

# Analytical Calculation of Bulk Velocity Inside a Sphere given a Tangential Surface Velocity

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## 1 Calculation of the bulk velocity

A velocity field can be expanded in vector spherical harmonics as follows :

$$\mathbf{V} = \sum_{l=0}^{\infty} \sum_{m=-l}^l \left( V_{lm}^Y(r) \mathbf{Y}_{lm} + V_{lm}^{\psi}(r) \mathbf{\Psi}_{lm} + V_{lm}^{\phi}(r) \mathbf{\Phi}_{lm} \right) \quad (1)$$

In more compact form, we can write them as:

$$\mathbf{V} = \mathbf{V}^Y + \mathbf{V}^{\psi} + \mathbf{V}^{\phi} \quad (2)$$

Where,

$$\mathbf{V}^Y = \sum_{l=0}^{\infty} \sum_{m=-l}^l V_{lm}^Y(r) \mathbf{Y}_{lm} \quad (3)$$

$$\mathbf{V}^{\psi} = \sum_{l=0}^{\infty} \sum_{m=-l}^l V_{lm}^{\psi}(r) \mathbf{\Psi}_{lm} \quad (4)$$

$$\mathbf{V}^{\phi} = \sum_{l=0}^{\infty} \sum_{m=-l}^l V_{lm}^{\phi}(r) \mathbf{\Phi}_{lm} \quad (5)$$

We take vector Laplacian of this form of the velocity with the rules that ,

$$\Delta (v(r) \mathbf{Z}_{lm}) = \left( \frac{1}{r^2} \frac{\partial}{\partial r} r^2 \frac{\partial}{\partial r} \right) \mathbf{Z}_{lm} + v(r) \Delta \mathbf{Z}_{lm} \quad (6)$$

$$\mathbf{Z}_{lm} = \mathbf{Y}_{lm}, \mathbf{\Phi}_{lm}, \mathbf{\Psi}_{lm} \quad (7)$$

where Z can take the values

$$\mathbf{Z}_{lm} = \mathbf{Y}_{lm}, \mathbf{\Psi}_{lm}, \mathbf{\Phi}_{lm} \quad (8)$$

$$\Delta \mathbf{Y}_{lm} = -\frac{1}{r^2} (2 + l(l+1)) \mathbf{Y}_{lm} + \frac{2}{r^2} \mathbf{\Psi}_{lm} \quad (9)$$

$$\Delta \mathbf{\Psi}_{lm} = \frac{2}{r^2} l(l+1) \mathbf{Y}_{lm} - \frac{1}{r^2} l(l+1) \mathbf{\Psi}_{lm} \quad (10)$$

$$\Delta \mathbf{\Phi}_{lm} = -\frac{1}{r^2} l(l+1) \mathbf{\Phi}_{lm} \quad (11)$$

Thus operating the vector laplacian on the velocity,we get

$$\Delta \mathbf{V} = \sum_{z=r,\psi,\phi} \sum_{l=0}^{\infty} \sum_{m=-l}^l \left( \frac{1}{r^2} \frac{\partial}{\partial r} r^2 \frac{\partial v^z}{\partial r} \right) \mathbf{Z}_{lm} + v(r) \Delta \mathbf{Z}_{lm} \quad (12)$$

We can use compact notation to simplify further as follows: Let

$$F^z = \left( \frac{1}{r^2} \frac{\partial}{\partial r} r^2 \frac{\partial V^z}{\partial r} \right) \quad (13)$$

Using the identities (5),(6) and (7) in equation ,we seporate the coefficients of the three VSH as,

$$(\Delta \mathbf{V})_{lm}^Y = F^Y - \frac{2 + (l(l+1))}{r^2} V_{lm}^Y + \frac{2(l(l+1))}{r^2} V_{lm}^\psi = P_{lm} \quad (14)$$

$$(\Delta \mathbf{V})_{lm}^\psi = F^\psi + \frac{2}{r^2} V_{lm}^Y - \frac{(l(l+1))}{r^2} V_{lm}^\psi = Q_{lm} \quad (15)$$

$$(\Delta \mathbf{V})_{lm}^\phi = F^\phi - \frac{(l(l+1))}{r^2} V_{lm}^\phi = R_{lm} \quad (16)$$

