

# Estimating Joint Distribution of Output and PC

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## 1 Kernel Density Estimator

- Draw  $n$  samples of  $k$  from  $p(k)$
- For a fixed  $\alpha$  and  $k$ , we can calculate output,  $O$ , and 'PC' (direction describing most variance)  $\alpha_0$  where  $\alpha_0 = \alpha^T k$
- We can draw  $n$  2D gaussians centered around  $(O, \alpha_0)$  with covariance matrix:  $\epsilon I$  (tune  $\epsilon$  as hyperparameter). taking the sum of gaussians normalizing by  $1/N$ , we have:

$$P(O, \alpha_0) = \frac{1}{N} \sum_i N((O, \alpha_0); (O_i, \alpha_i), \epsilon I) \quad (1)$$

$$P(\alpha_0) = \frac{1}{N} \sum_i N(\alpha_0; \alpha_i, \epsilon) \quad (2)$$

- Sample many  $\alpha_0$  according to  $P(\alpha_0)$ . At each  $\alpha_0$ , we have a conditional distribution given by:

$$P(O|\alpha_0) = \frac{P(O, \alpha_0)}{P(\alpha_0)} = \frac{\sum_i N((O, \alpha_0); (O_i, \alpha_i), \epsilon I)}{\sum_i N(\alpha_0; \alpha_i, \epsilon)} \quad (3)$$

- Find the expectation  $E(O|\alpha_0)$  for all  $n$  alpha given by (4). Find the variance of these expectations,  $V(E(O|\alpha_0))$  and normalize by  $V(O)$

$$E(O|\alpha_0) = \frac{\sum_i O_i N(\alpha_0; \alpha_i, \epsilon)}{\sum_i N(\alpha_0; \alpha_i, \epsilon)} \quad (4)$$

## 2 Coding

- Given:  $kdraws$  ( $numSamples \times numK$ ) drawn from  $p(k)$ ,  $alpha$  ( $numK \times 1$ )
- calculate output and  $np.matmul(kdraws, alpha)$ , denote these  $O, \alpha_0$

- Fix  $\epsilon$  to some value. Determine how many samples we want from  $p(\alpha)$ , numAlpha
- for  $i$  in range(numAlpha), repeat the following steps:
  - randomly choose an element of  $a_0$ . draw a point from a gaussian  $N(a_0, \epsilon)$ , denote this value as  $a$ .
  - loop through every element of  $a_0$ ,  $a_0[i]$ . for each element, calculate the pdf:  $N(a; a_0[i], \epsilon)$ . Save all these entries as an array,  $N_i$
  - Calculate  $\text{np.dot}(O, N_i) / \text{np.sum}(N_i)$  to get  $E(O|a_0)$
- go up to step 3. Should have a matrix of expectations (numAlpha x numOutput),  $E$ . Take variance of this array over numAlpha to find the estimated SI for each output. Average over numOutput to find average SI. Normalize SI by variance

### 3 Gaussian Mixture Model

- We assume a gaussian mixture model has already been fitted to the data with  $n$  components. The probability space is 2-D with variables given by  $(O, \alpha)$ .
- Given weights,  $w$ , mean,  $\mu$ , and covariance,  $\Sigma$ , the joint probability of the GMM is given by:

$$p(O, \alpha) = \sum_{k=1}^n w_k N(O, \alpha; \mu_k, \Sigma_k) \quad (5)$$

Where  $\mu_k$  and  $\Sigma_k$  are given by:

$$\begin{aligned} \mu_k &= (\mu_{O, \alpha}) \\ \Sigma_k &= \begin{bmatrix} \Sigma_{\alpha, \alpha} & \Sigma_{\alpha, O} \\ \Sigma_{O, \alpha} & \Sigma_{O, O} \end{bmatrix} \end{aligned} \quad (6)$$

- The marginal probability of  $\alpha$  is given by:

$$P(\alpha) = \sum_{k=1}^n w_k N(\alpha; \mu_{k, \alpha}, \Sigma_{k, \alpha, \alpha}) \quad (8)$$

- The conditional probability is given by:

$$P(O|\alpha) = \frac{P(O, \alpha)}{P(\alpha)} = \frac{\sum_{k=1}^n w_k N(O, a; \mu_k, \Sigma_k)}{\sum_{k=1}^n w_k N(\alpha; \mu_{k, \alpha} \Sigma_{k, \alpha, \alpha})} \quad (9)$$

The Normal distribution in the numerator can be further simplified given that for a fixed k:

$$N(O, a; \mu, \Sigma) = N(\alpha; \mu_\alpha, \Sigma_{\alpha, \alpha}) N(O; \mu_{O|\alpha}, \Sigma_{O|\alpha}) \quad (10)$$

$$P(O|\alpha) = \sum_{k=1}^n \frac{w_k N(\alpha; \mu_\alpha, \Sigma_{\alpha, \alpha})}{\sum_{k=1}^n w_k N(\alpha; \mu_{k, \alpha} \Sigma_{k, \alpha, \alpha})} N(O; \mu_{O|\alpha}, \Sigma_{O|\alpha}) \quad (11)$$

The expectation of this distribution is given by the following:

$$E(O|\alpha) = \sum_{k=1}^n \frac{w_k N(\alpha; \mu_\alpha, \Sigma_{\alpha, \alpha})}{\sum_{k=1}^n w_k N(\alpha; \mu_{k, \alpha} \Sigma_{k, \alpha, \alpha})} \mu_{O|\alpha} \quad (12)$$

$$\mu_{O|\alpha} = \mu_O + \frac{\Sigma_{O, \alpha}}{\Sigma_{\alpha, \alpha}} (\alpha - \mu_\alpha) \quad (13)$$

Now we can draw  $\alpha$  n times, calculate Eqtn 12 for a given  $\alpha$ , and then find the variance of the expectations. The estimated sensitivity index is given by:

$$SI = \frac{Var(E(O|\alpha))}{Var(O)} \quad (14)$$

$$Var(O) = \sum_{k=1}^N w_k \cdot (\Sigma_{O, O} + \mu_{O, k}^2) - \left( \sum_{i=k}^N w_k \cdot \mu_k \right)^2 \quad (15)$$

## 4 GMM Higher Dimensions

- If we have multiple 'principle components' the formulae in the previous section can be easily adjusted
- For N PC's, we can treat  $\alpha$  as an N-dimensional vector

$$E(O|\alpha) = \sum_{k=1}^n \frac{w_k N(\alpha; \mu_\alpha, \Sigma)}{\sum_{k=1}^n w_k N(\alpha; \mu_{k, \alpha} \Sigma_{k, \alpha, \alpha})} \mu_{O|\alpha} \quad (16)$$

## 5 GMM Algorithm

- Fit a GMM with  $nComponents$  to the data, yielding weights, covariances, and means for the gaussian mixture
- Draw  $nSamples$  number of samples from the GMM.
- For each drawn sample, calculate  $E(O|\alpha)$  given in Eqtn 12.
- Calculate the variance of all the expectations.
- Calculate the total variance of  $O$  using Eqtn 15 and normalize the variance  $Var(E(O|\alpha))$  by the total variance