 0x00020000 xr 0x00005000 xrw 0xffffffff
.text *(.vectors*) .vectors	0x08000000 0x08000000 0x08000000	0x180  0x1c startup.o  vectors
*(.text) .text	0x0800001c 0x0800001c 0x080000cc 0x080000cc 0x080000cc	0xbc <mark>startup.o</mark> Reset_Handler MM_Fault_Handler Bus_Fault_Handler Default_Handler Usage_Fault_Handler
.text	0x080000cc 0x080000cc 0x080000d8 0x080000d8 0x08000180	Hard_Fault_Handler NMI_Handler 0xa8 app.o main . = ALIGN (0x4)

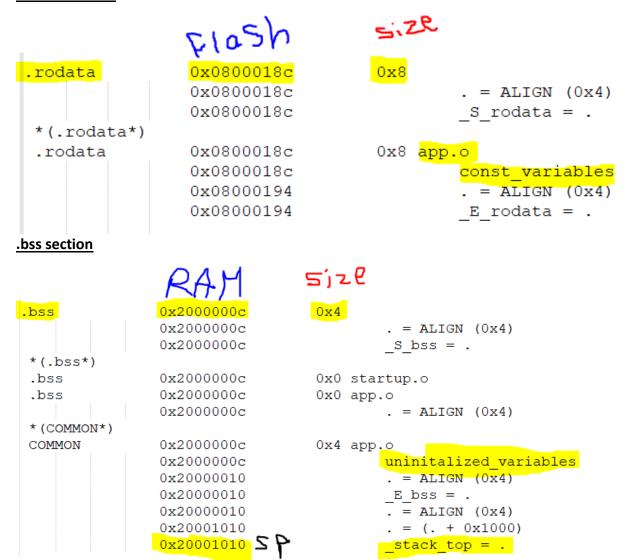
E text = .

.data section



0x08000180

#### .rodata section



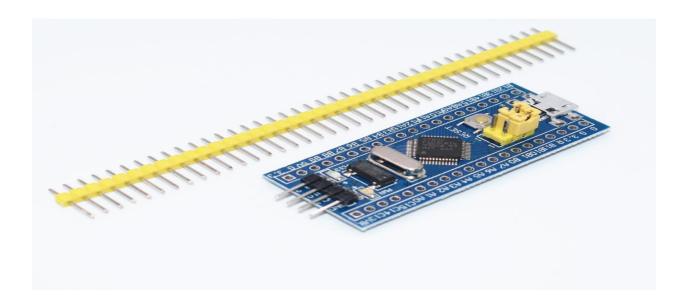
# Conclusion

After doing this lab we know important note:

"We can write startup code with C not only assembly."

### **Explanation:**

In some processor like CORTEX-M3 we should put address of SP (stack pointer) at the entry point of the program so the processor define SP without we write assembly code to do that so after this operation the CPU will understand C so we can write startup with C and put it after the address containing the address of SP if the processor don't have this feature we will write startup code with assembly and we will define SP by using assembly before we jump to main function.



# **Good Luck**