

view\_frames Result

Recorded at time: 60.095

world

map

odom

base\_footprint

base\_link\_offset

base\_link

caster\_link

hokuyo\_link

left\_wheel\_link

right\_wheel\_link

Broadcaster: /mapper  
Average rate: 30.277 Hz  
Most recent transform: 60.144 ( -0.049 sec old)  
Buffer length: 3.468 sec

Broadcaster: /gazebo  
Average rate: 50.286 Hz  
Most recent transform: 60.095 ( 0.000 sec old)  
Buffer length: 3.500 sec

Broadcaster: /offset\_publisher  
Average rate: 97.032 Hz  
Most recent transform: 60.105 ( -0.010 sec old)  
Buffer length: 3.504 sec

Broadcaster: /icart/robot\_state\_publisher  
Average rate: 10000.000 Hz  
Most recent transform: 0.000 ( 60.095 sec old)  
Buffer length: 0.000 sec

Broadcaster: /icart/robot\_state\_publisher  
Average rate: 10000.000 Hz  
Most recent transform: 0.000 ( 60.095 sec old)  
Buffer length: 0.000 sec

Broadcaster: /icart/robot\_state\_publisher  
Average rate: 10000.000 Hz  
Most recent transform: 0.000 ( 60.095 sec old)  
Buffer length: 0.000 sec

Broadcaster: /icart/robot\_state\_publisher  
Average rate: 50.286 Hz  
Most recent transform: 60.095 ( 0.000 sec old)  
Buffer length: 3.500 sec

Broadcaster: /icart/robot\_state\_publisher  
Average rate: 50.286 Hz  
Most recent transform: 60.095 ( 0.000 sec old)  
Buffer length: 3.500 sec