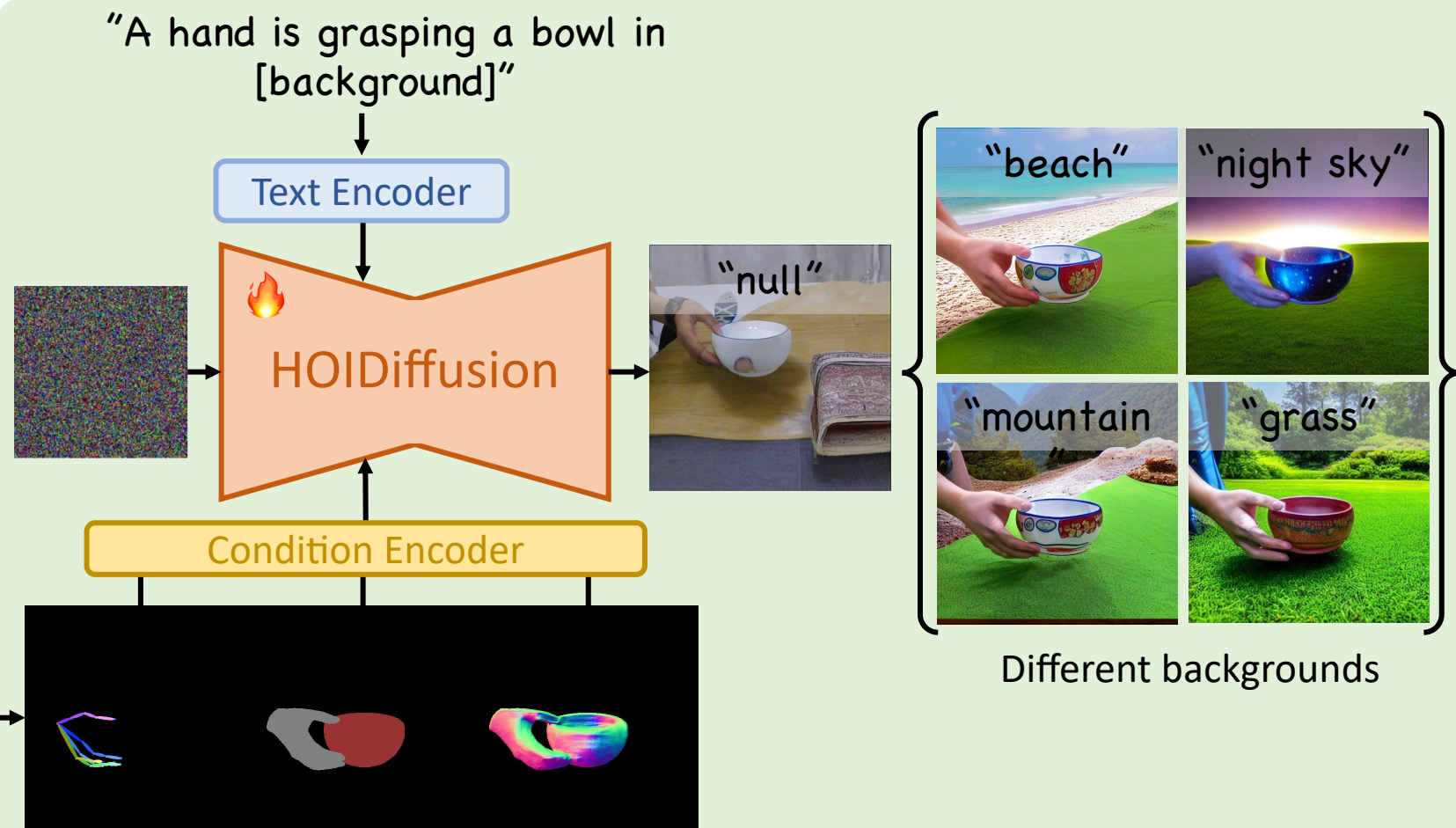**Stage 1:** Generate hand grasping trajectory pose

Stage 2: Use prompts control appearance