Maze Solver

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Link to Project Repo

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Overview

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Introduction

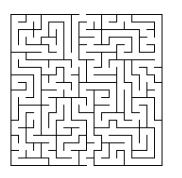
Problem Description

Given two points on a maze (start, end) we find the shortest path between them.

Applications of Maze Solver:

- Robotics
- Path-Planning

Maze Generation



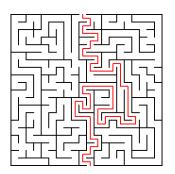


Figure: Generated Maze (on left), Solved Maze (on right)

Approach

- 1. Divide the graphs into subgraphs and stitch their solutions together.
- 2. Parallelize the search algorithm BFS.
- 3. Apply mincut and perform search on two different graphs in parallel.

Our Implementation

We opted to implement the **second approach** - parallelizing the search algorithm. The limitations of the other approaches are discussed in the coming slides.

Parallelizing Maze Solving

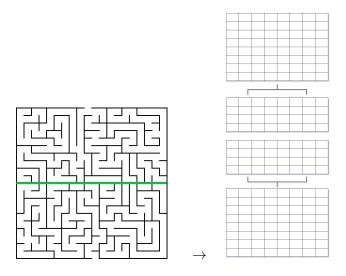


Figure: Generated Maze (on left), Solved Maze (on right)

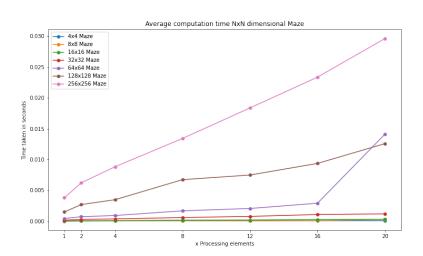
Drawbacks

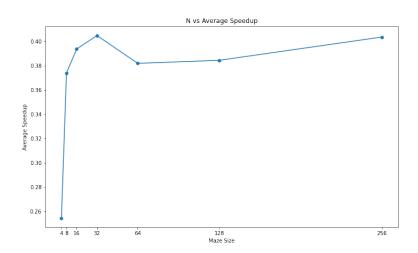
Approach one and three

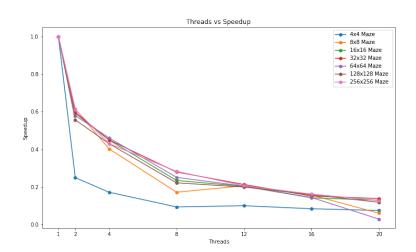
 Synchronizing solutions and re-running searches on them proved more time-consuming than in the 2nd approach.

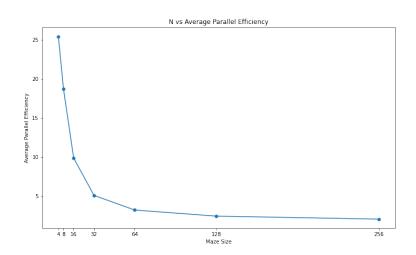
Approach two

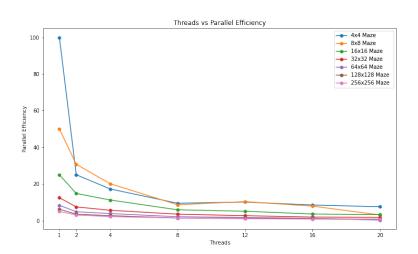
- In the Maze Graph, each traversal layer typically contains only 2 to 10 nodes.
- Furthermore, the necessity for synchronization to update the queue introduced additional overhead.











References



Samya Ahsan (2023)

Parallel Functional Programming Report: MazeSolver



A. Botea et al

Near Optimal Hierarchical Path-Finding

Journal of Game Development Vol. 1, pp.7-28, 2004