

A dark blue vertical bar on the left side of the slide. A blue arrow points to the right from the bar, containing the date.

4/23/2023

Lab1

Embedded C Lesson 3

Several thin, curved lines in dark blue and light grey originate from the bottom left corner and sweep upwards and to the right.

Mostafa Mohamed Edrees
LEARN-IN-DEPTH

Lab1

Required:

You have to create a bare metal Software to send a “learn-in-depth :< Your_Name >” using UART.

Physical Board:

VersatilePB

Processor:

Arm926ej-s

With debug information & Makefile.

Name:

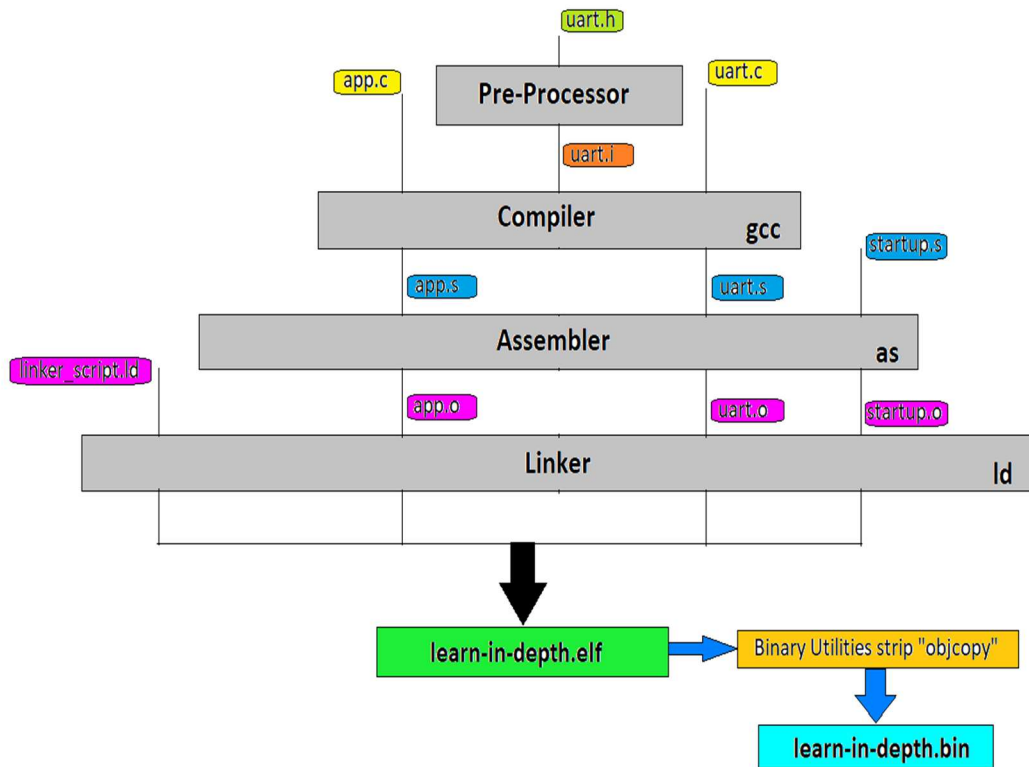
Mostafa Mohamed Edrees

Supervisor:

Eng. Keroles Shenouda

Steps:

- Create C code files. >> app.c , uart.c , uart.h
- Write Startup code file. >> startup.s
- Write Linker Script file. >> linker_script.ld
- Write Makefile to automate build.
- Build the program by Makefile.
- Run the program in the QEMU Simulator.
- Debug the program using gdb.
- Debug the program using eclipse.



Create C code files:

Uart.c

```
1  /**
2  ****
3  * @file      : uart.c
4  * @author    : Mostafa Edrees
5  * @brief     : lab1 in lesson2 in Embedded C
6  * @date      : 17/4/2023
7  * @board     : versatilePB physical board
8  ****
9  **/
10
11 #include "uart.h"
12 #include "Platform_types.h"
13
14 // Base Address of UART0:      0x101f1000
15 // Offset of Data Register(DR): 0x0
16 #define UART0DR *((volatile uint32_t *) (0x101f1000))
17
18 //P_tx_String >> Pointer to transmitting string
19 void UART0_Send_String(uint8_t * P_tx_String)
20 {
21     while(*P_tx_String != '\0') //loop to print all characters of the string
22     {
23         UART0DR = *P_tx_String; //send string to UART0 byte by byte
24         P_tx_String++; //next character
25     }
26 }
```

