### PS1-MNIST-Handout

October 3, 2020

# 1 CS7180 Problem Set 1: Implement a two-layer neural network to recognize hand-written digits (40 points)

Welcome to CS7180!

Before you start, make sure to read the problem description in the handout pdf.

```
[1]: # Uncomment the below line and run to install required packages if you have not □ → done so

# !pip install torch torchvision matplotlib tqdm
```

```
[2]: | # pip install torch
```

```
[17]: # Setup
    import torch
    import matplotlib.pyplot as plt
    from torchvision import datasets, transforms
    from tqdm import trange
    from torch.autograd import Variable

    %matplotlib inline
    DEVICE = 'cuda' if torch.cuda.is_available() else 'cpu'

# Set random seed for reproducibility
    seed = 1234

# cuDNN uses nondeterministic algorithms, set some options for reproducibility
    torch.backends.cudnn.deterministic = True
    torch.backends.cudnn.benchmark = False
    torch.manual_seed(seed)
```

[17]: <torch.\_C.Generator at 0x2ddc1192030>

#### 1.1 Get MNIST Data

The torchvision package provides a wrapper to download MNIST data. The cell below downloads the training and test datasets and creates dataloaders for each.

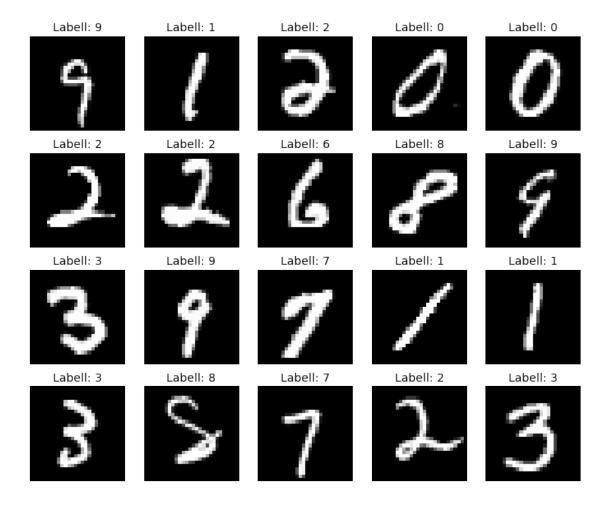
```
[18]: # Initial transform (convert to PyTorch Tensor only)
      transform = transforms.Compose([
          transforms.ToTensor(),
      ])
      train_data = datasets.MNIST('data', train=True, download=True,
       →transform=transform)
      test_data = datasets.MNIST('data', train=False, download=True,_
       →transform=transform)
      # Calculate training data mean and standard deviation to apply normalization to _{	extsf{L}}
       \rightarrow data
      # train_data.data are of type uint8 (range 0,255) so divide by 255.
      # train_mean = train_data.data.double().mean() / 255.
      # train_std = train_data.data.double().std() / 255.
      # print(f'Train Data: Mean={train_mean}, Std={train_std}')
      # Perform normalization of train and test data using calculated training mean
       → and standard deviation
      # This will convert data to be in the range [-1, 1]
      #transform = transforms.Compose([
           transforms.ToTensor(),
           transforms.Normalize((train mean, ), (train std, ))
      #1)
      train_data.transform = transform
      test_data.transform = transform
      batch_size = 64
      torch.manual_seed(seed)
      train_loader = torch.utils.data.DataLoader(train_data, batch_size=batch_size,_
       ⇒shuffle=True, num_workers=True)
      test_loader = torch.utils.data.DataLoader(test_data, batch_size=batch_size,_u
       ⇒shuffle=False, num_workers=True)
```

