

1. Environment:

- a) version of OS: Ubuntu 16.04.2
- b) version of kernel: 4.10.14

2. Design of the program:

a) Basic ideas

This project will create a device which can do simple arithmetic operations and find n-th prime number. The device will be created in the “/dev” folder using “mknod” command. Also, the project will implement some basic operations to the device in the kernel which can responds to the function calls in the user space.

b) `init_modules(void)`

The function will execute the following operations step by step to set up the device:

- i. add an interrupt service routine(ISR) to the interrupt request(IRQ). For the ISR, a function called “`record_interrrupt`” is used to count the interrupt times of the keyboard.
- ii. allocate device numbers for the device using “`alloc_chrdev_region`” function.
- iii. create a character device using “`cdev_alloc`” function. Initialize it with its file operations using “`cdev_init`”. Then, the device will be bound to the device number generated in the second step using “`cdev_add`”.
- iv. allocate memory to simulate the `dma_buffer` using “`kmalloc`”.
- v. allocate memory for `work_routine` using “`kmalloc`”.

c) `drv_read(struct file *filp, char __user *buffer, size_t ss, loff_t* lo):`

First the program will check out whether the result is readable or not.

- 1. If it is readable, the program would read the data to the user buffer. After that, it will clean the result and set the result to be non-readable.

2. If it is not readable, the program would print out the error information in the logs.

d) `drv_write(struct file *filp, const char __user *buffer, size_t ss, loff_t* lo) :`

- i. First, it will read the data from the user using “get_user” and put in the dma buffer.
- ii. Then it will initialize a `work_routine` and schedule it according to the IO mode:
 - a) If the IO mode is blocking, then it will first schedule the `work_routine` and then flush it out. After that, it will set the result to be readable.
 - b) If the IO mode is non_blocking, then it will first schedule the `work_routine`. Then it will set the answer to be non-readable.

e) `drv_ioctl(struct file *filp, unsigned int cmd, unsigned long arg):`

The function will check the input command from user and do the corresponding operations in the kernel space.

- i. If “cmd” is `HW5_IOCSETSTUID`:
Store the data passed from the user space in “arg” to the DMA buffer indicated by `DMASTUIDADDR` and print out the operation.
- ii. If “cmd” is `HW5_IOCSETRWOK`:
Store the data passed from the user space in “arg” to the DMA buffer indicated by `DMARWOKADDR` and print out the operation.
- iii. If “cmd” is `HW5_IOCSETIOCOK`:
Store the data passed from the user space in “arg” to the DMA buffer indicated by `DMAIOCOKADDR` and print out the operation.
- iv. If “cmd” is `HW5_IOCSETIRQOK`:
Store the data passed from the user space in “arg” to the DMA buffer

indicated by DMAIRQOKADDR and print out the operation.

- v. If “cmd” is HW5_IOCSETBLOCK:

Store the data passed from the user space in “arg” to the DMA buffer indicated by DMABLOCKADDR and print out the blocking type according to the user input.

- vi. If “cmd” is HW5_IOCWAITREADABLE:

First, it will check out the readable signal in the DMA which is indicated by DMAREADABLEADDR. If the readable signal 0 which means the answer is not ready, then it will wait until the work routine is finished. After that, it will return the readable signal 1 to the user.

- vii. If “cmd” is not one of the previous signals:

The function will print out the error.

- f) `drv_arithmetic_routine(struct work_struct* ws):`

This function is used to do the arithmetic calculation in the work routine.

- i. First, it will set the readable signal to 0 indicating false.
- ii. Second, it will retrieve the data stored in the DMA memory.
- iii. Third, it will do the corresponding operations of the data according to the operator character. And the calculated result will be store in the DMA buffer indicated by DMAANSADDR.
- iv. Then it will check the I/O mode in the DMA and set the readable to 1 if it is in non-blocking mode.

- g) `prime(int base, short nth):`

This function is just the one used in the test.c. It is used to find out the n^{th} prime number.

- h) `record_interrupt(int irq, void* dev_id):`

This function is used to record the interrupt count. If the keyboard interrupt occurs, it will increment the count by 1.

i) `exit_modules(void)`:

This function will be called when the module is removed from the kernel. And it will do the following steps by order:

- i. free the interrupt service routine using “`free_irq`”
- ii. free the DMA memory using “`kfree`”
- iii. delete the character device using “`cdev_del`”. Then it will unregister the device numbers allocated for the device.
- iv. free the work routine.

3. Execution steps of the program:

- a) open the terminal in the “Source” folder.
- b) enter the command “`sudo make`” in the terminal
- c) type the “`dmesg`” to get the allocated device number
- d) use “`sudo ./mkdev.sh (major) (minor)`” to create the device to create a file system node. The (major) and (minor) in the command are the device numbers shown in the last step.
- e) if the node already exists, you can type “`sudo ./rmdev.sh`” to remove the existed node and created it again with last step.
- f) type “`./test`” in the terminal to run the test program.
- g) type “`sudo make clean`” to remove the module.
- h) type “`sudo ./rmdev.sh`” to remove the created system node.

4. Output:

- a) user program:

```

[12/06/20]seed@VM:~/.../Source$ ./test
.....Start.....
100 p 10000 = 105019

Blocking IO
ans=105019 ret=105019

Non-Blocking IO
Queueing work
Waiting
Can read now.
ans=105019 ret=105019

.....End.....

```

b) kernel output:

```

[ 344.586140] OS_AS5:init_modules():.....Start.....
[ 344.586148] OS_AS5:init_modules(): request_irq 1 return 0
[ 344.586150] OS_AS5:init_modules(): register chrdev(245,0)
[ 344.586152] OS_AS5:init_modules(): allocate dma buffer
[ 377.327567] OS_AS5:drv_open(): device open
[ 377.327571] OS_AS5:drv_ioctl(): My STUID is = 118010224
[ 377.327572] OS_AS5:drv_ioctl(): RW OK
[ 377.327573] OS_AS5:drv_ioctl(): IOC OK
[ 377.327574] OS_AS5:drv_ioctl(): IRQ OK
[ 378.410424] OS_AS5:drv_ioctl(): Blocking IO
[ 378.410427] OS_AS5:drv_write(): queue work
[ 378.410428] OS_AS5:drv_write(): block
[ 379.104313] OS_AS5:drv_arithmetic_routine(): 100 p 10000 = 105019
[ 379.106820] OS_AS5:drv_read(): ans = 105019
[ 379.106830] OS_AS5:drv_ioctl(): Non-Blocking IO
[ 379.106832] OS_AS5:drv_write(): queue work
[ 379.797744] OS_AS5:drv_arithmetic_routine(): 100 p 10000 = 105019
[ 384.231228] OS_AS5:drv_ioctl(): wait readable 1
[ 384.231249] OS_AS5:drv_read(): ans = 105019
[ 384.231530] OS_AS5:drv_release(): device close
[ 396.259526] OS_AS5:exit_modules(): interrupt count=128
[ 396.259530] OS_AS5:exit_modules(): free dma buffer
[ 396.259531] OS_AS5:exit_modules(): unregister chrdev
[ 396.259532] OS_AS5:exit_modules():.....End.....
[12/06/20]seed@VM:~/.../Source$ █

```

5. Problems I met in this project:

Since it is the first time for me to program with the I/O operation, I didn't know where to start this project at first. Then after reading and studying the tutorials' materials and lecture notes, I got to know the basic knowledge of this program and understand the basic framework of this project. Finally, I managed to finish the project.

6. What I learnt from this project:

First, I learnt some basic knowledge of the I/O system. By implementing a simple prime number device, I learnt how to allocate device numbers and set up and initialize devices. Also, I also learnt the basic knowledge of the interrupt routine and how to set the handler when the interrupt occurs.