

German University in Cairo

Mechatronics Lab (MCTR704)

Size-Based Sorting Machine

Project No. [1]

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Project Description

The aim of the project is to sort two different sizes of objects by height using actuators and sensors. As shown in figure (a, b) and according to the numbering of figure (c): The objects will be supplied from the magazine (8) to the cylinder (1) where the cylinder will extend and feed the object to the position where height measuring will take place; In front of the wall, above the end effector (5). After the height is measured using the sensor, cylinder (3) will place the suitable chamber of end effector (6) under the hole made in the table. Then cylinder (2) (which is normally extended) will take action by retracting its end effector (5) exposing the whole and making the object fall in the chamber chosen by cylinder (3) where the objects will fall in end effector's (6) proper chamber. End effector (6) is a box with 2 chambers; one for the short objects and the other for the tall ones. The objects will keep on stacking above each other in the box as the process continues.

The signal of whether it's a short or tall object will come from 2 vertically collinear sensors: if only the lower sensor is sensing the object, its labeled as short; if both the sensors are sensing the object, its labeled as tall and actions are taken accordingly whether its short or tall as explained above.

Solid works Design: 3D Schematic Diagram

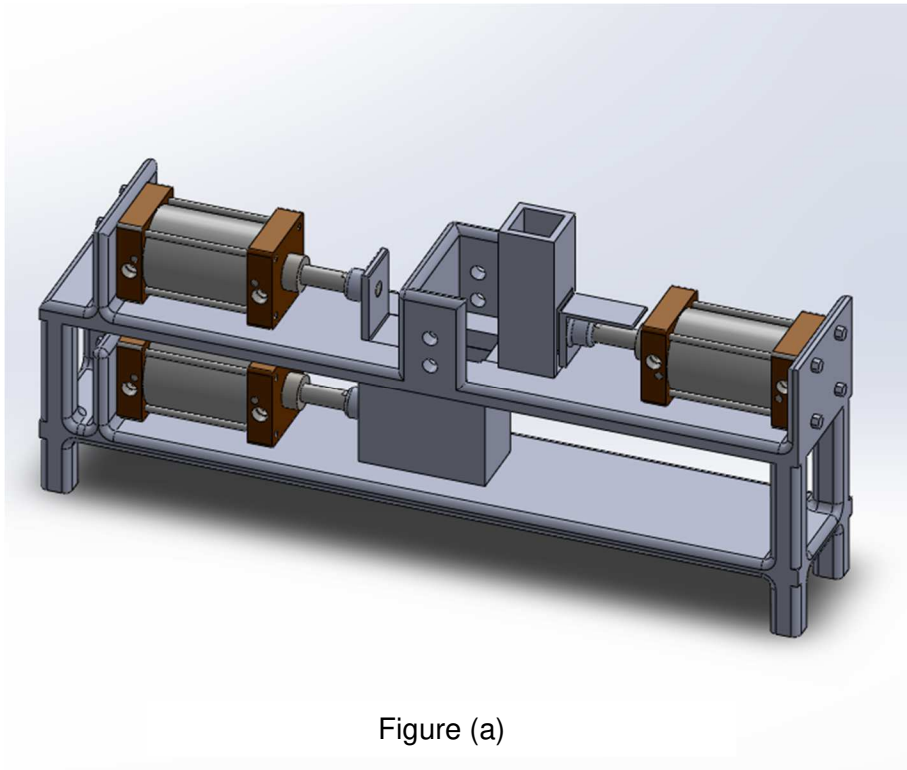


Figure (a)

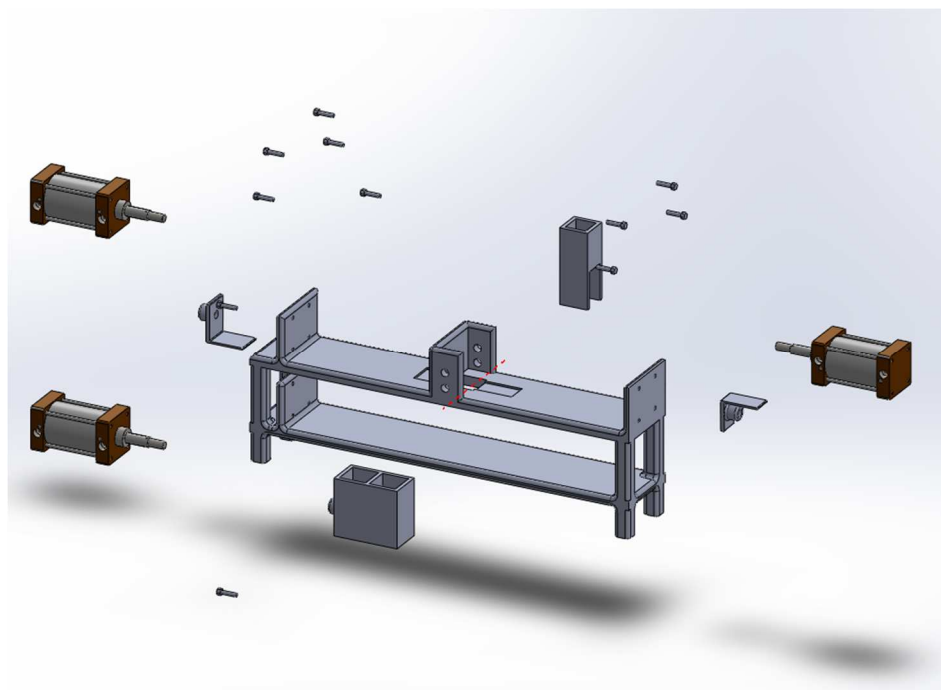


Figure (b)