Uart.h

```
1  /**
2  ****
3  * @file      : uart.h
4  * @author    : Mostafa Edrees
5  * @brief     : lab1 in lesson2 in Embedded C
6  * @date      : 17/4/2023
7  * @board     : versatilePB physical board
8  ****
9  **/
10
11 #ifndef _UART_H_
12 #define _UART_H_
13
14 #include "Platform_types.h"
15
16 //UART0 API
17 void UART0_Send_String(uint8_t * P_tx_String);
18
19
20
21 #endif
```

App.c

```
1  /**
2  ****
3  * @file      : app.c
4  * @author    : Mostafa Edrees
5  * @brief     : lab1 in lesson2 in Embedded C
6  * @date      : 17/4/2023
7  * @board     : versatilePB physical board
8  ****
9  **/
10
11 #include "uart.h"
12 #include "Platform_types.h"
13
14 //String that will send to UART0
15 uint8_t String_Buffur[100] = "learn-in-depth:<Mostafa Mohamed Edrees>";
16
17 void main(void)
18 {
19     UART0_Send_String(String_Buffur);
20 }
21
```

Write Startup code file:

startup.s:

```
1  /**
2  ****
3  * @file      : startup.s
4  * @author    : Mostafa Edrees
5  * @brief     : lab1 in lesson2 in Embedded C
6  * @date      : 17/4/2023
7  * @board     : versatilePB physical board
8  ****
9  */
10
11 .globl reset
12
13 reset:
14     ldr sp, =0x00110000 //before linker
15     bl main
16
17 stop:
18     b stop
19
20
21
22
23
24 4: 4728203a      moveml    r4, #0
25 5: 2029554e      eorcs     r5, r9, lr, asr #10
26 6: 3e372e34      mrcs      r14, r1, r2, cr7, cr4, {1}
27 7: 10: Address 0x00000010 is out of bounds.
28
29
30 Disassembly of section .ARM.attributes:
31
32 00000000 <.ARM.attributes>:
```

Write Linker Script file:

Linker_script.ld

```
1  /**
2  ****
3  * @file      : linker_script.ld
4  * @author    : Mostafa Edrees
5  * @brief     : lab1 in lesson2 in Embedded C
6  * @date      : 17/4/2023
7  * @board     : versatilePB physical board
8  ****
9  */
10
11 ENTRY(reset)
12
13 MEMORY
14 {
15     Mem (rwx) : ORIGIN = 0x00000000 , LENGTH = 64M
16 }
17
18 SECTIONS
19 {
20     . = 0x10000;
21
22     .startup . :
23     {
24         startup.o(.text)
25     } > Mem
26     .text :
27     {
28         *(.text)
29     } > Mem
30     .date :
31     {
32         *(.date)
33     } > Mem
34     .bss :
35     {
36         *(.bss)
37     } > Mem
38
39     . = . + 0x1000; /* 1000 >> 4KB for stack */
40     stack_top = .;
41 }
42
```

After linker_script the addresses will be physical with SOC

We put address of `stack_top` at `startup.s` to put this address in stack pointer register (PC).

Startup.s

```
tenovo@MostafaEdrees MINGW32 /d/Mastering Embedded System/GitHub_Repo/Mastering_
Embedded_System_Online_Diploma/Embedded C/Lesson 2/Lab1 (master)
$ arm-none-eabi-nm.exe startup.o
U main
00000000 T reset
U stack_top
00000008 t stop

11  .globl reset
12
13  reset:
14      ldr sp, =stack_top //after linker
15      bl main
16
17  stop:
18      b stop
```

Write Makefile to automate build:

```
8
9 CC = arm-none-eabi-
10 CFLAGS = -g -mcpu=$(Arm_Processor)
11 INCS = -I .
12 LIBS =
13 SRC = $(wildcard *.c)
14 OBJ = $(SRC:.c=.o)
15 As = $(wildcard *.s)
16 AsOBJ = $(As:.s=.o)
17
18
19 Project_Name = learn-in-depth
20 Copyrights = Mostafa Edrees
21 date = 23/4/2023
22 Board = VersatilePB
23 Arm_Processor = arm926ej-s
24
25
26 all: learn-in-depth.bin
27     @echo -e "\n*****"
28     @echo -e "\tBuild is Done"
29     @echo -e "Project Name:" $(Project_Name)
30     @echo -e "Copyrights:" $(Copyrights)
31     @echo -e "date:" $(date)
32     @echo -e "Board:" $(Board)
33     @echo -e "Arm Processor:" $(Arm_Processor)
34     @echo -e "*****\n"
35
36
37 startup.o: startup.s
38     $(CC)as.exe $(CFLAGS) $< -o $@
39
40
41 %.o: %.c
42     $(CC)gcc.exe -c $(CFLAGS) $(INCS) $< -o $@
43
44
45 $(Project_Name).elf: $(OBJ) $(AsOBJ)
46     $(CC)ld.exe -T linker_script.ld $(OBJ) $(AsOBJ) -o $@
47
48
49 $(Project_Name).bin: $(Project_Name).elf
50     $(CC)objcopy.exe -O binary $< $@
51
52
53
54 clean_all:
55     rm *.o *.elf *.bin
56
57 clean:
58     rm *.elf .bin
```

