Concurrent and Distributed Erlang

Lectures F6 + F7 (Chapters 11..14)

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W6/F6 - Concurrent Erlang

- Chapters 11,12.
- Concurrency Intro.
- Concurrency Primitives.
- Client Server.
- Processes are cheap.
- Send/Receive.
- Spawn.
- Registered Processes .

Concurrency Intro

- The World is Parallel.
- Concurrency should be in the programming language not the operating system.
- Concurrent is not parallel.

Explain it to a five year old

Concurrent vs Parallelism

- Concurrent = the illusion of parallelism.
- Parallel = *really parallel*.
- On a quad core there can only really be 4 things happening at the same time.
 - Note that in reality there is more parallelism than is implied by the number of cores:
- Instruction level parallelism (several assembly instructions can execute at the same time).
- Memory fetch/store parallelism (several memory locations can be transferred to registers at the same time).
- Pipeline parallelism (several things can happen in the pipeline at the same time).
- I/O parallelism (SSD's can have several controllers).
 All the above are very difficult to program.

Concurrency Primitives

• spawn, send, receive

```
Pid = spawn(fun() -> ... end)
Pid = spawn(Mod, Func, [Arg1, Arg2, ...])

Pid ! Value

receive
   Pattern1 -> Actions1;
   Pattern2 -> Actions2;
   ...
end
```

• receive is similar to case

```
case Value of
  Pattern1 -> Actions1;
  Pattern2 -> Actions2;
  ...
end
```

Exercise

- Create a registered server called double.
- If you send it an integer it doubles it and sends back the reply.
- It crashes if you send it an atom.
- Make a process that sleeps for a random time and sends a message to the double server and causes it to crash.
- Make a monitor process that detects that the server has crashed.
 It restarts the server after a random delay.
- Make a client function that sends a request to the server and times out if the request is not satisfied. We can assume the server has crashed. The client should wait a second and then try again.
- Abort the client if it has tried more than ten times.

- Run with f6:start1().
- Pid always means Process Identifier.
- How do we get the result back?

Getting the result back?

 How do we know the result we got back was from the server and not from some other process that just happend to send us a message?

 Pattern match the reply message to check that the reply comes from the correct process.

```
start3() ->
    spawn(f6, loop3, []).

loop3() ->
    receive
    {From, {square, X}} ->
        From ! {self(), X*X},
        loop3()
    end.

area_square(Pid, X) ->
    Pid ! {self(), {square, X}},
    receive
    {Pid, Area} -> Area
end.
```

Say something about selective receive ...

Selective Receive

```
receive
  Pattern1 ->
    Actions1;
  Pattern2 ->
    Actions2
end
```

This suspends until a message matching Pattern1 or Pattern2 is received. All other messages are queued.

Client - Server 4 (abstract the RPC)

```
%% old
area_square(Pid, X) ->
   Pid ! \{self(), \{square, X\}\},\
   receive
    {Pid, Area} -> Area
end.
%% refactored
area_square(Pid, X) ->
   rpc(Pid, {square, X}).
rpc(Pid, Query) ->
   Pid ! {self(), Query},
   receive
      {Pid, Reply} ->
         Reply
   end.
```

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Client - Server 5 (Tagged replies)

```
Pid = spawn(fun() -> loop() end)
loop() ->
  receive
     \{From, Tag, \{square, X\}\} \rightarrow
       Result = X * X,
       From ! {Tag, Result},
       loop()
  end.
rpc(Pid, Query) ->
   Tag = erlang:make_ref(),
   Pid ! {self(), Tag, Query},
   receive
     {Tag, Result} ->
        Result
   end.
```

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Timeouts

```
receive
  Pattern1 ->
    Actions1;
  Pattern2 ->
    Actions2;
    ...
after Time ->
    Actions
end.
```