Expressing the laplacian of the velocity in compact form as:

$$(\Delta \mathbf{V})_{lm} = P_{lm} \mathbf{Y}_{lm} + Q_{lm} \mathbf{\Psi}_{lm} + R_{lm} \mathbf{\Phi}_{lm} \quad (17)$$

Now , taking curl of the laplacian of the velocity using the standard identitys , we have :

$$\nabla \times (P \mathbf{Y}_{lm}) = -\frac{1}{r} P \mathbf{\Phi}_{lm} \quad (18)$$

$$\nabla \times (Q \mathbf{\Psi}_{lm}) = \left( \frac{dQ}{dr} + \frac{1}{r} Q \right) \mathbf{\Phi}_{lm} \quad (19)$$

$$\nabla \times (R \mathbf{\Phi}_{lm}) = -\frac{l(l+1)}{r} R \mathbf{Y}_{lm} - \left( \frac{dR}{dr} + \frac{1}{r} R \right) \mathbf{\Psi}_{lm} \quad (20)$$

Thus we have the curl of the laplacian as:

$$\nabla \times (\nabla^2 \mathbf{V})_{lm} = -\frac{l(l+1)}{r} R \mathbf{Y}_{lm} - \left( \frac{dR}{dr} + \frac{1}{r} R \right) \mathbf{\Psi}_{lm} + \left( -\frac{1}{r} P + \frac{dQ}{dr} + \frac{1}{r} Q \right) \mathbf{\Phi}_{lm} \quad (21)$$

From the Orthogonality and linear Independence of VSH's,each term in the beackets must be identically zero . Thus we get the differential equations as :

$$\frac{l(l+1)}{r} R = 0 \quad (22)$$

$$\left( \frac{dR}{dr} + \frac{1}{r} R \right) = 0 \quad (23)$$

$$\left( -\frac{1}{r} P + \frac{dQ}{dr} + \frac{1}{r} Q \right) = 0 \quad (24)$$

We can now expand the two equations and removing the redundant equations , we get

$$\left( \frac{1}{r^2} \frac{\partial}{\partial r} r^2 \frac{\partial V_{lm}^\phi}{\partial r} \right) - \frac{(\ell(\ell+1))}{r^2} V_{lm}^\phi = 0 \quad (25)$$

$$-\frac{1}{r} P + \frac{dQ}{dr} + \frac{1}{r} Q = 0 \quad (26)$$

The general Solution to equation(23) is:

$$V_{lm}^\phi = A_m^l r^\ell + B_m^l r^{-(\ell+1)} \quad (27)$$

With the condition that at  $r = 0$  ,  $V_{lm}^\phi = 0, B_m^l = 0$ . Hence the general solution to  $\mathbf{V}^\phi$  is :

$$\mathbf{V}^\phi = \sum_{l=1}^{\infty} \sum_{m=-l}^l A_m^l r^\ell \Phi_{lm} \quad (28)$$

Equation (26) can be expanded as ;

$$\begin{aligned} & \frac{d}{dr} \left( F^\psi + \frac{2}{r^2} V^Y - \frac{\ell(\ell+1)}{r^2} V^\psi \right) \\ & + \frac{1}{r} \left( F^\psi + \frac{2}{r^2} V^Y - \frac{\ell(\ell+1)}{r^2} V^\psi \right) - \frac{1}{r} \left( F^r - \frac{2 + (\ell(\ell+1))}{r^2} V^Y + \frac{2\ell(\ell+1)}{r^2} V^\psi \right) = 0 \end{aligned} \quad (29)$$

We have simplified with the assumption that the flow is incompressible

$$\nabla \cdot \mathbf{V} = 0 \quad (30)$$

$$\nabla \cdot \mathbf{V} = \sum_{l=0}^{\infty} \sum_{m=-l}^l \left( \frac{dV_{lm}^Y}{dr} + \frac{2}{r} V_{lm}^Y - \frac{l(l+1)}{r} V_{lm}^\psi \right) \mathbf{Y}_{lm} \quad (31)$$

$$\Rightarrow \left( \frac{dV_{lm}^Y}{dr} + \frac{2}{r} V_{lm}^Y - \frac{l(l+1)}{r} V_{lm}^\psi \right) = 0 \quad (32)$$