Part number	Name
1	Single acting cylinder for feeding
2	First double acting cylinder for opening the hole that the objects will fall from
3	Second double acting cylinder that adjusts the right chamber of box (6) according to the object's height
4	End effector of feeding cylinder
5	End effector of cylinder (2) acting as a gate for the hole
6	End effector of cylinder (3) where the objects will get sorted
7	Table where the whole system is mounted
8	Magazine used as a storage to feed the system with objects that will be sorted
0	screws

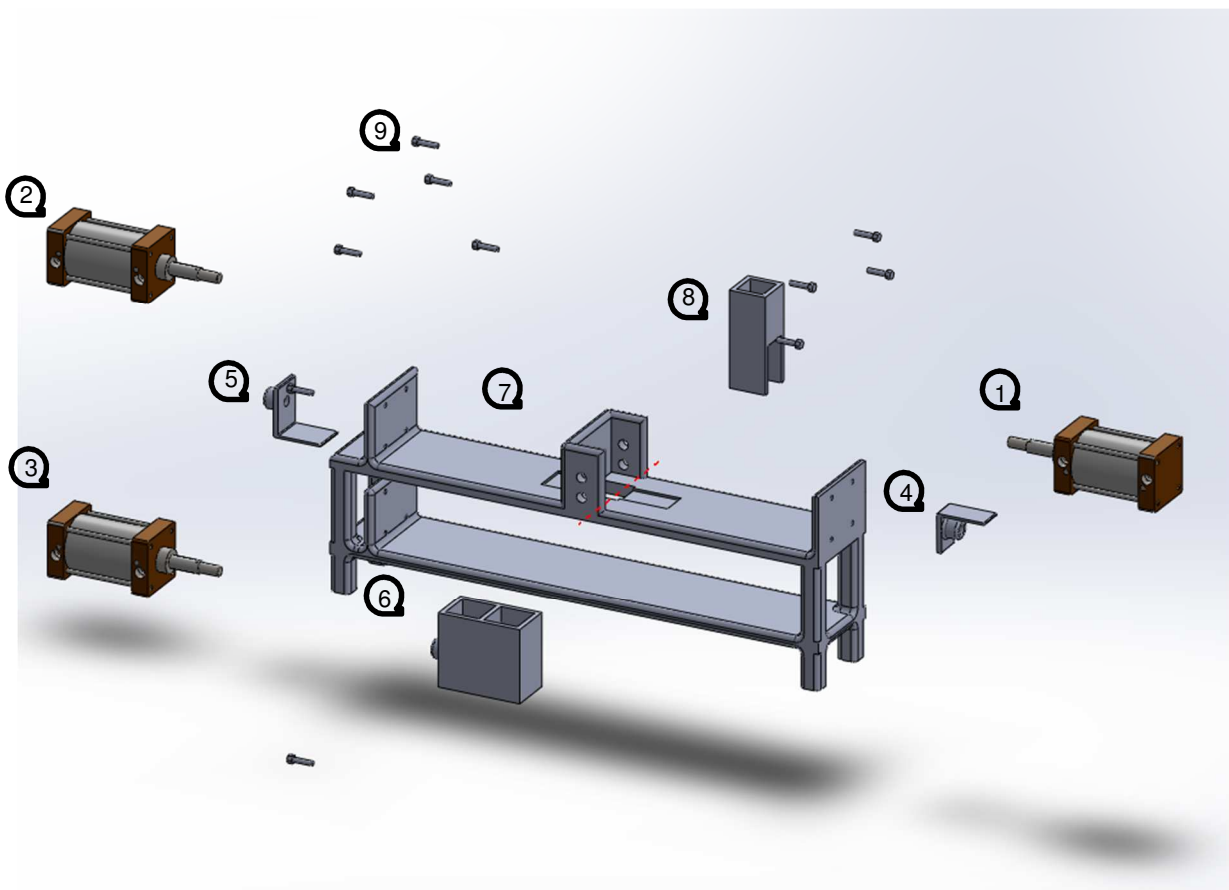
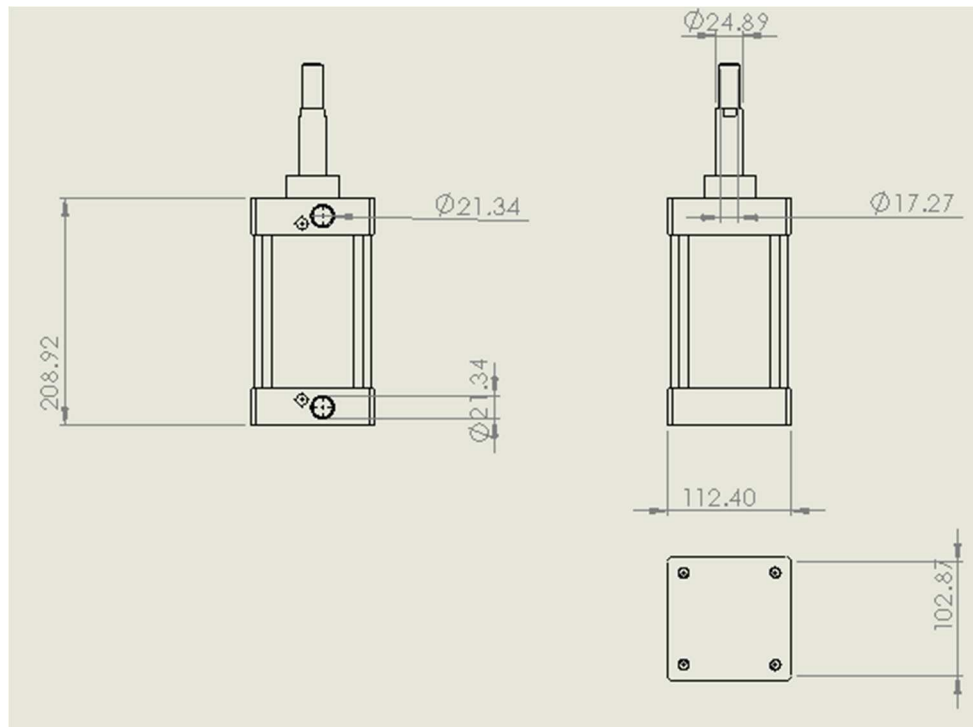


