Frequency Domain Filtering - Overlap-Add method

Implement the Frequency Domain Filtering between x[n] and h[n] using the Overlap-Add method.

Parameters

```
• x[n] = cos(2\pi F_0 n T_s) + cos(2\pi F_1 n T_s)

• F_0 = 31.25 \text{ [Hz]}

• F_1 = 312.5 \text{ [Hz]}

• F_s = 1 \text{ [kHz]};

• N=256; M=129;

• h=fir1(M-1,0.25);
```

Clear

Parameters

```
Fc0 = 31.25;

Fc1 = 312.5;

Fs = 1000;

Ts = 1/Fs;

N = 256; % FFT Points

M = 129; % Length of the filter

h = fir1(M-1,0.25).';
```

Exercise

```
len = 1e4;
n = 0:len-1;
x = cos(2*pi*Fc0*n*Ts).' + cos(2*pi*Fc1*n*Ts).';
% Linear Convolution used as reference
y_L = conv(x,h);
```

Frequency transform and zero padding

Filtering is done using a N-FFT, and to use it, the signal must be used to create many N-length vectors. These vectors are composed of the signal samples and a zero-filled vector. In this example, N=64 and a FFT input vector is composed of N/2 samples of the signal and N/2 zeros.

```
% Signal buffering of length N_fft/2
x_b = buffer(x,N/2);
```

```
% Zero padding
zero_b = zeros(size(x_b));

% Concatenation
x_b = [x_b; zero_b];

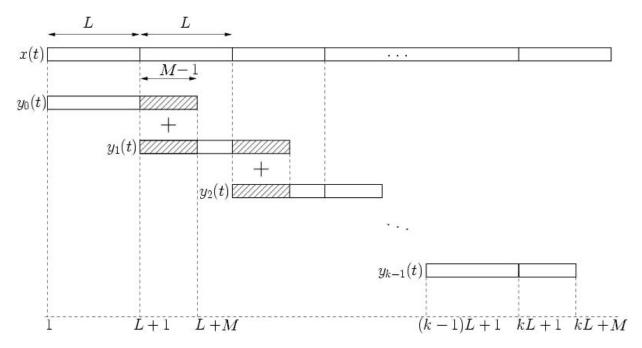
% FFT performed to each column
X_b_f = fft(x_b,N);

% FFT of the filter
% If the FFT length is larger than the length of the vector,
% the input vector is padded with zeros
H_f = fft(h,N);
```

Product in the frequecy domain and IFFT

Post IFFT processing

Since N/2 zeros have been added, the IFFT output sequences must be added between them as shown in the following figure: (https://upload.wikimedia.org/wikipedia/commons/7/77/Depiction_of_overlap-add_algorithm.png)

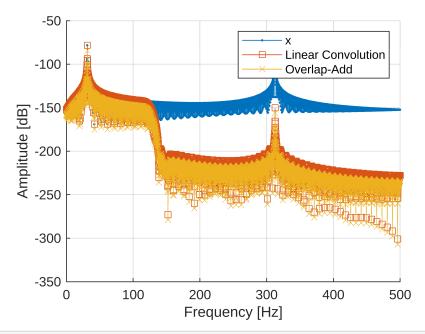


```
y = zeros(size(y_b,1)*size(y_b,2),1);
for i = 1:size(y_b,2)
    n_temp_1 = 1 + (i-1)*(N/2) : i*N/2;
    n_temp_2 = 1 + i*N/2 : (i+1)*N/2;
    y(n_temp_1) = y(n_temp_1) + y_b(1:N/2,i);
    y(n_temp_2) = y(n_temp_2) + y_b(1+N/2:end,i);
end
```

Plot

```
% Using 'freqz'
nFFT = 2^12; % Number of points of the fft
      = freqz(x, length(x), nFFT);
      = freqz(y_L, length(y_L), nFFT);
Yf_L
[Yf, w] = freqz(y, length(y), nFFT);
% Frequency normalization
w = w/pi * (Fs/2);
% Mag to dB
    = mag2db(abs(Xf)/nFFT);
Χf
Yf_L = mag2db(abs(Yf_L)/nFFT);
Υf
    = mag2db(abs(Yf)/nFFT);
% Frequency Response
figure
hold on
plot(w, Xf, '.-')
plot(w, Yf_L, 's-')
plot(w, Yf, 'x-')
```

```
hold off
grid on
legend({'x','Linear Convolution', 'Overlap-Add'})
xlabel('Frequency [Hz]')
ylabel('Amplitude [dB]')
```



```
% Error between the Linear convolution and the frequency filtering
len_err = min([length(y_L),length(y)]);
error = y_L(1:len_err)-y(1:len_err);
error = abs(error);
figure;
subplot(2,1,1)
  hold on
 plot(y_L,'s-')
 plot(y, 'x--')
 hold off
  xlim([1,1e3])
  legend({'Linear Convolution', 'Overlap-Add'})
  grid on
  xlabel('Samples')
subplot(2,1,2)
  hold on
 plot(error,'s-')
 hold off
  xlim([1,1e3])
  legend({'Error'})
  grid on
  xlabel('Samples')
```