The equation (28) can be simplified as follows:

$$\frac{r^3 \partial^3}{\partial r^3} V_{lm}^\psi + \frac{3r^2 \partial^2}{\partial r^2} V_{lm}^\psi - \frac{l(l+1)r \partial}{\partial r} V_{lm}^\psi - \frac{r^2 \partial^2}{\partial r^2} V_{lm}^Y + \ell(\ell+1) (V_{lm}^Y - V_{lm}^\psi) = 0 \quad (33)$$

(34)

For the velocity component  $V_{lm}^\phi$  and  $V_{lm}^r$ . Equation (31) and (32) are coupled differential equations and reduce to euler form of differential equation. The simplified equations are solvable. Using the incompressibility condition , we get the ordinary differential equation below.

$$\frac{r^4 \partial^4}{\partial r^4} V_{lm}^Y + \frac{8r^3 \partial^3}{\partial r^3} V_{lm}^Y - \frac{12 - 2\ell(\ell+1)r^2 \partial^2}{\partial r^2} V_{lm}^Y - \frac{4\ell(\ell+1)r \partial}{\partial r} V_{lm}^Y + ((\ell(\ell+1))^2 - 2\ell(\ell+1)) V_{lm}^Y = 0 \quad (35)$$

The above is an Euler-Lagrange type differential equation and can be solved by substituting  $r = e^z$  and then transforming the ode into the following form:

$$\frac{\partial^4}{\partial z^4} V_{lm}^Y + \frac{2\partial^3}{\partial z^3} V_{lm}^Y + \frac{-2 - \ell(\ell+1)\partial^2}{\partial z^2} V_{lm}^Y + \frac{(-1 - 3\ell(\ell+1))\partial}{\partial z} V_{lm}^Y + ((\ell(\ell+1))^2 - 2\ell(\ell+1)) V_{lm}^Y = 0 \quad (36)$$

The solution to this has the form:

$$V_{lm}^Y = C_1^\ell r^{\ell-1} + C_2^\ell r^{\ell+1} + C_3^\ell r^{-\ell} + C_4^\ell r^{-(\ell+2)} \quad (37)$$

The Boundary condition inside the cell i.e finite at centre and zero at the surface does not permit solutions which diverge at the centre. The coefficients  $C_1^0$  and  $C_4^0$  must vanish and  $C_3^\ell$  and  $C_4^\ell$  must vanish for all  $\ell > 1$ . The solution thus retained must be of the form

$$V_{lm}^Y = \begin{cases} C_2^0 r + C_3^0, \ell = 0 \\ C_1^\ell r^{\ell-1} + C_2^\ell r^{\ell+1}, \ell > 0 \end{cases}$$

At the surface of the cell  $r = R$ , the radial velocity must be zero. This condition must be satisfied individually for every mode present i.e. for each value of  $\ell$ . Using this condition, we get for  $\ell = 0$  mode  $C_3^0 = -C_2^0 R$  and for  $\ell > 0$  modes  $C_1^\ell = -C_2^\ell R^2$

$$\mathbf{V}^Y = C_2^0 (r - R) \mathbf{Y}_{00} + \sum_{l=1}^{\infty} \sum_{m=-l}^{m=l} C_2^l (r^{\ell+1} - R^2 r^{\ell-1}) \mathbf{Y}_{lm} \quad (38)$$

Now from the incompressibility condition, we have :

$$\frac{dV_{lm}^Y}{dr} + \frac{2}{r} V_{lm}^Y - \frac{\ell(\ell+1)}{r} V_{lm}^\psi = 0 \quad (39)$$

This condition can be used to determine  $V_{lm}^r$  along with the condition that at  $r = 0$ ,  $V_{lm}^\psi = 0$ , we find that only  $\ell \geq 1$  and higher modes exist.

$$\mathbf{V}^\psi = \sum_{l=1}^{\infty} \sum_{m=-l}^l C_m^\ell \left( -\frac{R^2 r^{\ell-1}}{\ell} + \frac{r^{\ell+1}(\ell+3)}{\ell(\ell+1)} \right) \mathbf{\Psi}_{lm} \quad (40)$$