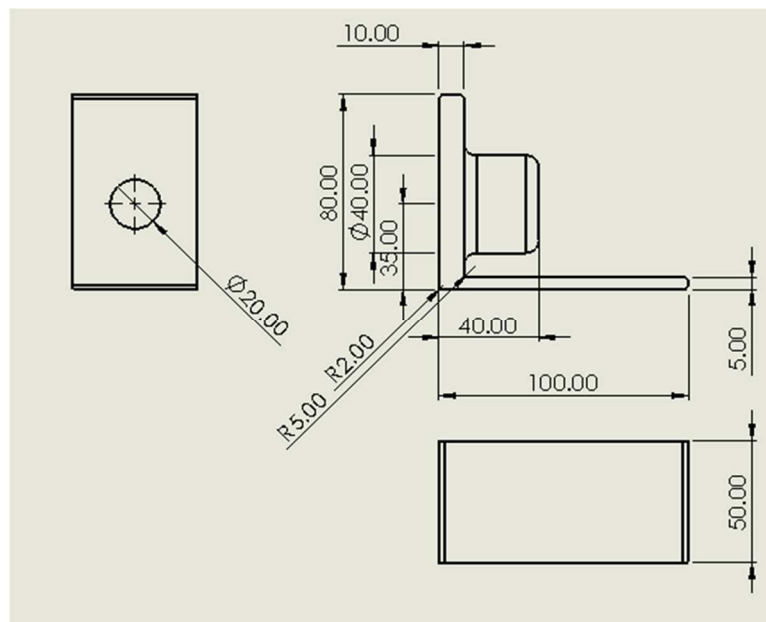
Figure (c)

Mechanical Components 2D Projections with Dimensions

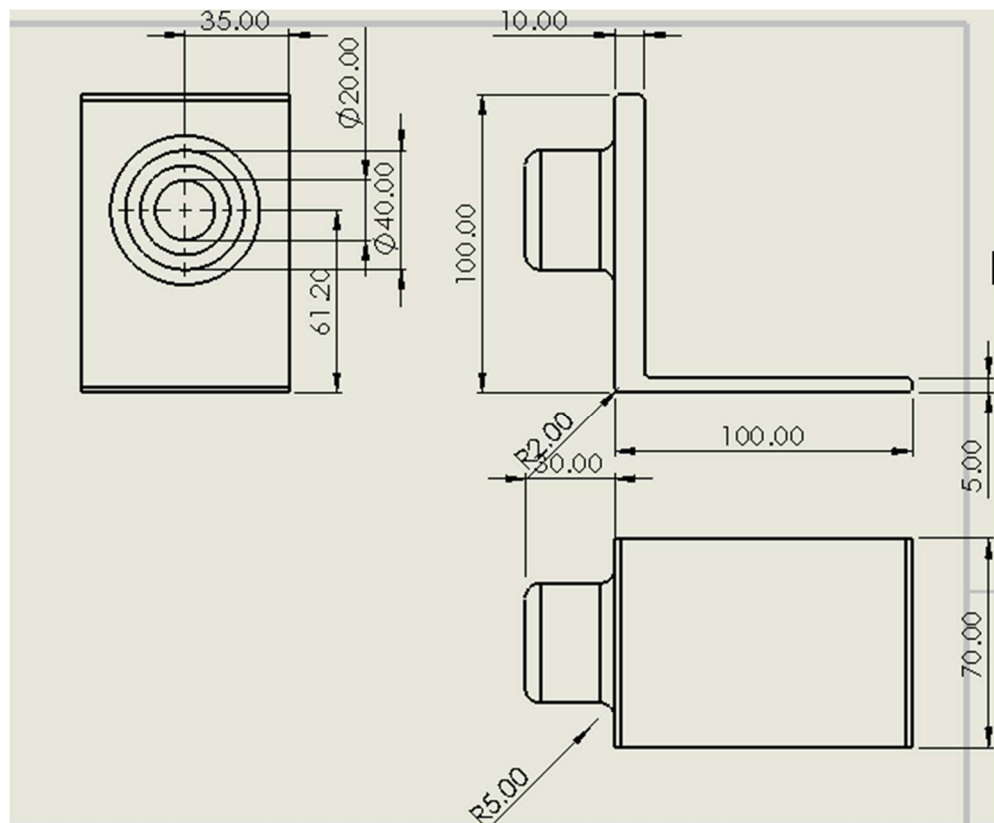
Cylinders parts (1,2,3)



End effector part 4



End effector part 5



End effector part 6

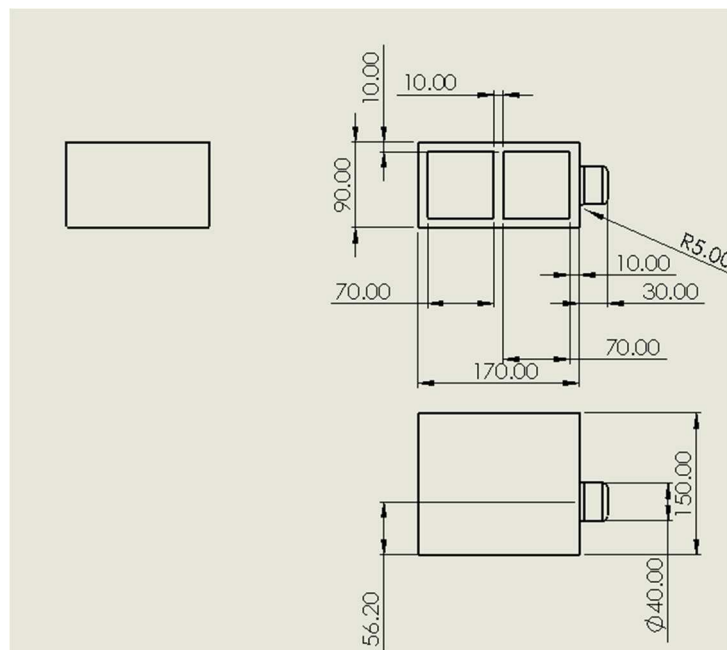
