

EEEE1002 Applied Engineering Design

I2C Example Code Breakdown



Overview

- This PowerPoint discusses the code contained inside 'Example 1: Arduino to Arduino I2C Communication' and 'Example 2: Master Device to ESP32 Slave I2C Communication'
- Remember that if you want to run Example 2 with an Arduino as the master, you need a voltage logic level shifter on both data lines (SDA, SCL)
- This PowerPoint covers:
 - The operators and syntax used in the code
 - Overview of the data handling and communication used

Data being transmitted and received can be handled in a variety of ways using a variety of data types – these examples present one such method; however feel free to implement your own



Note on the I2C Libraries Between Example 1 & Example 2

- The difference between example 1 and example 2 is that for Arduino I2C communication, the standard Wire.h library can be used
- In example 2, as an ESP32 is setup as a slave device, the ESP32 I2C Slave library (WireSlave.h) is used however the code functionality and general I2C process is identical to Example 1
- This can be downloaded from: https://github.com/gutierrezps/ESP32_I2C_Slave
- It is recommended you read through and run the example programs contained in this library



The following operators are used within the example code



Bitwise Right Shift



- **Definition:** The right shifter operator causes the bits of the left operand to be shifted right by the number of positions specified by the right operand
- Syntax: variable >> number_of_bits;
- **Example:** Assuming int has a variable size of 8-bits...

```
int x = 241;  // 8-bit binary value of 11110001
int y = x >> 3;  // 8-bit binary value of 00011110; note that bits outside of the variable size are lost
```

If no bits are lost, shifting a binary number N bits to the right is equivalent to dividing the denary equivalent by 2^N



Bitwise Left Shift



- **Definition:** The left shift operator causes the bits of the left operand to be shifted left by the number of positions specified by the right operand
- Syntax: variable << number_of_bits;</p>
- **Example:** Assuming int has a variable size of 8-bits...

```
int x = 241;  // 8-bit binary value of 11110001 int y = x << 3;  // 8-bit binary value of 10000010; note that bits outside of the variable size are lost
```

If no bits are lost, shifting a binary number N bits to the left is equivalent to multiplying the denary equivalent by 2^N



Bitwise AND

&

• **Definition:** The AND operator compares the bits in the same position of the two variables, returning a value of TRUE (i.e. 1) if both of the bit inputs are TRUE – otherwise it returns FALSE (i.e. 0). See the following truth table and logic gate symbol.

Input_A Output

2 - input AND gate

Α	В	Output
0	0	0
0	1	0
1	0	0
1	1	1

This will be covered in H61INF: Information & Systems

- Syntax: variable1 & variable2;
- **Example:** Assuming int has a variable size of 8-bits...

```
int x = 23;  // binary: 00010111
int y = 24;  // binary: 00011000
int z = x & y;  // binary: 00010000 – equivalent to 16 in denary
```

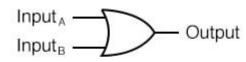
Its purpose in the code is explained later...



Bitwise OR

Definition: The OR operator compares the bits in the same position of the two variables, returning a value of TRUE (i.e. 1) if either, or both, of the bit inputs are TRUE – otherwise it returns FALSE (i.e. 0). See the following truth table and logic gate symbol.

2 - input OR gate



Α	В	Output
0	0	0
0	1	1
1	0	1
1	1	1

This will be covered in H61INF: Information & Systems

- Syntax: variable1 | variable2;
- **Example:** Assuming int has a variable size of 8-bits...

```
int x = 23;  // binary: 00010111
int y = 24;  // binary: 00011000
int z = x \mid y;  // binary: 00011111 – equivalent to 31 in denary
```

Its purpose in the code is explained later...



I2C Communication & Data Handling Overview



12C Communication Overview

- We will follow the code used in Example 1, except with a simple case of just transferring the variable x
- Remember the communication and data handling process is identical between Example 1 and Example 2
- We will assume that the int variable size is 32-bits, however the principle described is the same just with a varying amount of bytes (1 byte = 8 bits)
- The int variable size varies depending which microcontroller you are using – research this before you write your code



A Note on Signed Integer Representation

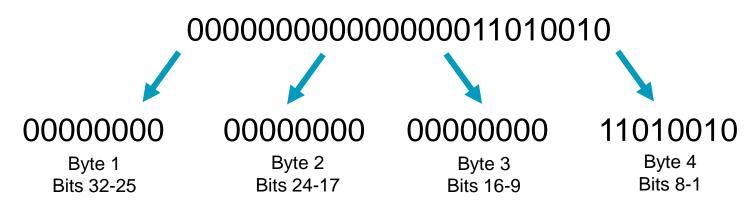
- If we have an N-bit number, it can store 2^N unsigned integers, with the range 0 to $2^N 1$
- However if we want to represent negative (i.e. signed) integer, we have to use the most significant bit to indicate if the value is positive or negative this method is called 'Two's Complement', do your own research on how use this
- As a result, we can still store 2^N values, however the range is now between -2^{N-1} to $2^{N-1}-1$
- For example, if we have an 8-bit variable, it can store 128 values. For unsigned integers, the range is 0 to 255. For signed integers, the range is -128 to 127



Integer Representation

```
int x = -210;
```

- Let us take a simple case, with x equal to the integer value of 210
- In binary this is 11010010 (represented by 0b000000000000000000000011010010 in the code – remember the 32-bit variable size!)
- This is equivalent to four bytes:





```
Wire.write((byte)((x & 0x0000FF00) >> 8));
Wire.write((byte)(x & 0x00000FF));
```

- Starting from inside the brackets and working out...
- We first just want the 8 bits we are interested in
- Like how 0b represents a binary number, 0x represents a hexadecimal number; with F being 15 in denary or 1111 in binary – note that each character in hexadecimal is equivalent to 4 bits
- In order to get bytes 3 and 4, that were labelled in the previous slide, we AND the variable x with the hexadecimal equivalent of 11111111 in the positions of the bits we want; as a 0 ANDed with another bit results in 0 and a 1 ANDed with another bit results in 1



```
Wire.write((byte)((x & 0x0000FF00) >> 8));
Wire.write((byte)(x & 0x000000FF));
```

- But what about bytes 1 and 2!
- In order to reduce the amount of data we are sending, we are not extracting these bytes of data – as in our EEEBot, we only need to send values between -255 and 255 (requiring 9 bits – remember Two's Compliment!)
- Bytes 1 and 2 (holding bits 32 to 17) are only needed if we wanted to send signed integers between -2,147,483,648 and -65,536 or between 65,535 and 2,147,483,647 – rather excessive for us!



```
Wire.write((byte)((x & 0x0000FF00) >> 8));
Wire.write((byte)(x & 0x000000FF));
```

Result:

Result:

• With x = 210, $x \in 0x0000FF00$ looks like:

x: 0000000000000000000000011010010 & (AND)

• With x = 210, $x \in 0x000000$ looks like:

All the bits not of interest are set to 0

```
x: 0000000000000000000000011010010 & (AND)
```

00000000000000000000000011010010

■ The need for this operator is best seen with a negative number...



- If x = -210, the binary representation would instead be 0b111111111111111111111111111100101110
- Therefore to get bytes 3 and 4...
- With x = -210, $x \in 0x0000FF00$ looks like:

Result:

All the bits not of interest are set to 0

• With x = -210, $x \in 0x0000000$ looks like:

```
x: 1111111111111111111111111111001011110 & (AND)
```

Result: 0000000000000000000000000011110



```
Wire.write((byte)((x & 0x0000FF00) >> 8));
Wire.write((byte)(x & 0x000000FF));
```

- Back to x = 210
- As I2C communication can only send information one byte at a time, we need to split the variable, x, into 8-bit segments of data
- Note; as we are now ignoring bytes 1 and 2 of the 32-bit variable, x we will only split x into two bytes (bytes 3 and 4) of data
- As a byte is only 8 bits and (byte) ignores bits 9 and above, we need to 'shuffle' our 8 bits of interest (in each case), to the right X times until they are in the positions of 8 to 1
- This is where we use the Bitwise Right Shift operator (>>)



```
Wire.write((byte)((x & 0x0000FF00) >> 8));
Wire.write((byte)(x & 0x000000FF));
```

- For (byte) (x & 0x000000FF), the bits of interest, relating to byte 4, are already in positions 8 to 1 so no shifting is required
- However, for (byte) ((x & 0x0000FF00) >> 8), the bits of interest, relating to byte 3, are in positions 16 to 9 and so required shifting to the right by 8 bits i.e. subtracting 8 off the bit's position
- The data (byte 3) for (byte) ((x & 0x0000FF00) >> 8) looks like: 000000000 Although for this value of x, byte 3 is 0 -this will not always be the case i.e. when x < -128
- The data (byte 4) for (byte) (x & 0x0000000FF) looks like: 11010010



Transmitting & Receiving Bytes

- Each byte is then sent sequentially along the I2C data lines using Wire-write - in Example 2 the bytes are first written in 'packer'
- In the slave code, each byte is received sequentially, i.e. in the same order as it was sent, and is assigned to a variable using Wire.read()
- In Example 2, WireSlave.read() is used instead
- Therefore, the first byte received is equivalent to byte 3 and the second is byte 4 as these are bytes we read them into an 8-bit integer type so the bit-size does not change but they can now be manipulated as integers; rather than bytes



Data Types

- Remember these examples show just one way of handling I2C data,
 the most suitable data types to use will vary with the code purpose
- Just remember that the incoming data will be one byte long (8-bits)
- This must be considered when handling the data otherwise conversion into other data types may result in unpredictable results with bits either being lost or added
- A quick google of the Arduino IDE data types will show their bit lengths; https://learn.sparkfun.com/tutorials/data-types-in-arduino/all



$$x = (x16 9 \ll 8) | x8 1;$$

As a recap, the data stored in the two variables relating to x is:

Byte that the Bits Relate to from the Original Number (Slide 12)	Bits Stored	Variable
Byte 3	00000000	x16_9
Byte 4	11010010	x8_1

 So now we need to reconstruct the original number that was stored in 'x' in the master code...



```
int16_t x = 0;

x = (x16_9 << 8) | x8_1;
```

- Working from inside the brackets outwards, we first shift the bits relating to byte 3 to the left by 8 bits
- This effectively undoes the right bit shift that was performed in the master code, in order to restore the bits original position in the original integer
- The bits aren't lost as x has been defined as a 16-bit integer which by default has a value of 0 i.e. 16 0-bits
- Again, as for x = 210 bits 16 to 9 are all 0, this is best shown with a different example...



```
int16_t x = 0;

x = (x16_9 << 8) | x8_1;
```

- Referring back to x = -210 from Slide 16...
- Byte 3 has a value of 111111111
- Therefore, the result from ×16_9 << 8 looks like 11111111100000000
- Now you can clearly see that the bits have all been shifted to the left by 8-bits, restoring their original position in original number



```
int16_t x = 0;

x = (x16_9 << 8) | x8_1;
```

- Back to x = 210...
- Now we have a 16-bit value with only bits 16 to 9 with the correct value, and an 8-bit value with only bits 8 to 1 with the correct value
- Note that is we take an 8-bit variable and assign it to a 16-bit variable, by default the extra bits i.e. bits 16 to 9 are set to 0's
- Likewise, if we put an operator between a 16-bit and 8-bit number, the extra 'empty' bits (16 to 9) are treated as 0
- Therefore, in order to combine these two values and restore the bitstream of the original value, we use an OR operator



- We use the OR operator as no bits are changed due to the fact that if a '1' bit is ORed with a '0' bit, the result is 1
- We don't need to worry about when both bits are 1 as these never occur because only the 8 'potentially non-zero' bits in each variable never are in the same position
- In denary, this is equivalent to 210 i.e. the original number has been successfully transmitted and received
- Remember x is in Two's Compliment if you are working in binary, however the int variables handles this automatically



End of I2C Example Code Breakdown