CS 4104
APPLIED MACHINE LEARNING

Dr. Hashim Yasin

National University of Computer and Emerging Sciences,

Faisalabad, Pakistan.

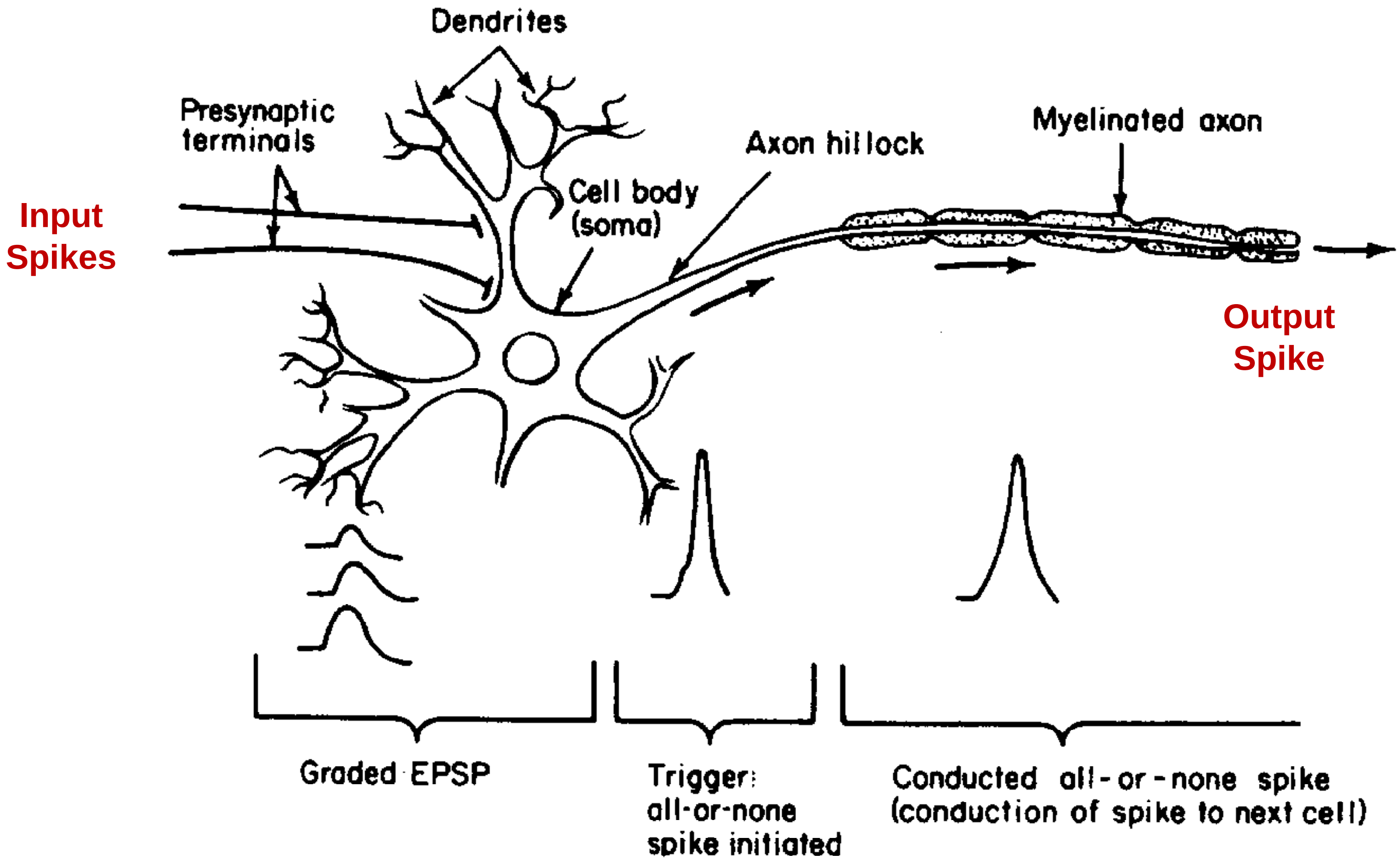
ARTIFICIAL NEURAL NETWORK

Biological Inspiration

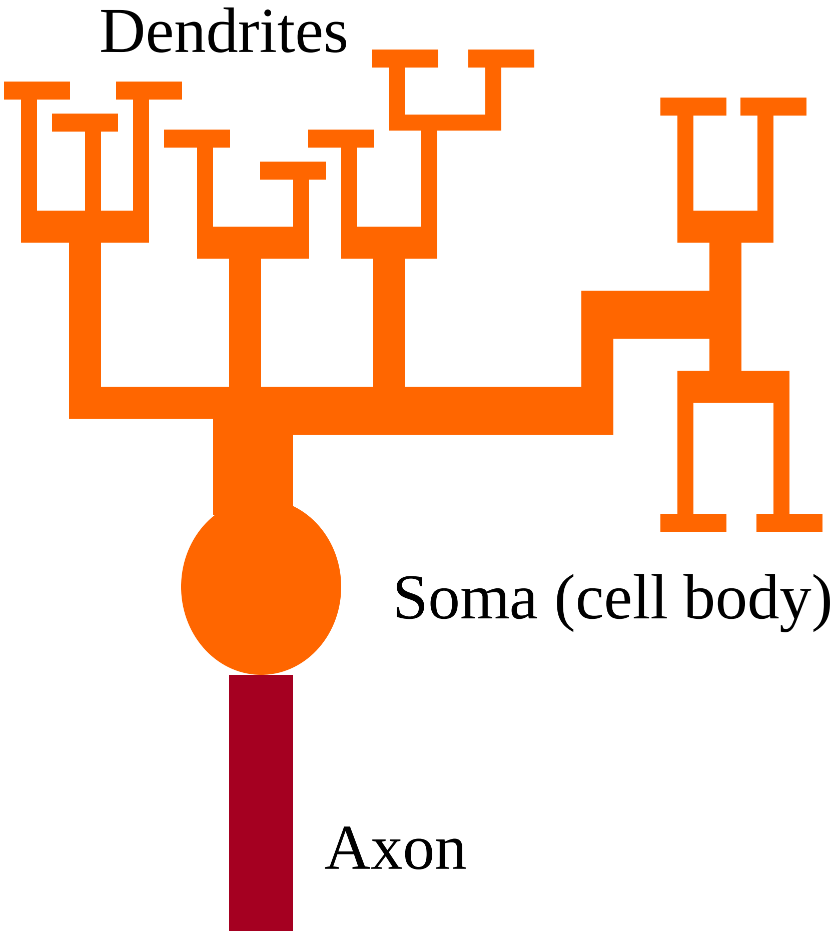
- Animals are able to **react adaptively to changes** in their external and internal environment, and they use their **nervous system** to perform these behaviours.

