1. (Math) Nonlinear least-squares. Suppose that $\mathbf{f}(\mathbf{x}) = (f_1(\mathbf{x}), f_2(\mathbf{x}), ..., f_m(\mathbf{x})) : \mathbb{R}^n \to \mathbb{R}^m$, $\mathbf{x} \in \mathbb{R}^n, \mathbf{f} \in \mathbb{R}^m$ and some $f_i(\mathbf{x}) : \mathbb{R}^n \to \mathbb{R}$ is a (are) non-linear function(s). Then, the problem,

$$\mathbf{x}^* = \arg\min_{\mathbf{x}} \frac{1}{2} \|\mathbf{f}(\mathbf{x})\|_2^2 = \arg\min_{\mathbf{x}} \frac{1}{2} (\mathbf{f}(\mathbf{x}))^T \mathbf{f}(\mathbf{x})$$

is a nonlinear least-squares problem. In our lecture, we mentioned that Levenberg-Marquardt algorithm is a typical method to solve this problem. In L-M algorithm, for each updating step, at the current \mathbf{x} , a local approximation model is constructed as,

$$L(\mathbf{h}) = \frac{1}{2} (\mathbf{f}(\mathbf{x} + \mathbf{h}))^T \mathbf{f}(\mathbf{x} + \mathbf{h}) + \frac{1}{2} \mu \mathbf{h}^T \mathbf{h}$$

$$= \frac{1}{2} (\mathbf{f}(\mathbf{x}))^T \mathbf{f}(\mathbf{x}) + \mathbf{h}^T (\mathbf{J}(\mathbf{x}))^T \mathbf{f}(\mathbf{x}) + \frac{1}{2} \mathbf{h}^T (\mathbf{J}(\mathbf{x}))^T \mathbf{J}(\mathbf{x}) \mathbf{h} + \frac{1}{2} \mu \mathbf{h}^T \mathbf{h}$$

where J(x) is f(x)'s Jacobian matrix, and $\mu>0$ is the damped coefficient. Please prove that $L(\mathbf{h})$ is a strictly convex function. (Hint: If a function $L(\mathbf{h})$ is differentiable up to at least second order, L is strictly convex if its Hessian matrix is positive definite.)

We know he R n , and L(h) is differentiable at second order, olom L \in R n , then

we need to prove JTJ +MI is positive definite

for JT) is eigenvalues
$$\lambda i$$
, $i=1,...,n$, we have $\lambda i \geq 0$ for positive semi-positive matrix

(Math) In our lecture, we mentioned that for logistic regression, the cost function is,

$$J(\boldsymbol{\theta}) = -\sum_{i=1}^{m} y_i \log(h_{\boldsymbol{\theta}}(\boldsymbol{x}_i)) + (1 - y_i) \log(1 - h_{\boldsymbol{\theta}}(\boldsymbol{x}_i))$$

Please verify that the gradient of this cost function is

$$\nabla_{\boldsymbol{\theta}} J(\boldsymbol{\theta}) = \sum_{i=1}^{m} \boldsymbol{x}_{i} \left(h_{\boldsymbol{\theta}}(\boldsymbol{x}_{i}) - \boldsymbol{y}_{i} \right)$$

$$h_{\theta}(x) = 6(\theta^{T}x + b) = \frac{1}{1 + e^{-(\theta^{T}x + b)}}$$
Let $t = \theta^{T}x + b$, $\frac{\partial t}{\partial \theta} = X$

$$\frac{\partial h_{\theta}(x)}{\partial t} = \frac{\partial G(t)}{\partial t} = 6(t)(1 - 6(t)) = h_{\theta}(x)(1 - h_{\theta}(x))$$

$$50: \nabla_{\theta} J(\theta) = -\sum_{i=1}^{m} (y_i \frac{\partial \log(h_{\theta}(x_i))}{\partial h_{\theta}(x_i)} \frac{\partial h_{\theta}(x_i)}{\partial t} \frac{\partial h_{\theta}(x_i)}{\partial t} \frac{\partial t}{\partial \theta}$$

$$+ ([-y_i]) \frac{\partial \log(h_{\theta}(x_i))}{\partial h_{\theta}(x_i)} \frac{\partial h_{\theta}(x_i)}{\partial t} \frac{\partial h_{\theta}(x_i)}{\partial t} \frac{\partial t}{\partial \theta})$$

$$= -\sum_{i=1}^{m} (y_i \frac{1}{h_{\theta}(x_i)} h_{\theta}(x_i) ([-h_{\theta}(x_i))] x_i$$

$$+ ([-y_i]) \frac{-(-h_{\theta}(x_i))}{([-h_{\theta}(x_i))} h_{\theta}(x_i) ([-h_{\theta}(x_i))] x_i)$$