

773. Sliding Puzzle

On an 2×3 board, there are five tiles labeled from 1 to 5, and an empty square represented by 0. A **move** consists of choosing 0 and a 4-directionally adjacent number and swapping it.

The state of the board is solved if and only if the board is $[[1, 2, 3], [4, 5, 0]]$.

Given the puzzle board `board`, return *the least number of moves required so that the state of the board is solved*. If it is impossible for the state of the board to be solved, return -1.

Example 1:

1	2	3
4		5

Input: `board = [[1,2,3],[4,0,5]]`

Output: 1

Explanation: Swap the 0 and the 5 in one move.

Example 2:

1	2	3
5	4	

Input: `board = [[1,2,3],[5,4,0]]`

Output: -1

Explanation: No number of moves will make the board solved.

Example 3:

4	1	2
5		3

Input: board = `[[4,1,2],[5,0,3]]`

Output: 5

Explanation: 5 is the smallest number of moves that solves the board.

An example path:

After move 0: `[[4,1,2],[5,0,3]]`

After move 1: `[[4,1,2],[0,5,3]]`

After move 2: `[[0,1,2],[4,5,3]]`

After move 3: `[[1,0,2],[4,5,3]]`

After move 4: `[[1,2,0],[4,5,3]]`

After move 5: `[[1,2,3],[4,5,0]]`

Constraints:

- `board.length == 2`
- `board[i].length == 3`
- `0 <= board[i][j] <= 5`
- Each value `board[i][j]` is **unique**

773. Sliding Puzzle

```
/*
    DFS
*/
typedef std::vector<int> vi;
typedef std::vector<vi> vvi;
class Solution{
private:
    int m; // Row
    int n; // Cols
    vvi directions={
        {-1,0}, // Up
        {1,0}, // Down
        {0,-1}, // Left
        {0,1} // Right;
    };
    vvi target={{1,2,3},{4,5,0}};
    std::map<vvi,int> visited;

class Puzzle{
public:
    vvi board;

    // Position of empty tile in the cureent state
    int x_empty_tile;
    int y_empty_tile;

    int steps; // Number of steps to reach the current state
public:
    Puzzle(vvi board,int x_empty_tile,int y_empty_tile,int steps):
        board(board),
        x_empty_tile(x_empty_tile),
        y_empty_tile(y_empty_tile),
        steps(steps) {}
};

public:
    // Find the position of the empty tile (0)
    std::pair<int,int> find_zero_pos(vvi& board){
        for(int i=0;i<m;++i){
            for(int j=0;j<n;++j){
                if(board[i][j]==0) return {i,j};
            }
        }
        return {-1,-1}; // Never reached
    }
}
```

```

void dfs(Puzzle* puzzle){
    if(visited.find(puzzle->board)!=visited.end() && visited[puzzle->board]<=puzzle->steps)
return;
    visited[puzzle->board]=puzzle->steps;

    for (auto& dir: directions){
        int x=puzzle->x_empty_tile + dir[0];
        int y=puzzle->y_empty_tile + dir[1];

        if ( x < 0 || x >= m || y < 0 || y >= n) continue;

        vvi next_board = puzzle->board;
        int tmp = next_board[x][y];
        next_board[x][y] = 0;
        next_board[puzzle->x_empty_tile][puzzle->y_empty_tile] = tmp;

        Puzzle* next_puzzle = new Puzzle(next_board, x, y,puzzle->steps+1);

        dfs(next_puzzle);
    }
}

```

```

int slidingPuzzle(vvi& board){
    m=board.size();
    n=board[0].size();

    // Find position of empty tile
    std::pair<int,int> zero_pos=find_zero_pos(board);

    // Create the puzzle
    Puzzle* puzzle=new Puzzle(board,zero_pos.first,zero_pos.second,0);

    dfs(puzzle);

    return visited.find(target)!=visited.end()?visited[target]:-1;
}
};

