



School of Computer Science
Faculty of Science
National University of Engineering

Test 4

Topics: convex sets; convex functions; optimality conditions; Iterative Solution Algorithm for Unconstrained NLPPs

Subject: Computational Mathematics

Period: 2020-2

1. Let a in \mathbb{R}^n , d in $\mathbb{R}^n \setminus \{0\}$, c in \mathbb{R} and r be a positive number. Show whether the following sets are convex or not:
 - (a) (1 pt.) $\mathcal{H}(d, c) := \{v \in \mathbb{R}^n ; \langle v, d \rangle = c\}$;
 - (b) (2 pts.) $Hole := \{v \in \mathbb{R}^n ; |v - a| \geq r\}$;
 - (c) (2 pts.) $X := \{v \in \mathbb{R}^n ; A \cdot v \leq b\}$, where A is an $m \times n$ matrix and b is in \mathbb{R}^m .
2. Let $f : \mathbb{R} \rightarrow \mathbb{R}$ be such that $f(x) = \ln(1 + e^x)$.
 - (a) (2 pts.) Determine whether f is convex. The assertion must be proven.
 - (b) (2 pts.) Determine whether f has a global minimum. The assertion must be proven.
 - (c) (1 pt.) Sketch the graph of f .
3. Consider the following unconstrained NLOP:

$$\min_{(x_1, x_2) \in \mathbb{R}^2} f(x_1, x_2),$$

where $f(x_1, x_2)$ is defined by

$$14 \cdot \sqrt{(x_1 - 7)^2 + (x_2 - 2)^2} + 20 \cdot \sqrt{(x_1 - 5)^2 + (x_2 + 3)^2} + 30 \cdot \sqrt{(x_1 + 6)^2 + (x_2 - 4)^2}.$$

In a .ipynb file using only python code:

- (a) (3 pts.) Plot the graph of f over an appropriate domain.
- (b) (5 pts.) Starting from the point $x^0 := (0, 0)$ conduct iterations of the Generic Algorithm for Unconstrained Nonlinear Optimization Problems using the steepest descent search direction and an exact line search to solve this problem.
- (c) (2 pts.) Is the point at which the algorithm terminates guaranteed to be a local or global optimum? Why? (only for this it is not necessary to use python code.)

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