

Frequency Domain Filtering - Overlap-Add method

Implement the Frequency Domain Filtering between $x[n]$ and $h[n]$ using the Overlap-Add method.

Parameters

- $x[n] = \cos(2\pi F_0 n T_s) + \cos(2\pi F_1 n T_s)$
- $F_0 = 31.25$ [Hz]
- $F_1 = 312.5$ [Hz]
- $F_s = 1$ [kHz];
- $N=256$; $M = 129$;
- $h = \text{fir1}(M-1, 0.25)$;

Clear

```
clc;           % Clear the text from the Command Window
clear;         % Remove all variables from the current workspace
close all;     % Close all figures
```

Parameters

```
Fc0 = 31.25;
Fc1 = 312.5;
Fs = 1000;
Ts = 1/Fs;

N = 256;      % FFT Points
M = 129;      % Length of the filter
h = fir1(M-1, 0.25).';
```

Exercise

```
len = 1e4;
n = 0:len-1;
x = cos(2*pi*Fc0*n*Ts).' + cos(2*pi*Fc1*n*Ts).';

% Linear Convolution used as reference
y_L = conv(x, h);
```

Frequency transform and zero padding

Filtering is done using a N-FFT, and to use it, the signal must be used to create many N-length vectors. These vectors are composed of the signal samples and a zero-filled vector. In this example, $N=64$ and a FFT input vector is composed of $N/2$ samples of the signal and $N/2$ zeros.

```
% Buffer del segnale di lunghezza N_fft/2
x_b = buffer(x, N/2);
```

```

% Buffer di zeri
zero_b = zeros(size(x_b));

% Buffer del segnale
x_b = [x_b; zero_b];

% Trasformata del segnale
X_b_f = fft(x_b,N);

% Buffer del filtro di lunghezza N_fft/2
h_b = [h.', zeros(1,N/2)];

% Trasformata del filtro
H_f = fft(h_b,N);

```

Product in the frequency domain and IFFT

```

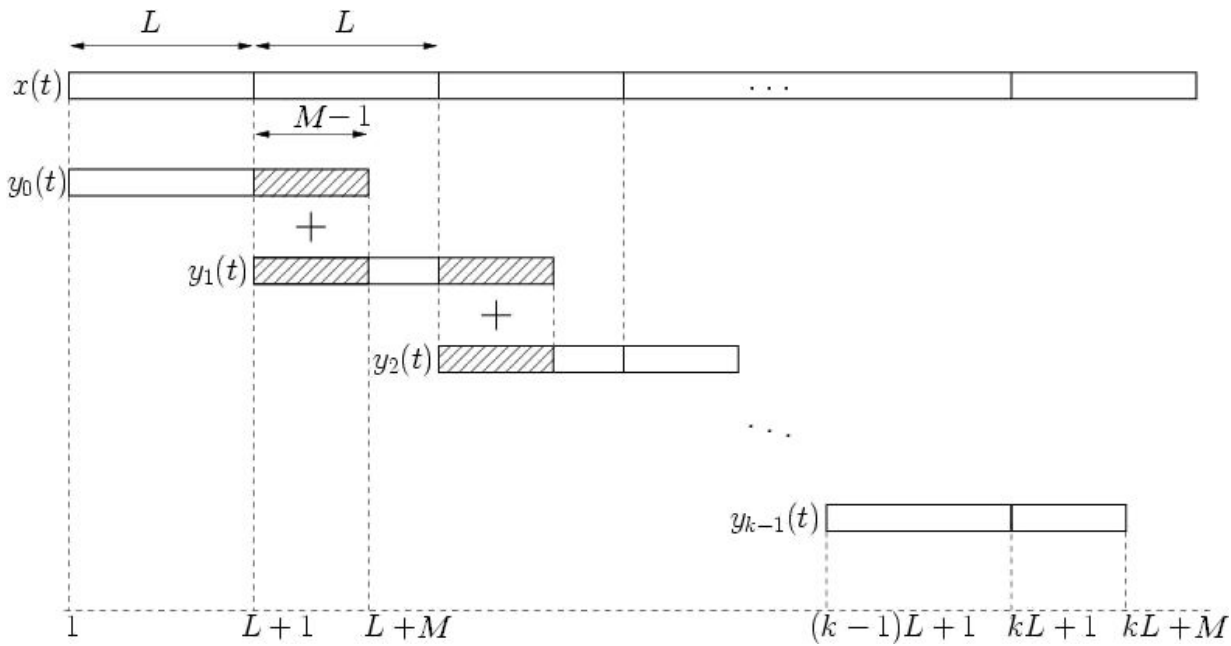
% Product
Y_f = zeros(size(X_b_f));
for i=1:size(Y_f,2)
    Y_f(:,i) = X_b_f(:,i).*(H_f. ');
end

% IDFT
y_b = ifft(Y_f,N);

```

Post IFFT processing

Since $N/2$ zeros have been added, the IFFT output sequences must be added between them as shown in the following figure: (https://upload.wikimedia.org/wikipedia/commons/7/77/Depiction_of_overlap-add_algorithm.png)



```

y = zeros(size(y_b,1)*size(y_b,2),1);
for i = 1:size(y_b,2)
    n_temp_1 = 1 + (i-1)*(N/2) : i*N/2;
    n_temp_2 = 1 + i*N/2 : (i+1)*N/2;
    y(n_temp_1) = y(n_temp_1) + y_b(1:N/2,i);
    y(n_temp_2) = y(n_temp_2) + y_b(1+N/2:end,i);
end

```

Plot

```

% Using 'freqz'
nFFT = 2^12; % Number of points of the fft
Xf      = freqz(x, length(x), nFFT);
Yf_L    = freqz(y_L, length(y_L), nFFT);
[Yf, w] = freqz(y, length(y), nFFT);

% Frequency normalization
w = w/pi * (Fs/2)/1e3;

% Mag to dB
Xf      = mag2db(abs(Xf)/nFFT);
Yf_L    = mag2db(abs(Yf_L)/nFFT);
Yf      = mag2db(abs(Yf)/nFFT);

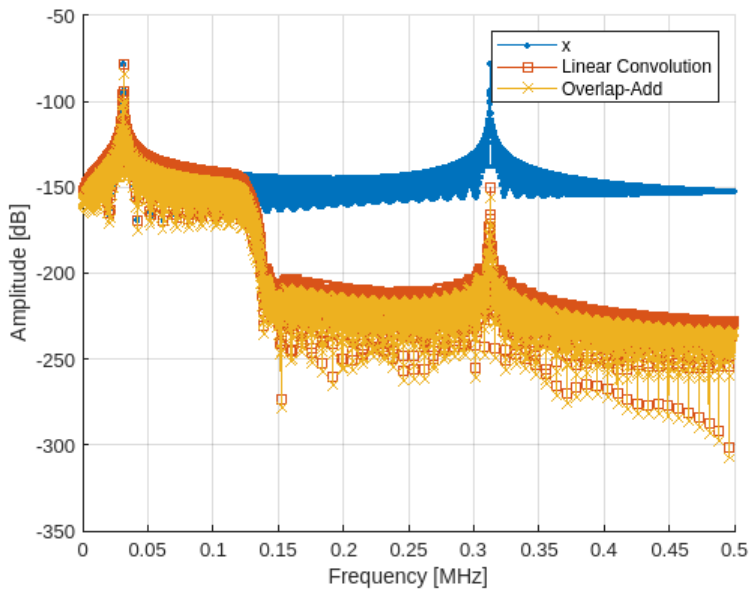
% Frequency Response
figure
hold on
plot(w, Xf,    '.-')
plot(w, Yf_L,  's-')
plot(w, Yf,    'x-')

```

```

hold off
grid on
legend({'x','Linear Convolution', 'Overlap-Add'})
xlabel('Frequency [MHz]')
ylabel('Amplitude [dB]')

```



```

% Error between the Linear convolution and the frequency filtering
len_err = min([length(y_L),length(y)]);
error = y_L(1:len_err)-y(1:len_err);
error = abs(error);

figure;
subplot(2,1,1)
    hold on
    plot(y_L,'s-')
    plot(y,'x--')
    hold off
    xlim([1,1e3])
    legend({'Linear Convolution', 'Overlap-Add'})
    grid on
    xlabel('Samples')
subplot(2,1,2)
    hold on
    plot(error,'s-')
    hold off
    xlim([1,1e3])
    legend({'Error'})
    grid on
    xlabel('Samples')

```

