

Unit 14

Iterative Solution Algorithms for Nonlinear Optimization

14.1 Iterative Solution Algorithm for Constrained Nonlinear Optimization Problems

Let us remember that a **constrained NLPP** can be generically written as:

$$\begin{array}{ll}\min & f(x) \\ \text{s.t.} & x \in C,\end{array}$$

where $C := \{x \in \mathbb{R}^n ; h_1(x) = 0, \dots, h_p(x) = 0, g_1(x) \leq 0, \dots, g_q(x) \leq 0\}$ is the feasible set, $h_1, \dots, h_p : \mathbb{R}^n \rightarrow \mathbb{R}$ are the equality-constraint functions, $g_1, \dots, g_q : \mathbb{R}^n \rightarrow \mathbb{R}$ are the less-than-or-equal-to-constraint functions, $p, q \in \{0, 1, 2, \dots\}$ and $f : \mathbb{R}^n \rightarrow \mathbb{R}$ is the objective function.

14.1.1 Multiplier Method

Example 14.1. Consider $f, h, g : \mathbb{R}^2 \rightarrow \mathbb{R}$ defined by $f(x_1, x_2) = (x_1 + 2)^2 + (x_2 - 3)^2$, $h(x_1, x_2) = x_1 + 2 \cdot x_2 - 4$ and $g(x_1, x_2) = -x_1$, respectively. Solve the problem by the **Multiplier Method** using:

1. a tolerance of 0.001;
2. $x^0 = (-1, -1, -1)$;
3. initial λ equal to $(1, 1)$;
4. initial ρ equal to $(1, 1)$;

5. the steepest descent search direction with the Armijo rule with $\sigma = 0.1$, $\beta = 0.1$ and $s = 1$;

And if a constraint is violated, multiply the penalty weight on that constraint by 3.

Solution. First, we convert the inequalities to equalities; thus, we have $h_1, h_2 : \mathbb{R}^3 \rightarrow \mathbb{R}$ defined by $h_1(x_1, x_2, x_3) = x_1 + 2 \cdot x_2 - 4$ and $h_2(x_1, x_2, x_3) = -x_1 + x_3^2$, respectively. Second, we denote the augmented Lagrangian function

$$A_{\lambda, \rho}(x) := f(x_1, x_2) + \lambda_1 \cdot h_1(x) + \lambda_2 \cdot h_2(x) + \rho_1 \cdot h_1(x)^2 + \rho_2 \cdot h_2(x)^2,$$

where $x := (x_1, x_2, x_3)$. Third, after conducting the following:

Algorithm 1: Multiplier method for problem stated in Example 14.1

```

1  $k \leftarrow 0$ 
2  $x^k := (x^k_1, x^k_2, x^k_3) \leftarrow (-1, -1, -1)$ 
3  $\lambda := (\lambda_1, \lambda_2) \leftarrow (1, 1)$ 
4  $\rho := (\rho_1, \rho_2) \leftarrow (1, 1)$ 
5 Update augmented Lagrangian function  $A_{\lambda, \rho}$ 
6  $grad \leftarrow \nabla A_{\lambda, \rho}(x^k)$ 
7 while  $grad \neq 0$  or  $h(x^k_1, x^k_2) \neq 0$  or  $g(x^k_1, x^k_2) > 0$  do
8    $d^k \leftarrow -grad$ 
9   Determine step size,  $\alpha^k$ 
10   $x^{k+1} \leftarrow x^k + \alpha^k \cdot d^k$ 
11   $k \leftarrow k + 1$ 
12  for  $j \leftarrow 1, 2$  do
13     $\lambda_j \leftarrow \lambda_j + 2 \cdot \rho_j \cdot h_j(x^k)$ 
14    if  $h_j(x^k) \neq 0$  then
15       $\rho_j \leftarrow 3 \cdot \rho_j$ 
16    end
17  end
18  Update augmented Lagrangian function  $A_{\lambda, \rho}$ 
19   $grad \leftarrow \nabla A_{\lambda, \rho}(x^k)$ 
20 end
```

We have:

```

Iteration 0
x          : Matrix([[-1], [-1], [-1]])
f(x[:2])   : 17.00000000000000
direction   : Matrix([[16.000000000000], [34.000000000000], [10.000000000000]])
alpha       : 0.1

Iteration 1
x          : Matrix([[0.60000000000000], [2.40000000000000], [0]])
f(x[:2])   : 7.12000000000000
direction   : Matrix([[-21.200000000000], [-23.200000000000], [0]])
alpha       : 0.01000000000000002

Iteration 2
x          : Matrix([[0.38800000000000], [2.16800000000000], [0]])
f(x[:2])   : 6.39476800000000
direction   : Matrix([[-35.464000000000], [-40.688000000000], [0]])
alpha       : 0.01000000000000002

```

Figure 14.1: Results of first iterations.

```

Iteration 123
x          : Matrix([[1.50493221790030e-10], [1.99999999984951], [0]])
f(x[:2])   : 5.00000000000296
direction   : Matrix([[0.00328433096398357], [-0.0032843313472496], [0]])
alpha       : 1.000000000000005e-07

Iteration 124
x          : Matrix([[4.78926318188388e-10], [1.99999999952107], [0]])
f(x[:2])   : 5.00000000287356
direction   : Matrix([[0.00156807579155078], [-0.00156807585644030], [0]])
alpha       : 1.000000000000005e-07

x          : Matrix([[6.35733897343466e-10], [1.99999999936427], [0]])
f(x[:2])   : 5.00000000381440

```

Figure 14.2: Results of last iterations.