# A simple multi-objective optimization problem







#### Introduction

Let's introduce a geometrical optimization problem, named **cones problem**, with the following characteristics:

- **multi-objective** problem (two objective functions): the solution is not a single optimum design, but instead it is represented by the set of designs belonging to the *Pareto frontier*
- simple mathematical formulation: easy and quick implementation from scratch of the relevant modeFRONTIER project
- constrained problem: objectives space and designs space present feasible and unfeasible regions





#### Problem definition

#### Right circular cone:

r =base radius

h = height

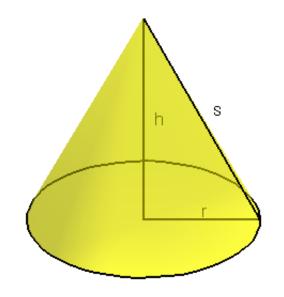
s =slant height

V = volume

B = base area

S =lateral surface area

T = total area



$$s=\sqrt{r^2+h^2}$$

$$V = \frac{\pi}{3} r^2 h$$

$$B = \pi r^2$$

$$S = \pi r s$$

$$T = B + S = \pi r (r + s)$$







# Cones problem

two input variables: r, h



The cone shape (i.e. the design) is defined univocally when both *r* and *h* are given.

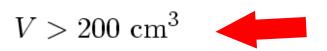
$$r \in [0, 10] \text{ cm} , h \in [0, 20] \text{ cm}$$

two objectives:

$$\min S$$
  
 $\min T$ 

We want to minimize both the lateral surface area and the total surface area

one constraint:



A constraint for the cone volume is given, in order to guarantee a minimum volume.







# Project building

Let's build from scratch the pertinent modeFRONTIER project:

- 1. Work Flow setup: fill the work canvas with the project's building blocks
- 2. Script Node setup: use your favourite math tool
  - Jython script
  - Matlab node
  - Excel Workbook node
  - OpenOffice Spreadsheet node