```

773. Sliding Puzzle

```
/*
  BFS
*/
typedef std::vector<int> vi;
typedef std::vector<vi> vvi;
class Solution{
private:
    int m; // Row
    int n; // Cols

    vvi directions={
        {-1,0}, // Up
        {1,0}, // Down
        {0,-1}, // Left
        {0,1} // Right;
    };
    vvi target={{1,2,3},{4,5,0}};
```

```
class Puzzle{
public:
    vvi board;

    // Position of empty tile in the cureent state
    int x_empty_tile;
    int y_empty_tile;

    int steps; // Number of steps to reach the current state
public:
    Puzzle(vvi board,int x_empty_tile,int y_empty_tile,int steps):
        board(board),
        x_empty_tile(x_empty_tile),
        y_empty_tile(y_empty_tile),
        steps(steps) {}
};
```

```
public:
    // Find the position of the empty tile (0)
    std::pair<int,int> find_zero_pos(vvi& board){
        for(int i=0;i<m;++i){
            for(int j=0;j<n;++j){
                if(board[i][j]==0) return {i,j};
            }
        }
        return {-1,-1}; // Never reached
    }
```

```

// Perform BFS
int bfs(Puzzle* puzzle){
    std::queue<Puzzle*> q;
    q.push(puzzle);

    std::map<vvi, bool> visited;

    while(!q.empty()){
        Puzzle* current_puzzle=q.front();
        q.pop();

        vvi current_board = current_puzzle->board;

        if(current_board==target) return current_puzzle->steps;

        // State visited, no need to do it again
        if (visited[current_board]) continue;
        visited[current_board] = true;

        // Move empty tile in four directions
        for (auto& dir: directions){
            int x=current_puzzle->x_empty_tile + dir[0];
            int y=current_puzzle->y_empty_tile + dir[1];

            if ( x < 0 || x >= m || y < 0 || y >= n) continue;

            vvi next_board = current_board;
            int tmp = next_board[x][y];
            next_board[x][y] = 0;
            next_board[current_puzzle->x_empty_tile][current_puzzle->y_empty_tile] = tmp;

            // If the next state is not visited,
            if (!visited[next_board]){

                // Create next puzzle
                Puzzle* next_puzzle = new Puzzle(next_board, x, y,current_puzzle->steps+1);

                // Add it to the queue
                q.push(next_puzzle);
            }
        }
    }
    return -1; // If target not reached at all
}

```

```

int slidingPuzzle(vvi& board){
    m=board.size();
    n=board[0].size();

    // Find position of empty tile
    std::pair<int,int> zero_pos=find_zero_pos(board);

    // Create the puzzle
    Puzzle* puzzle=new Puzzle(board,zero_pos.first,zero_pos.second,0);

    return bfs(puzzle);
}
};

```

773. Sliding Puzzle

```
/*
  A*
*/
typedef std::vector<int> vi;
typedef std::vector<vi> vvi;
class Solution{
private:
    int m; // Row
    int n; // Cols

    vvi directions={
        {-1,0}, // Up
        {1,0}, // Down
        {0,-1}, // Left
        {0,1} // Right;
    };

    vvi target={{1,2,3},{4,5,0}};
```

```
class Puzzle{
public:
    vvi board;

    // Position of empty tile in the cureent state
    int x_empty_tile;
    int y_empty_tile;

    int steps; // Number of steps to reach the current state
    int h; // Heuristic value: number of misplaced tiles
    int coast; // The coast to get target state from an actual state.
public:
    Puzzle(vvi board,int x_empty_tile,int y_empty_tile,int steps,int h, int coast):
        board(board),
        x_empty_tile(x_empty_tile),
        y_empty_tile(y_empty_tile),
        steps(steps),
        h(h),
        coast(coast) {}
};
```


