

```
#include <kipr/wombat.h>
```

```
int main()
```

```
{
```

```
    printf("Hello World\n");
```

```
    create_connect();
```

```
    enable_servos();
```

```
    set_servo_position(3,1100);
```

```
    msleep(1000);
```

```
    create_drive_direct(-500,-500);
```

```
    msleep(500);
```

```
    create_drive_direct(1,300);
```

```
    msleep(1003);
```

```
    return 0;
```

```
}
```