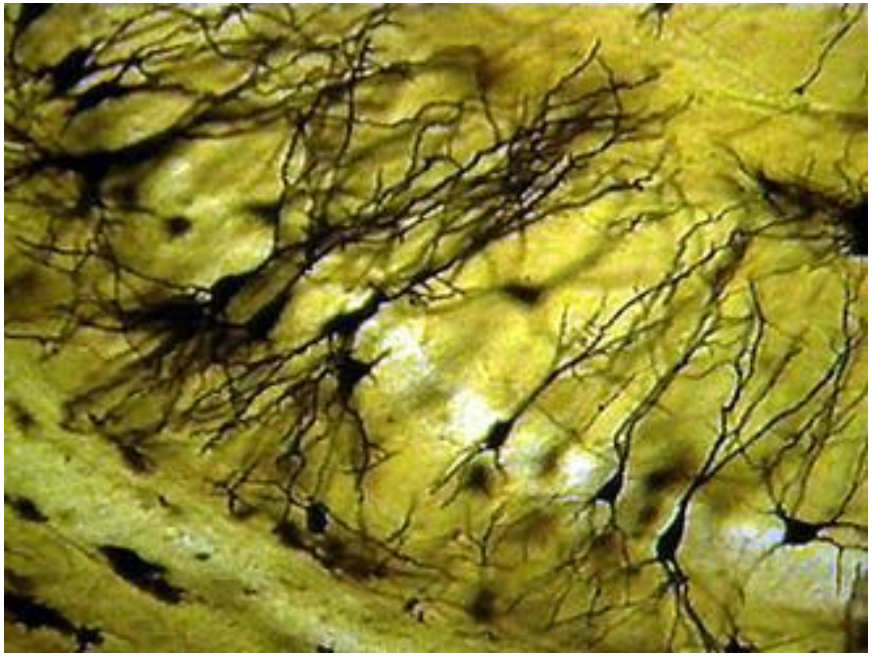
- An *appropriate model/simulation of the nervous system* should be able to produce similar responses and behaviours in artificial systems.

Biological Inspiration



Biological Inspiration





Biological Inspiration

Four Parts of Typical Nerve Cell:

- **Dendrites:**

  accepts the inputs

- **Soma:**

  process the inputs

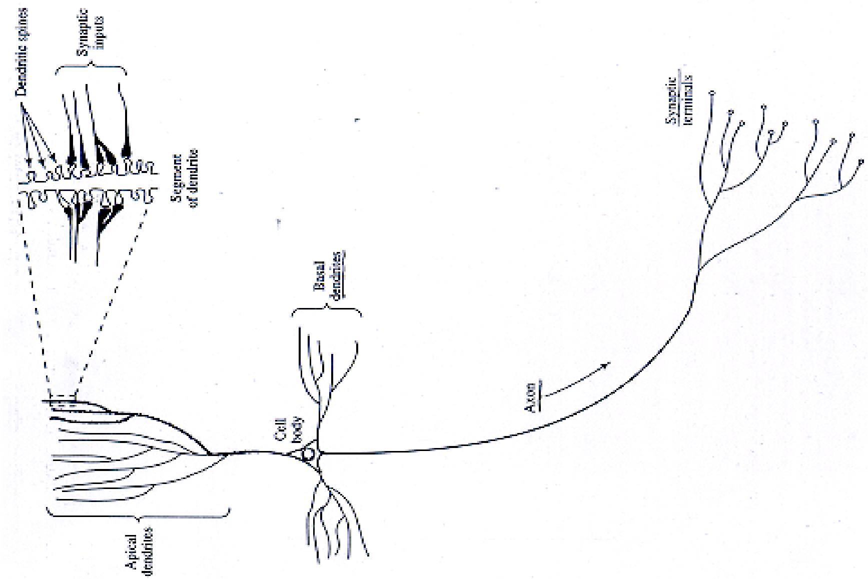
- **Axon:**

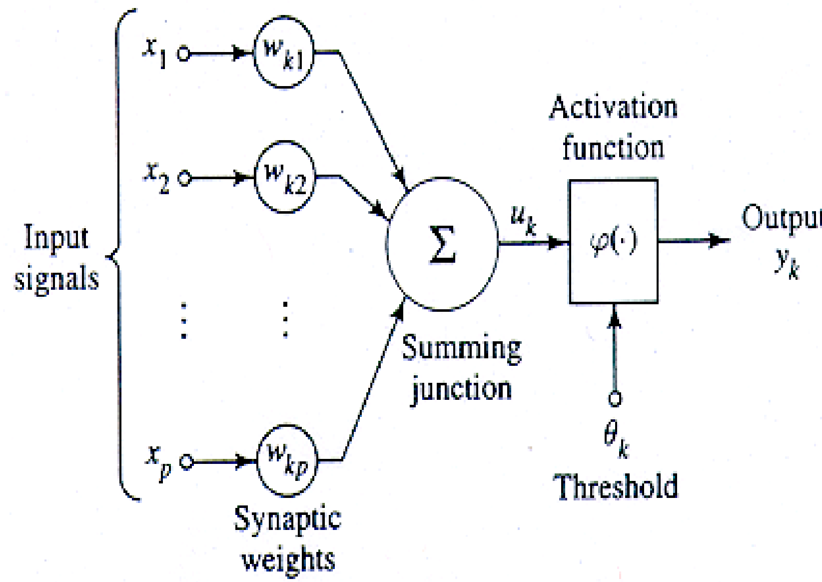
  turns the process input into outputs

- **Synapses:**

  the electromechanical contact between the neurons

Biological Inspiration



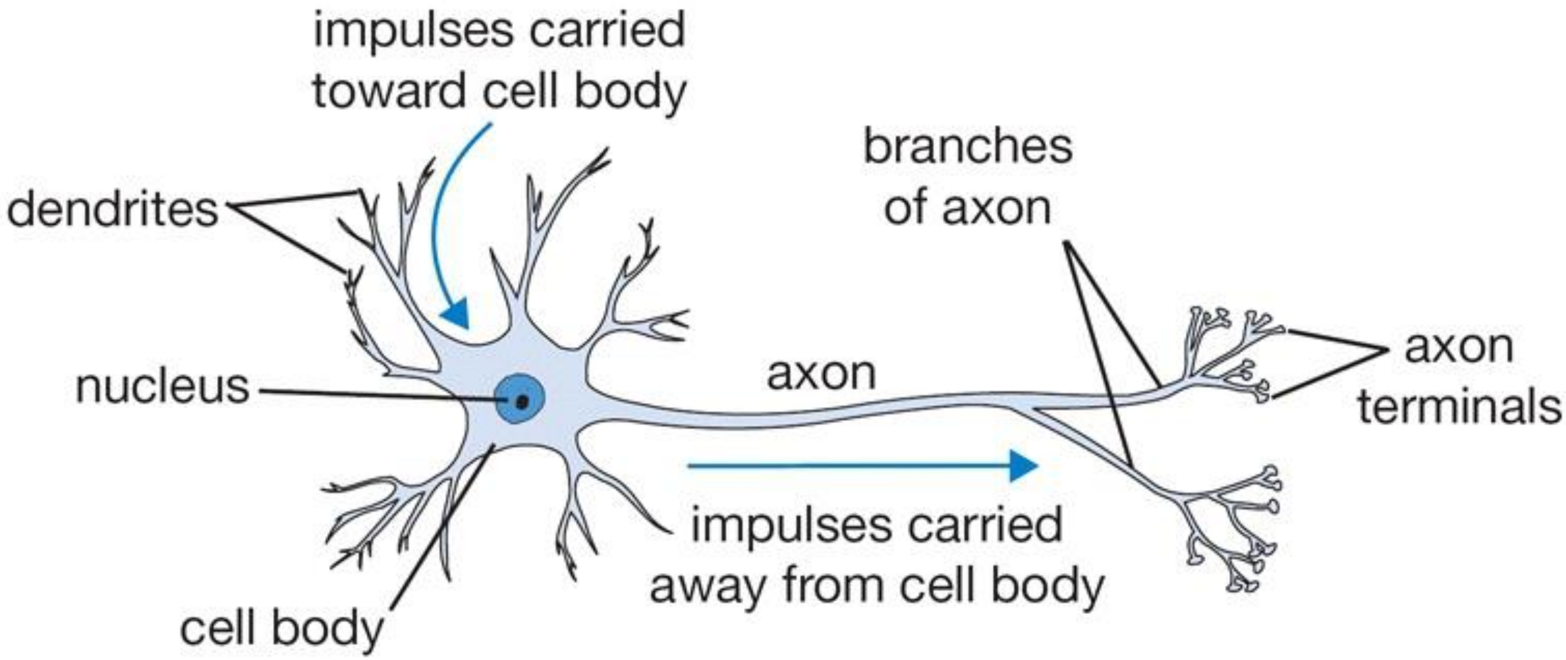


Dendrite

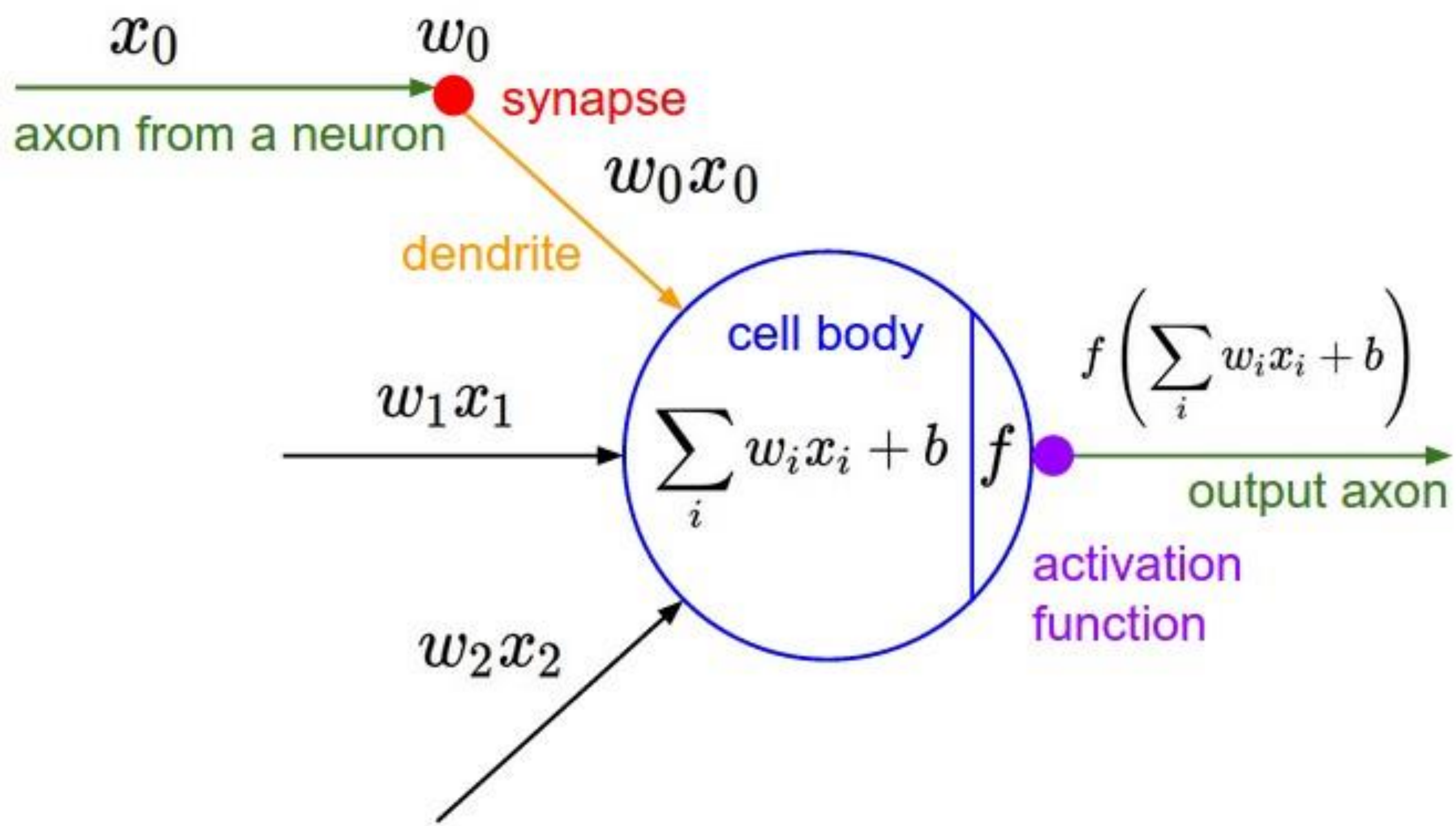
Cell Body

Axon

Biological Inspiration



Biological Inspiration



PERCEPTRON

Perceptron

- A simplest type of ANN system is based on a unit called a **perceptron**. A perceptron
  - takes a **vector of real-valued inputs**,
  - calculates a linear combination of these inputs,
  - then **outputs** a 1 if the result is greater than some ***threshold*** and -1 otherwise.
- More precisely, given inputs $\boldsymbol{x_1}$ through $\boldsymbol{x_n}$ the output $\boldsymbol{o(x_1, \ldots, x_n)}$ computed by the perceptron is

