

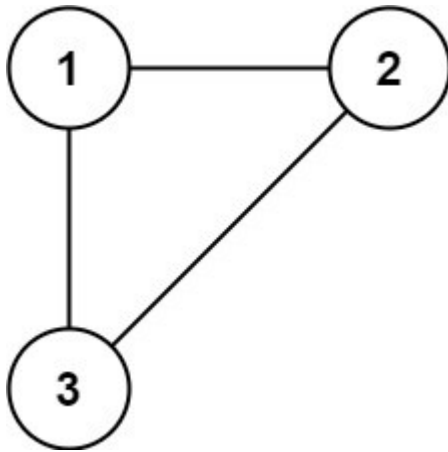
684. Redundant Connection

In this problem, a tree is an **undirected graph** that is connected and has no cycles.

You are given a graph that started as a tree with n nodes labeled from 1 to n , with one additional edge added. The added edge has two **different** vertices chosen from 1 to n , and was not an edge that already existed. The graph is represented as an array `edges` of length n where `edges[i] = [ai, bi]` indicates that there is an edge between nodes a_i and b_i in the graph.

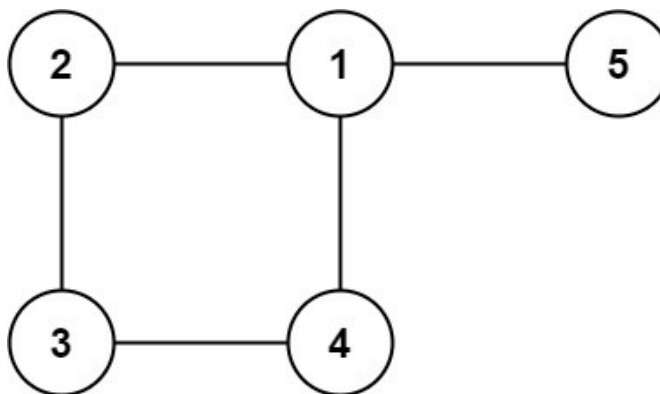
Return an edge that can be removed so that the resulting graph is a tree of n nodes. If there are multiple answers, return the answer that occurs last in the input.

Example 1:



Input: `edges = [[1,2],[1,3],[2,3]]`
Output: `[2,3]`

Example 2:



Input: `edges = [[1,2],[2,3],[3,4],[1,4],[1,5]]`
Output: `[1,4]`

Constraints:

- `n == edges.length`
- `3 <= n <= 1000`
- `edges[i].length == 2`
- `1 <= ai < bi <= edges.length`
- `ai != bi`
- There are no repeated edges.
- The given graph is connected.

Overview

We are given a graph consisting of N nodes and $N-1$ edges, which means the graph initially forms a tree. A tree is a special type of graph that is connected (there is a path between any two nodes) and acyclic (it does not contain any cycles). However, a new edge is added to the tree, connecting two nodes that are already part of the graph. This new edge creates a cycle because there are now two distinct paths between some pairs of nodes. As a result, the graph is no longer a tree but a single-cycle graph.

Our goal is to identify the edge that, if removed, will restore the graph to its original state as a tree. Since the tree must be connected and acyclic, removing any edge from the cycle will break the cycle and turn the graph into a tree. However, if there are multiple edges that can be removed to achieve this, we are required to return the edge that appears last in the given list of edges.

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```
/*  
    Union Find: Kruskal's MST algorithm  
    Time complexity:  $O(n\alpha(n))$   
    Space complexity:  $O(3n)$   
    n: #node = #edges  
*/  
typedef std::vector<int> vi;  
typedef std::vector<vi> vvi;
```

```

class DSU{
public:
    vi parent;
    vi group;

    DSU(int _N){
        parent.resize(_N);
        group.resize(_N,1);
        for(int i=0;i<_N;++i){
            parent[i]=i;
        }
    }

    int find(int p){
        if(p==parent[p]) return p;
        return parent[p]=find(parent[p]);
    }

    bool unify(int p,int q){
        int parent_p=find(p);
        int parent_q=find(q);
        if(parent_p==parent_q) return false;

        if(group[parent_p]<group[parent_q]){
            group[parent_q]+=group[parent_p];
            group[parent_p]=1;
            parent[parent_p]=parent_q;
        }
        else{
            group[parent_p]+=group[parent_q];
            group[parent_q]=1;
            parent[parent_q]=parent_p;
        }

        return true;
    }
};

```

```

class Solution {
public:
    vi findRedundantConnection(vvi& edges) {
        int n=edges.size();

        DSU dsu=DSU(n);

        for(auto& edge: edges){
            int u=--edge[0];
            int v=--edge[1];
            if(!dsu.unify(u,v)) return {++u,++v};
        }

        return {};
    }
};

```