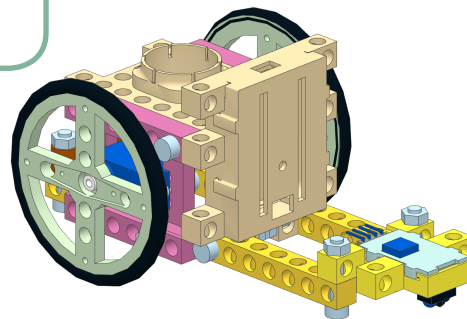
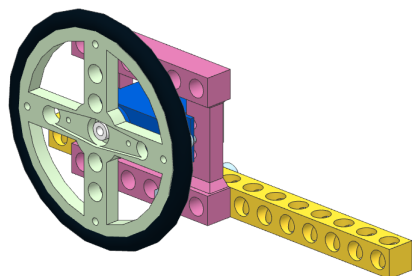
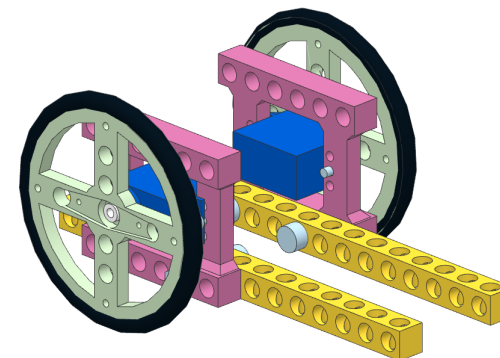


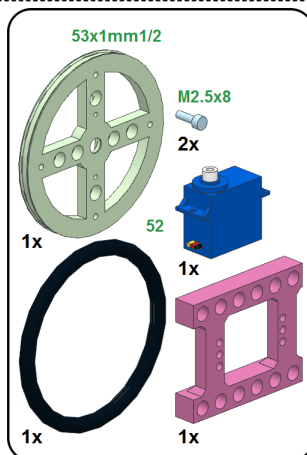
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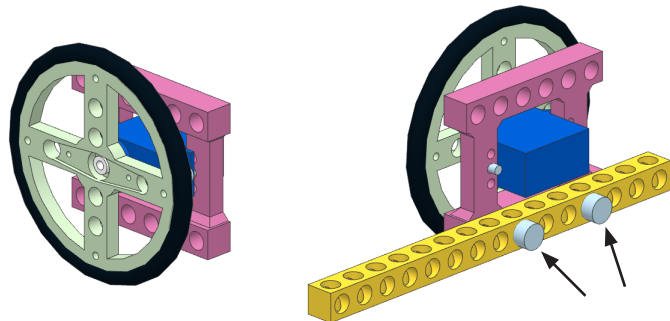
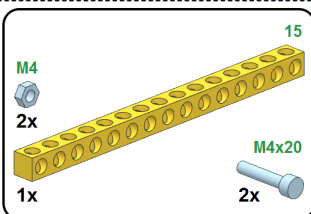
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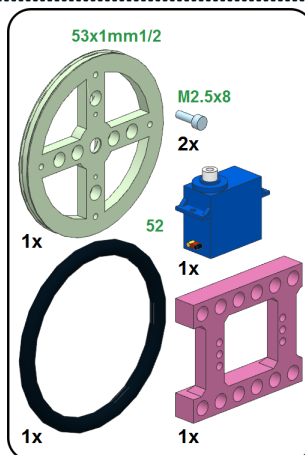
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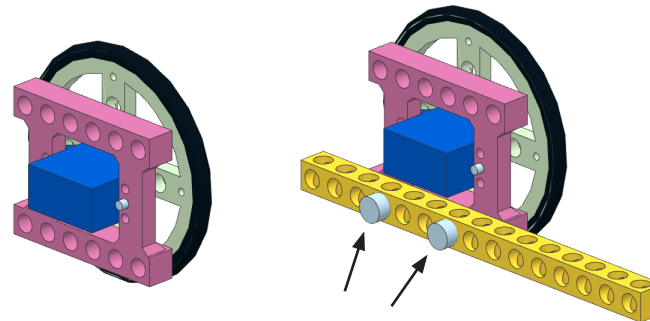
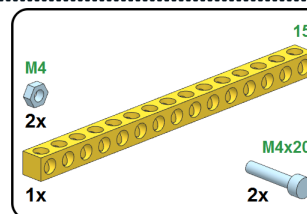
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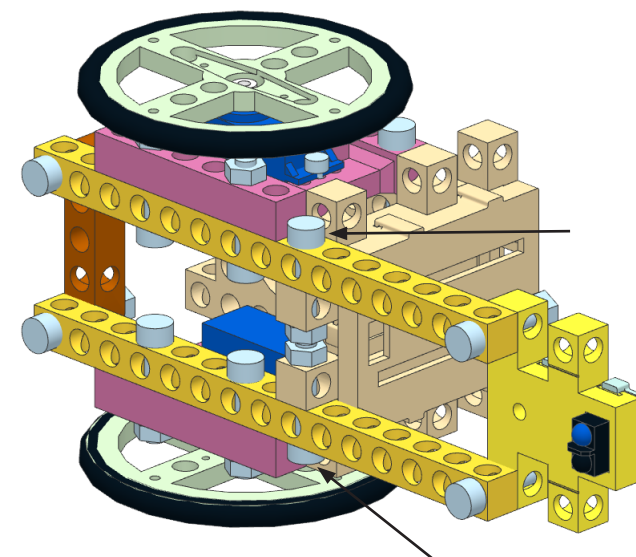
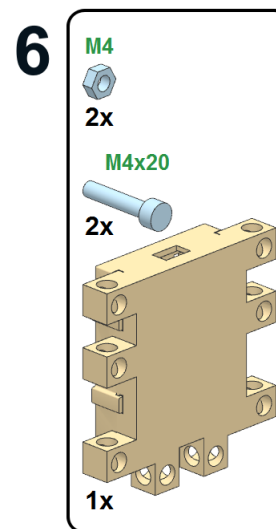
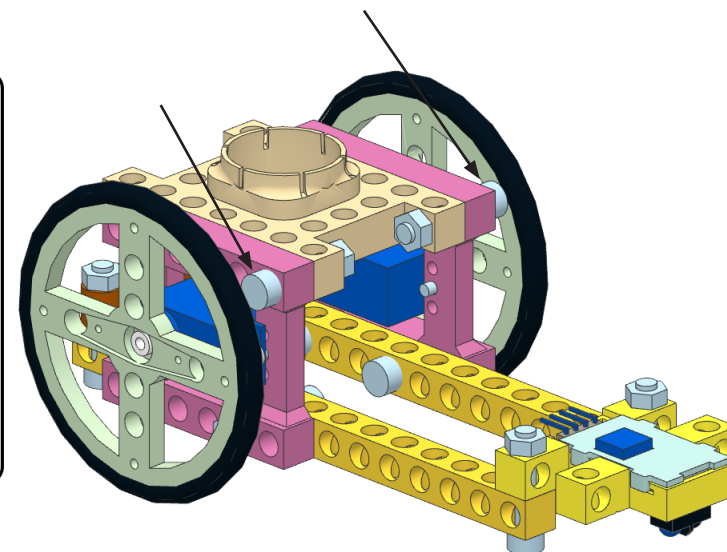
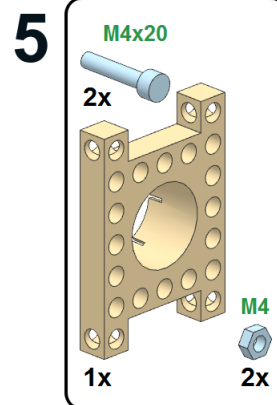
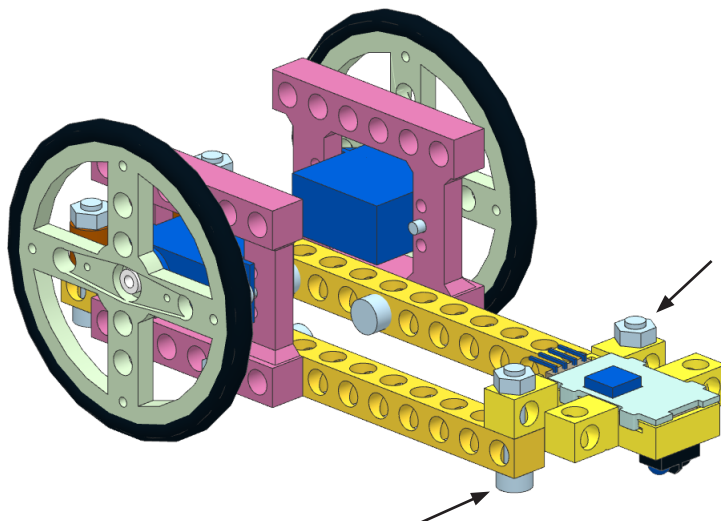
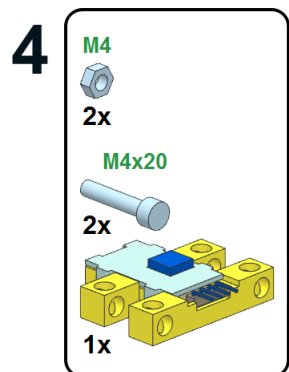
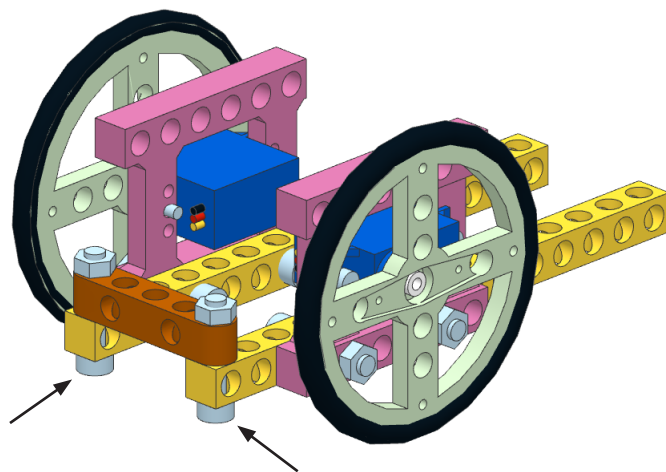
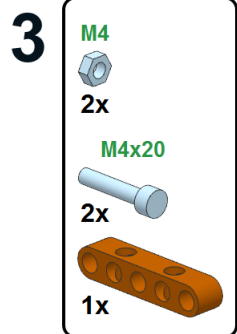


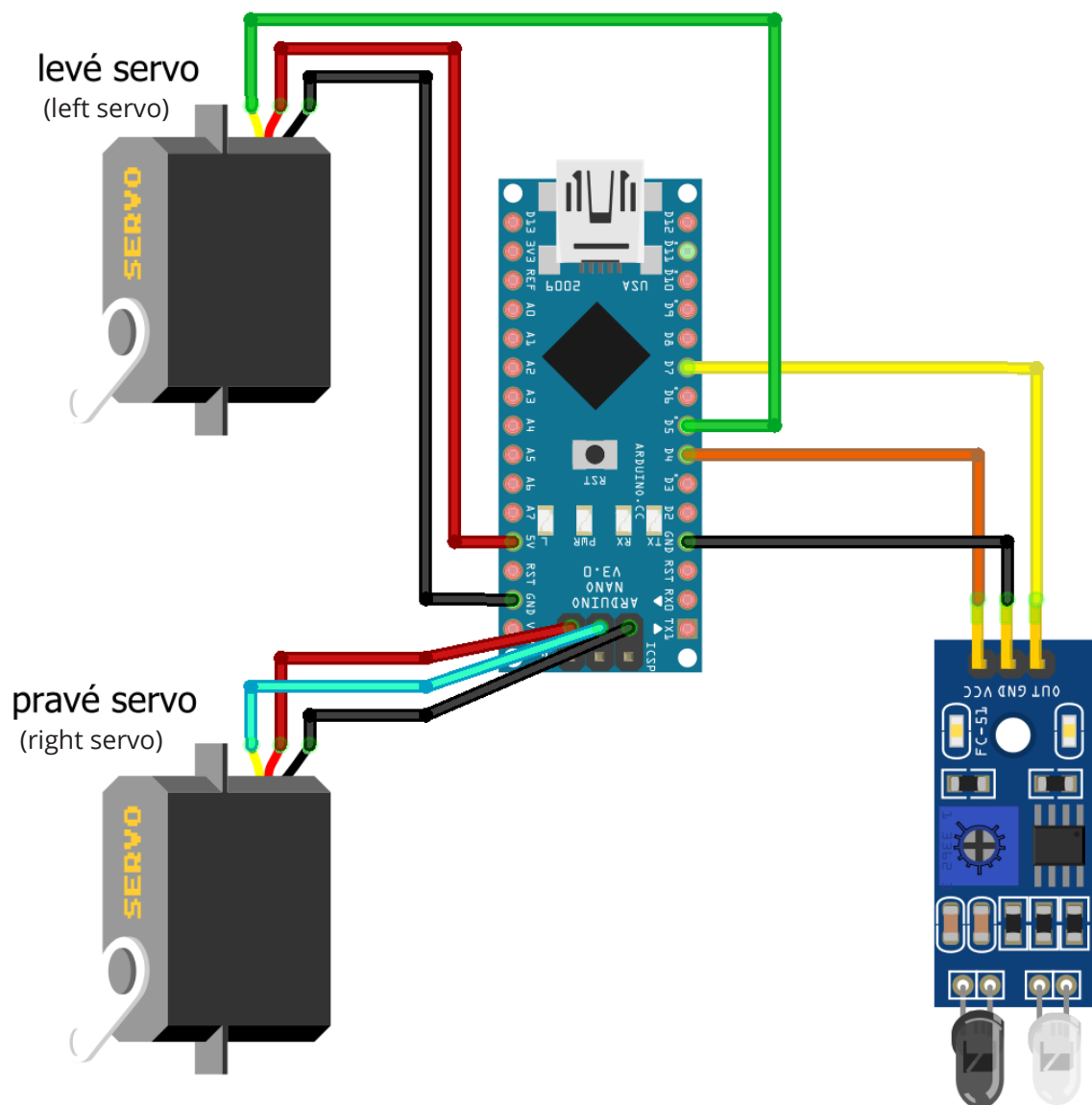
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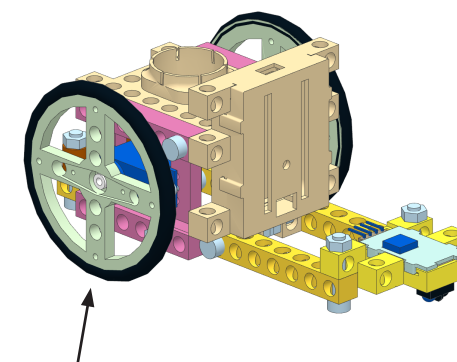
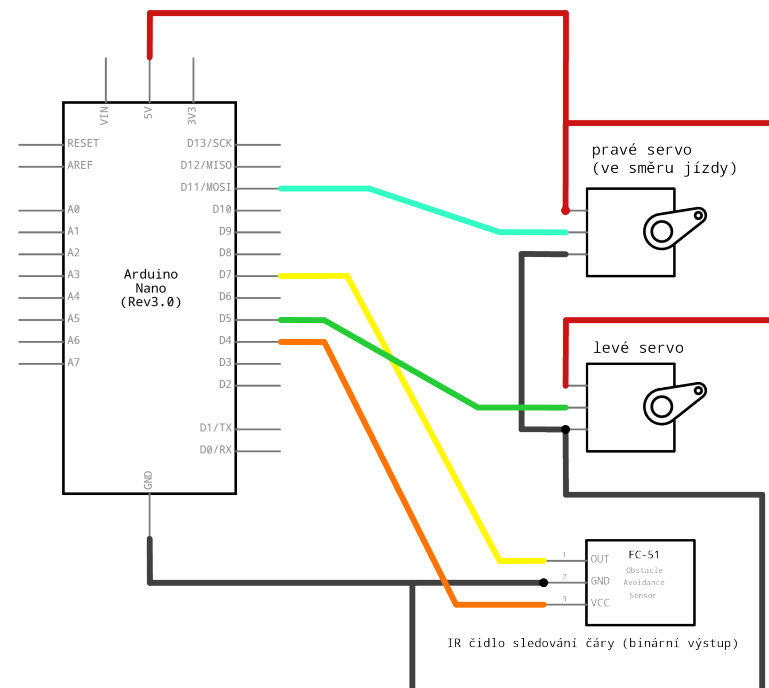
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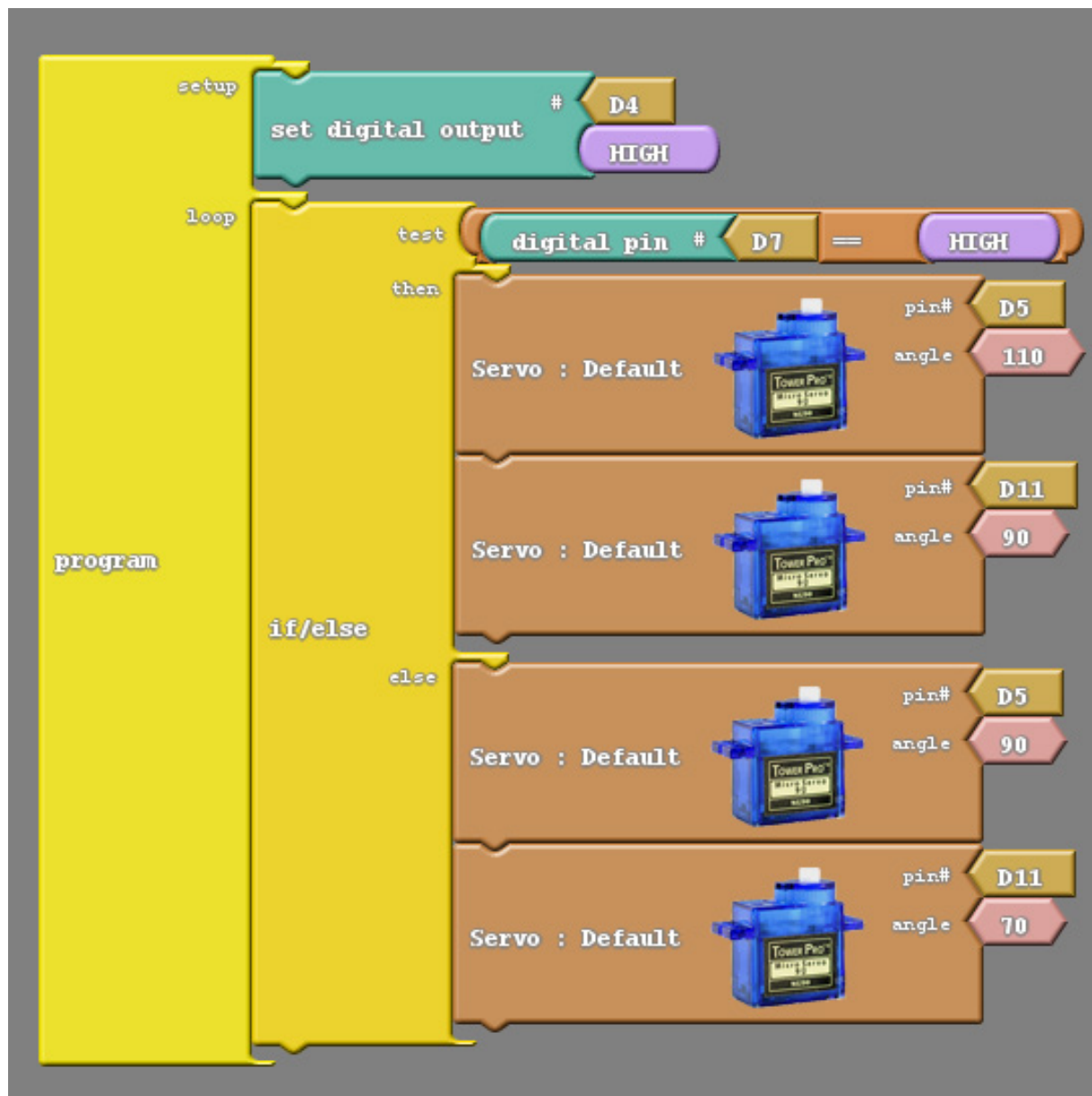


fritzing



pravá (right) strana robota





```
#include <Servo.h>
```

```
void __ardublockDigitalWrite(int pinNumber, boolean status)
{
  pinMode(pinNumber, OUTPUT);
  digitalWrite(pinNumber, status);
}
```

```
boolean __ardublockDigitalRead(int pinNumber)
{
  pinMode(pinNumber, INPUT);
  return digitalRead(pinNumber);
}
```

```
Servo servo_pin_5;
Servo servo_pin_11;
```

```
void setup()
{
  servo_pin_5.attach(5);
  servo_pin_11.attach(11);
  __ardublockDigitalWrite(4, HIGH);
}
```

```
void loop()
{
  if (( (__ardublockDigitalRead(7) ) == ( HIGH ) ))
  {
    servo_pin_5.write( 110 );
    servo_pin_11.write( 90 );
  }
  else
  {
    servo_pin_5.write( 90 );
    servo_pin_11.write( 70 );
  }
}
```