$$o(x_1, \ldots, x_n) = \begin{cases} 1 & \text{if} \quad w_0 + w_1 x_1 +, \ldots, +w_n x_n > 0 \\ -1 & \text{otherwise} \end{cases}$$

Perceptron

$$o(x_1, \ldots, x_n) = \begin{cases} 1 & \text{if} \quad w_0 + w_1 x_1 +, \ldots, +w_n x_n > 0 \\ -1 & \text{otherwise} \end{cases}$$

- where each w_i is a real-valued constant, or weight,
  - that *determines the contribution of input* x_i to the perceptron output.
- The quantity (w_0) is a threshold
  - the weighted combination of inputs $w_1 x_1 + \ldots + w_n x_n$ must exceed in order for the perceptron to output a 1.

Perceptron

- We may imagine an *additional constant input* $x_0 = 1$, allowing to write the above inequality as,

$$\sum_{i=0}^{n} w_i x_i > 0$$

or in **vector form** as

$$o(\mathbf{x}) = \begin{cases} 1 & \text{if} \quad \mathbf{w}.\mathbf{x} > 0 \\ -1 & \text{otherwise} \end{cases}$$

$$\mathbf{x} = \vec{x}$$

$$sgn(y) = \begin{cases} 1 & \text{if} \quad y > 0 \\ -1 & \text{otherwise} \end{cases}$$

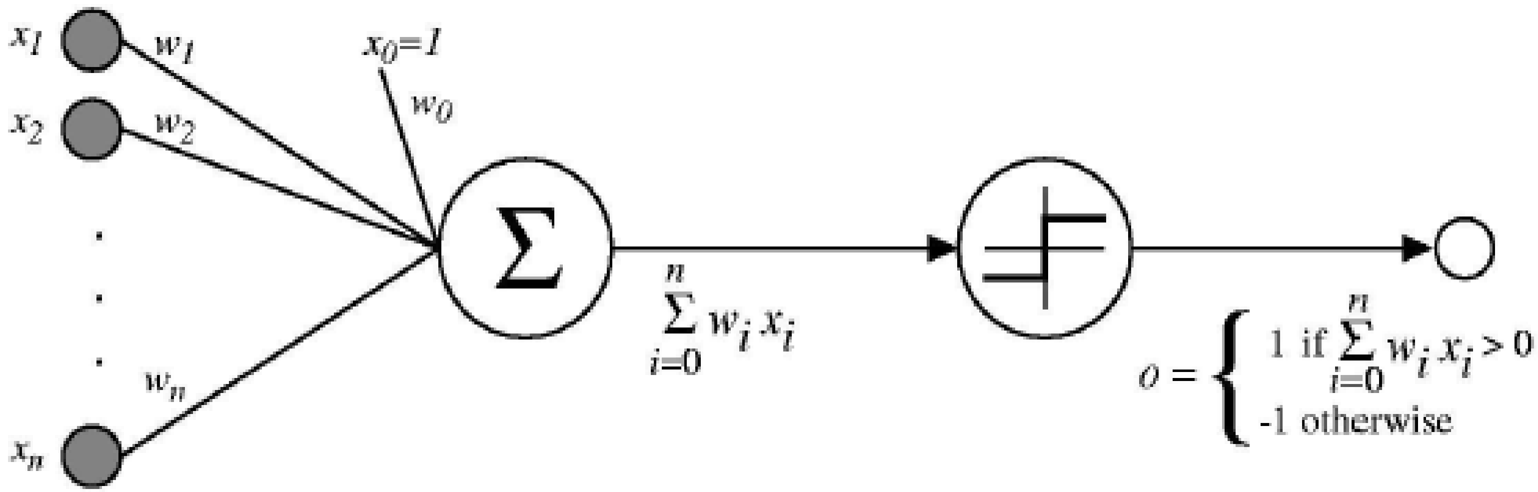
Perceptron

- *Learning a perceptron involves choosing values for the weights* $w_0, \ldots, w_n$.

- Therefore, the space H of candidate hypotheses considered in perceptron learning is the *set of all possible real-valued weight vectors*

$$H = \left\{\vec{w} \mid \vec{w} \in \Re^{(n+1)}\right\}$$

Perceptron



$$o(x_1, \ldots, x_n) = \begin{cases} 1 & \text{if } w_0 + w_1 x_1 + \cdots + w_n x_n > 0 \\ -1 & \text{otherwise.} \end{cases}$$

Perceptron

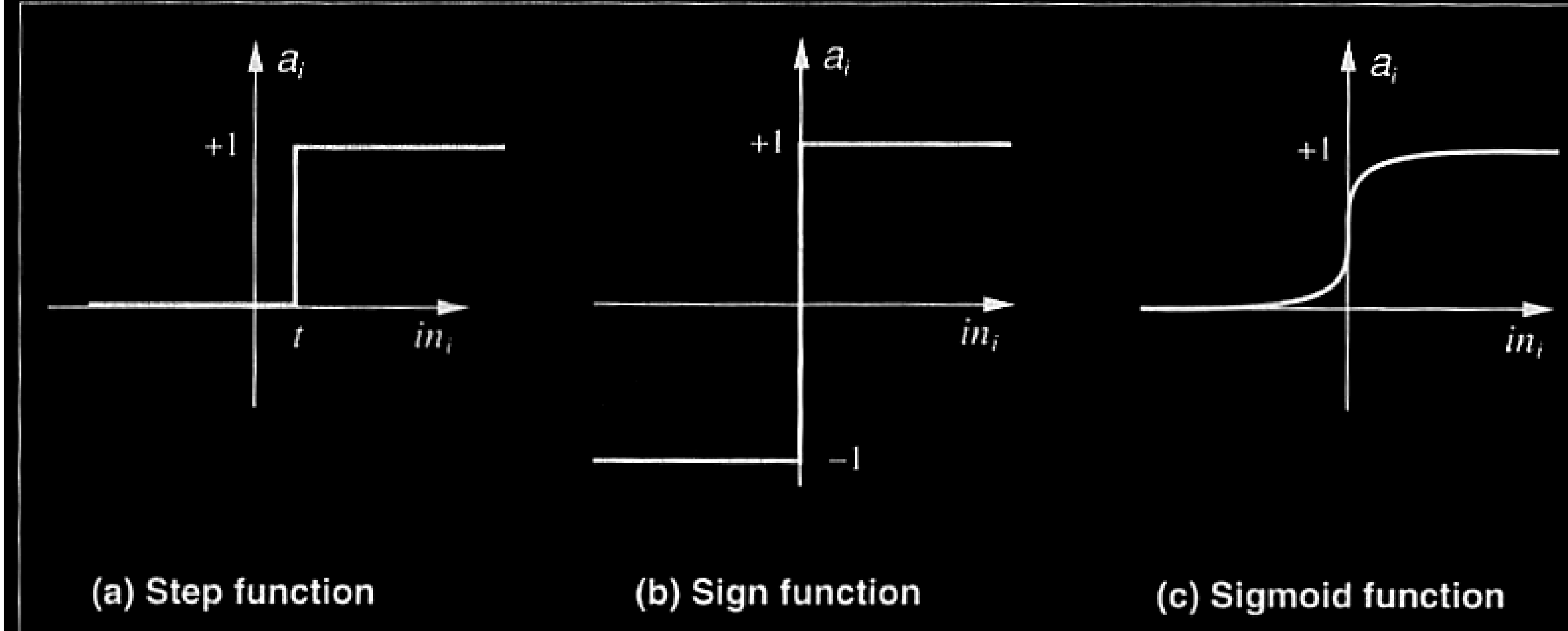


Figure 19.5 Three different activation functions for units.

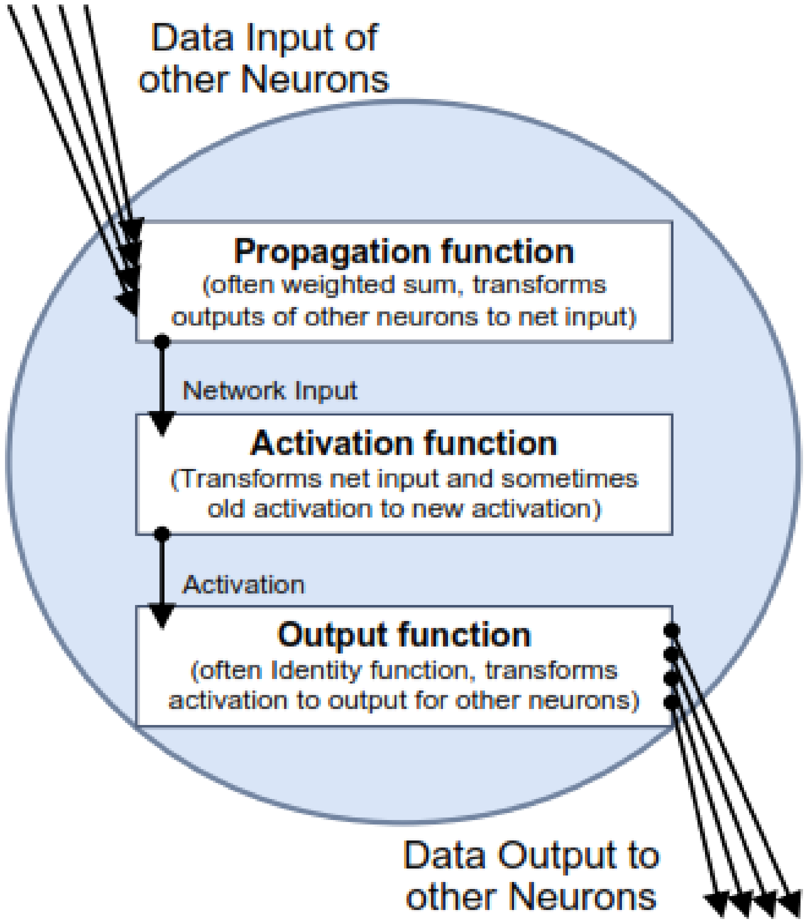
$$\text{step}_t(x) = \begin{cases} 1, & \text{if } x \geq t \\ 0, & \text{if } x < t \end{cases} \quad \text{sign}(x) = \begin{cases} +1, & \text{if } x \geq 0 \\ -1, & \text{if } x < 0 \end{cases} \quad \text{sigmoid}(x) = \frac{1}{1 + e^{-x}}$$

NEURAL NETWORK COMPONENTS

Neural Network Components

- A ***neural network*** is a sorted **triple (N, V, w)** with two sets N, V and a function w,
  - whereas N is the set of *neurons* and
  - V is a sorted set $\{(i, j) | i, j \in N\}$ whose elements are called ***connections*** between neuron i and neuron j.
- The function $w : V \rightarrow R$ defines the ***weights***, where as $w(i, j)$,
  - The weight of the connection between neuron i and neuron j, is shortly referred to as $w_{i,j}$.

Neural Network Components

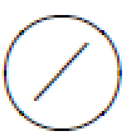


Input Neuron

- An ***input neuron*** is an ***identity neuron***. It exactly forwards the information received.

- Input neuron only forwards data

- Thus, it represents the **identity function**, which can be indicated by the symbol /

- The input neuron is represented by the symbol 

Binary Neuron

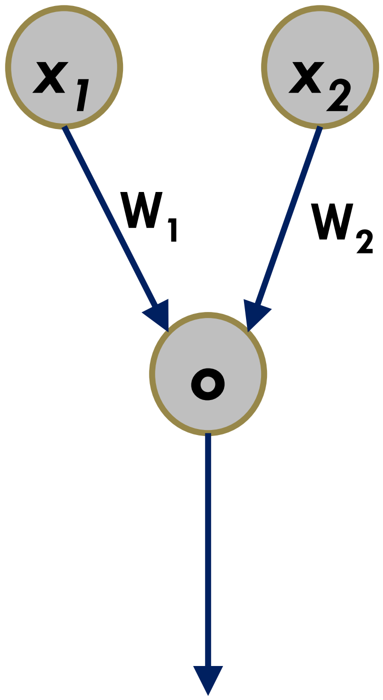
- **Information processing neurons** process the input information somehow, *i.e.* do not represent the identity function.
- A **binary neuron** sums up all inputs by using the weighted sum as **propagation function**, which is illustrate by the sigma sign.