Also the equation (42) changes as

$$\mathbf{V}^Y = \sum_{l=1}^{\infty} \sum_{m=l}^{m=-l} C_2^l (r^{\ell+1} - R^2 r^{\ell-1}) \mathbf{Y}_{lm} \quad (41)$$

Given any cortical flow of the form:

$$\mathbf{V}_s = \sum_{l=1}^{\infty} \sum_{m=-l}^l \left( v_{lm}^\psi \mathbf{\Psi}_{lm} + v_{lm}^\phi \mathbf{\Phi}_{lm} \right) \quad (42)$$

Now, given that we have the cortical Velocity we can determine the coefficients  $C_m^l$  and  $A_m^l$  by matching the general velocity at  $r = R$  for  $\ell \geq 1$

$$A_m^l = \frac{v_{lm}^\phi}{R^\ell} \quad (43)$$

$$C_m^l = \frac{\ell(\ell+1)v_{lm}^\psi}{2R^{\ell+1}} \quad (44)$$

Once we have determined these coefficients, we can build the bulk flow inside the sphere. Comparing equation (3),(4),(5) with (28),(40),(41), we get

$$V_{lm}^Y = C_m^\ell (r^{\ell+1} - R^2 r^{\ell-1}) \quad (45)$$

$$V_{lm}^\psi = C_m^\ell \left( -\frac{R^2 r^{\ell-1}}{\ell} + \frac{r^{\ell+1}(\ell+3)}{\ell(\ell+1)} \right) \quad (46)$$

$$V_{lm}^\phi = A_m^\ell r^\ell \quad (47)$$

Also, We can expand  $\Psi_{lm}$  and  $\Phi_{lm}$  in terms of scalar  $Y_{lm}$  as

$$\Psi_{lm} = \frac{\partial Y_{lm}}{\partial \theta} \hat{\theta} + \frac{\partial Y_{lm}}{\sin \theta \partial \phi} \hat{\phi} \quad (48)$$

$$\Phi_{lm} = -\frac{\partial Y_{lm}}{\partial \theta} \hat{\phi} + \frac{\partial Y_{lm}}{\sin \theta \partial \phi} \hat{\theta} \quad (49)$$

Thus we can write the velocity back in terms of  $r, \theta, \phi$  basis as:

$$\mathbf{v} = \sum_{lm} (V_{lm}^Y Y_{lm}) \hat{r} + \left( V_{lm}^\psi \frac{\partial Y_{lm}}{\partial \theta} + \frac{V_{lm}^\phi \partial Y_{lm}}{\sin \theta \partial \phi} \right) \hat{\theta} + \left( V_{lm}^\psi \frac{\partial Y_{lm}}{\sin \theta \partial \phi} - \frac{V_{lm}^\phi \partial Y_{lm}}{\partial \phi} \right) \hat{\phi} \quad (50)$$

## 2 Calculation of Stress Tensor

We can compute the Stress generated by the flows inside the sphere by the expression :

$$[\sigma] = \nabla \mathbf{v} + (\nabla \mathbf{v})^T \quad (51)$$

where

$$\nabla = \hat{r} \frac{\partial}{\partial r} + \hat{\theta} \frac{\partial}{r \partial \theta} + \hat{\phi} \frac{\partial}{r \sin \theta \partial \phi} \quad (52)$$

The two simple cases where we can easily compute the independent components of the stress tensor are given below:

### 2.1 Case I : All $C_{lm}$ are zero

In this case we have only  $V_{lm}^\phi$  non-zeros. The Velocity field reduces to the form:

$$\mathbf{v} = \sum_{lm} \left( V_{lm}^\phi \frac{\partial Y_{lm}}{\sin \theta \partial \phi} \right) \hat{\theta} + \left( -\frac{V_{lm}^\phi \partial Y_{lm}}{\partial \theta} \right) \hat{\phi} \quad (53)$$