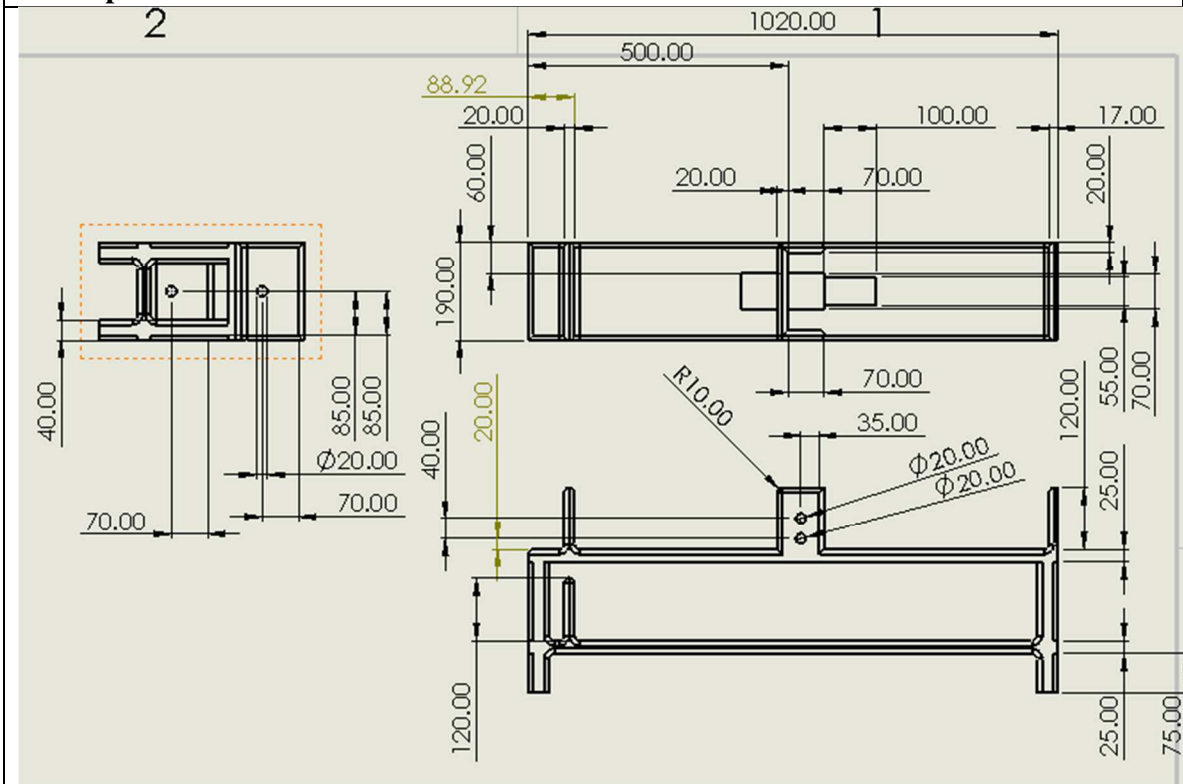
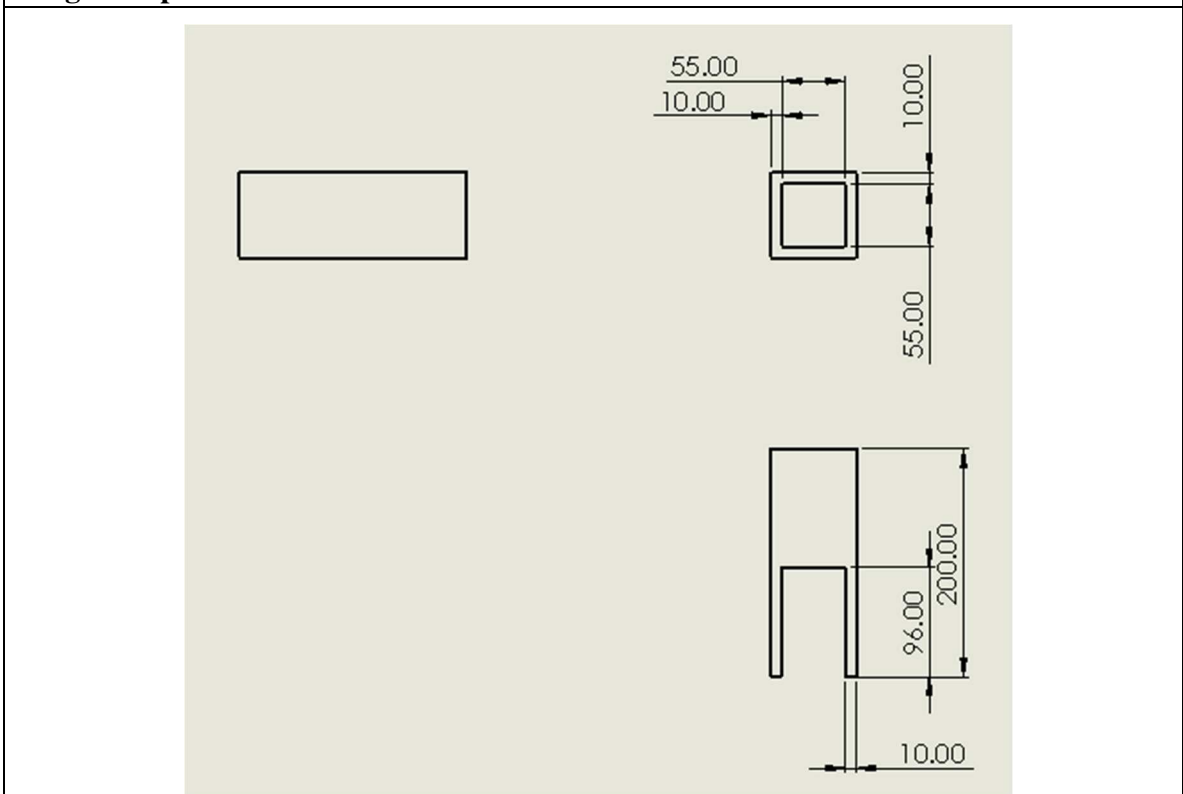


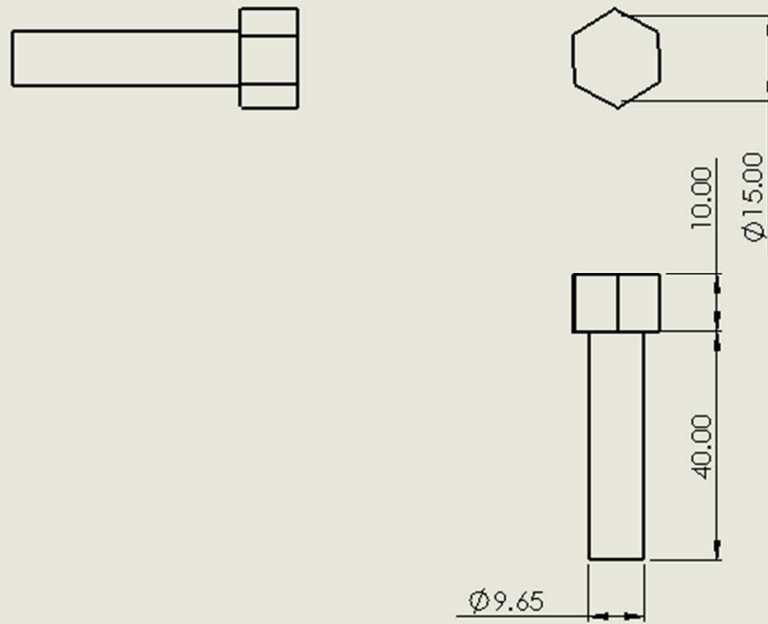
Table part 7



Magazine part 8



Screw part 9



Project Components list and PDF Description

Components	Quantity
16x100 Pneumatic Cylinder	3
24V Relay	8
Reed Switch	6
IR Sensor	2
5/2 way Solenoid Valve	3

Pneumatic Cylinder



The cylinders will be used to feed the pieces and direct them to their designated places, hence a low-pressure cylinder will be used.

Specifications

Bore size [mm]		8	10	12	16	20	25
Type	Pneumatic						
Action	Double acting, Double rod						
Fluid	Air						
Proof pressure	1.5 MPa						
Max. operating pressure	1.0 MPa						
Min. operating pressure	Rubber bumper	0.1 MPa	0.08 MPa		0.05 MPa		
	Air cushion	—	0.08 MPa		0.05 MPa		
Ambient and fluid temperature	Without auto switch: -20 °C to 80 °C (No freezing)						
	With auto switch: -10 °C to 60 °C (No freezing)						
Lubricant	Not required (Non-lube)						
Stroke length tolerance	+1.0 0 mm					+1.4 0 mm	
Piston speed	50 to 1500 mm/s						
Cushion	Rubber bumper						
	—	Air cushion					
Allowable kinetic energy	Rubber bumper	0.02 J	0.03 J	0.04 J	0.09 J	0.27 J	0.4 J
	Air cushion	—	0.17 J	0.19 J	0.4 J	0.66 J	0.97 J

Standard Strokes

Bore size [mm]	Standard stroke [mm] ^{*2+4}	Max. stroke ^{*3} [mm]
8 ^{*1}	10, 25, 40, 50, 80, 100	100
10	10, 25, 40, 50, 80, 100, 125, 160, 200	200
12	10, 25, 40, 50, 80, 100, 125, 160, 200	200
16	10, 25, 40, 50, 80, 100, 125, 160, 200, 250, 300	500
20	10, 25, 40, 50, 80, 100, 125, 160, 200, 250, 300	500
25	10, 25, 40, 50, 80, 100, 125, 160, 200, 250, 300	500

*1 Not available with air cushion.

*2 Other strokes are available on request.

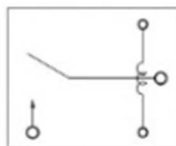
*3 For exceeding the standard stroke range, it will be available as a special order (-X2018).

*4 The minimum stroke with air cushion is 25 mm.

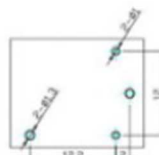
Universal Relay 24 VDC 10 A 4 Pins



The relays will be used for each reed switch and sensor to be able to observe and control the position of the cylinders.



T73 Schematic H



T73 FOOT DIMENSION H



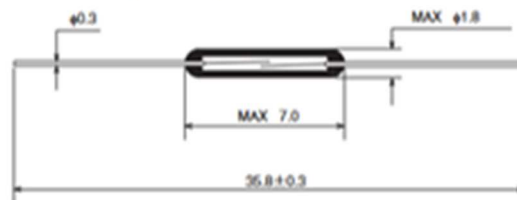
Pins.....	4
Outline Dimension.....	19 * 15.5 * 15 mm
Contact form.....	1a
Contact form (resistance).....	10A 240 VAC / 125VAC / 28VDC
Coil voltage (DC).....	24 V
Coil power (DC).....	0.36 W
Close voltage	≤ 75% V
Release voltage	≥ 10% V
Strength between Contacts	1000 VAC/min
Strength Contacts and coils	1500 VAC/min
Contact resistance	≤ 50 mΩ
Insulation resistance	≥ 500 mΩ
Ambient temperature	-40 - 70 Celsius degree
Mechanical life	10.000.000 times/OPC
Electrical life	100.000 times/OPC
Mounting form	PCB
Weight	0.0078 KG
Application.....	Mete , Range hood
Operation temperature and humidity.....	- 40 ~ 70 degree Celsius ; 35% ~ 85% RH
Storage temperature and humidity	0 ~ 70 degree Celsius ; 35% ~ 80% RH
Dimension drawing with tolerance	Out dimension ≤ 1 mm, Tolerance: ± 0.2 mm; ≤ 1~5 mm, Tolerance: ± 0.3 mm
.....	Out dimension > 5 mm, Tolerance: ± 0.4 mm
Tolerance of mounting hole.....	± 0.1 mm

Reed Switch



The reed switch is needed to be able to know if the cylinders are completely extended or retracted.