Build the program by Makefile:

```
lenovo@MostafaEdrees MINGW32 /d/Mastering Embedded System/GitHub_Repo/Mastering_
Embedded_System_Online_Diploma/Embedded C/Lesson 3/Lab1 (master)
$ mingw32-make.exe all
arm-none-eabi-gcc.exe -c -g -mcpu=arm926ej-s -I . app.c -o app.o
arm-none-eabi-gcc.exe -c -g -mcpu=arm926ej-s -I . uart.c -o uart.o
arm-none-eabi-as.exe -g -mcpu=arm926ej-s startup.s -o startup.o
startup.s: Assembler messages:
startup.s: Warning: end of file not at end of a line; newline inserted
arm-none-eabi-ld.exe -T linker_script.ld app.o uart.o startup.o -o learn-in-dept
h.elf
arm-none-eabi-objcopy.exe -O binary learn-in-depth.elf learn-in-depth.bin

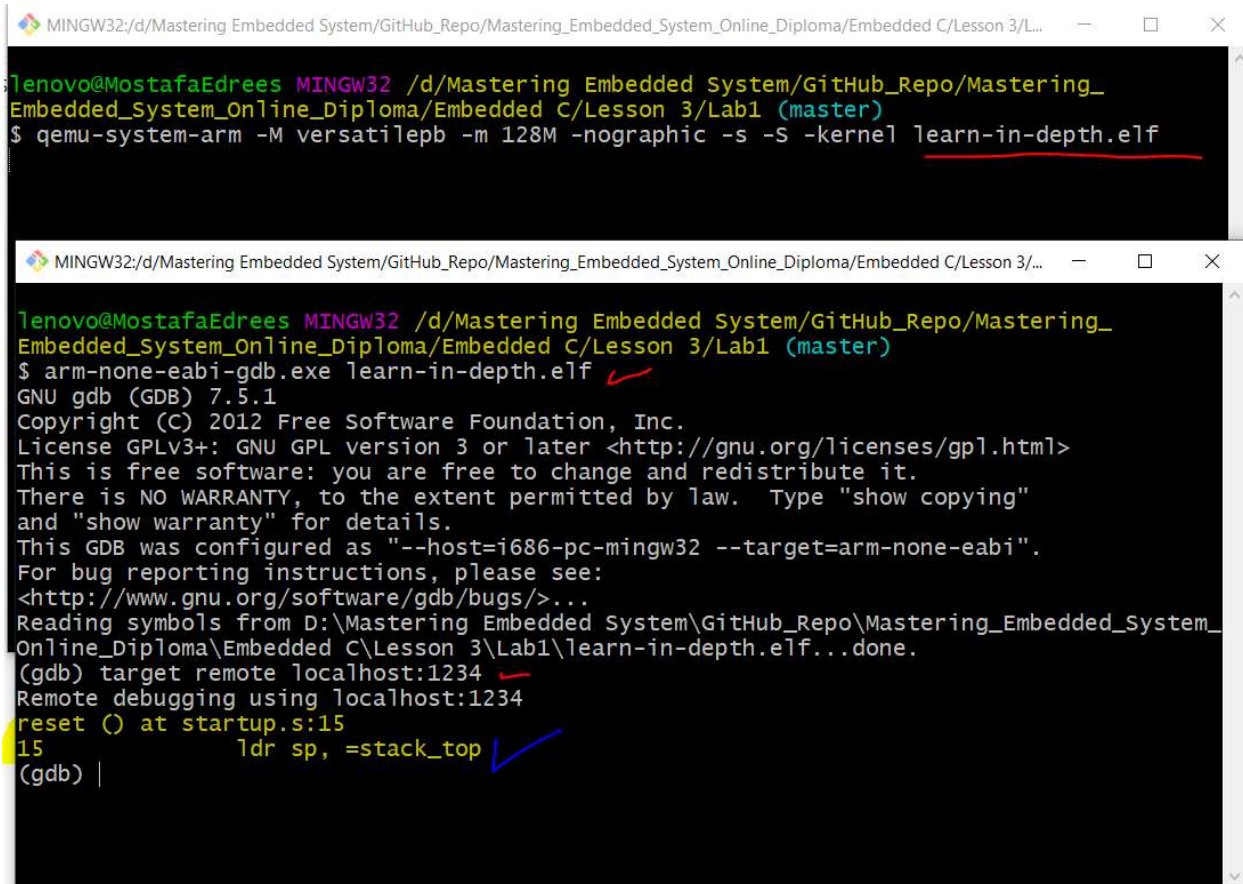
*****
      Build is Done
Project Name: learn-in-depth
Copyrights: Mostafa Edrees
date: 23/4/2023
Board: VersatilePB
Arm Processor: arm926ej-s
*****
```