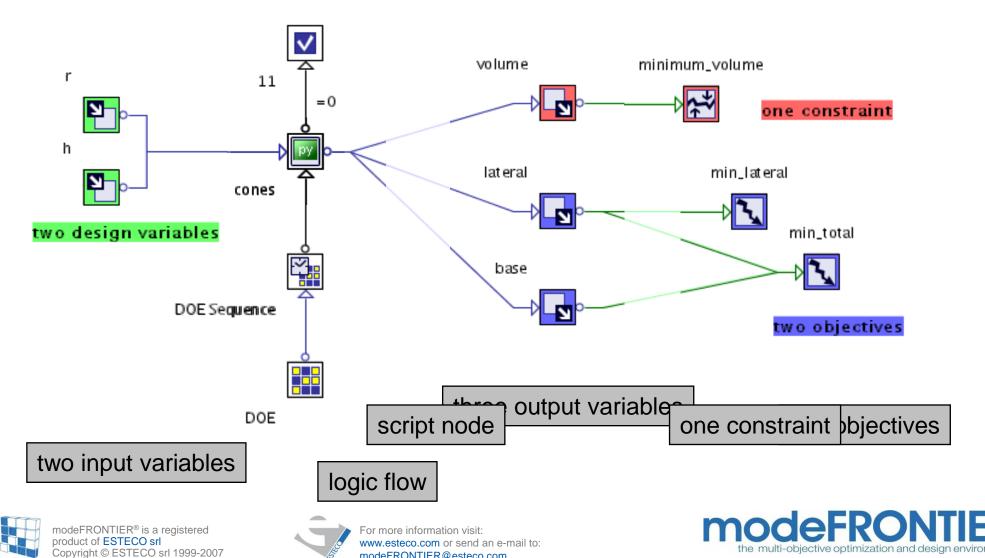






# Work Flow setup

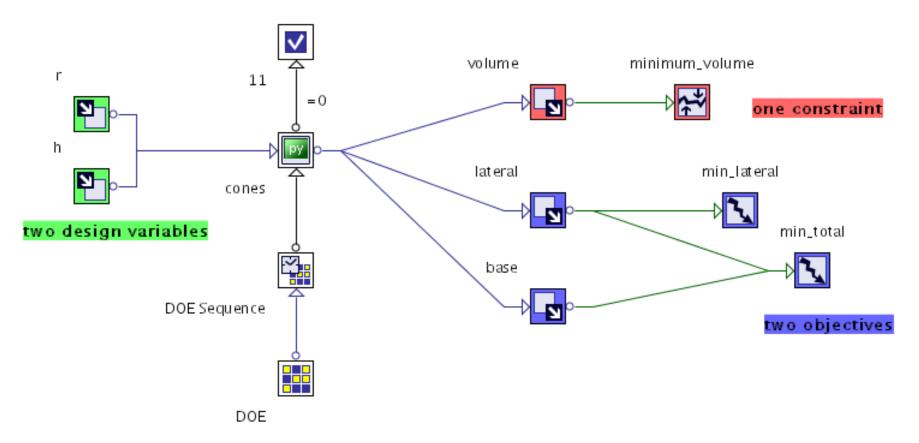
#### cones: two-objective optimization problem



modeFRONTIER@esteco.com

# Work Flow setup

#### cones: two-objective optimization problem





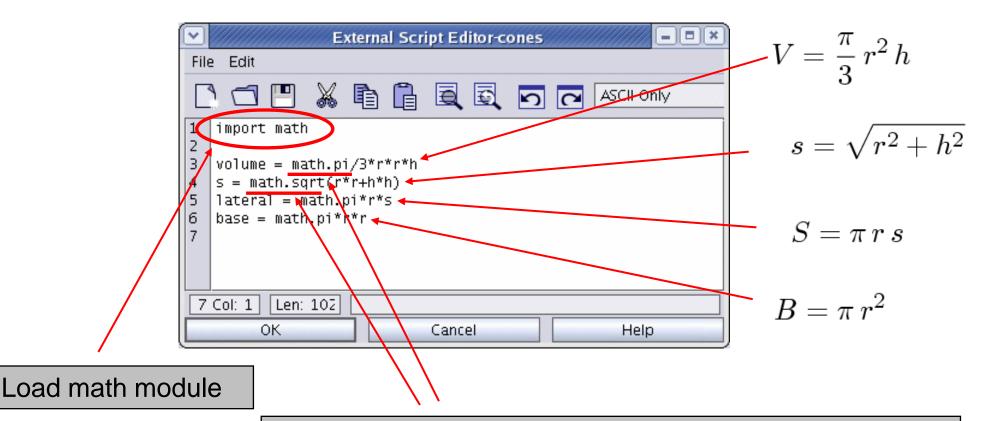


# Script node: Jython

Jython (Python) script case:



#### Write down the formulae



Note the syntax of mathematical functions and constants







# Script node: Matlab

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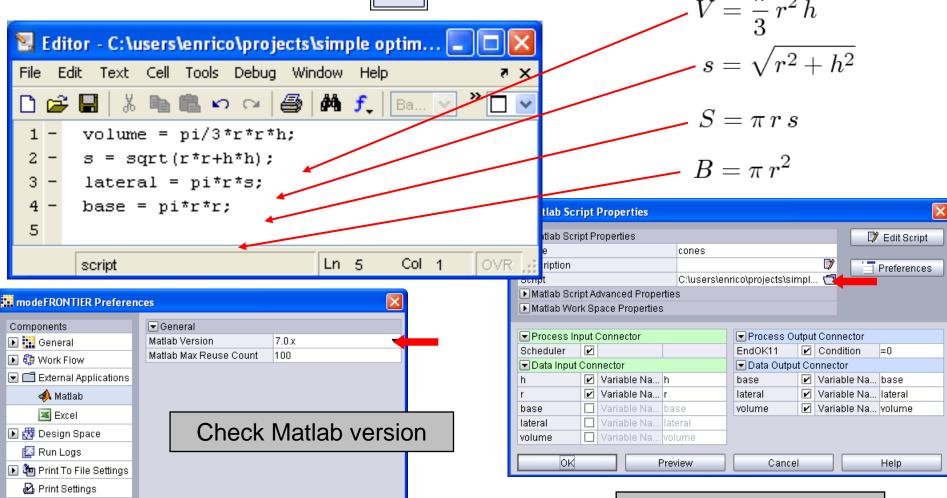
Matlab case:

Cancel



#### Write down the formulae

Load the matlab file



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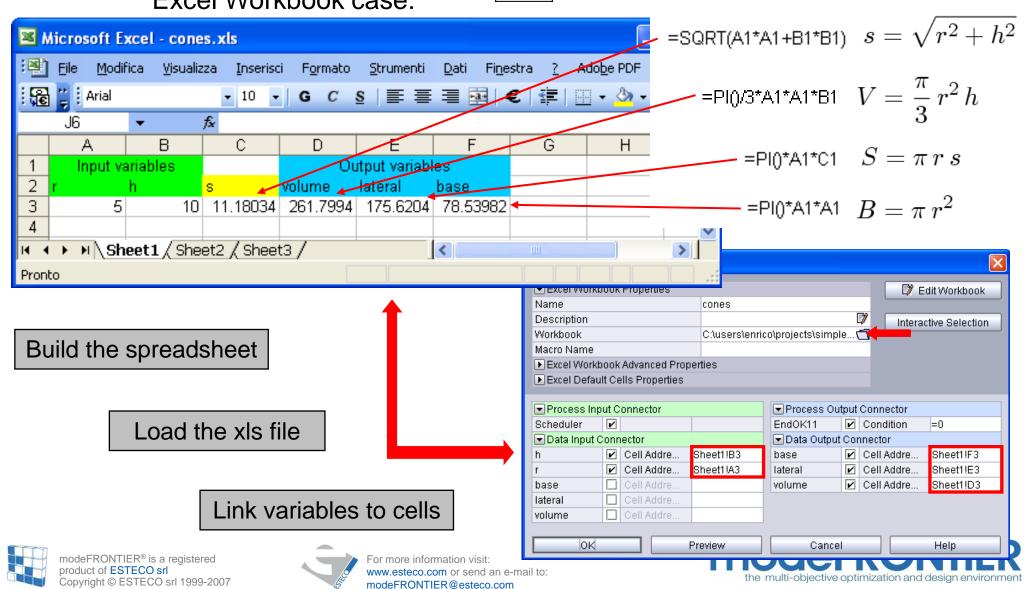
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## Script node: Excel



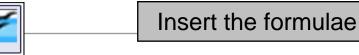
#### Insert the formulae

**Excel Workbook case:** 



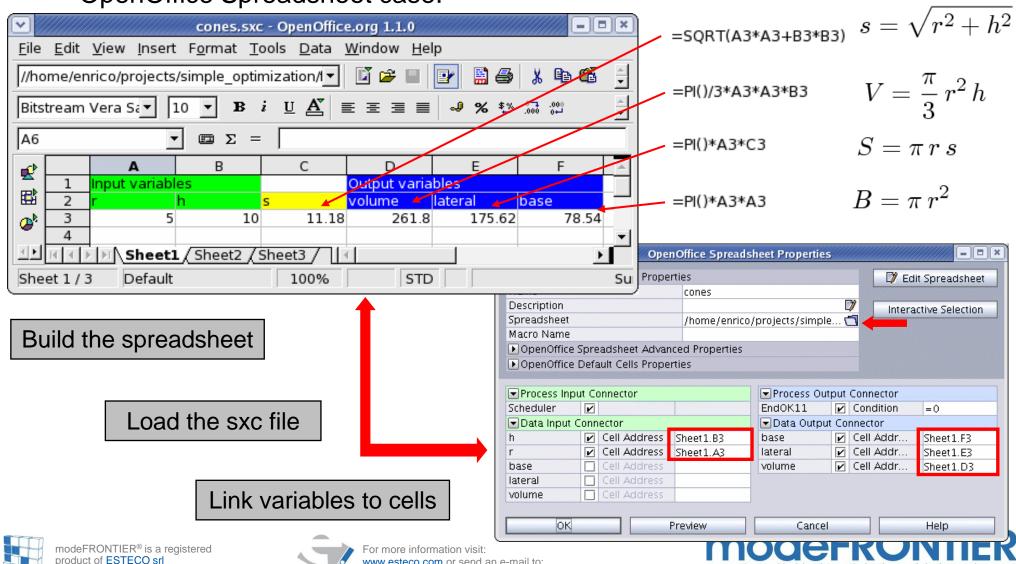
# Script node: OpenOffice

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the multi-objective optimization and design environment