#### 1.2 Part 0: Inspect dataset (0 points)

```
[20]: # Randomly sample 20 images of the training dataset
      # To visualize the i-th sample, use the following code
      \# > plt.subplot(4, 5, i+1)
      # > plt.imshow(images[i].squeeze(), cmap='gray', interpolation='none')
      # > plt.title(f'Label: {labels[i]}', fontsize=14)
      # > plt.axis('off')
      images, labels = iter(train_loader).next()
      # Print information and statistics of the first batch of images
      print("Images shape: ", images.shape)
      print("Labels shape: ", labels.shape)
      print(f'Mean={images.mean()}, Std={images.std()}')
      fig = plt.figure(figsize=(12, 10))
      for i in range(20):
         plt.subplot(4, 5, i+1)
          plt.imshow(images[i].squeeze(), cmap='gray', interpolation='none')
          plt.title(f'Labell: {labels[i]}', fontsize=14)
          plt.axis('off')
```

Images shape: torch.Size([64, 1, 28, 28])
Labels shape: torch.Size([64])

Mean=0.12825286388397217, Std=0.3058689832687378



#### 1.3 Part 1: Implement a two-layer neural network (10 points)

Write a class that constructs a two-layer neural network as specified in the handout. The class consists of two methods, an initialization that sets up the architecture of the model, and a forward pass function given an input feature.

```
# Linear layer obtaining input to the hidden layer from the input layer
        self.fc1 = torch.nn.Linear(input_size,hidden_size)
         # Applying activation to the output of hidden layer before feeding into_{\sqcup}
 \rightarrow final layer
        self.act = torch.nn.ReLU()
         # Linear layer -> narrowing to 10 outputs from hidden layer
        self.fc2 = torch.nn.Linear(hidden_size,output_size)
         # Prevent overfitting
         # self.dropout = torch.nn.Dropout(0.2)
         self.log_softmax = torch.nn.LogSoftmax(dim=1)
         # -----
    def forward(self, x):
         # Input image is of shape [batch_size, 1, 28, 28]
         # Need to flatten to [batch_size, 784] before feeding to fc1
        x = self.flatten(x)
        x = self.act(self.fc1(x))
        x = self.act(x)
        x = self.fc2(x)
        x = self.log_softmax(x)
        y_output = x
        return y_output
model = MNISTClassifierMLP().to(DEVICE)
# sanity check
print(model)
MNISTClassifierMLP(
  (flatten): Flatten()
  (fc1): Linear(in_features=784, out_features=128, bias=True)
  (act): ReLU()
  (fc2): Linear(in_features=128, out_features=10, bias=True)
  (log_softmax): LogSoftmax()
)
```

#### 1.4 Part 2: Implement an optimizer to train the neural net model (10 points)

Write a method called train\_one\_epoch that runs one step using the optimizer.

```
[22]: def train_one_epoch(train_loader, model, device, optimizer, log_interval,_
       →epoch):
          model.train()
          losses = []
          counter = []
          for i, (img, label) in enumerate(train loader):
              img, label = img.to(device), label.to(device)
                imq, label = Variable(imq), Variable(label)
              # clear the gradients of all optimized variables
              optimizer.zero grad()
              # forward pass: compute predicted outputs by passing inputs to the model
              output = model(img)
              # calculate the loss
              loss = torch.nn.functional.nll_loss(output,label)
              # backward pass: compute gradient of the loss with respect to model
       \rightarrow parameters
              loss.backward()
              # perform a single optimization step (parameter update)
              optimizer.step()
              # Record training loss every log_interval and keep counter of total_
       \rightarrow training images seen
              if (i+1) % log_interval == 0:
                  losses.append(loss.item())
                  counter.append(
                       (i * batch_size) + img.size(0) + epoch * len(train_loader.
       →dataset))
          return losses, counter
```

