

Volcanic Eruption Simulation

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Abstract

When thinking about physical phenomenon, lava flows often come first in mind being both visually impressive and a real natural threat for its surrounding areas. Although being popular, fast and physically accurate eruption simulations can be tricky because of the unusual laws the flow follows and the hard solver needed to resolve them. This paper present a new Lagrangian technique to efficiently simulate lava flows using shallow water equations.

Introduction

Being able to simulate lava flows in a physically accurate manner can lead to both visually stunning results and a useful prediction tool to prevent casualties of real eruptions. During eruptions, the flow of lava can be seen as a pretty thin layer of fluid; this observation leads us to the idea of using shallow water equations[1] to simulate the flow.

State of the art

Simulation of fluids in 3D are well studied in the literature either for Lagrangian solvers or Eulerian methods. Usually these simulations come at high cost, requiring millions of particles to reproduce small scale effects. A way to reduce this cost, as used in *insert citation*, is to solve only two components in the 3D space hence reducing the number of operations and the internal size of the simulation.

- SWE adding horizontal velocity field [1]
- SWE for non-uniform terrain [2] (but uniform particles, i.e. same height everywhere)

Method

First approach: Shallow-water

- 2D sph -> sphere over height map
- Each particle represents a column of lava of a certain height

- Each column same velocity + parallel to the terrain (for now, later add horizontal velocity ?)

$$\frac{Dh}{Dt} = -h\nabla \cdot u \quad (1)$$

$$u = -\frac{g}{k}\nabla S + a_{ext} \quad (2)$$

H : height of the terrain at a given position $\rightarrow H(x, y) = z$

h : height of a particle representing the column of lava, h is calculated using the formula: $h\rho_0 = \rho$,

$\rho_0 = 2500 \text{ kg.m}^{-3}$ (lava rest density [3]), ρ : the current density of the particle

S : surface at a given position $\rightarrow S_i = H(x_i, y_i) + h_i$

a_{ext} : contains the viscosity force

g : the gravitational constant

k : the stiffness coefficient

terrain gradient:

- euler method

$$y = H(x, z)$$

$$\Delta x = \Delta z = 1$$

$$\frac{\partial H}{\partial x}(x, z) = \frac{H(x + \Delta x, z) - H(x, z)}{x + \Delta x - x} = H(x + 1, z) - y$$

$$\frac{\partial H}{\partial z}(x, z) = \frac{H(x, z + \Delta z) - H(x, z)}{z + \Delta z - z} = H(x, z + 1) - y$$

\rightarrow simulation explodes without viscosity force so adding them

SPH

Since we're using 2D SPH, to evaluate a quantity q at an arbitrary position x , we interpolate a weighted sum of contribution of the particles j around x within the radius l of a kernel W .

$$q(x) = \sum_j \frac{m_j}{\rho_j} q_j W(x - x_j, l) \quad (3)$$

Where x_j is the position of the particle j , m_j its mass and ρ_j its density.

We discrete the space with particles, so, instead of arbitrary positions, we only consider quantities at each particle position x_i

$$q(x_i) = \sum_j \frac{m_j}{\rho_j} q_j W(x_i - x_j, l) = \sum_j \frac{m_j}{\rho_j} q_j W(r, l) \quad (4)$$

Differential operators act on the kernel only and can be computed using the formulas:

$$\nabla q(x_i) = \sum_j \frac{m_j}{\rho_j} q_j \nabla W(r, l) \quad (5)$$

$$\nabla \cdot q(x_i) = \sum_j \frac{m_j}{\rho_j} q_j \nabla \cdot W(r, l) \quad (6)$$

$$\Delta q(x_i) = \sum_j \frac{m_j}{\rho_j} q_j \Delta W(r, l) \quad (7)$$

Algorithm

The algorithm for the update loop is the following:

1. Compute the neighbours for each particle
2. Compute the density for each particle using 2D SPH formulas and update the height accordingly
3. Compute the viscosity
4. Time integration
5. Removing particles outside the grid

To get more into the details of each point:

1. Basic grid search using a simple 2D grid ($z = 0$) ($cell_{width} = 4 * W_{radius}$), get the particles within the cell in which is the current particle and then check if $dist(p_i, p_j) < W_{radius}$ (todo: plot image of the grid)
2. We use a Poly6 Kernel[1] to calculate the density overtime

$$W_{poly6} = \frac{4}{\pi l^8} \begin{cases} (l^2 - r^2)^3 & 0 \leq r \leq l \\ 0 & \text{otherwise} \end{cases} \quad (8)$$

Once we have the new density for each particle we can find the height of the lava column they represent :

$$h_i = \frac{\rho_i}{\rho_0} \quad (9)$$

$$\rho_0 = 2500 kg.m^{-3} (\text{lava rest density [3]})$$

3. The viscosity is very important to stabilize the simulation and since the Laplacien of the poly6 kernel8 can lead to negative values, we used another kernel[1] for the viscosity.

$$W_{viscosity} = \frac{10}{9\pi l^5} \begin{cases} -4r^3 + 9r^2l - 5l^3 + 6l^3(\ln l - \ln r) & 0 \leq r \leq l \\ 0 & \text{otherwise} \end{cases} \quad (10)$$

$$\Delta W_{viscosity} = \frac{40}{\pi l^5} (l - r) \quad (11)$$

4.

Better approach: Stokes problem

Rendering

- rendu sur texture

Results

Conclusion

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