OpenOffice Spreadsheet case:



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## Runs examples

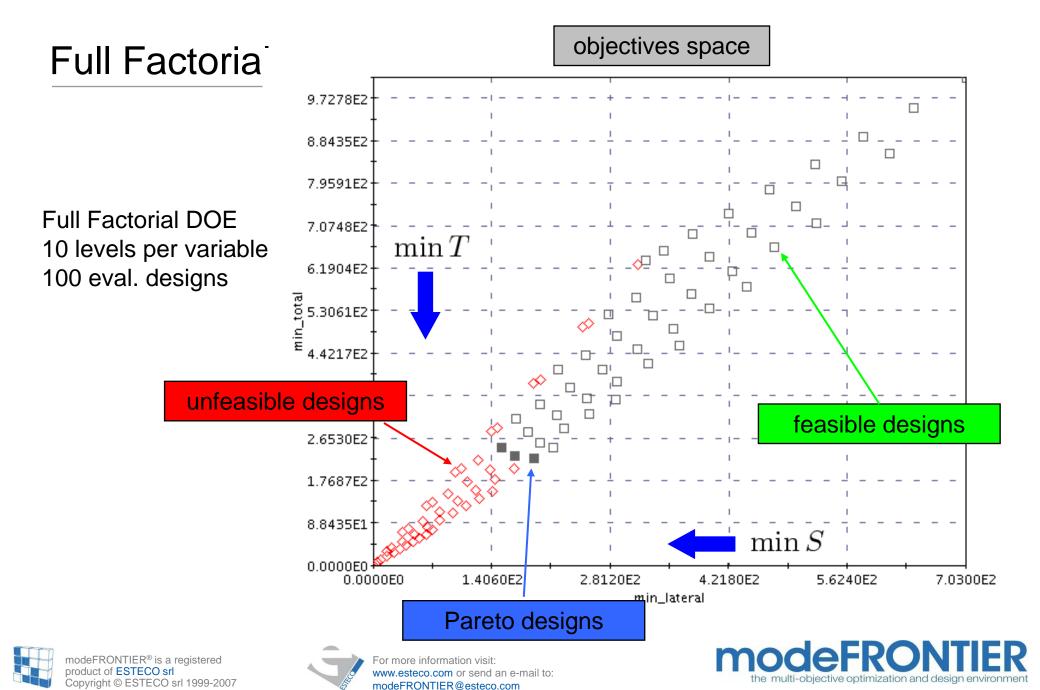
Let's see some examples of runs with different DOEs and/or schedulers:

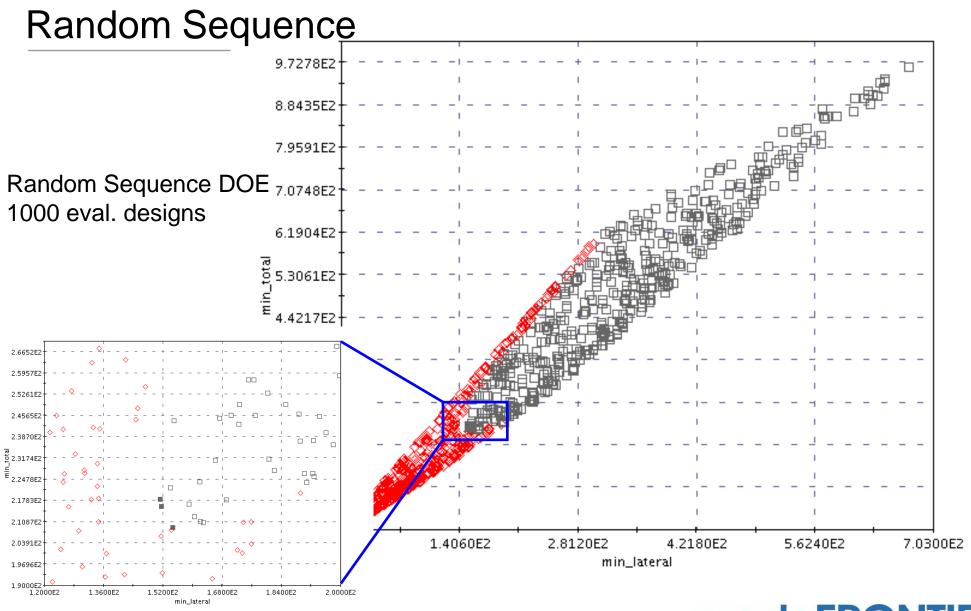
- Full Factorial DOE
- random samplings: Random Sequence and Sobol DOEs
- genetic algorithms: MOGA-II, NSGA-II
- MOSA
- NBI-NLPQLP