## 1.5 Part 3: Run the optimization procedure and test the trained model (10 points)

Write a method called test\_one\_epoch that evalutes the trained model on the test dataset. Return the average test loss and the number of samples that the model predicts correctly.

```
[23]: def test_one_epoch(test_loader, model, device):
    model.eval()
    test_loss = 0
    num_correct = 0

# model.eval()
```

```
with torch.no_grad():
    for i, (img, label) in enumerate(test_loader):
        img, label = img.to(device), label.to(device)

#        img, label = Variable(img), Variable(label)
        output = model(img)
        pred = output.argmax(dim=1)
        test_loss += torch.nn.functional.

Inll_loss(output,label,reduction='sum').item()
        num_correct += pred.eq(label.view_as(pred)).sum().item()

test_loss /= len(test_loader.dataset)

# test_loss /= len(test_loader)
    return test_loss, num_correct
```

Train the model using the cell below. Hyperparameters are given.

```
[24]: # Hyperparameters
      lr = 0.01
      max_epochs=10
      gamma = 0.95
      # Recording data
      log_interval = 100
      # Instantiate optimizer (model was created in previous cell)
      optimizer = torch.optim.SGD(model.parameters(), lr=lr)
      train_losses = []
      train_counter = []
      test_losses = []
      test_correct = []
      for epoch in trange(max_epochs, leave=True, desc='Epochs'):
          train_loss, counter = train_one_epoch(train_loader, model, DEVICE,__
       →optimizer, log_interval, epoch)
          test_loss, num_correct = test_one_epoch(test_loader, model, DEVICE)
          # Record results
          train losses.extend(train loss)
          train_counter.extend(counter)
          test losses.append(test loss)
          test_correct.append(num_correct)
      print(f"Test accuracy: {test_correct[-1]/len(test_loader.dataset)}")
```

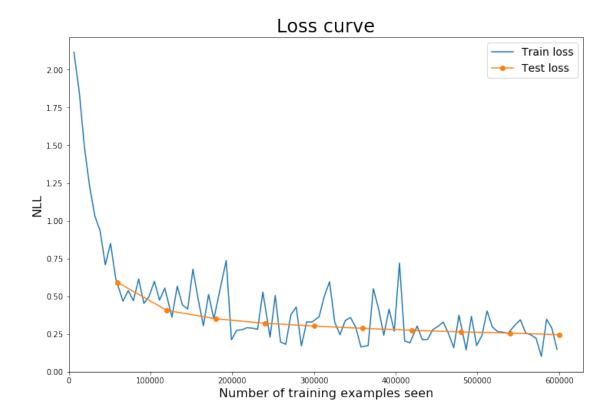
Epochs:

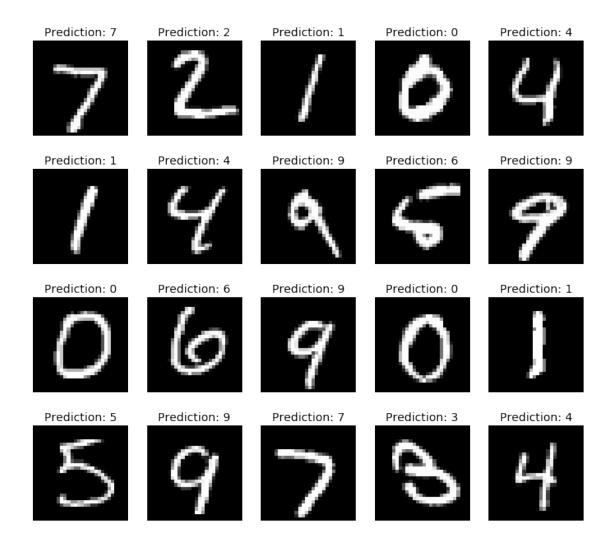
```
100%|
10/10 [01:44<00:00, 10.44s/it]
Test accuracy: 0.9305
```

#### 1.6 Part 4: Ablation studies (10 points)

- 1. Plot the loss curve as the number of epochs increases
- 2. Show the predictions of the first 20 images of the test set (4 points)
- 3. Show the first 20 images that the model predicted incorrectly. Discuss about some of the common scenarios that the model predicted incorrectly (4 points)
- 4. Go back to Part 0, where we created the tranform component to apply on the training and test datasets. Re-run the code after normalizing the training and test dataset to have mean zero and unit variance. Report what you find (2 points)

[25]: <matplotlib.legend.Legend at 0x2ddc419e608>





```
# Collect the images, predictions in test dataset

# Collect the images, predictions, labels for the first 20 incorrect predictions

# Initialize empty tensors and then keep appending to the tensor.

# Make sure that the first dimension of the tensors is the total number of

incorrect

# predictions seen so far

# Ex) incorrect_imgs should be of shape i x C x H x W, where i is the total

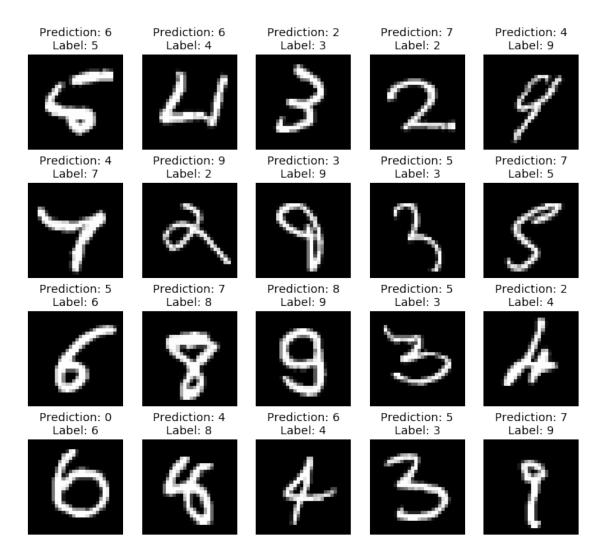
number of

# incorrect images so far.

incorrect_imgs = torch.Tensor().to(DEVICE)

# creating lists as we cannot append predictions and labels to tensor objects
incorrect_preds = []
incorrect_labels = []
```

```
with torch.no_grad():
   # Test set iterator
   it = iter(test_loader)
    # Loop over the test set batches until incorrect_imgs.size(0) >= 20
   while incorrect_imgs.size(0) < 20:</pre>
        images, labels = it.next()
        images, labels = images.to(DEVICE), labels.to(DEVICE)
        # -----
        # Write your implementation here.
       output = model(images)
       pred = output.argmax(dim=1)
        # Compare prediction and true labels and append the incorrect_
 \rightarrowpredictions
        # using `torch.cat`.
       for index, i in enumerate(output):
           if pred[index] !=labels[index]:
               incorrect_imgs = torch.cat([incorrect_imgs,__
→images[index]],dim=0)
               incorrect_preds.append(pred[index])
               incorrect_labels.append(labels[index])
        # -----
# Show the first 20 wrong predictions in test set
# incorrect_labels = str(incorrect_labels)
# incorrect_preds = str(incorrect_preds)
fig = plt.figure(figsize=(12, 11))
for i in range(20):
   plt.subplot(4, 5, i+1)
   plt.imshow(incorrect_imgs[i].squeeze().cpu().numpy(), cmap='gray',_
plt.title(f'Prediction: {incorrect_preds[i].item()}\nLabel:__
 →{incorrect_labels[i].item()}', fontsize=14)
   plt.axis('off')
```



Discuss about some of the common scenarios that the model predicted incorrectly (4 points)

The numbers that are predicted incorrectly might be because of training data being too similar to each other, so when deployed on testing data gives poor accuracy.

Also, few digits are hard to recognize for human eyes.

MNSIT data is already somewhat preprocessed. So model might expect to preprocess our test images as well. (like normalizing the training and testing data in the same way). Can also follow PCA or normalizing by Z-score.