public:

```
// Find the position of the empty tile (0)
std::pair<int,int> find_zero_pos(vvi& board){
    for(int i=0;i<m;++i){
        for(int j=0;j<n;++j){
            if(board[i][j]==0) return {i,j};
        }
    }
    return {-1,-1}; // Never reached
}
```

```
// Heuristic function
// #misplaced tiles in actual state by comparing with the target state.
int heuristic(vvi& board){
    int h=0;
    int tile=1;
    for (int i=0;i<m;++i){
        for (int j=0;j<n;++j){
            if ( (i!=m-1 || j!=n-1) &&board[i][j]!=tile) h++;
            tile++;
        }
    }
    return h+int(board[m-1][n-1]!=0);
}
```

```

// A* algorithm
int a_star(Puzzle* puzzle){
    // Use min heap to get the minimum coast
    std::priority_queue<std::pair<int,Puzzle*>,std::vector<std::pair<int,Puzzle*>>,
std::greater<std::pair<int,Puzzle*>>> min_heap;

    // Push initial state to the min heap
    min_heap.push({puzzle->coast, puzzle});

    std::map<vvi,bool> visited;

    while (!min_heap.empty()){
        // Get the puzzle with the minimum coast
        Puzzle* current_puzzle=min_heap.top().second;
        min_heap.pop();

        vvi current_board=current_puzzle->board;

        // If number of misplaced tiles is equal to 0, means we reached the target
        // then return the number of steps
        if (current_puzzle->h==0) return current_puzzle->steps;

        // if the board's state is visited, no need to continue with it
        if (visited[current_board]) continue;

        // If not visited, mark it as visited
        visited[current_board]=true;

        // Move empty tile in four directions
        for (auto& dir: directions){
            int x=current_puzzle->x_empty_tile + dir[0];
            int y=current_puzzle->y_empty_tile + dir[1];

            if ( x<0 || x>=m || y<0 || y>=n) continue;

            // Get next state
            vvi next_board=current_board;
            int tmp=next_board[x][y];
            next_board[x][y]=0;
            next_board[current_puzzle->x_empty_tile][current_puzzle->y_empty_tile]=tmp;

            // If the next state is not visited,
            if (!visited[next_board]){
                int f=current_puzzle->steps+1; // Add one step to the current state
                int h=heuristic(next_board); // Determine the heuristic value of the next state
                int coast=f+h; // Compute the coast to go from current state to next state

                // Create next puzzle
                Puzzle* next_puzzle=new Puzzle(next_board,x,y,f,h,coast);

                // Add it to min heap
                min_heap.push({coast,next_puzzle});
            }
        }
    }

    return -1; // If target not reached at all
}

```

```

int slidingPuzzle(vvi& board){
    m=board.size();
    n=board[0].size();

    // Find position of empty tile
    std::pair<int,int> zero_pos=find_zero_pos(board);

    // Compute heuristic value
    int h0=heuristic(board);

    // Create the puzzle
    Puzzle* puzzle=new Puzzle(board,zero_pos.first,zero_pos.second,0,h0,0+h0);

    return a_star(puzzle);
}
};

```

Time Complexity Analysis

1. State Space Size:

- The problem involves solving the sliding puzzle. Each configuration of the board is a unique state.
- For a $m \times n$ board, the total number of states is $(m \times n)!$, as all tiles can be permuted (factorial of the total number of tiles).

2. Heuristic Calculation (**heuristic**):

- The **heuristic** function iterates over all tiles in the $m \times n$ grid, making its complexity $O(m \cdot n)$.

3. Priority Queue Operations:

- The algorithm uses a **min-heap** to store puzzle states, and operations on the heap (insertion and extraction) have a complexity of $O(\log(S))$, where S is the number of states in the heap.
- In the worst case, all possible states $(m \times n)!$ can be generated.

4. State Expansion:

- Each state expands to at most 4 neighbors (up, down, left, right), though some moves may be invalid.
- For each valid neighbor, the **heuristic** function is called, costing $O(m \cdot n)$.

5. Visited Map:

- Checking and marking states as visited involves hashing the $m \times n$ board, which takes $O(m \cdot n)$.

6. Overall Time Complexity:

- In the worst case, the algorithm could explore all possible states, and for each state, it performs $O(m \cdot n)$ operations.
 - **Time complexity:** $O((m \cdot n) \cdot (m \cdot n)!)$.
-

Space Complexity Analysis

1. Priority Queue:

- The min-heap can store at most $(m \cdot n)!$ states in the worst case.
- Each state requires space to store:
 - The $m \times n$ board $O(m \cdot n)$.
 - Additional metadata (like position of the empty tile, steps, heuristic, and cost).
- Space for the priority queue: $O((m \cdot n)! \cdot (m \cdot n))$.

2. Visited Map:

- Stores $(m \cdot n)!$ states as keys. Each state (board configuration) requires $O(m \cdot n)$ space.
- Space for visited map: $O((m \cdot n)! \cdot (m \cdot n))$.

3. Recursive Calls and Local Variables:

- There are no recursive calls in this implementation, so no additional stack space is needed.

4. Overall Space Complexity:

- Dominated by the storage requirements of the priority queue and the visited map.
 - **Space complexity:** $O((m \cdot n)! \cdot (m \cdot n))$.
-

Key Points

- **Time complexity** is exponential due to the factorial growth of the state space.
- **Space complexity** is also exponential, driven by the need to store all explored states.
- Practical performance depends heavily on the heuristic function's ability to prune the search space effectively. The better the heuristic, the fewer states are expanded.