# Electric motors data analysis

Group 8: Viktor Snesarevskii Edoardo Belli Guendalina Biava Ozrenka Dragiċ Madina Kalenova

March-April 2018





#### Dataset

- Measurements of torque and current from electric motors
- ► Time-series data with frequency 20KHz
- ▶ Data taken from 5 distinct motors in AC and DC modes
- Each data sample is one recorded operation
- Operations are recorded while motor is working properly, then a fault is induced and the same operations are recorded again
- ▶ In total 1066 AC samples, 924 DC samples



## Data Example

| Torque | Current |
|--------|---------|
| 16.693 | 0.023   |
| 16.739 | 0.019   |
| 16.823 | 0.010   |
| 16.810 | 0.007   |
| 16.823 | -0.002  |
| 16.849 | -0.010  |
| 16.992 | -0.018  |
| 17.108 | -0.033  |
| 17.290 | -0.035  |
| 17.297 | -0.052  |

#### Main Goals

#### 3 main goals:

- Motor Classification Can we identify a motor by a recorded operation?
- ► Fault Classification Can we group faults?
- ► Fault Prediction
  Can we predict the state of motor by a recorded operation?

## First Steps

First problem — data is very high-dimensional ( $p \approx 10^5$ ) Solution — do PCA first to select the most important moments

 $\begin{tabular}{ll} Then $-$ data exploration \\ For example, do faulty and working operations have the same or different mean, distribution etc \\ \end{tabular}$ 

### PCA

PCA results go here



## **Data Properties**

Things like mean, covariance, distribution etc

## Conclusions

What we got so far



Questions?