Go back to Part 0, where we created the tranform component to apply on the training and test datasets. Re-run the code after normalizing the training and test dataset to have mean zero and unit variance. Report what you find (2 points)

```
])
train_data = datasets.MNIST('data', train=True, download=True,
 →transform=transform)
test_data = datasets.MNIST('data', train=False, download=True,
→transform=transform)
# Calculate training data mean and standard deviation to apply normalization to _{	extsf{L}}
\hookrightarrow data
# train_data.data are of type uint8 (range 0,255) so divide by 255.
train_mean = train_data.data.double().mean() / 255.
train_std = train_data.data.double().std() / 255.
print(f'Train Data: Mean={train_mean}, Std={train_std}')
# Perform normalization of train and test data using calculated training mean_
→ and standard deviation
# This will convert data to be in the range [-1, 1]
transform = transforms.Compose([transforms.ToTensor(),transforms.
 →Normalize((train_mean, ), (train_std, ))])
train_data.transform = transform
test_data.transform = transform
batch_size = 64
torch.manual_seed(seed)
train_loader = torch.utils.data.DataLoader(train_data, batch_size=batch_size,_u
⇒shuffle=True, num_workers=True)
test_loader = torch.utils.data.DataLoader(test_data, batch_size=batch_size,_u
 ⇒shuffle=False, num_workers=True)
```

Train Data: Mean=0.1306604762738429, Std=0.30810780717887876

```
[29]: # Hyperparameters
lr = 0.01
max_epochs=10
gamma = 0.95

# Recording data
log_interval = 100

# Instantiate optimizer (model was created in previous cell)
optimizer = torch.optim.SGD(model.parameters(), lr=lr)

train_losses = []
train_counter = []
test_losses = []
test_correct = []
for epoch in trange(max_epochs, leave=True, desc='Epochs'):
```

```
train_loss, counter = train_one_epoch(train_loader, model, DEVICE,
optimizer, log_interval, epoch)
test_loss, num_correct = test_one_epoch(test_loader, model, DEVICE)

# Record results
train_losses.extend(train_loss)
train_counter.extend(counter)
test_losses.append(test_loss)
test_correct.append(num_correct)

print(f"Test accuracy: {test_correct[-1]/len(test_loader.dataset)}")
```

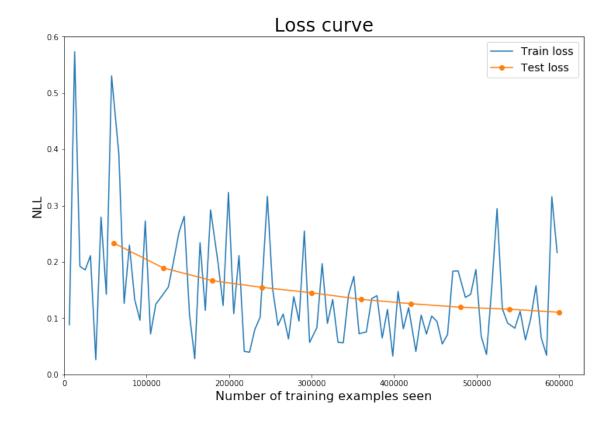
#### Epochs:

100%| 10/10 [02:38<00:00, 15.80s/it]

Test accuracy: 0.968

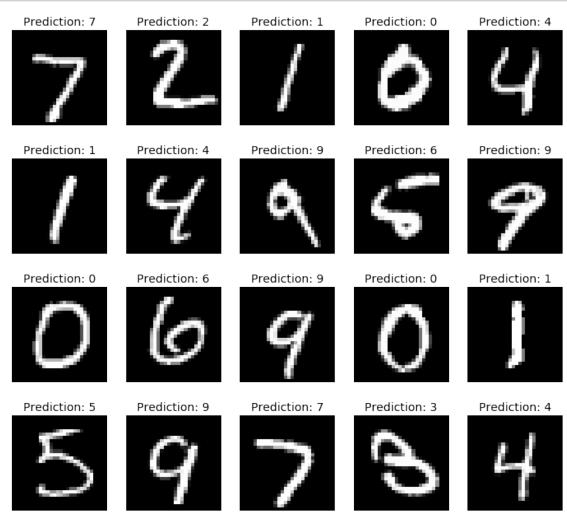
The accuracy of the model has however improved from 0.93 to 0.96.