Run the program in the QEMU Simulator:

```
lenovo@MostafaEdrees MINGW32 /d/Mastering Embedded System/GitHub_Repo/Mastering_
Embedded_System_Online_Diploma/Embedded C/Lesson 3/Lab1 (master)
$ qemu-system-arm -M versatilepb -m 128M -nographic -kernel learn-in-depth.bin
learn-in-depth<Mostafa Edrees>
```


Debug the program using gdb:

When we open the debug.

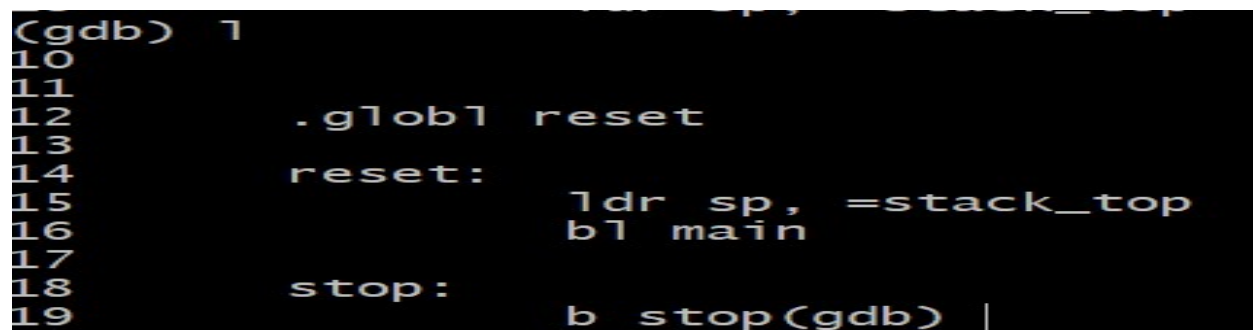


The first screenshot shows a terminal window with the command `qemu-system-arm -M versatilepb -m 128M -nographic -s -S -kernel learn-in-depth.elf` being executed. The second screenshot shows the GDB interface where the user has entered `arm-none-eabi-gdb.exe learn-in-depth.elf`, and the GDB version (7.5.1) and target configuration (`--host=i686-pc-mingw32 --target=arm-none-eabi`) are displayed. The user has also entered `target remote localhost:1234` and `reset () at startup.s:15`, which has been executed, showing the instruction `ldr sp, =stack_top`.

```
tenovo@MostafaEdrees MINGW32 /d/Mastering Embedded System/GitHub_Repo/Mastering_
Embedded_System_Online_Diploma/Embedded C/Lesson 3/Lab1 (master)
$ qemu-system-arm -M versatilepb -m 128M -nographic -s -S -kernel learn-in-depth.elf

tenovo@MostafaEdrees MINGW32 /d/Mastering Embedded System/GitHub_Repo/Mastering_
Embedded_System_Online_Diploma/Embedded C/Lesson 3/Lab1 (master)
$ arm-none-eabi-gdb.exe learn-in-depth.elf
GNU gdb (GDB) 7.5.1
Copyright (C) 2012 Free Software Foundation, Inc.
License GPLv3+: GNU GPL version 3 or later <http://gnu.org/licenses/gpl.html>
This is free software: you are free to change and redistribute it.
There is NO WARRANTY, to the extent permitted by law. Type "show copying"
and "show warranty" for details.
This GDB was configured as "--host=i686-pc-mingw32 --target=arm-none-eabi".
For bug reporting instructions, please see:
<http://www.gnu.org/software/gdb/bugs/>...
Reading symbols from D:\Mastering Embedded System\GitHub_Repo\Mastering_Embedded_System_
Online_Diploma\Embedded C\Lesson 3\Lab1\learn-in-depth.elf...done.
(gdb) target remote localhost:1234
Remote debugging using localhost:1234
reset () at startup.s:15
15          ldr sp, =stack_top
(gdb) |
```