■ EXTERNAL DIMENSIONS (Unit: mm)



■ APPLICATIONS

- Automotive electronic devices
- Control equipment
- Communication equipment
- Measurement equipment
- Household appliances

■ ELECTRICAL CHARACTERISTICS

Parameter	Rated value	Unit
Pull-in Value (PI)	10~40	AT
Drop-out Value (DO)	5min	AT
Contact resistance (CR)	200max	mΩ
Breakdown voltage	150min	VDC
Insulation resistance	10 ⁹ min	Ω
Electrostatic capacitance	0.4max	pF
Contact rating	1.0	VA
Maximum switching voltage	24 ($\frac{DC}{AC}$)	V
Maximum switching current	0.1	A
Maximum carry current	0.3	A

IR Sensor



The IR sensors will be used to know whether the object is big or small.

Specifications

Parameter	typical	units
Number of thermojunctions	100	
Active area	0,5	mm ²
Die size	2,2 x 2,2	mm ²
Resistance of thermopile (Rth)	50±15	KΩ
Sensitivity	110±20	V/W ¹⁾
Temp. Coeff. Of sensitivity	-0,52±0,08	%/K
Specific Detectivity	2,1 * 10E8	cm.Hz ^{1/2} /W ¹⁾
noise equivalent power	0,35	nW ¹⁾
Noise voltage	37	nV/Hz ^{1/2}
Time constant	40±10	ms (63%)
Temperature range (sensor)	-20 - + 100	°C
Storage temperature	-40 - +100	°C
Filter (high pass)	5,5	μm
¹⁾ at 500 K dc		
Reference Thermistor (SMTIR9902 only)		
Resistance	1,000 ±0,004	KΩ (@ 0 °C

5/2 Way Solenoid Valve



This valve controls the cylinders (extend or retract) when operated by the solenoid.

Technical data	
Orifice	DN 6.0
Body material	PA (Polyamide)
Seal material	NER
Media	Lubricated and non-lubricated dry air; neutral gases (10 µm-fiber)
Media temperature	-10 to +50 °C
Ambient temperature	-10 to +55 °C
Manual override	As a standard feature
Port connection	Flange for MP12 (please see illustration)
Pneumatic module	Type MP12 with G 1/8, Push-in connection Ø 8 mm
Voltage	24 V DC
Voltage tolerance	±10%
Nominal power	2W, 1W
Duty cycle	Continuous operation (100%)
Electrical connection	Tag connector acc. to DIN EN 175301-803 (previously DIN 43650) Form C Type 2506
Protection class	IP 65 (with cable plug)
Weight	95g
Mounting	with 2 screws M3x30
Installation	Any, preferably solenoid system upright

