

# Computer Vision Final Project — Image Captioning

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# 1 Abstract

In this project, we implement a complete image captioning system using a classical encoder–decoder framework enhanced with **soft attention**, following the **Show, Attend, and Tell** approach. We employ a pre-trained **ResNet-101 CNN** as the encoder to extract dense spatial features, and a **Bahdanau-style attention LSTM** as the decoder to sequentially generate captions. The pipeline includes detailed steps for data preprocessing, vocabulary design, CNN feature extraction, attention-based decoding, model training with teacher forcing, evaluation using BLEU metrics, and inference via beam search. Experiments on the **Flickr8k dataset** yielded a **BLEU-4 score of 0.2818**, which aligns well with established attention-based baselines. This report outlines the dataset, preprocessing strategy, model design, training procedure, evaluation metrics, results, key challenges, and potential avenues for future work.

## 2 1. Introduction

Image captioning is a multimodal task that bridges computer vision and natural language processing. It requires understanding the semantic content of an image and generating coherent textual descriptions. Traditional approaches adopt an **encoder–decoder** framework: a CNN encoder extracts visual features, while an RNN decoder generates captions sequentially. Incorporating **attention mechanisms** allows the model to dynamically focus on relevant regions in an image during decoding, improving both interpretability and descriptive accuracy, especially in complex scenes. In this work, we build an end-to-end pipeline encompassing dataset preprocessing, feature extraction, vocabulary construction, attention-based decoding, model training, and evaluation, providing hands-on experience in multimodal deep learning.

## 3 2. Dataset Description

The **Flickr8k dataset** consists of 8,000 images, each paired with five human-annotated captions. The dataset covers diverse real-world scenarios, including: - People performing various actions (e.g., running, sitting, interacting) - Animals such as dogs, horses, and elephants - Indoor and outdoor scenes - Vehicles, sports, food, and miscellaneous objects

Actual: a man on a motorcycle touches his knee to the ground during a sharp turn



The richness of the captions allows the model to learn robust visual–linguistic mappings. Evaluation is performed using **BLEU metrics**, which measure both lexical correctness and sentence fluency.

## 4 3. Data Preprocessing

Proper preprocessing is essential for stable training and accurate caption generation.

### 4.1 3.1 Caption Cleaning

Captions were normalized to reduce noise: 1. Converted all text to **lowercase** to avoid duplications caused by casing. 2. Removed **punctuation, special characters, and numbers**. 3. Collapsed multiple spaces into a single space. 4. Filtered out very short or meaningless tokens (e.g., single letters). 5. Added special tokens: **<start>** to indicate the beginning, and **<end>** to mark the end of a caption.

This ensures a standardized structure for each caption, which is crucial for consistent model training.

### 4.2 3.2 Vocabulary Construction

A word frequency threshold of  $\geq 5$  occurrences was applied, selecting only meaningful tokens and limiting vocabulary size to around 2,000 words. Special tokens **<pad>**, **<start>**, **<end>**, and **<unk>** were manually included.

**Benefits of frequency thresholding:** - Reduces overfitting on rare words - Stabilizes the softmax output by limiting dimensionality - Improves training efficiency and reduces memory usage

### 4.3 3.3 Image Preprocessing

- Images were resized to  $256 \times 256$  and normalized using ImageNet mean and standard deviation.
- Training images underwent **random cropping and horizontal flipping**; validation/test images used center cropping.
- Final tensors had shape  $3 \times 224 \times 224$ , suitable for the ResNet-101 encoder.

## 5 4. Model Architecture

The model follows the **Show, Attend, and Tell** paradigm, composed of three main components: encoder, attention mechanism, and decoder.

### 5.1 4.1 Encoder — ResNet-101 CNN

We used a pre-trained **ResNet-101** as the encoder. The global pooling and final fully connected layers were removed to retain spatial feature maps. Adaptive average pooling reshaped the features into a  $14 \times 14$  grid (196 regions), each with 2048 dimensions.