[30]: <matplotlib.legend.Legend at 0x2ddc66a0d08>



The curve depicts that the train loss is fluctuating with samples but the test loss is decreasing with increase in samples or examples. The pattern is quite similar to what we obtained before normalizing our data but the numbers and depth of curves vary slightly. Say the test loss is going below 0.2 in the above plot whereas before normalizing it was between 0.3 to 0.5

```
plt.title(f'Prediction: {pred[i]}',fontsize=14)
  plt.axis('off')
# ------
```



```
# 3. Get 20 incorrect predictions in test dataset

# Collect the images, predictions, labels for the first 20 incorrect predictions

# Initialize empty tensors and then keep appending to the tensor.

# Make sure that the first dimension of the tensors is the total number of □

□ incorrect

# predictions seen so far

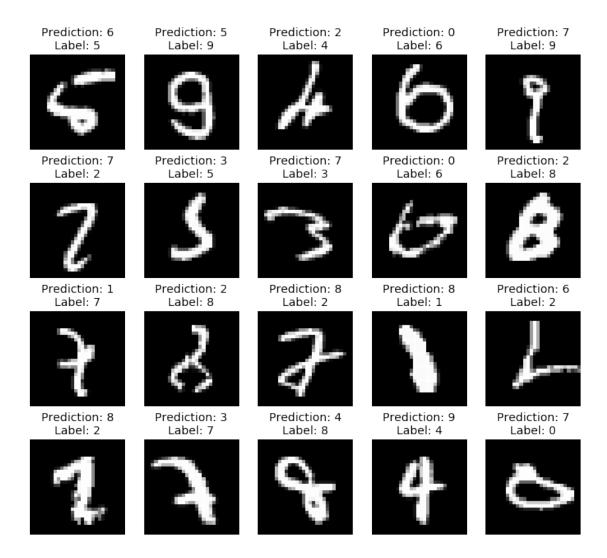
# Ex) incorrect_imgs should be of shape i x C x H x W, where i is the total □

□ number of

# incorrect images so far.

incorrect_imgs = torch.Tensor().to(DEVICE)
```

```
incorrect_preds = []
incorrect_labels = []
with torch.no_grad():
   # Test set iterator
   it = iter(test_loader)
   # Loop over the test set batches until incorrect_imgs.size(0) >= 20
   while incorrect_imgs.size(0) < 20:</pre>
        images, labels = it.next()
        images, labels = images.to(DEVICE), labels.to(DEVICE)
        # Write your implementation here.
       output = model(images)
       pred = output.argmax(dim=1)
        # Compare prediction and true labels and append the incorrect_
 \rightarrowpredictions
        # using `torch.cat`.
       for index, i in enumerate(output):
            if pred[index] !=labels[index]:
                incorrect_imgs = torch.cat([incorrect_imgs,__
→images[index]],dim=0)
               incorrect_preds.append(pred[index])
                incorrect_labels.append(labels[index])
        # -----
# Show the first 20 wrong predictions in test set
# incorrect_labels = str(incorrect_labels)
# incorrect_preds = str(incorrect_preds)
fig = plt.figure(figsize=(12, 11))
for i in range(20):
   plt.subplot(4, 5, i+1)
   plt.imshow(incorrect_imgs[i].squeeze().cpu().numpy(), cmap='gray',__
plt.title(f'Prediction: {incorrect_preds[i].item()}\nLabel:__
→{incorrect_labels[i].item()}', fontsize=14)
   plt.axis('off')
```



In terms of Predictions, the model has improved after normalizing the data. The incorrect predictions above are genuinely hard for humans too recognize at times. *Prediction: 6, Label:2* is hard to predict and there are chances for predicting it as 4 or 6. Similarly all the above incorrect predictions are genuine and the model performance also improved considerally after data normalization.