

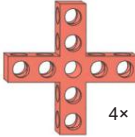
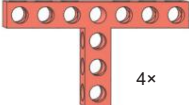
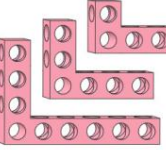
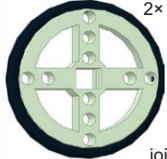
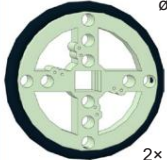
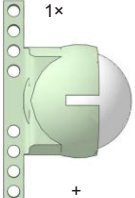


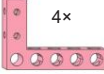
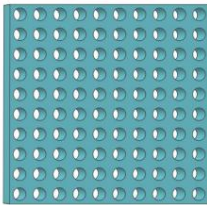




















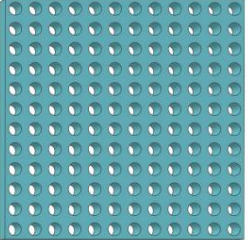
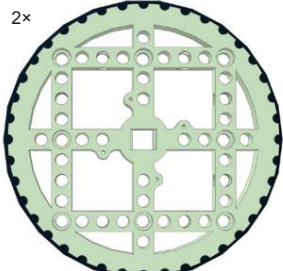
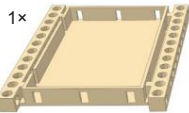
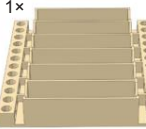
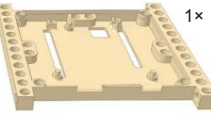
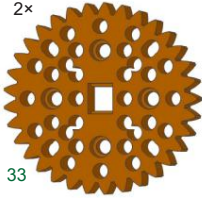
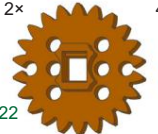

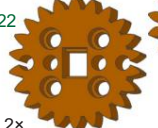



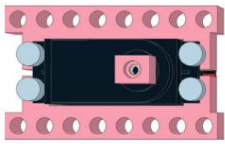
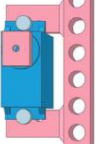



24	 rondelles M4 100×	 vis M4 × 30 40×	 4×	 4×	 4× 4× 4×	 2× joint torique ø 51 mm (4× )  2×	 1× + balle de ping pong 1×
18	 matky M4 100×	 vis M4 × 20 60×	 4× 1×  1×	aimant en plastique. . . . . 1× DEL rouge. . . . . 2× DEL jaune. . . . . 2× Voyant vert. . . . . 2× fin de course. . . . . 4× petit interrupteur. . . . . 4× grand potentiomètre. . . 1× petit potentiomètre. . . 2× Résistance 150R. . . . . 6× résistance 10K. . . . . 4×	cable USB . . . . . 1×  4×	 3 4×  5 4×  9 4×  11 4×  13 4×  15 4×  24 2×	<h2>m-BITBEAM</h2> <p>Un kit de robot de construction open source qui utilise largement des pièces imprimées en 3D. Les pièces imprimées en 3D ne sont pas incluses dans l'ensemble ! Chacun doit imprimer et remplir lui-même ces parties.</p> <p>Schéma de stockage des pièces dans le boîtier</p>
12	clé en plastique . . . . . 1×						
11	 capteur de son. . . . . 1×  capteur de température. . . . . 1×  capteur de champ magnétique 1×  capteur de lumière. . . . . 1×  Capteur IR (obstacles/ligne). . . 1×  DEL RVB. . . . . 1×  buzzer piézo. . . . . 1×  Récepteur infrarouge. . . . . 1×	 télémètre à ultrasons. . . . 1×  manette. . . . . écran 1×  (OLED). . . . . 1×  module bluetooth. . . . . 1×	 1×  2×  1×  1×  1×	 2×  2×  4×  22 2×  19 2×  11 2×  13 2×			
6							
5							
4	 2×  2×						
3							
2							
1	réduction de l'alimentation des servomoteurs. . . . . 1×						



časopis o výuce  
nejen s digitálními technologiemi