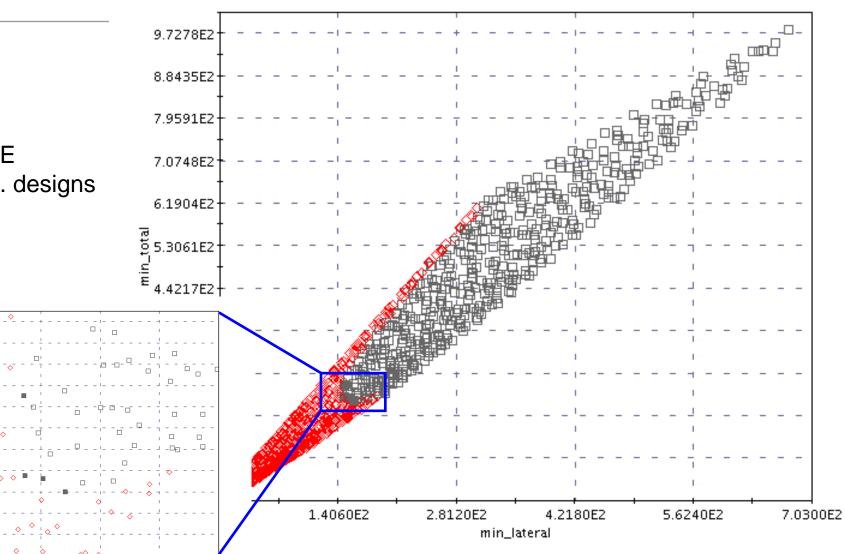






#### Sobol

Sobol DOE 1000 eval. designs





1.5200E2

2.1087E2

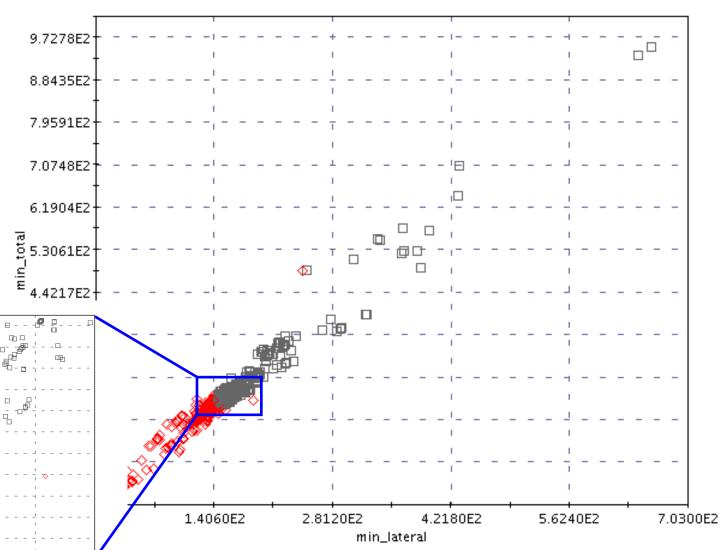


2.0000E2



#### **MOGA-II**

MOGA-II 20 individuals (Sobol) 50 generations 1000 eval. designs





1.5200E2

1.6800E2

2.6652E2 2.5957E2 2.5261E2 2.4565E2 2.3870E2 E 2.3174E2 E 2.2478E2 2.1783E2 2.1087E2

2.0391E2

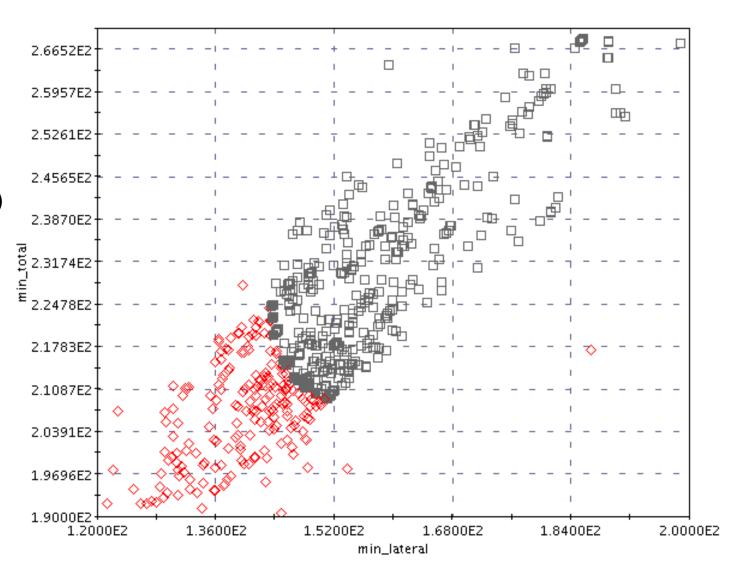


2.0000E2



## **MOGA-II**

MOGA-II 20 individuals (Sobol) 50 generations 1000 eval. designs



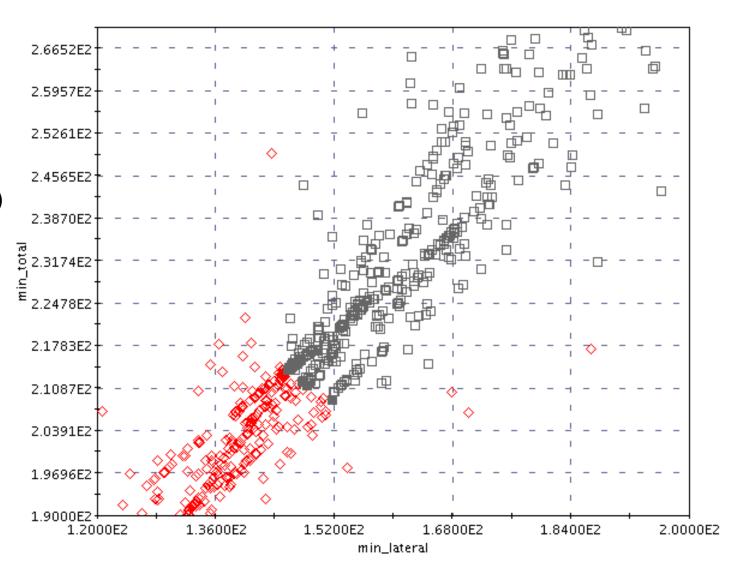






## **NSGA-II**

NSGA-II 20 individuals (Sobol) 50 generations 1000 eval. designs



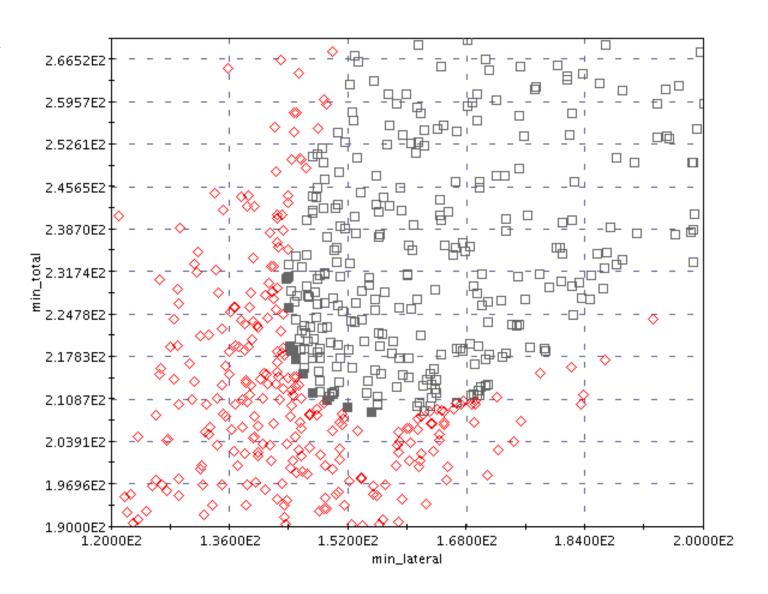






## MOSA

MOSA 10 points (Sobol) 100 iterations 1000 eval. designs



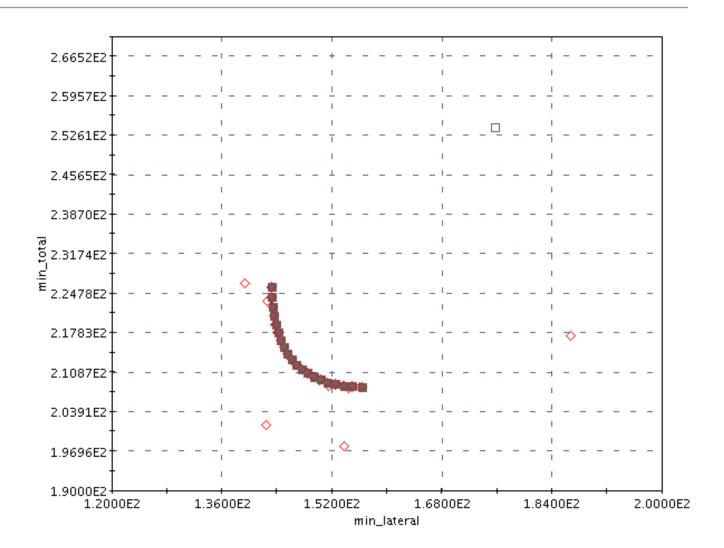






## **NBI-NLPQLP**

NBI-NLPQLP (DOE: 10 Sobol) 20 NBI-subproblems 346 eval. designs









#### Final considerations

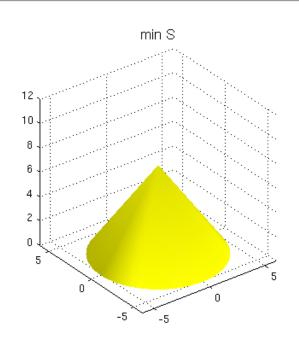
Let's consider the difference between

- single-objective problem solutions: two different minima
- multi-objective problem solutions: the Pareto frontier





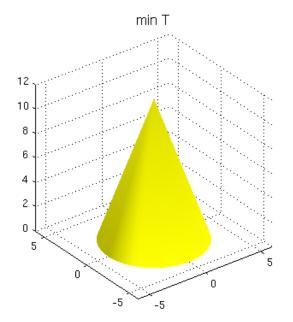
# Single-objectives minima



Each design represents the optimum solution for its corresponding singleobjective problem.



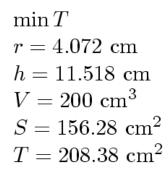
...but what about the in between designs?



...we would like to get a compromise solution. A trade-off of the two objectives...

 $\min S$  r = 5.131 cm h = 7.256 cm  $V = 200 \text{ cm}^3$   $S = 143.23 \text{ cm}^2$  $T = 225.92 \text{ cm}^2$ 

What we want is the Pareto frontier!









#### The Pareto frontier