$$\sum$$

- The **activation function** of the neuron is also binary threshold function, which can be illustrated by

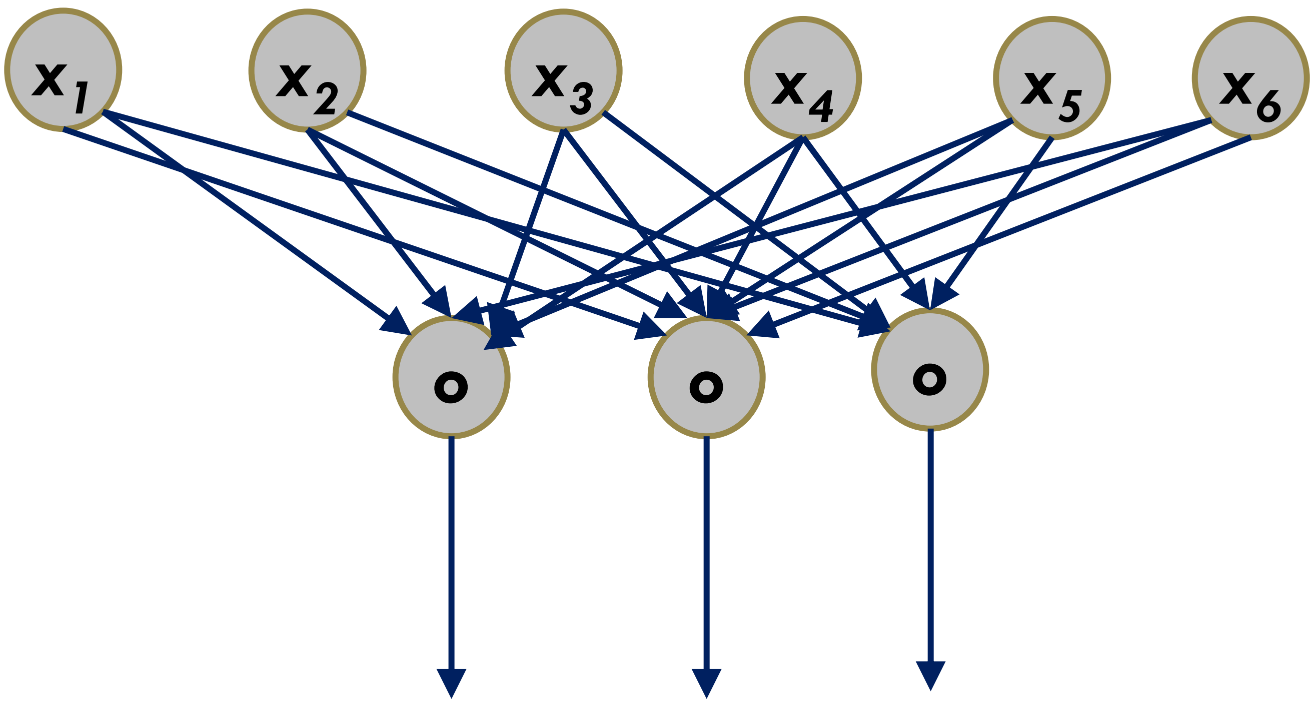
Single-Layer Perceptron

- A ***Single-layer perceptron (SLP)*** is a perceptron having only one variable-weight layer and one layer of output neurons.
- The technical view of an SLP with two input neurons and one output neuron is shown in the figure.
- The network returns the output by means of the arrow leaving the network.



Single-Layer Perceptron

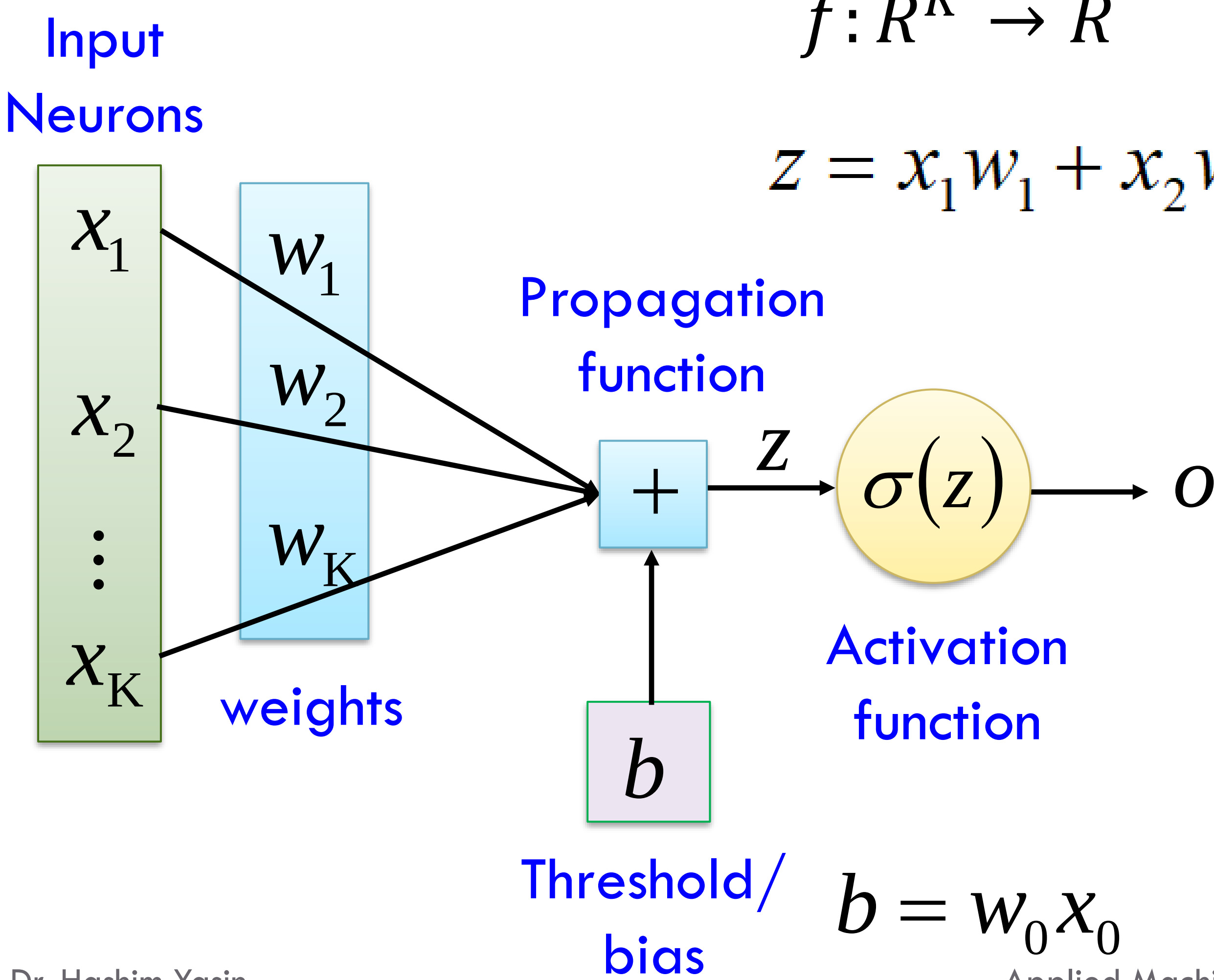
- A ***Single-layer perceptron*** (***SLP***) with several output neurons.