• We detect that the server has not replied with a timeout...

```
rpc(Pid, Query) ->
  Tag = erlang:make_ref(),
  Pid ! {self(), Tag, Query},
  receive
    {Tag, Result} ->
      {ok, Result}
    after 1000 ->
      {error, timeout}
  end.
```

• Umm

```
rpc(Pid, Query) ->
   Tag = erlang:make_ref(),
   Pid ! {self(), Tag, Query},
   receive
      {Tag, Result} ->
        Result
   after TIME ->
        DO SOMETHING
   end.
```

- What is DO SOMETHING?
- What is TIME?
- Idempotence.
- Getting DO SOMETHING and TIME right is incredibly difficult.

Why is this difficult?

- We send a message to a server.
- We do not get a reply So:
- Either the server has crashed, or,
- The communication channel is broken.
 Recovering from this is very difficult (in many cases it is impossible).

Exercise (reminder)

DO SOMETHING means:

- Try again N times with a random delay and then give up.
- Write some code to randomly crash the server.
- Write some code to restart the server if it crashes.

What really happens - the mailbox

- Each process has a mailbox.
- Send causes a message to be added to the mailbox.
- When a process message is added to a mailbox the process is scheduled for execution.
- When the process next executes it checks if the new mails match any of the receive patterns.
- If the message does not match the process suspends.

The scheduler

- Processes run for 1000 reductions and are then suspended. They stay in the run queue.
- Processes waiting for a message are removed from the run-queue.
- When a message is added to the mailbox we add it to the run queue (if it is not in the run queue).
- There is one sheduler per core not really true can be two or more.
- Processes can be moved between schedulers.



The scheduler

Client Server patterns

```
Pid = spawn(fun() -> loop(State) end)
loop(State) ->
  receive
    {From, Pattern1} ->
      State1 = ...
      Result = ...
      From ! {self(), Result},
      loop(State1);
    {From, Pattern2} ->
  end.
func1(Pid, Args) -> rpc(Pid, Args).
rpc(Pid, Args) ->
  Pid ! {self(), Args},
   receive
      {Pid, Ret} -> Ret
   end.
```

A Stateful counter

```
Pid = spawn(fun() -> counter(0) end)
counter(N) ->
  receive
     \{From, \{add, K\}\} \rightarrow
       From ! \{self(), ok\},\
       counter(N+K)
  end.
add(K) \rightarrow rpc(Pid, {add, K}).
rpc(Pid, Msq) ->
  Pid ! {self(), Msg},
  receive
     {Pid, Reply} ->
        Reply
  end.
```

Extend the server

- Add extra patterns in the server.
- Add API routines.

Send functions in the messages

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Send the server in a message

```
start() ->
   spawn(fun() -> wait() end)
wait() ->
  receive
     \{become, F\} \rightarrow
      F()
  end.
Pid = start(),
Pid ! \{become, fun() \rightarrow loop/1\}.
loop(State) ->
   receive
   end
```

processes are cheap

• show this.

erl -smp disable

```
erl -smp disable
Eshell V5.10.1 (abort with ^G)

1> f6:time(100000).
{spawned, 1027305, 'processes/sec'}

2> f6:time(1000000).
{spawned, 1212416, 'processes/sec'}
```

1.2 Million processes/sec.

Registered Processes

- Pid! Message sends a message to the mailbox of the process Pid.
- How do we know Pid?
- Only the parent knows Pid

```
start() ->
  Pid = spawn(...),
  Pid ! Message,
  ...
```

Registered Processes

```
start() ->
  Pid = spawn(...),
  register(counter, Pid),
  ...
```

Now any process can send a message to the process

```
> counter ! {add, 12}
```

Tail recursion

The last thing you do is call yourself.

Non Tail recursion

Tail recursion (again)

- Co-routines.
- Continuation passing style.

If something never returns, it must be the last thing you call.

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What does Mod:Func really mean?

What's the difference between loop and loop1?

Mod:Func calls the latest version.

Spawn MFA - or fun

```
start1() ->
    spawn(Mod, Func, [Arg1, Arg2, ..., ArgN])
start2() ->
    spawn(fun() -> ... end)
```

W6/F7 - Error and Distributed Programming

- Chapters 13,14.
- Links.
- Monitors.
- The error model.
- Firewall.
- Generic Allocator.
- Why Distributed Programming?
- Erlang distribution.
- Explicit sockets and protocols.
- Distribution BIFS.
- Nano-twitter.
- Security.

Links

- When an unlinked process dies nobody will know about it.
- When a linked process dies the processes in the link-set of the process will be sent an error signal.
- A normal process receiving a non-normal error signal will die.
- A system process will convert the error signal to an error message and can receive it like any other message.
- A processes that terminates normally sends a normal error singular to its link set.

signal: {'EXIT', Pid, Why}

Why kan vara: normal

Error handling BIFs

- link (Pid) unlink (Pid)
- process_flag(trap_exit, true)
- spawn_link(Fun) spawn_link(M,F,A)
- exit(Pid, Why) exit(Pid, kill)

Trapping exits

A process that restarts a failed process

Running the watcher

Spawn and Link race conditions

```
start_and_watch() ->
  Pid = spawn(f6, loop1, []),
  spawn(f6, watch, [Pid]),
  Pid.

watch(Pid) ->
  link(Pid),
  process_flag(trap_exit, true),
  ...
```

- If you are very quick, loop1 might crash before the watcher executes the link statement.
- That's why we have spawn_link.

Monitors

- One directional links.
- A monitor is like two links "back to back".

monitors: ---->

links: <---->

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The Worker/Manager model

- Workers do work. They crash if they cannot do what they are supposed to do.
- Managers detect the failure of workers and restart them.
- start_and_watch was a very simple Worker/Manager program.
- OTP has supervisors which generalises this idea.
- Akka (Java) is a clone of this idea.

Generic Allocator

 Server links to clients and deallocates respources if the clients crash

Distributed Programming?

- Fun.
- World is distributed.

Why? ITS FUN =]

Erlang distribution

Needs only one new idea.

extra

- spawn (Node, Mod, Func, Args).
- Remote Pids work just like local Pids.
- Can test on one machine, deploy on many.

Nano twitter

```
start() ->
   register(twit, spawn(nano_twitter, watcher, [])).
watcher() ->
  receive
      Anv ->
         print({tweet, Any}),
         wat.cher()
      after 5000 ->
           print (yawn),
           watcher()
      end.
connect() ->
  pong = net_adm:ping('twit@joe').
tweet (Msg) ->
  rpc:cast('twit@joe', erlang, send, [twit, Msq]).
```

Running Nano Twitter

In one terminal:

```
erl -noshell -sname twit -s nano_twitter start yawn
```

Someplace else:

```
$ erl -sname one
(one@joe)1> nano_twitter:connect().
pong
(one@joe)2> nano_twitter:tweet('hi joe').
true
```

Back where you started:

```
yawn {tweet,'hi joe'}
```

Fun Exercise (1)

- No credits.
- Extend nano_twitter
- Work in pairs.
- Client on one machine.
- Same LAN.
- Server on a different machine

Fun Exercise (2)

- No credits.
- Server on a different machine with a different OS.
- On a WAN.

Fun Exercise (3)

- No credits.
- Get the entire class running.

Fun Exercise (4)

- Credits.
- \$\$\$\$
- Quit school.
- Form a company.
- Connect the world togther.

RTFM

- http://www.erlang.org/doc/reference_manual/distribute
- Designed for clusters in the same LAN not wide scale distribution.
- Cookie security.
- Great for tightly connected clusters in the samer administrative domain.
- Code distribution problem not solved (assumes same backend to fetch the code from) - originally all nodes read from a NFS file system.

Next Week

• Doing it with sockets :-)

Have fun