**Fine-tuning strategy:** - **Freeze early layers** to preserve generic visual features. - **Fine-tune the last two convolutional blocks** for Flickr8k-specific adaptation.

**Output shape:** (batch\_size, 196, 2048)

### 5.2 4.2 Attention Mechanism — Bahdanau Additive Attention

The attention module allows the decoder to focus on relevant image regions at each time step: 1. Compute alignment scores between decoder hidden state and encoder features. 2. Apply softmax to obtain attention weights. 3. Compute the context vector as a weighted sum of encoder features. 4. Concatenate the context vector with the current word embedding before feeding it to the LSTM.

**Advantages:** - Provides visual interpretability - Handles complex or cluttered scenes - Improves descriptive accuracy by emphasizing salient objects

### 5.3 4.3 Decoder — LSTM with Attention

The decoder is an **LSTMCell** with attention. Key components: - Embedding layer (256-dimensional) - LSTMCell for sequential decoding - Attention gate modulating the context vector - Linear + softmax layer for vocabulary prediction - Dropout (0.5) for regularization

**Teacher forcing** was used during training to feed ground-truth words to the model, improving convergence and stability.

### 5.4 4.4 Beam Search Inference

**Beam search** with a size of 3–5 was used during inference to maintain multiple caption hypotheses, producing more fluent and accurate captions compared to greedy decoding.

Example: - Greedy: “A dog running in the grass.” - Beam: “A brown dog is running across a grassy field.”

## 6 5. Training Procedure

### 6.1 5.1 Training Configuration

Component	Value
Loss Function	Cross-Entropy + Attention Regularization
Optimizer	Adam
Learning Rate	4e-4
Batch Size	32
Epochs	60
Gradient Clipping	5.0
Hardware	NVIDIA RTX GPU

## 6.2 5.2 Overfitting Prevention

- Data augmentation (random cropping/flipping)
- Dropout in decoder
- Attention regularization
- Limited CNN fine-tuning
- Monitoring validation BLEU scores

## 7 6. Evaluation Metrics

BLEU-1 to BLEU-4 metrics were used to measure n-gram precision, capturing both object-level accuracy and sentence-level fluency.

## 8 7. Results

### 8.1 7.1 BLEU Score Summary

Metric	Score
BLEU-1	0.6689
BLEU-2	0.5038
BLEU-3	0.3818
BLEU-4	<b>0.2818</b>

### 8.2 7.2 Final Image Captions

Here we present the three final results for the actual and generated captions.

Generated: a man is playing with a dog on the beach  
Actual: a man holds a ball in the air for a brown dog to catch on the beach



Generated: a person is surfing in the ocean  
Actual: a surfer on a blue surfboard is falling off of it as he hits a wave



Generated: a little boy is standing in front of his head  
Actual: a child with a skull on his shirt is sitting in front of some plants and a building and is holding onto handlebars



## 9 8. Discussion

### 9.1 Strengths:

- Accurate object recognition and description
- Attention provides visual interpretability
- Beam search improves fluency
- Teacher forcing stabilizes learning

## 9.2 Challenges:

- Small or occluded objects may be missed
- Limited vocabulary can lead to repetitive captions
- LSTM struggles with **long-range dependencies**
- Small dataset increases overfitting risk

## 9.3 Potential Improvements:

- **Transformer-based decoder**
- Vision Transformer or DETR encoder
- **CLIP embeddings** for multimodal alignment
- Larger datasets (MS-COCO)
- Additional metrics like CIDEr and SPICE
- **Scheduled sampling** to reduce exposure bias

## 10 9. Conclusion

We presented a full pipeline for image captioning using an encoder–decoder framework with attention. The BLEU-4 score of 0.2818 demonstrates reasonable performance and establishes a baseline. This framework lays the groundwork for further improvements using transformer-based models, larger datasets, and advanced multimodal embeddings.

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