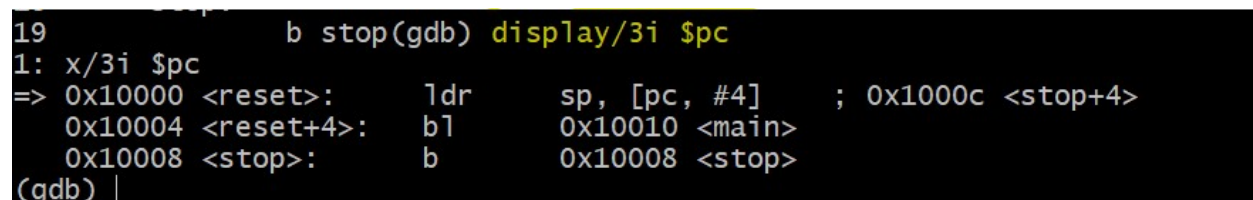
using "l" to print the code of file that we in it:



The screenshot shows the GDB interface with the command `l` entered, which displays the disassembly of the `reset` function. The disassembly shows the instructions `ldr sp, =stack_top` and `b1 main`.

```
(gdb) l
10
11
12          .globl reset
13
14          reset:
15              ldr sp, =stack_top
16              b1 main
17
18          stop:
19              b stop(gdb) |
```

using `display/3i $pc`




The screenshot shows the GDB interface with the command `display/3i $pc` entered, which displays the current instruction pointer (PC) and the next instructions. The output shows the PC at `0x10000` and the next instructions `ldr sp, [pc, #4]` and `b1 0x10010 <main>`.

```
19          b stop(gdb) display/3i $pc
1: x/3i $pc
=> 0x10000 <reset>:      ldr      sp, [pc, #4]      ; 0x1000c <stop+4>
    0x10004 <reset+4>:    b1       0x10010 <main>
    0x10008 <stop>:      b        0x10008 <stop>
(gdb) |
```

breakpoint at "UART0DR = *P_tx_String;"

```
(gdb) s
22          UART0DR = *P_tx_String; //send string character by character
1: x/3i $pc
=> 0x10044 <UART0_Send_String+20>:
    1dr r3, [pc, #48] ; 0x1007c <UART0_Send_String+76>
    0x10048 <UART0_Send_String+24>: 1dr r2, [r11, #-8]
    0x1004c <UART0_Send_String+28>: 1drb r2, [r2]
(gdb) b uart.c:22
Breakpoint 1 at 0x10044: file uart.c, line 22.
```

The string will be printed character by character and we use "c" to pause the breakpoint.

```
lenovo@MostafaEdrees MINGW32 /d/Mastering Embedded System/GitHub_Repo/Mastering_
Embedded_System_Online_Diploma/Embedded C/Lesson 3/Lab1 (master)
$ qemu-system-arm -M versatilepb -m 128M -nographic -s -S -kernel learn-in-depth.elf
1e| 

MINGW32:/d/Mastering Embedded System/GitHub_Repo/Mastering_Embedded_System_Online_Diploma/Embedded C/Lesson 3/L...
(gdb) c
Continuing.
Breakpoint 1, UART0_Send_String (
  P_tx_String=0x10081 <String_Buffer+1> "earn-in-depth<Mostafa Edrees>")
  at uart.c:22
22          UART0DR = *P_tx_String; //send string character by character
1: x/3i $pc
=> 0x10044 <UART0_Send_String+20>:
    1dr r3, [pc, #48] ; 0x1007c <UART0_Send_String+76>
    0x10048 <UART0_Send_String+24>: 1dr r2, [r11, #-8]
    0x1004c <UART0_Send_String+28>: 1drb r2, [r2]
(gdb) c
Continuing.
Breakpoint 1, UART0_Send_String (
  P_tx_String=0x10082 <String_Buffer+2> "arn-in-depth<Mostafa Edrees>")
  at uart.c:22
22          UART0DR = *P_tx_String; //send string character by character
1: x/3i $pc
=> 0x10044 <UART0_Send_String+20>:
    1dr r3, [pc, #48] ; 0x1007c <UART0_Send_String+76>
    0x10048 <UART0_Send_String+24>: 1dr r2, [r11, #-8]
    0x1004c <UART0_Send_String+28>: 1drb r2, [r2]
```

And we complete to print all characters of the string.

There are other commands like:

si , s , c , watch , print , where , info breakpoints ,

Debug the program using eclipse:

