

# ADC

## Type definitions:

<b>Name:</b>	<b>strGroupInfo</b>
<b>Type:</b>	structure
<b>Range:</b>	Implementation Specific
<b>Description:</b>	This type of the external data structure shall contain the initialization data for the ADC group.

For the type **strGroupInfo**, the definition for each Channel shall contain:

- Group id , it shall be unique.
- Conversion mode , one shot or continuous.
- Access mode, single access or streaming.
- Trigger , software or hardware.
- Hardware trigger source , in case of hardware trigger , it can be PWM or timer or comparator or GPIO pins.
- Number of streaming samples , started from 1.
- Array of the pins in the group

<b>Name:</b>	<b>strModuleInfo</b>
<b>Type:</b>	structure
<b>Range:</b>	Implementation Specific
<b>Description:</b>	This type of the external data structure shall contain the initialization data for the ADC module.

For the type **strModuleInfo**, the definition for each Channel shall contain:

- Module ID, it shall be unique , started from 0.

- Sequencer number , it can be 0,1,2,3.
- the sampling rate , it can be 125k , 250k, 500k, 1M.
- Number of input channels of the group which will parsed to this module.
- The group ID which will be parsed to this module with those specification.

<b>Name:</b>	<b>ADC_enumerr</b>		
<b>Type:</b>	Enumeration		
<b>Range:</b>	ADC_OKAY	0x00	The function is done without any error.
	ADC_NOTOKAY	0x01	The function contains an error.
<b>Description:</b>	This type is an indication for most of the functions if there's an error through the run time or not.		

<b>Name:</b>	<b>ADC_enumconv</b>		
<b>Type:</b>	Enumeration		
<b>Range:</b>	CONV_DONE	0x00	The conversion is done
	CONV_NOT_YET	0x01	Conversion in process
	error	0x02	There is an error during the conversion
<b>Description:</b>	This type is an indication for the ADC conversion.		

## Function definitions:

<b>Service name:</b>	<b>ADC_enuminit</b>	
<b>Syntax:</b>	ADC_enumerr ADC_enuminit(void);	
<b>Sync/Async:</b>	Synchronous	
<b>Arguments:</b>	None	
<b>Return value:</b>	ADC_enumerr	ADC_OKAY:No error. ADC_NOTOKAY:Error.
<b>Description:</b>	It initiate the ADC with the configuration chosen at config.h file and config.c	

<b>Service name:</b>	<b>ADC_enumSetBuffer</b>	
<b>Syntax:</b>	ADC_enumerr ADC_enumSetBuffer(u8 GP_ID, u32 * BufferPtr)	
<b>Sync/Async:</b>	Asynchronous	
<b>Arguments:</b>	GP_ID	Numeric ID of requested ADC channel group.
	BufferPtr	pointer to result data buffer
<b>Return value:</b>	ADC_enumerr	ADC_OKAY:No error. ADC_NOTOKAY:Error.
<b>Description:</b>	it gives for a certain group its buffer pointer to hold the converted values. * Note: it has to be called before the conversion	

<b>Service name:</b>	<b>ADC_enumInterrupt_Enable</b>	
<b>Syntax:</b>	ADC_enumerr ADC_enumInterrupt_Enable(u8 module_id);	
<b>Sync/Async:</b>	Asynchronous	
<b>Arguments:</b>	module_id	Numeric ID of requested ADC sequencer.
<b>Return value:</b>	ADC_enumerr	ADC_OKAY:No error. ADC_NOTOKAY:Error.

<b>Description:</b>	it enables the interrupt for a specific module "sequencer"
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<b>Service name:</b>	<b>ADC_vidStartConv</b>	
<b>Syntax:</b>	void ADC_vidStartConv(u8 module_id);	
<b>Sync/Async:</b>	synchronous	
<b>Arguments:</b>	module_id	Numeric ID of requested ADC sequencer.
<b>Return value:</b>	None.	
<b>Description:</b>	it starts the module conversion with the trigger chosen at config.c file. note: ADC_Interrupt_Enable has to be called first	

<b>Service name:</b>	<b>ADC_enumGetData</b>		
<b>Syntax:</b>	ADC_enumconv ADC_enumGetData(u8 group_ID);		
<b>Sync/Async:</b>	Asynchronous		
<b>Arguments:</b>	group_ID	Numeric ID of requested ADC channel group.	
<b>Return value:</b>	ADC_enumconv	CONV_DONE	Conversion is done , so it's ready to get the converted data.
		CONV_NOT_YET	Conversion is not done , so it's not to get the converted data.
		error	There is an error , maybe the group id is not exist.
<b>Description:</b>	It checks whether the conversion is done or not yet, and if it's done it moves the data from the FIFO to the group buffer.		