Neural Network Components

$$f: R^K \to R$$

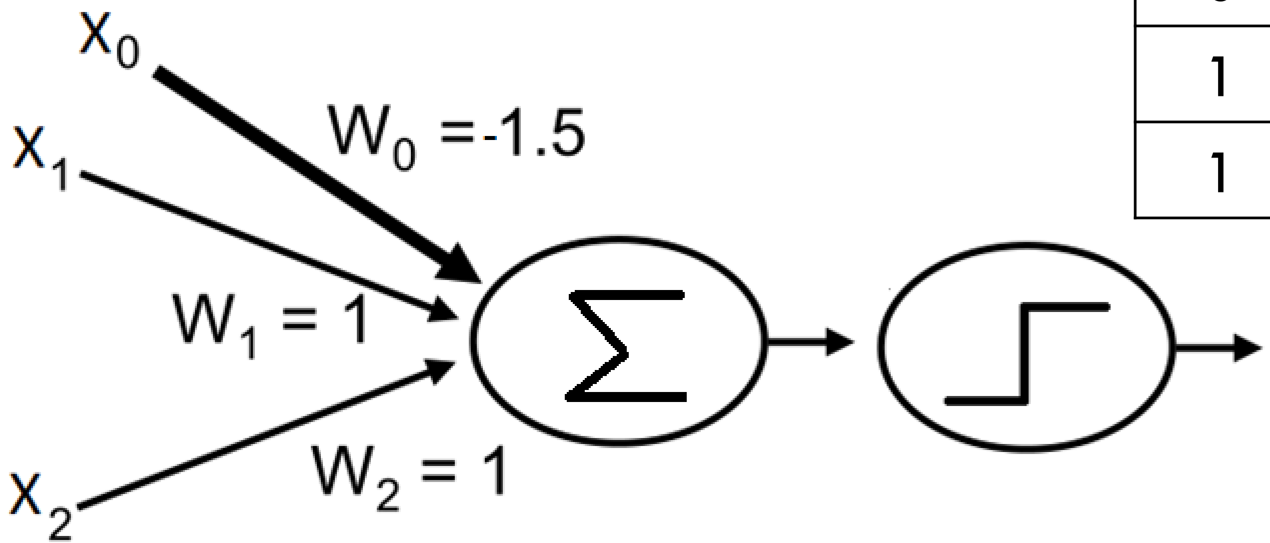
$$z = x_1 w_1 + x_2 w_2 + x_K w_K + b$$



$$b = w_0 x_0$$

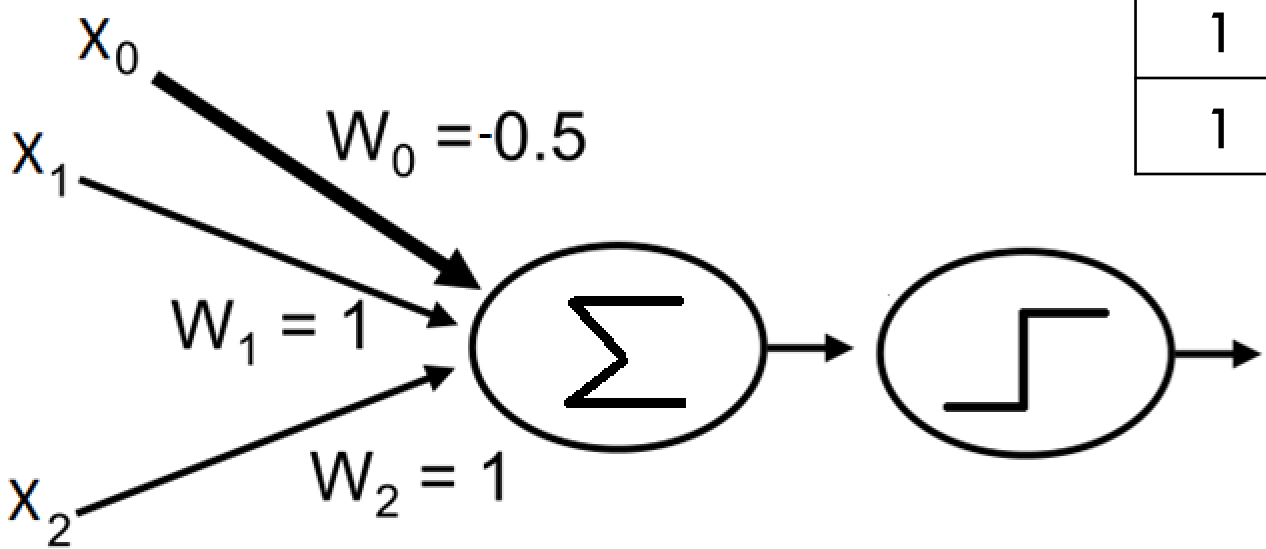
AND Function

X_1	X_2	Y
0	0	0
0	1	0
1	0	0
1	1	1

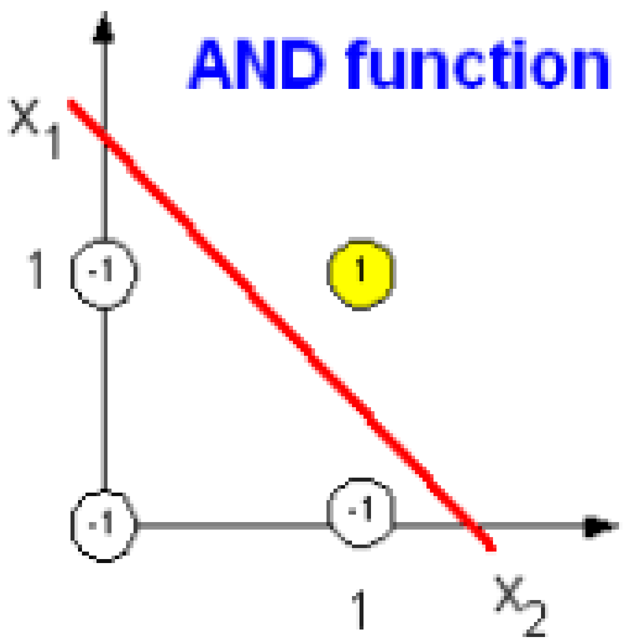


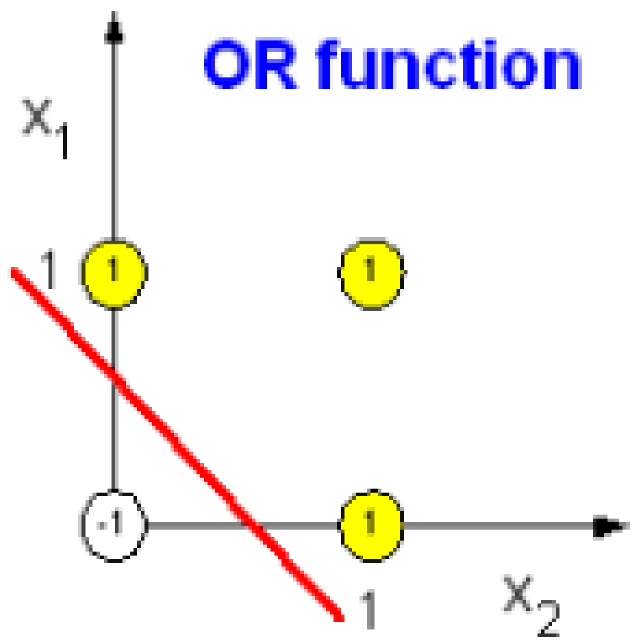
OR Function

X_1	X_2	Y
0	0	0
0	1	1
1	0	1
1	1	1



AND OR Functions





PERCEPTRON TRAINING RULE

Perceptron Training Rule

- **How to learn the weights for a single perceptron.**
  - Begin with random weights,
  - Iteratively apply the perceptron to each training example,
  - Modifying the perceptron weights whenever it misclassifies an example.
  - This process is repeated, iterating through the training examples as many times as needed until the perceptron classifies all training examples correctly.
  - Weights are modified at each step according to the perceptron training rule.

Perceptron Training Rule

- The ***perceptron training rule,*** which revises the weight w_i associated with input x_i according to the rule:

$$w_i \leftarrow w_i + \Delta w_i$$

where

$$\Delta w_i = \eta(t - o)x_i$$

Where:

- t is target value
- o is perceptron output
- η is small constant (e.g., 0.1) called *learning rate*

Perceptron Training Rule

- The weight changes Δw_{ij} need to be applied repeatedly … for each weight w_{ij} in the network, and for each training pattern in the training set.
- One pass through all the weights for the whole training set is called one ***epoch*** of training
- Eventually, usually after many epochs, when all the network outputs match the targets for all the training patterns,
  - all the Δw_{ij} will be zero and the process of training will cease.
  - We then say that the training process has ***converged*** to a solution

Perceptron Training Rule

Example:

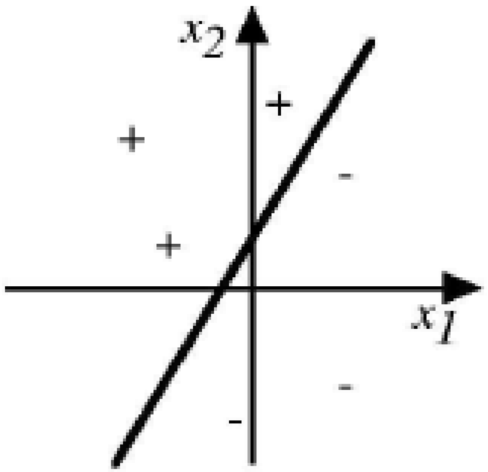
- The training rule will increase w, if $(t - o), \eta$ and x_i are all positive.
  - if $x_i = 0.8, \eta = 0.1, t = 1$, and $o = -1$, then the weight update will be

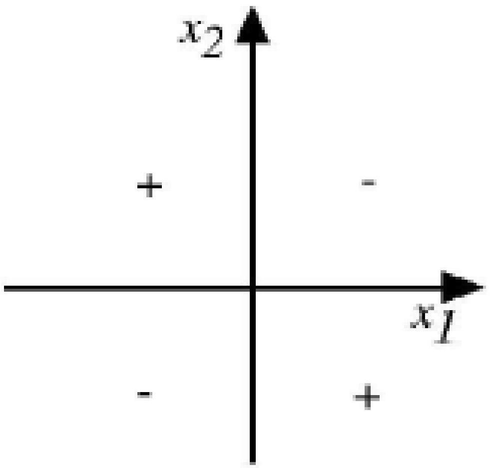
$$\Delta w_i = \eta(t - o)x_i = 0.1(1 - (-1))0.8 = 0.16.$$

- On the other hand,
  - if $x_i = 0.8, \eta = 0.1, t = -1$ and $o = 1$, then weights associated with positive x_i will be decreased rather than increased.

$$\Delta w_i = \eta(t - o)x_i = 0.1(-1 - (1))0.8 = -0.16.$$

Perceptron





The **decision surface** represented by a **two-input perceptron x_1** and **x_2**.
(a) A set of training examples and the decision surface of a perceptron that classifies them correctly. ***(b)*** A set of training examples that is not linearly separable.

Perceptron Training Rule

- The **perceptron rule** finds a successful weight vector when the training examples are **linearly separable,**
- It fails to converge if the examples are **not linearly separable.**
- The solution is … **Delta Rule** also known as **(Widrow-Hoff Rule)**

Delta Rule

- use ***gradient descent*** to search the hypothesis space of possible weight vectors to find the weights that best fit the training examples.

Reading Material

- **Artificial Intelligence,** A Modern Approach

  Stuart J. Russell and Peter Norvig

  - **Chapter 18.**
- **Machine Learning**

  Tom M. Mitchell

  - **Chapter 4.**