

1) ~~dog~~ dog(x); own(x,y), feed(x,y), available(x), happy(x)
E, F, P, Fd

- 1) $\text{dog}(F) \wedge \text{dog}(P) \wedge \text{own}(E, F) \wedge \text{own}(E, P)$
- 2) $\forall x [\text{dog}(x) \wedge \exists y (\text{own}(y, x) \wedge \text{feed}(y, x))] \Rightarrow \text{happy}(x)$
- 3) $\forall x [\text{dog}(x) \wedge \text{own}(E, x)] \Rightarrow \text{loves}(E, x)$
- 4) ~~available~~ available(food) $\Rightarrow \forall x \forall y [\text{loves}(x, y) \Rightarrow \text{feed}(x, y)]$

Th) $\text{happy}(F) \wedge \text{happy}(P) \rightarrow \neg \text{Th} \cdot \neg \text{happy}(F) \vee \neg \text{happy}(P)$

1a) $\text{dog}(F)$ 1b) $\text{dog}(P)$ 1c) $\text{own}(E, F)$ 1d) $\text{own}(E, P)$

2) $\forall x \forall y [\text{dog}(x) \wedge \text{own}(y, x) \wedge \text{feed}(y, x)] \Rightarrow \text{happy}(x)$

$(\text{dog}(x) \wedge \text{own}(y, x) \wedge \text{feed}(y, x)) \Rightarrow \text{happy}(x)$

$\neg \text{dog}(x) \vee \neg \text{own}(y, x) \vee \neg \text{feed}(y, x) \vee \text{happy}(x)$

3) $\neg \text{dog}(x) \vee \neg \text{own}(E, x) \vee \text{loves}(E, x)$

4) ~~available~~ ~~food~~ $\forall x \forall y [\text{available}(\text{food}) \Rightarrow [\text{loves}(x, y) \Rightarrow \text{feed}(x, y)]]$
 $\neg \text{available}(\text{food}) \vee \neg \text{loves}(x, y) \vee \text{feed}(x, y)$

5) $\neg \text{happy}(F) \vee \neg \text{happy}(P)$

6) we ADD "available(food)"

1c) and 3) $x/F \rightarrow \neg \text{dog}(F) \vee \text{loves}(E, F)$ ⑦

1a) and ⑦ $\text{loves}(E, F)$ ⑧

8) and ④ $\neg \text{available}(\text{food}) \vee \text{feed}(E, F)$ ⑨

$x/E, y/F$

9) and 6) $\text{feed}(E, F)$ ⑩

10) and 2) $\neg \text{dog}(F) \vee \neg \text{own}(E, F) \vee \text{happy}(F)$ ⑪

11) and 1a) + 11 and 1c) $\rightarrow \text{happy}(F)$. . .

$$R(h(x), f(h(b), y)) \stackrel{?}{=} R(y, f(y, h(g(a))))$$

1) SAME NAME ✓

2) $m = n$ ✓

$$a) h(x) \stackrel{?}{=} y, b) f(h(b), y) \stackrel{?}{=} f(y, h(g(a)))$$

$$a) h(x) = y \quad \sigma = \{y / h(x)\}$$

we apply σ to b)

$$b) f(h(b), h(x)) \stackrel{?}{=} f(h(x), h(g(a)))$$

1) SAME NAME ✓

2) $m = n$ ✓

$$c) h(b) \stackrel{?}{=} h(x) \quad d) h(x) \stackrel{?}{=} h(g(a))$$

$$c) h(b) \stackrel{?}{=} h(x)$$

1) SAME NAME ✓

2) $m = n = 1$ ✓

$$e) b \stackrel{?}{=} x \Rightarrow \sigma = \{x / b, y / h(b)\}$$

we apply σ to d)

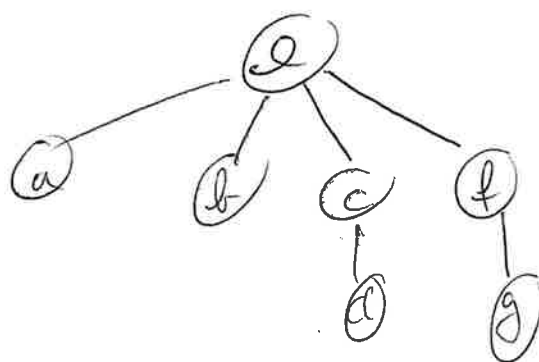
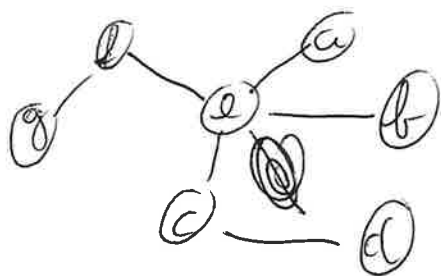
$$d) h(b) \stackrel{?}{=} h(g(a))$$

$m = n = 1$ ✓

SAME NAME ✓

$$f) b \stackrel{?}{=} g(a) \Rightarrow \text{NO UNIFICATION IS POSSIBLE}$$

$$\begin{aligned} e &= 2a & f &= 2e + 1 & c &= e + 1 \\ b &= e & g &= f - 2 & d &= 2c - 2 \end{aligned}$$



1 2 3 4 5 6 7
e, a, b, c, e, f, g

- $i = 7$
Reverse (γ, f, g) $f = g + 2$; $D_f = \{3, 4, 5, 6\}$
 - $i = 6$
Reverse (γ, e, f) $e = \frac{f-1}{2}$; $D_e = \{1, 2\}$
 - $i = 5$
Reverse (γ, c, d) $c = \frac{d+2}{2}$; $D_c = \{2, 3\}$
 - $i = 4$
Reverse (γ, e, c) $e = c - 1$; $D_e = \{2\}$
 - $i = 3$
Reverse (γ, e, b) $e = b$; $D_e = \{2\}$
 - $i = 2$
Reverse (γ, e, a) $e = 2a$; $D_e = \{2\}$
- $a = 1$, $b = 2$, $c = 3$ $d = 4$, $f = 5$, $g = 3$

$$\Delta = \{\{A, \neg C\}, \{B, C, E\}, \{B, \neg E\}, \{\neg A, C\}, \{D, E\}, \{B, \neg D\}, \{\neg D, \neg E\}, \{A, C\}\}$$

• SR $A \rightarrow F$, $\Delta = \{\{\neg C\}, \{B, C, E\}, \{B, \neg E\}, \{D, E\}, \{B, \neg D\}, \{\neg D, \neg E\}, \{C\}\}$

\hookrightarrow • UP $C \rightarrow T$ conflict, we learn $\{A\}$

$$\Delta' = \Delta \cup \{A\}$$

• UP $A \rightarrow \neg T$, $\Delta = \{\{B, C, E\}, \{B, \neg E\}, \{C\}, \{D, E\}, \{B, \neg D\}, \{\neg D, \neg E\}\}$

• UP $C \rightarrow T$, $\Delta = \{\{B, \neg E\}, \{D, E\}, \{B, \neg D\}, \{\neg D, \neg E\}\}$

• SR $B \rightarrow F$, $\Delta = \{\{\neg E\}, \{D, E\}, \{\neg D\}, \{\neg D, \neg E\}\}$

\hookrightarrow • UP $D \rightarrow \neg F$ $\Delta = \{\{\neg E\}, \{E\}\}$

\hookrightarrow • UP $E \rightarrow T$ conflict, we learn $\{B\}$

$$\Delta = \{\{B\}, \{B, \neg E\}, \{D, E\}, \{B, \neg D\}, \{\neg D, \neg E\}\}$$

• UP $B \rightarrow T$, $\Delta = \{\{D, E\}, \{\neg D, \neg E\}\}$

• SR $D \rightarrow F$, $\Delta = \{\{E\}\}$

• UP $E \rightarrow T$, $\Delta = \{\}$ ✓

MODEL : A, B, C, \bar{D}, E

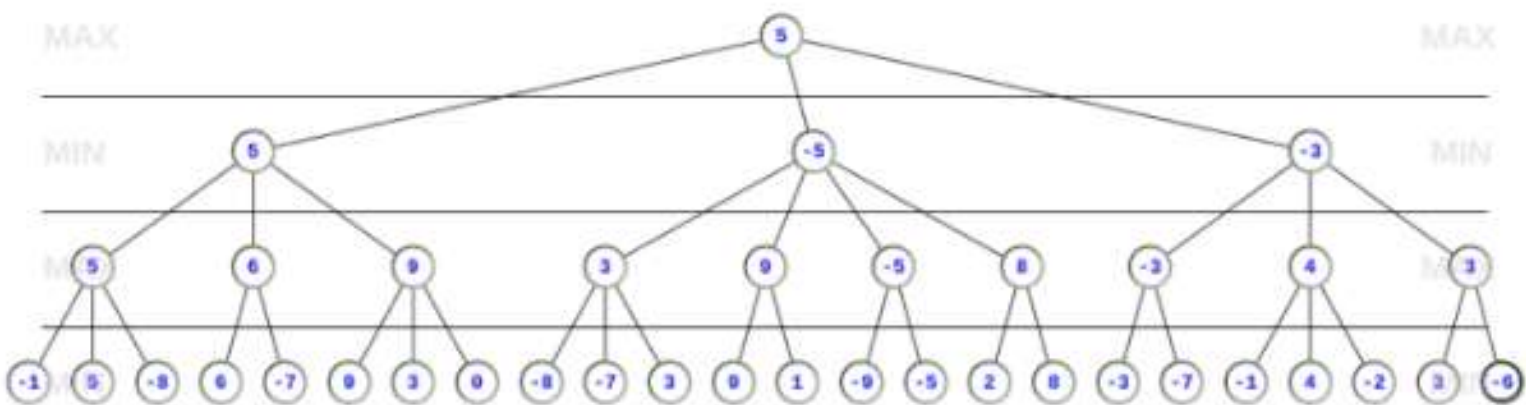


Figure 1: Caption

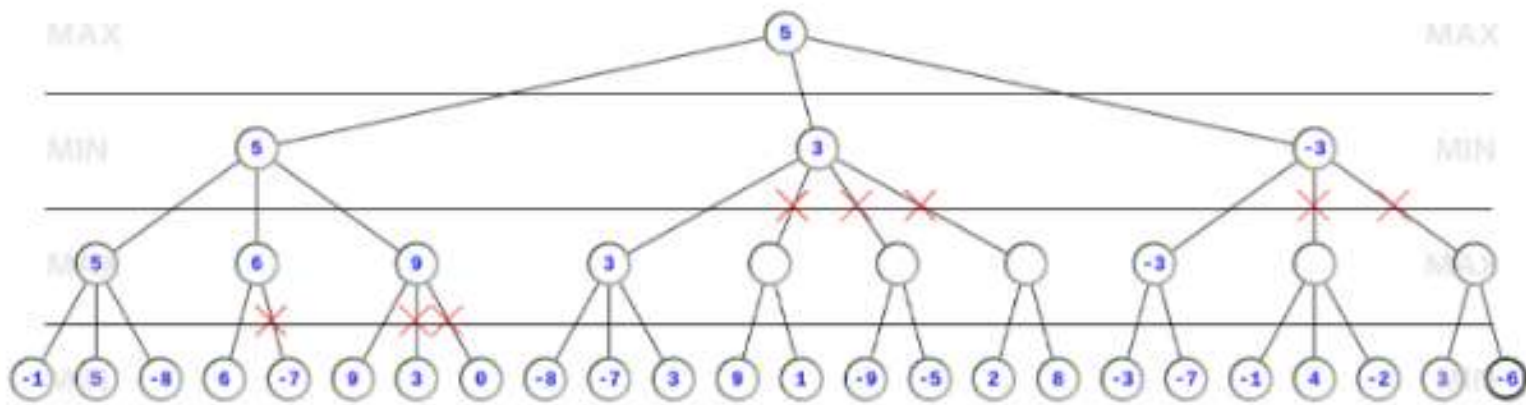


Figure 2: Caption