

Triadic Projection Semantics

Abstract

We refine the Deleuze-aligned difference triad to a mathematically auditable device that integrates with a pullback-based structural core. The projection pipeline

$$\Phi_\kappa = q_\kappa \circ \rho \circ \text{Obs}_\star : X \rightarrow I_\kappa$$

induces three regimes: *Displacement* (kernel flow), *Symmetry/Masquerade* (a Φ_κ -preserving étale groupoid action), and *Bifurcation* (transverse discriminant crossings). We separate the discriminant into mechanism-side differential criticality, appearance-side image singularities, and policy-side semantic jumps, and we upgrade the space of forms by a jet-augmented orbit construction. On a regularity hypothesis we prove invariance laws, a short exact sequence

$$0 \rightarrow \ker d\Phi_\kappa \rightarrow TX \xrightarrow{d\Phi_\kappa} \Phi_\kappa^*(TI_\kappa) \rightarrow 0,$$

a Lie correspondence on the identity component, and a dynamic normal form (displacement \circ symmetry \circ displacement). Interfaces to the event-visible layer and to the pullback alignment space are stated explicitly.

1 Motivation and Adjustments

We adopt the standard academic naming and strengthen audibility: (i) rename *Masquerade* as *Symmetry (Masquerade)* to emphasize groupoid actions; (ii) explicitly use an étale groupoid for Φ_κ -preserving local diffeomorphisms, recording isotropy types; (iii) add a jet-augmentation to boundary types to stabilize audits near singular sets; (iv) separate the discriminant into three disjoint sources (mechanism/appearance/policy) to avoid conflation; (v) retain the triad as complete for regular-region classification; singular windows are handled by exception rules only.

Structure of the Section. Section 2 fixes notation and the regularity hypothesis. Section 3 defines the triad and the discriminant calculus. Section 4 constructs forms via groupoid orbits with jet augmentation. Section 5 proves the regular-region results (exactness, Lie correspondence, dynamic normal form). Section 6 states the event-visible and pullback interfaces. A two-line toy example closes the section.

2 Notation and Regularity

Let $X = \Delta_{\text{gen}}$ be the generated difference space. Fix a readable gate $U_\star \subseteq X$ and an observation map $\text{Obs}_\star : U_\star \rightarrow \delta_\star$ with a public test family T_\star (calibration, thresholds, time windows, sampling law). Let $\rho : \delta_\star \rightarrow \mathcal{R}$ be a least-form selector; let $q_\kappa : \mathcal{R} \rightarrow I_\kappa$ be an identity-criterion projection ($\kappa \in \{\text{identity, similarity, analogy, negation}\}$). Set $\Phi_\kappa = q_\kappa \circ \rho \circ \text{Obs}_\star : X \rightarrow I_\kappa$. Write $\Sigma \subset I_\kappa$ for appearance singularities and $I_\kappa^{\text{reg}} = I_\kappa \setminus \Sigma$. Let $\nu : I_\kappa^{\text{reg}} \rightarrow \mathcal{R}$ be the type map; define the kernel distribution $\mathcal{V} := \ker d\Phi_\kappa \subset TX$.

Regularity hypothesis (H_{reg}). On $X \setminus \text{Disc}(\Phi_\kappa)$ the differential $d\Phi_\kappa$ has locally constant rank; ρ is locally constant; ν is locally constant along Φ_κ -fibres.

3 The Triad and the Discriminant Calculus

Definition 3.1 (Difference triad). Displacement is the flow along $\mathcal{V} = \ker d\Phi_\kappa$; if $\dot{x} \in \mathcal{V}$, then $\Phi_\kappa(x(t))$ is locally constant. Symmetry (Masquerade) is the action of the Φ_κ -preserving étale groupoid

$$\text{Aut}_{\Phi_\kappa} := \{ g : U \rightarrow V \text{ local diffeomorphism} \mid \Phi_\kappa \circ g = \Phi_\kappa \text{ on } U \}.$$

Bifurcation (deterritorialization) is a transverse crossing of the discriminant that changes the type ν .

Definition 3.2 (Discriminant split). The discriminant decomposes as

$$\text{Disc}(\Phi_\kappa) = \underbrace{\text{Crit}(\Phi_\kappa)}_{\text{mechanism: rank drop}} \cup \underbrace{\Phi_\kappa^{-1}(\Sigma)}_{\text{appearance: image folds}} \cup \underbrace{J(\rho \circ \text{Obs}_\star)}_{\text{policy: semantic jump}}.$$

On $X \setminus \text{Disc}(\Phi_\kappa)$ the map Φ_κ is a submersion and ν is locally constant.

Remark 3.1 (Boundary semantics). A pair (r_i, r_j) is a semantic boundary when $\overline{\nu^{-1}(r_i)}$ and $\overline{\nu^{-1}(r_j)}$ meet along $\text{Disc}(\Phi_\kappa)$. A boundary witness is a curve γ with $\gamma \pitchfork \text{Disc}(\Phi_\kappa)$ and a recorded jet-type change.

4 Forms by Groupoid Orbits and Jet Augmentation

Definition 4.1 (Orbit forms). Let \mathcal{P} be the pseudogroup generated by local flows of vector fields in $\Gamma(\mathcal{V})$ and by arrows of Aut_{Φ_κ} . For $z, z' \in \delta_\star$, write $z \sim z'$ if $z' = h \cdot z$ for some $h \in \mathcal{P}$. The space of forms is $\mathcal{R} := \delta_\star / \sim$, stratified by isotropy type. A jet-augmented representative is

$$r = (\text{nf}(z), [\text{Iso}(z)], \mathbf{j}_z),$$

where $[\text{Iso}(z)]$ is the stabilizer class and \mathbf{j}_z is a finite germ/jet anchored on $\text{Disc}(\Phi_\kappa)$ for auditable boundary types.

5 Regular-Region Results

Proposition 5.1 (Exactness at regular points). *Under (H_{reg}) there is a short exact sequence of vector bundles*

$$0 \longrightarrow \mathcal{V} \longrightarrow TX \xrightarrow{d\Phi_\kappa} \Phi_\kappa^*(TI_\kappa) \longrightarrow 0,$$

and $\mathcal{V}_x = T_x(\Phi_\kappa^{-1}(\Phi_\kappa(x)))$.

Theorem 5.1 (Lie correspondence, identity component). *Let $\Gamma(\mathcal{V}) = \{V \in \mathfrak{X}(X) : d\Phi_\kappa \circ V = 0\}$. If V integrates, its local flow ψ_t preserves Φ_κ . Conversely, a path $g_t \in \text{Aut}_{\Phi_\kappa}$ with $g_0 = \text{id}$ has generator $V \in \Gamma(\mathcal{V})$. Hence*

$$\text{Lie}(\text{Aut}_{\Phi_\kappa}^0) \cong \Gamma(\mathcal{V}).$$

Theorem 5.2 (Dynamic normal form). *Any local Φ_κ -preserving evolution on I_κ^{reg} factors as*
displacement \circ symmetry (masquerade) \circ displacement.

Near the singular set, bifurcations must be admitted.

Remark 5.1 (Exception window). *At $\text{Disc}(\Phi_\kappa)$, the dimension of \mathcal{V} may jump; vertical flows may fail to preserve Φ_κ globally. Results above apply on regular open sets; singular cases require stratified or semialgebraic refinements.*

6 Event-Visible and Pullback Interfaces

Event-visible layer. Equip the bridging theory \mathcal{A}_{\min} with time and replayable traces, producing \mathcal{A}_{evt} and a functor $J : \mathcal{A}_{\min} \rightarrow \mathcal{A}_{\text{evt}}$. Define the event-visible alignment space

$$\mathcal{P}_{\text{evt}} := \mathcal{C}_W \times_{\mathcal{A}_{\text{evt}}} \mathcal{D}_W.$$

Non-isolated interleavings that change Φ_κ or ν across executions break alignment; isolation/compensation must be declared.

Pullback interface. Let $F : \mathcal{C}_W \rightarrow \mathcal{A}_{\min}$ and $G : \mathcal{D}_W \rightarrow \mathcal{A}_{\min}$ be faithful bridging functors; let $S : \mathcal{A}_{\min} \rightarrow \delta_\star$ preserve T_\star . For $(X, A, \theta) \in \mathcal{P} := \mathcal{C}_W \times_{\mathcal{A}_{\min}} \mathcal{D}_W$, *semantic compatibility* holds when

$$\rho(S \circ F(X)) = \rho(S \circ G(A)), \quad \Phi_\kappa(S \circ F(X)) = \Phi_\kappa(S \circ G(A))$$

on a regular neighborhood in I_κ^{reg} .

7 Toy Example (two lines)

Let $\Phi(x, y) = (x, y^2)$ and $\rho(u, v) = \mathbf{1}_{\{v \geq 1\}}$. Then

$$\text{Crit}(\Phi) = \{y = 0\}, \quad \Sigma = \{v = 0\} = \Phi(\text{Crit}), \quad J(\rho \circ \Phi) = \{y = \pm 1\}.$$

Displacement flows slide along $\{(x, y) : y \neq 0\}$ preserving $v = y^2$; symmetry adds $(x, y) \mapsto (x, -y)$; crossing $y = \pm 1$ flips the type ν .

Minimal Audit Ledger (this module)

Gate U_\star and tests T_\star ; ρ , q_κ , Φ_κ ; discriminant report $\text{Crit} \cup \Phi_\kappa^{-1}(\Sigma) \cup J(\rho \circ \text{Obs}_\star)$; groupoid data (arrows, isotropy classes); jet-augmented form representatives; regularity domain; boundary witnesses (curves and jet-type transitions).