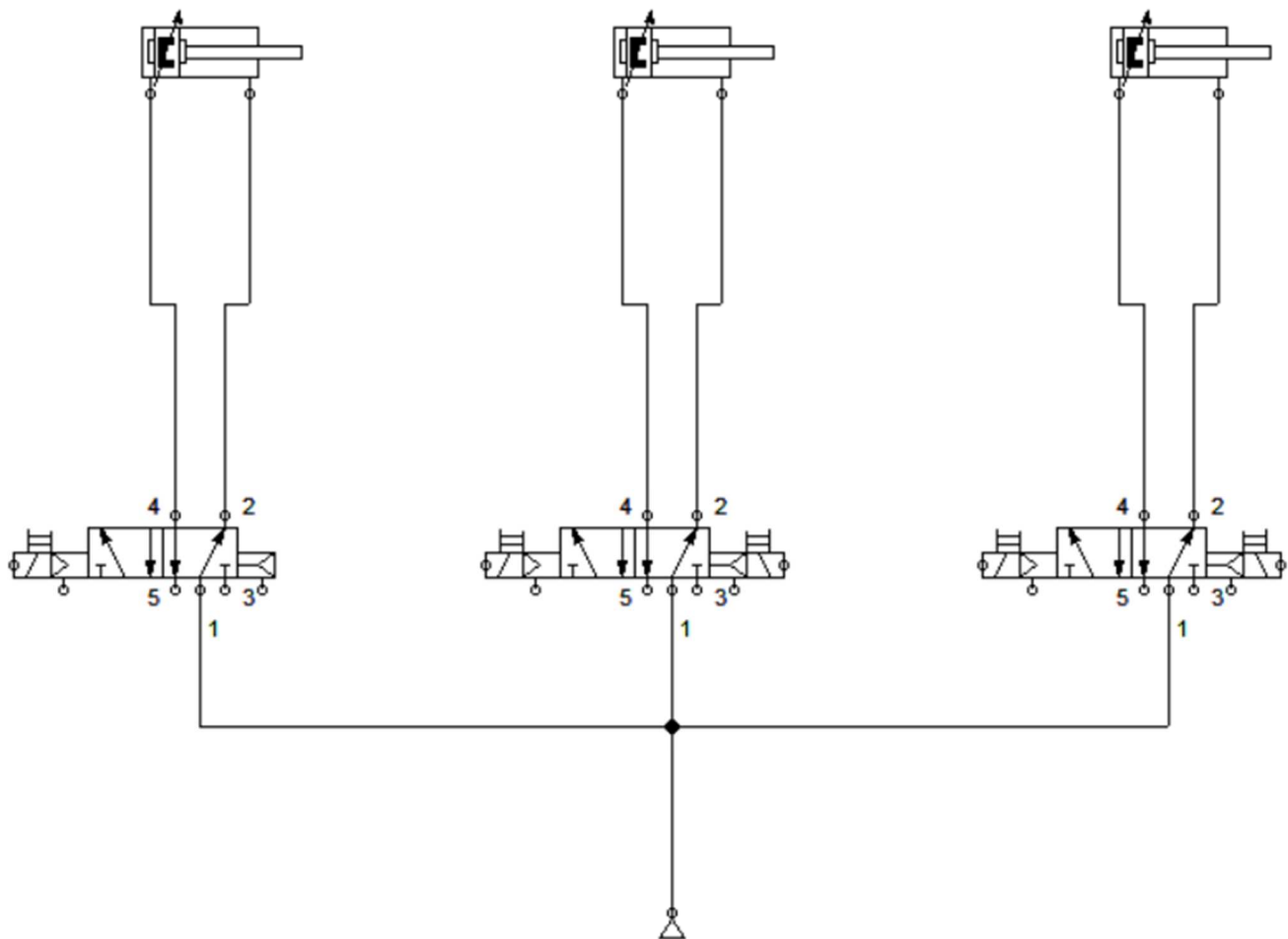
Module	Version	Feature	Item No.
Connection module	right	G 3/8	655 110
	left	NPT 3/8	655 112
Pneumatic basic module 2 valves	push-in connection Ø 8 mm	G 3/8	655 109
		NPT 3/8	655 111
		without check valve	156 517
		with integrated check valve with R-channel	156 519
	connection G 1/8	without check valve	156 522
		with integrated check valve with R-channel	156 520
		with integrated check valve with R and S-channel	156 535
		with integrated check valve with R and S-channel	156 533
	connection NPT 1/8	without check valve	156 531
		with integrated check valve with R-channel	156 537
		with integrated check valve with R and S-channel	156 534
Pneumatic basic module 4 valves	push-in connection Ø 8 mm	without check valve	156 532
		with integrated check valve with R-channel	156 565
		with integrated check valve with R and S-channel	156 562
		with integrated check valve with R and S-channel	156 569
	connection G 1/8	without check valve	156 567
		with integrated check valve with R-channel	156 563
		with integrated check valve with R and S-channel	156 560
		with integrated check valve with R and S-channel	156 568
	NPT 1/8	without check valve	156 564
		with integrated check valve with R-channel	156 561
		with integrated check valve with R and S-channel	156 566
Coaming plate		for unused valve positions	655 755

5/2-way solenoid valve without cable plug

Circuit function	Orifice [mm]	Q _N value air [l/min]	Pressure range [bar]	Power consumption [W]	Response times		Item no. 24 V DC
					Opening [ms]	Closing [ms] ¹⁾	
H 5/2-way valve 	6	700	1.0 - 10 ⁰	2	20	12	156 828
			1.0 - 10 ⁰	2	20	12	163 030 ¹⁾
			2.0 - 10	2	20	12	156 337
			2.0 - 10	2	20	12	156 842 ¹⁾
			2.0 - 8.0	1	20	17	156 827
			2.0 - 8.0	1	20	12	156 843 ¹⁾

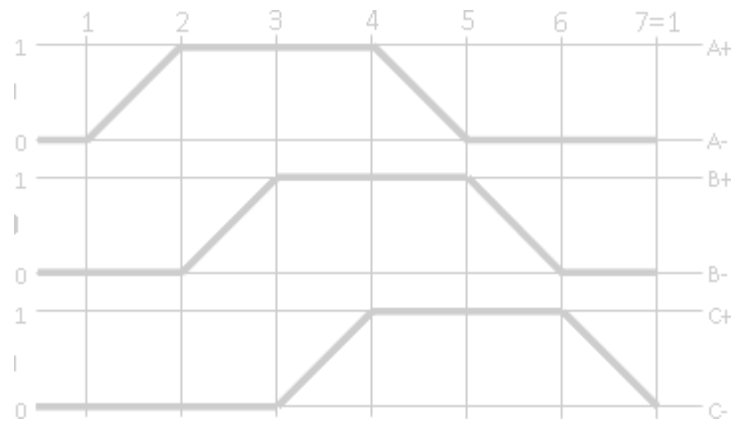
¹⁾Valve with auxiliary pilot air

Pneumatic Circuit



Pneumatic Step Diagram and Description

- Draw the pneumatic step diagram based on your project's operation, as shown in the example below.
- Explain your provided pneumatic step diagram; the sequence and the project's operation.
- Example for the pneumatic step diagram



Controller Operating Panel/ Classic Control Implementation

As you already have the information for each component (power supply, solenoids, relays, I/O terminals...), you can configure the size of the panel you need for your project. Implement the classic control by using the fluidSim software

An example for a panel configuration is shown below:

