CS 7180 Algorithmic and Statistical Aspects of Deep Learning Mounica Subramani Problem Set 1

1) a) W, and W, denote the weight matrices of each layer. Sample -> x -E R28x28 label -> y + {0,1,2,...,9} y pred = ?

Let the 2 layer newal network architecture be like.

Equation of yeard as a function of w, and w, given input x is written as, output from hidden layer =) reLU(WI.X) along with weights and activation.

> y red = ReLU[W2 (ReLU (W, x + b,)) + b2] x- input matrix of size 784x1

b, and be one blow vector. ReLU-activation function

W1-weight matrix of size Kx 784 W2-weight matrix of size lox K

Output of hidden layer => RelU (W,x) => ReLU([KXT8A].[784 X]) X2 = ReLU[KXI]

hidden layer to output layer = ReLU (W2. X2)

- ReLU ([10xk],[kx1]) output = ReLUCIOXI]

Ib) Given:

 (x_1, y_1) ... (x_m, y_m) where m = 50,000 - training data $x_i \in \mathbb{R}^{28 \times 28}$

y; € {0,1, ... 9} , i=1...m

Loss of predicted label compared to correct label = ?

Here, optimization of the network referents, reducing the loss of predicted label and bringing close to cornect label.

cross-entropy & widely used loss function for optimizing classification models. So lets minimize that.

Cross-entropy equation,

$$L(\omega) = -\left[\sum_{i=1}^{m} \sum_{k=1}^{10} I_{i}^{2} + k_{i}^{2} \log \frac{\exp(\omega_{k}^{T} x_{i}^{2})}{\sum_{i=1}^{10} \exp(\omega_{i}^{T} x_{i}^{2})}\right]$$

where Pfy:= 2 - indicator function

W - w, and we weight matrices together k - no. of classes. L(w) - loss

Prob 2 a)

Given:

 W_1, W_2 - weight matrices of the network ReLU activation and cluadratic loss function is used. Training data = (x_1, y_1) ... (x_m, y_m)

yi ∈ R

Training loss,

y red can be written as [ReLU(W2 (ReLU(W, x)+b1)) +b2)]
[referred. from prob 1 a)]

26) Backpropagation algorithm.

Back-propagation is the practice of fine-tuning the weights of neural net based on the error rate obtained in the previous expoch)

Neural networks uses back propagation as a learning algorithm. It is used to calculate derivates quickly. The weights are updated backwards, from output towards input

Proper tuning of weights results in lower error rates, making the

model more reliable by generalizing it.

this algorithm looks for minimum value of the error function in the weight space using a technique called delta rule (or) gradient descent.

Gradient descent is an 9 terrative optimization algorithm for finding the minimum of a function (error function)

The error function desiration for w, & w2,

$$\frac{\partial L(\omega)}{\partial w_2} = \frac{\partial L(\omega)}{\partial O} \cdot \frac{\partial D}{\partial Z} \cdot \frac{\partial Z}{\partial D}$$

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$$\begin{array}{c}
O_2 = ReLU(W_2 (ReLU(W_2 + b_1))) \\
O_1 = ReLU(W_1 \times + b_1) \\
Z = W_1 \times + b_1
\end{array}$$

Backward Pass: computing gradients,

$$\frac{9m!}{9\Gamma(m)} = \frac{90}{9\Gamma(m)} \cdot \frac{95}{90} \cdot \frac{9m!}{95}$$

$$\frac{3m^3}{9r(m)} \Rightarrow \frac{90^5}{9r(m)} \cdot \frac{9m^5}{90^5}$$

$$\frac{2m!}{gr(m)} = \frac{908}{90!} \cdot \frac{90!}{90!} \cdot \frac{92}{95!} \cdot \frac{9m!}{95!}$$