For this case now, we six independent components of the stress tensor for a particular mode ( $\ell m$ ) of the velocity are

$$\sigma_{rr} = 0 \quad (54)$$

$$\sigma_{r\theta} = im \csc \theta Y_{lm} \left( \frac{-V_{lm}^\phi}{r} + \frac{\partial V_{lm}^\phi}{\partial r} \right) \quad (55)$$

$$\sigma_{r\phi} = m \cot^2 \theta \left( Y_{lm} + e^{i\phi} \sqrt{(\ell-m)(\ell+m+1)} Y_{\ell m+1} \right) \left( \frac{V_{lm}^\phi}{r} - \frac{\partial V_{lm}^\phi}{\partial r} \right) \quad (56)$$

$$\sigma_{\theta\phi} = \left( \frac{V_{lm}^\phi}{r} \right) \left( m (\cot^2 \theta + \csc^2 \theta) Y_{lm} + 2e^{-i\phi} m \cot \theta \sqrt{(\ell-m)(\ell+m+1)} Y_{lm+1} + e^{-2i\phi} \sqrt{(\ell-m)(\ell-m-1)(\ell+m+1)(\ell+m+2)} Y_{lm+2} \right) \quad (57)$$

$$\sigma_{\theta\theta} = -2im \csc \theta \left( -(-1+m) \cot \theta Y_{lm} - e^{-i\phi} (\ell-m)(\ell+m+1) Y_{lm+1} \right) \frac{V_{lm}^\phi}{r} \quad (58)$$

$$\sigma_{\phi\phi} = -2im \csc \theta \left( -(-1+m) \cot \theta Y_{lm} + e^{-i\phi} (\ell-m)(\ell+m+1) Y_{lm+1} \right) \frac{V_{lm}^\phi}{r} \quad (59)$$

## 2.2 Case II : All $\mathbf{A}_{lm}$ are zeros

In this case we have  $V_{lm}^Y$  and  $V_{lm}^\psi$  as non-zeros. The Velocity field reduces to the form:

$$\mathbf{V} = \sum_{lm} (V_{lm}^Y Y_{lm}) \hat{r} + \left( V_{lm}^\psi \frac{\partial Y_{lm}}{\partial \theta} \right) \hat{\theta} + \left( V_{lm}^\psi \frac{\partial Y_{lm}}{\sin \theta \partial \phi} \right) \hat{\phi} \quad (60)$$

For this case, the six independent components of the stress tensor for particular mode  $(\ell m)$  of the velocity are

$$\sigma_{rr} = 2Y_{lm} \frac{\partial V_{lm}^Y}{\partial r} \quad (61)$$

$$\sigma_{r\theta} = \left( m \cot \theta Y_{lm} + e^{-i\phi} \sqrt{(\ell-m)(\ell+m+1)} Y_{lm+1} \right) \left( \frac{V_{lm}^Y - V_{lm}^\psi + r \frac{\partial V_{lm}^\psi}{\partial r}}{r} \right) \quad (62)$$

$$\sigma_{r\phi} = im \csc \theta Y_{lm} \left( \frac{V_{lm}^Y - V_{lm}^\psi + r \frac{\partial V_{lm}^\psi}{\partial r}}{r} \right) \quad (63)$$

$$\sigma_{\theta\phi} = \frac{2im \csc \theta}{r} \left( (m-1) \cot \theta Y_{lm} + e^{-i\phi} \sqrt{(\ell-m)(\ell+m+1)} Y_{lm+1} \right) \frac{V_{lm}^\psi}{r} \quad (64)$$

$$\sigma_{\theta\theta} = \left( Y_{lm} V_{lm}^Y + \left( m(m \cot^2 \theta - \csc^2 \theta Y_{lm} + e^{-i\phi} (1+2m) \cot \theta \sqrt{(\ell-m)(\ell+m+1)} Y_{lm+1} + e^{-i2\phi} \sqrt{(\ell-m)(\ell-m-1)(\ell+m+3)(\ell+m+2)} Y_{lm+2} V_{lm}^\psi \right) \right) \quad (65)$$

$$\sigma_{\phi\phi} = \frac{2 \csc \theta}{r} \left( \sin \theta Y_{lm} V_{lm}^Y + (m(\cos \theta \cot \theta - m \csc \theta) Y_{lm} + e^{-i\phi} \cos \theta \sqrt{(\ell-m)(\ell+m+1)} Y_{lm+1} V_{lm}^\psi \right) \quad (66)$$

In general, the stress tensor is a sum over all modes when both  $\mathbf{C}_{lm}$  and  $\mathbf{A}_{lm}$  are non-zero, stress tensor components would be the sum of the respective components as described in the above cases.