Chapter 2: Assembly Language Fundamentals

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Chapter Goals

- Understand the importance of assembly language.
 - The interface between hardware and software.
- Understand how assembly instruction are represented.
 - What and how much information is encoded in the instructions.
 - How these design choices affect the instruction format, and thus code density and power the power of the instructions

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2.1 Introduction

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Assembly Language

I speak Spanish to God,
Italian to women,
French to men,
And German to my horse

Charles V, King of France (1337-1380)

(An excerpt from Computer Organization & Design: The Hardware/Software Interface by Patterson and Hennessy)

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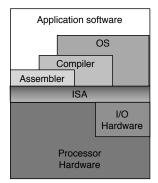
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2.2 How Do We Speak the Language of the Machine

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How Do We Speak the Language of the Machine?

- Instruction Set Architecture (ISA) is the portion of the machine visible to the programmer or compiler writer.
 - The basic operations of a computer are defined by its ISA.
 - Because instructions are the only information that the machine understands, an instruction set is also a machine language.
 - Sequences of instructions are called machine language programs, and the act of constructing such programs is machine language programming.



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2.3 Instruction Set Architecture

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Classification of ISA

- Four dimensions of instruction sets:
 - Operations provided in the instruction set.
 - Number of explicit operands named per instruction.
 - Location of the operands in the CPU and how operand locations are specified.
 - Type and size of operands.

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Operations in the ISA

- Important criteria for designing an instruction set are
 - Functional completeness
 - Efficiency (power of the instruction)
 - Simplicity of hardware design and/or programming

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Categories of Instructions

- Data transfer which cause information to be copied from one location to another either in the processor's internal memory (registers) or in the external main memory.
- 2. **Arithmetic** which perform operations on numeric data (e.g., add, subtract....).
- Logical which include Boolean and other non-numerical operations (e.g., and, not....)
- 4. **Control transfer** which change the sequence in which program are executed (jump, conditional branch...)
- 5. **I/O** which cause information to be transferred between the processor or its main memory and external I/O devices.
- 6. System used for operating system call, virtual memory management instructions....
- 7. Floating point used for floating point operations.
- 8. Decimal decimal arithmetic, decimal-to-character conversions...
- 9. String string move, compare, search....

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Number of Operands per Instruction

- The number of operands associated with each instruction can be considered in terms of the following issues:
 - Control circuit complexity (decoding).
 - Storage required for instructions (code density).
 - Power of instructions.
 - Number of instructions required to perform a given task.

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Example

Let x and y represent memory locations or registers.

• 4-address instruction: No longer in use

ADD
$$x + y \rightarrow z$$
, goto q

• 3-address instruction: General Purpose Register (GPR) architecture

ADD
$$x + y \rightarrow z$$
 (q is implied)

ADD
$$x + y \rightarrow x$$
, goto q

2-address instruction: General Purpose Register (GPR) architecture

ADD
$$x + y \rightarrow x$$

I-address instruction: Accumulator-based architecture

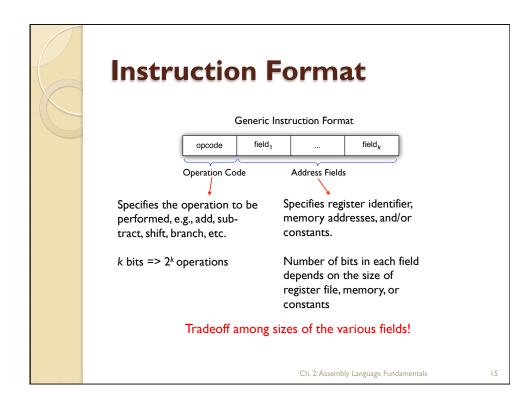
0-address instruction: Stack architecture

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2.4 Instruction Format

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• 2.4 A Pseudo-ISA Ch.2:Assembly Language Fundamentals

A Pseudo-ISA

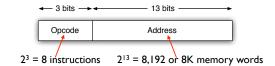
- Data transfer Instructions
 - LDA (Load Accumulator) Loads a memory word to accumulator · LDA x; x is a location in memory
 - STA (Store Accumulator) Stores the contents of accumulator to memory
- Arithmetic and Logical Instructions
 - ADD (Add to Accumulator) Adds the content of memory word specified by the effective address to the value of the accumulator.
 - ADD x; x is a location in memory
 - NAND (NAND to Accumulator)
 - SHFT (Shift Accumulator) Shifts the content of AC by one bit to the left. The bit shifted in is 0.
- Control Transfer
 - $^{\circ}$ J (Jump to x) Transfers the program control to the instruction specified by the address.
 - J x; jump to instruction in memory location x
 - BNE (Branch Conditionally to x) Transfers the program control to the instruction specified by the address based on condition NE (not equal).
 - BNE x; branch to instruction in memory location x if content of AC is not zero

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Instruction Format of Pseudo-ISA

I-address Instruction Format



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Example Assembly Program

```
;A simple C program main() 
 { int A=83, B=-23, C=0; C = 4*A + B; }
```

Label	Instructions		Comments
	ORG	0	/Origin of the program is location 0
	LDA	Α	/Load operand from location A
	SHIFT		/Multiply A by 2
	SHIFT		/Multiply 2*A by 2
	ADD	В	/Add operand from location B
	STA	С	/Store sum in location C
Loop	: J	Loop	/Loop forever
A:	DEC	83	/Decimal operand
B:	DEC	-23	/Decimal operand
C:	DEC	0	/Sum stored in location C
	END		/End of symbolic program

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Why Program in Assembly?

- For many applications the speed and/or size a program is critically important, e.g., embedded application, such as ABS.
 - Need to respond rapidly and predictably to events, e.g., I ms after the sensor detects that a tire is skidding.
 - Compiler introduces uncertainty about the time cost of operations. For complex problems, HLL preferable.

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Questions?



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